# Complexity of Roman \{2\}-domination and the double Roman domination in graphs 

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# Complexity of Roman \{2\}-domination and the double Roman domination in graphs 

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#### Abstract

For a simple, undirected graph $G=(V, E)$, a Roman \{2\}-dominating function (R2DF) $f: V \rightarrow$ $\{0,1,2\}$ has the property that for every vertex $v \in V$ with $f(v)=0$, either there exists a vertex $u \in$ $N(v)$, with $f(u)=2$, or at least two vertices $x, y \in N(v)$ with $f(x)=f(y)=1$. The weight of an R2DF is the sum $f(V)=\sum_{v \in V} f(v)$. The minimum weight of an R2DF is called the Roman \{2\}-domination number and is denoted by $\gamma_{\{R 2\}}(G)$. A double Roman dominating function (DRDF) on $G$ is a function $f: V \rightarrow\{0,1,2,3\}$ such that for every vertex $v \in V$ if $f(v)=0$, then $v$ has at least two neighbors $x, y \in N(v)$ with $f(x)=f(y)=2$ or one neighbor $w$ with $f(w)=3$, and if $f(v)=1$, then $v$ must have at least one neighbor $w$ with $f(w) \geq 2$. The weight of a DRDF is the value $f(V)=$ $\sum_{v \in V} f(v)$. The minimum weight of a DRDF is called the double Roman domination number and is denoted by $\gamma_{d R}(G)$. Given an graph $G$ and a positive integer $k$, the R2DP (DRDP) problem is to check whether $G$ has an R2DF (DRDF) of weight at most $k$. In this article, we first show that the R2DP problem is NP-complete for star convex bipartite graphs, comb convex bipartite graphs and bisplit graphs. We also show that the DRDP problem is NP-complete for star convex bipartite graphs and comb convex bipartite graphs. Next, we show that $\gamma_{\{R 2\}}(G)$, and $\gamma_{d R}(G)$ are obtained in linear time for bounded tree-width graphs, chain graphs and threshold graphs, a subclass of split graphs. Finally, we propose a $2(1+\ln (\Delta+1))$-approximation algorithm for the minimum Roman \{2\}-domination problem and $3(1+\ln (\Delta+1))$-approximation algorithm for the minimum double Roman domination problem, where $\Delta$ is the maximum degree of $G$.


## KEYWORDS

Roman \{2\}-domination; double Roman domination; tree convex bipartite graphs; NP-complete; approximation algorithm

## 2010 MSC

05C69; 68Q25

## 1. Introduction

Consider $G=(V, E)$ be a simple, undirected and connected graph. For a vertex $v \in V$, the open neighborhood of $v$ in $G$ is $N_{G}(v)=\{u \mid u \in V,(u, v) \in E\}$ and the closed neighborhood of $v$ is defined as $N_{G}[v]=N_{G}(v) \cup\{v\}$. We shall follow [11] for graph theoretic terminology. A bipartite graph $G=$ $(X, Y, E)$ is called tree convex if there exists a tree $T=(X, F)$ such that, for each $y$ in $Y$, the neighbors of $y$ induce a subtree in $T$. When $T$ is a star (comb), $G$ is called star (comb) convex bipartite graph [10]. A bisplit graph is a graph in which vertex set can be partitioned into an independent set and a complete bipartite graph.

A vertex $v$ in $G$ dominates the vertices of its closed neighborhood. A set of vertices $S \subseteq V$ is a dominating set (DS) in $G$ if for every vertex $u \in V \backslash S$, there exists at least one vertex $v \in S$ such that $(u, v) \in E$, i.e., $N_{G}[S]=V(G)$. The domination number is the minimum cardinality of a dominating set in $G$ and is denoted by $\gamma(G)$ [8].

The concept of Roman domination was introduced in 2004 by Cockayne et al. [5]. A function $f: V \rightarrow\{0,1,2\}$ is a Roman dominating function (RDF) on $G$ if every vertex $u \in V$ for which $f(u)=0$ is adjacent to at least one vertex $v$
for which $f(v)=2$. The weight of an RDF is the value $f(V)=\sum_{u \in V} f(u)$. The Roman domination number is the minimum weight of an RDF on $G$ and is denoted by $\gamma_{R}(G)$.

Roman $\{2\}$-domination was introduced in 2016 by Chellali et al. [4]. A Roman $\{2\}$-dominating function (R2DF) $f: V \rightarrow\{0,1,2\}$ has the property that for every vertex $v \in$ $V$ with $f(v)=0$, either there exists a vertex $u \in N(v)$, with $f(u)=2$, or at least two vertices $x, y \in N(v)$ with $f(x)=$ $f(y)=1$. The weight of an R2DF is the value $f(V)=$ $\sum_{v \in V} f(v)$. The minimum weight of an R2DF is called the Roman \{2\}-domination number and is denoted by $\gamma_{\{R 2\}}(G)$.

Double Roman domination was initiated in 2016 by Robert et al. [3]. A double Roman dominating function (DRDF) on $G$ is a function $f: V \rightarrow\{0,1,2,3\}$ such that for every vertex $v \in V$ if $f(v)=0$, then $v$ has at least two neighbors $x, y \in N(v)$ with $f(x)=f(y)=2$ or one neighbor $w$ with $f(w)=3$, and if $f(v)=1$, then $v$ must have at least one neighbor $w$ with $f(w) \geq 2$. The weight of a DRDF is the value $f(V)=\sum_{v \in V} f(v)$. The double Roman domination number equals the minimum weight of a DRDF on $G$, denoted by $\gamma_{d R}(G)$.

Given a graph $G$ and a positive integer $k$, the R2DP (DRDP) problem is to check whether $G$ has an R2DF

[^0](DRDF) of weight at most $k$. Chellali et al. [4] have proved that the R2DP problem is NP-complete for bipartite graphs. Ahangar et al. [1] have proved that the DRDP problem is NP-complete for bipartite and chordal graphs. Motivated by their work [1, 4], we investigate the complexity of R2DP and DRDP problems in subclasses of bipartite graphs and chordal graphs.

## 2. Complexity results

In this section, we show that the decision versions of the R2DF and DRDF problems are NP-complete for some subclasses of bipartite graphs by giving a polynomial time reduction from a well-known NP-complete problem, Exact-3-Cover (X3C) [9], which is defined as follows.
EXACT-3-COVER (X3C)
INSTANCE: A finite set $X$ with $|X|=3 q$ and a collection $C$ of 3-element subsets of $X$.
QUESTION: Is there a subcollection $C^{\prime}$ of $C$ such that every element of $X$ appears in exactly one member of $C^{\prime}$ ?
The decision versions of Roman $\{2\}$-domination and double Roman domination problems are defined below.
ROMAN $\{2\}$-DOMINATION PROBLEM (R2DP)
INSTANCE: Graph $G=(V, E)$ and a positive integer $k \leq|V|$.
QUESTION: Does $G$ have an R2DF of weight at most $k$ ?

## DOUBLE ROMAN DOMINATION PROBLEM (DRDP)

INSTANCE: Graph $G=(V, E)$ and a positive integer $k \leq 2|V|$.
QUESTION: Does $G$ have a DRDF of weight at most $k$ ?
Theorem 1. R2DP is NP-complete for star convex bipartite graphs.

Proof. Given a graph $G$ and a function $f$, whether $f$ is an R2DF of size at most $k$ can be checked in polynomial time. Hence R2DP is a member of NP. Now we show that R2DP is NP-hard by transforming an instance $\langle X, C\rangle$ of X 3 C , where $X=\left\{x_{1}, x_{2}, \ldots, x_{3 q}\right\}$ and $C=\left\{c_{1}, c_{2}, \ldots, c_{t}\right\}$, to an instance $\langle G, k\rangle$ of R2DP as follows.

Create vertices $x_{i}, y_{i}$ for each $x_{i} \in X, c_{i}$ for each $c_{i} \in C$ and also create vertices $a, a_{1}, a_{2}$ and $a_{3}$. Add edges $\left(x_{i}, y_{i}\right)$ for each $x_{i} \in X,\left(a_{i}, a\right)$ for each $a_{i}$ and $\left(c_{i}, a\right)$ for each $c_{i}$. Also add edges $\left(c_{j}, x_{i}\right)$ if $x_{i} \in c_{j}$. Let $A=\{a\} \cup\left\{x_{i}: 1 \leq i \leq 3 q\right\}$ and $B=\left\{y_{i}: 1 \leq i \leq 3 q\right\} \cup\left\{c_{i}: 1 \leq i \leq t\right\} \cup\left\{a_{1}, a_{2}, a_{3}\right\}$. The subgraph induced by $A$ is a star with vertex $a$ as central vertex and the neighbors of each element of $B$ induce a subtree of star. Therefore $G$ is a star convex bipartite graph and can be constructed from the given instance $\langle X, C\rangle$ of X3C in polynomial time.

Next we show that, $X 3 C$ has a solution if and only if $G$ has an R2DF with weight at most $4 q+2$. Let $k=4 q+2$. Suppose $C^{\prime}$ is a solution for $X 3 C$ with $\left|C^{\prime}\right|=q$. We define a function $f: V \rightarrow\{0,1,2\}$ as follows.

$$
f(v)= \begin{cases}1, & \text { if } v \in\left\{y_{i}: 1 \leq i \leq 3 q\right\} \cup\left\{c_{i}: c_{i} \in C^{\prime}\right\}  \tag{1}\\ 2, & \text { if } v=a \\ 0, & \text { otherwise }\end{cases}
$$

It can be easily verified that $f$ is an R2DF of $G$ and $f(V)=$ $4 q+2=k$.

Conversely, suppose that $G$ has an R2DF $g$ with weight $k$. Let $M=\left\{a, a_{1}, a_{2}, a_{3}\right\}$. Clearly, $\sum_{u \in M} g(u) \geq 2$, and so we may assume, without loss of generality, $g(a)=2$ and $g\left(a_{1}\right)=g\left(a_{2}\right)=g\left(a_{3}\right)=0$. Since $\left(a, c_{j}\right) \in E$, it follows that each vertex $c_{j}$ may be assigned the value 0 . Clearly, $g\left(x_{i}\right)=$ 0 and $g\left(y_{i}\right)=0$ case does not occur.

Claim 1. If $g(V)=k$ then for each pair of vertices $\left(x_{i}, y_{i}\right)$, $g\left(x_{i}\right)=0$ and $g\left(y_{i}\right)=1$.

Proof. (Proof by contradiction) Assume $g(V)=k$ and there exist some pairs $\left(x_{i}, y_{i}\right)$ such that $g\left(x_{i}\right)+g\left(y_{i}\right)>1$. Let $m$ be the number of pairs of $\left(x_{i}, y_{i}\right)$ with $g\left(x_{i}\right)+g\left(y_{i}\right)=2$. The number of pairs of $\left(x_{i}, y_{i}\right)$ with $g\left(x_{i}\right)=0$ and $g\left(y_{i}\right)=1$ is $3 q-m$. Since $g$ is an R2DF, each $x_{i}$ with $g\left(x_{i}\right)=0$, where $g\left(y_{i}\right)=1$, should have neighbor $c_{j}$ with $g\left(c_{j}\right)=1$. Then the minimum number of $c_{j}^{\prime}$ s required with $g\left(c_{j}\right)=1$ is $\left\lceil\frac{3 q-m}{3}\right\rceil$. Hence $g(V)=3 q+2+m+\left\lceil\frac{3 q-m}{3}\right\rceil$, which is greater than $k$. Our assumption leads to a contradiction. Therefore for each pair $\left(x_{i}, y_{i}\right), g\left(x_{i}\right)=0$ and $g\left(y_{i}\right)=1$. Hence the claim.

Since each $c_{i}$ has exactly three neighbors in $X$, clearly, there exist exactly $q$ number of $c_{i}$ 's with weight at least 1 such that $\left(\cup_{g\left(c_{i}\right) \geq 1} N\left(c_{i}\right)\right) \cap X=X$. Consequently, $C^{\prime}=\left\{c_{i}\right.$ : $\left.g\left(c_{i}\right)=1\right\}$ is an exact cover for $C$.

Theorem 2. R2DP is NP-complete for comb convex bipartite graphs.

Proof. Clearly, R2DP for comb convex bipartite graphs is a member of NP. We transform an instance $\langle X, C\rangle$ of X3C, where $X=\left\{x_{1}, x_{2}, \ldots, x_{3 q}\right\}$ and $C=\left\{c_{1}, c_{2}, \ldots, c_{t}\right\}$, to an instance $\langle G, k\rangle$ of R2DP as follows.

Create vertices $x_{i}, x_{i}^{\prime}$ and $y_{i}$ for each $x_{i} \in X, c_{i}$ for each $c_{i} \in C$ and also create vertices $a, a^{\prime}, a_{1}, a_{2}$ and $a_{3}$. Add edges $\left(x_{i}, y_{i}\right)$ for each $x_{i} \in X,\left(a_{i}, a\right)$ for each $a_{i}$ and $\left(c_{j}, x_{i}\right)$ if $x_{i} \in c_{j}$. Next add edges $\left(c_{j}, a\right)$ and $\left(c_{j}, a^{\prime}\right)$ for each $c_{j}$. Also add edges by joining each $c_{j}$ to every $x_{i}^{\prime}$. Let $A=\left\{a, a^{\prime}\right\} \cup$ $\left\{x_{i}, x_{i}^{\prime}: 1 \leq i \leq 3 q\right\}$ and $B=V \backslash A$. The subgraph induced by $A$ is a comb with the elements $\left\{x_{i}^{\prime}: 1 \leq i \leq 3 q\right\} \cup\left\{a^{\prime}\right\}$ as backbone and $\left\{x_{i}: 1 \leq i \leq 3 q\right\} \cup\{a\}$ as teeth and the neighbors of each element of $B$ induce a subtree of the comb. Therefore $G$ is a comb convex bipartite graph and can be constructed from the given instance $\langle X, C\rangle$ of X3C in polynomial time. Next, we show that, $X 3 C$ has a solution if and only if $G$ has an R2DF with weight at most $4 q+2$.

Suppose $C^{\prime}$ is a solution for $X 3 C$ with $\left|C^{\prime}\right|=q$. We construct an R2DF $f$, on $G$, same as in Theorem 1. Clearly, $f(V)=4 q+2=k$.

The proof of the converse is similar to the proof given in Theorem 1.

Theorem 3. R2DP is NP-complete for bisplit graphs.
Proof. It is clear that R2DP for bisplit graphs is in NP. We transform an instance of $X 3 C$, where $X=\left\{x_{1}, x_{2}, \ldots, x_{3 q}\right\}$ and $C=\left\{c_{1}, c_{2}, \ldots, c_{t}\right\}$, to an instance $\langle G, k\rangle$ of R2DP as follows.

Create vertices $x_{i}$ for each $x_{i} \in X, c_{i}$ for each $c_{i} \in C$ and also create vertices $a, a_{1}, a_{2}$ and $a_{3}$. Add edges $\left(a_{i}, a\right)$ for each $a_{i}$ and $\left(c_{i}, a\right)$ for each $c_{i}$. Also add edges $\left(c_{j}, x_{i}\right)$ if $x_{i} \in c_{j}$. Let $P=\left\{x_{i}: 1 \leq i \leq 3 q\right\}, \quad Q=\left\{c_{i}: 1 \leq i \leq t\right\} \cup\left\{a_{1}, a_{2}, a_{3}\right\}$ and $R=\{a\}$. In the constructed graph $G, P$ forms an independent set and $Q \cup R$ is a complete bipartite graph. Hence, making $G$ a bisplit graph and can be constructed from the given instance $\langle X, C\rangle$ of X3C in polynomial time. Next we show that, $X 3 C$ has a solution if and only if $G$ has an R2DF with weight at most $2 q+2$. Let $k=2 q+2$.

Suppose $C^{\prime}$ is a solution for $X 3 C$ with $\left|C^{\prime}\right|=q$. We define a function $f: V \rightarrow\{0,1,2\}$ as follows.

$$
f(v)= \begin{cases}2, & \text { if } v \in\{a\} \cup\left\{c_{i}: c_{i} \in C^{\prime}\right\}  \tag{2}\\ 0, & \text { otherwise }\end{cases}
$$

It can be easily verified that $f$ is an R2DF of $G$ and $f(V)=$ $2 q+2=k$.

Conversely, suppose that $G$ has an R2DF $g$ with weight $k$. Clearly, as in Theorem 1, $g(a)=2$ and $\forall a_{i}, g\left(a_{i}\right)=0$. Since $\left(a, c_{j}\right) \in E$, it follows that each vertex $c_{j}$ may be assigned the value 0 .

Claim 2. If $g(V)=k$ then for each $x_{i} \in X, g\left(x_{i}\right)=0$.
Proof. (Proof by contradiction) Assume $g(V)=k$ and there exist some $x_{i}^{\prime}$ s such that $g\left(x_{i}\right) \neq 0$. Let $m=\left|\left\{x_{i}: g\left(x_{i}\right) \neq 0\right\}\right|$. The number of $x_{i}$ 's with $g\left(x_{i}\right)=0$ is $3 q-m$. Since $g$ is an R2DF, each $x_{i}$ with $g\left(x_{i}\right)=0$ should have a neighbor $c_{j}$ with $g\left(c_{j}\right)=2$. So the number of $c_{j}$ 's required with $g\left(c_{j}\right)=2$ is $\left\lceil\frac{3 q-m}{3}\right\rceil$. Hence $g(V)=2+m+2\left\lceil\frac{3 q-m}{3}\right\rceil$, which is greater than $k$. Our assumption leads to a contradiction. Therefore for each $x_{i} \in X, g\left(x_{i}\right)=0$. Hence the claim.

Since each $c_{i}$ has exactly three neighbors in $X$, clearly, there exist $q$ number of $c_{i}$ 's with weight 2 such that $\left(\cup_{g\left(c_{i}\right)=2} N\left(c_{i}\right)\right) \cap X=X$. Consequently, $C^{\prime}=\left\{c_{i}: g\left(c_{i}\right)=2\right\}$ is an exact cover for $C$.

Theorem 4. DRDP is NP-complete for star convex bipartite graphs.

Proof. The proof is obtained with similar arguments as in Theorem 1, in which replace the assigned values 1 with 2 and 2 with 3 .

Theorem 5. DRDP is NP-complete for comb convex bipartite graphs.

Proof. The proof is obtained with similar arguments as in Theorem 2, in which replace the assigned values 1 with 2 and 2 with 3 .

## 3. Threshold graphs

In this section, we determine the Roman $\{2\}$-domination number and double Roman domination number of threshold graphs. A threshold graph is a graph that can be constructed from one vertex graph by repeated applications of


Figure 1. A threshold graph.
the following two operations: (i) Addition of a single isolated vertex to the graph. (ii) Addition of a single dominating vertex to the graph. For the graph to be connected the last vertex added must be a dominating vertex. Since every threshold graph is a split graph, $V=C \cup I$, where $C$ is a clique constituting all dominating vertices and $I$ is an independent set constituting all isolated vertices. Let $C=\left\{c_{1}, c_{2}, \ldots, c_{n}\right\}$ and $I=\left\{i_{1}, i_{2}, \ldots, i_{m}\right\}$. If the clique vertices are added in the order $c_{1}, c_{2}, \ldots, c_{n}$ and the independent vertices are added in the order $i_{1}, i_{2}, \ldots, i_{m}$ then by the definition it follows that $N_{G}\left[c_{1}\right] \subseteq N_{G}\left[c_{2}\right] \subseteq N_{G}\left[c_{3}\right] \subseteq \cdots \subseteq N_{G}\left[c_{n}\right]$ and $N_{G}\left(i_{1}\right) \supseteq$ $N_{G}\left(i_{2}\right) \supseteq N_{G}\left(i_{3}\right) \supseteq \cdots \supseteq N_{G}\left(i_{m}\right)$. For example, consider a threshold graph in Figure 1, where the vertices are added in the order $i_{1}, i_{2}, c_{1}, i_{3}, c_{2}, c_{3}, \ldots, i_{m-1}, i_{m}$ and $c_{n}$. The vertices constituting the clique are enclosed in a dotted rectangle in Figure 1. If $|V|=1$ then, clearly, $\gamma_{\{R 2\}}(G)=1$ and $\gamma_{d R}(G)=2$.
Theorem 6. Let $G$ be a threshold graph. Then $\gamma_{\{R 2\}}(G)=$ $k+1$ and $\gamma_{d R}(G)=2 k+1$, where $k$ is the number of connected components in $G$.
Proof. Let $G$ be a threshold graph with $n$ clique vertices such that $N_{G}\left[c_{1}\right] \subseteq N_{G}\left[c_{2}\right] \subseteq N_{G}\left[c_{3}\right] \subseteq \cdots \subseteq N_{G}\left[c_{n}\right]$. Now, define a function $f: V \rightarrow\{0,1,2\}$ as follows.

$$
f(v)= \begin{cases}1, & \text { if } \operatorname{deg}(v)=0  \tag{3}\\ 2, & \text { if } v=c_{n} \\ 0, & \text { otherwise }\end{cases}
$$

Clearly, $f$ is an R2DF and $\gamma_{\{R 2\}}(G) \leq k+1$. From the definition of R2DF, it follows that $\gamma_{\{R 2\}}(G) \geq k+1$. Therefore, $\gamma_{\{R 2\}}(G)=k+1$.
Similarly, let $g: V \rightarrow\{0,1,2,3\}$ be a function on $G$ defined as follows.

$$
g(v)= \begin{cases}2, & \text { if } \operatorname{deg}(v)=0  \tag{4}\\ 3, & \text { if } v=c_{n} \\ 0, & \text { otherwise }\end{cases}
$$

Clearly, $g$ is a DRDF and $\gamma_{d R}(G) \leq 2 k+1$. From the definition of DRDF, it follows that $\gamma_{d R}(G) \geq 2 k+1$. Therefore, $\gamma_{d R}(G)=2 k+1$.

## 4. Chain graphs

In this section, we propose a method to compute Roman $\{2\}$-domination number and double Roman domination
number of a chain graph in linear time. A bipartite graph $G=(X, Y, E)$ is called a chain graph if the neighborhoods of the vertices of $X$ form a chain, that is, the vertices of $X$ can be linearly ordered, say $x_{1}, x_{2}, \ldots, x_{p}$, such that $N_{G}\left(x_{1}\right) \subseteq$ $N_{G}\left(x_{2}\right) \subseteq \ldots \subseteq N_{G}\left(x_{p}\right)$. If $G=(X, Y, E)$ is a chain graph, then the neighborhoods of the vertices of $Y$ also form a chain. An ordering $\alpha=\left(x_{1}, x_{2}, \ldots, x_{p}, y_{1}, y_{2}, \ldots, y_{q}\right)$ of $X \cup Y$ is called a chain ordering if $N_{G}\left(x_{1}\right) \subseteq N_{G}\left(x_{2}\right) \subseteq \cdots \subseteq N_{G}\left(x_{p}\right)$ and $N_{G}\left(y_{1}\right) \supseteq N_{G}\left(y_{2}\right) \supseteq \ldots \supseteq N_{G}\left(y_{q}\right)$. Every chain graph admits a chain ordering [12]. The following is a proposition without proof.

Proposition 1. Let $G=K_{r, s}$ be a complete bipartite graph with $r \leq s$.
(a) If $r=1$ then $\gamma_{\{R 2\}}(G)=2$.
(b) If $r=2$ then $\gamma_{\{R 2\}}(G)=3$.
(c) If $r \geq 3$ then $\gamma_{\{R 2\}}(G)=4$.

If $G$ is a complete bipartite graph then $\gamma_{\{R 2\}}(G)$ is obtained directly from Proposition 1. Otherwise, the following theorem holds.

Theorem 7. Let $G\left(\neq K_{r, s}\right)$ be a connected chain graph. Then,

$$
\gamma_{\{R 2\}}(G)= \begin{cases}3, & \text { if }|X|=2 \text { or }|Y|=2  \tag{5}\\ 4, & \text { otherwise }\end{cases}
$$

Proof. Let $G(X, Y, E)$ be a connected chain graph with $|X|=$ $n$ and $|Y|=m$, where $n, m \geq 2$. Now, define a function $f$ : $V \rightarrow\{0,1,2\}$ as follows.
Case (1): $|X|=2$ and $|Y|=2$ then $f(v)= \begin{cases}2, & \text { if } v=y_{1} \\ 1, & \text { if } v=y_{2} \\ 0, & \text { otherwise }\end{cases}$
Case (2): $|X|=2$ and $|Y| \neq 2$ then $f(v)= \begin{cases}2, & \text { if } v=x_{2} \\ 1, & \text { if } v=x_{1} \\ 0, & \text { otherwise }\end{cases}$
Case (3): $|X| \neq 2$ and $|Y|=2$ then same condition holds as in case (1).

Clearly, $f$ is an R2DF and $\gamma_{\{R 2\}}(G) \leq 3$. From the definition of R2DF, it follows that $\gamma_{\{R 2\}}(G) \geq 3$. Therefore $\gamma_{\{R 2\}}(G)=3$. Case (4): $|X| \neq 2$ and $|Y| \neq 2$ then $f(v)= \begin{cases}2, & \text { if } v \in\left\{x_{n}, y_{1}\right\} \\ 0, & \text { otherwise }\end{cases}$

Clearly, $f$ is an R2DF and $\gamma_{\{R 2\}}(G) \leq 4$. By contradiction, it can be easily verified that $\gamma_{\{R 2\}}(G) \geq 4$. Therefore $\gamma_{\{R 2\}}(G)=4$.

If the chain graph $G$ is disconnected then weight of the R2DF is increased by $k$, where $k$ is the number of isolated vertices in $G$.

The following propositions are proved in [2, 3].
Proposition 2 ([2]). For any complete bipartite graph $K_{p, q}$, with $p, q \geq 3, \gamma_{d R}\left(K_{p, q}\right)=6$.

Proposition 3 ([3]). For any complete bipartite graph $K_{p, q}$ with $p \leq q, \quad \gamma_{d R}\left(K_{1, q}\right)=3$ and $\gamma_{d R}\left(K_{2, q}\right)=4$.

If $G$ is a complete bipartite graph then $\gamma_{d R}(G)$ is obtained directly from Propositions 2 and 3. Otherwise, the following theorem holds.

Theorem 8. Let $G\left(\neq K_{r, s}\right)$ be a connected chain graph. Then,

$$
\gamma_{d R}(G)= \begin{cases}5, & \text { if }|X|=2 \text { or }|Y|=2  \tag{6}\\ 6, & \text { otherwise }\end{cases}
$$

Proof. The proof is same as in Theorem 7 in which replace the assigned values 1 with 2 and 2 with 3 .

If the chain graph $G$ is disconnected then weight of the DRDF is increased by $2 k$, where $k$ is the number of isolated vertices in $G$.

## 5. Bounded tree-width graphs

Let $G$ be a graph, $T$ be a tree and $v$ be a family of vertex sets $V_{t} \subseteq V(G)$ indexed by the vertices $t$ of $T$. The pair ( $T, v$ ) is called a tree-decomposition of $G$ if it satisfies the following three conditions: (i) $V(G)=\cup_{t \in V(T)} V_{t}$, (ii) for every edge $e \in E(G)$ there exists a $t \in V(T)$ such that both ends of $e$ lie in $V_{t}$, and (iii) $V_{t_{1}} \cap V_{t_{3}} \subseteq V_{t_{2}}$ whenever $t_{1}, t_{2}$, $t_{3} \in V(T)$ and $t_{2}$ is on the path in $T$ from $t_{1}$ to $t_{3}$. The width of $(T, v)$ is the number $\max \left\{\left|V_{t}\right|-1: t \in T\right\}$, and the tree-width $t w(G)$ of $G$ is the minimum width of any tree-decomposition of G. By Courcelle's thoerem, it is well known that every graph problem that can be described by counting monadic second-order logic (CMSOL) can be solved in linear-time in graphs of bounded tree-width, given a tree decomposition as input [7]. We show that R2DP and DRDP problems can be expressed in CMSOL.

Theorem 9 (Courcelle's theorem [7]). Let $P$ be a graph property expressible in CMSOL and $k$ be a constant. Then, for any graph $G$ of tree-width at most $k$, it can be checked in lin-ear-time whether $G$ has property $P$.

Theorem 10. Given a graph $G$ and a positive integer $k$, R2DP can be expressed in CMSOL.

Proof. Let $f: V \rightarrow\{0,1,2\}$ be a function on a graph $G$, where $V_{i}=\{v \mid f(v)=i\}$ for $i \in\{0,1,2\}$. The CMSOL formula for the R2DP is expressed as follows.

$$
\begin{aligned}
& \quad \text { Rom_\{2\}_Dom }(V)=(f(V) \leq k) \wedge \exists V_{0}, V_{1}, V_{2}, \forall p\left(\left(p \in V_{0} \wedge\right.\right. \\
& \left.\left(\left(\exists q \in V_{2} \wedge \operatorname{adj}(p, q)\right) \vee\left(\exists r, s \in V_{1} \wedge \operatorname{adj}(p, r) \wedge \operatorname{adj}(p, s)\right)\right)\right) \vee \\
& \left.\left(p \in V_{1}\right) \vee\left(p \in V_{2}\right)\right)
\end{aligned}
$$

where $\operatorname{adj}(p, q)$ is the binary adjacency relation which holds if and only if, $p, q$ are two adjacent vertices of $G$.

Now, the following result is immediate from Theorems 9 and 10 .

Theorem 11. R2DP problem can be solvable in linear time for bounded tree-width graphs.

Theorem 12. Given a graph $G$ and a positive integer $k$, $D R D P$ can be expressed in CMSOL.

Proof. Let $g: V \rightarrow\{0,1,2,3\}$ be a function on a graph $G$, where $V_{i}=\{v \mid g(v)=i\}$ for $i \in\{0,1,2,3\}$. The CMSOL formula for the DRDP is expressed as follows.

Double_Rom_Dom $(V)=(g(V) \leq k) \wedge \exists V_{0}, V_{1}, V_{2}, V_{3}, \forall p((p \in$ $V_{0} \wedge\left(\left(\exists q, r \in V_{2} \wedge \operatorname{adj}(p, q) \wedge \operatorname{adj}(p, r)\right) \vee\left(\exists s \in V_{3} \wedge \operatorname{adj}(p, s)\right)\right) \vee$ $\left.\left(p \in V_{1} \wedge\left(\exists t \in V_{2} \wedge \operatorname{adj}(p, t) \vee\left(\exists u \in V_{3} \wedge \operatorname{adj}(p, u)\right)\right)\right)\right) \vee(p \in$ $\left.\left.V_{2}\right) \vee\left(p \in V_{3}\right)\right)$
where $\operatorname{adj}(p, q)$ is the binary adjacency relation which holds if and only if, $p, q$ are two adjacent vertices of $G$.

Now, the following result is immediate from Theorems 9 and 12.

Theorem 13. DRDP problem can be solvable in linear time for bounded tree-width graphs.

## 6. Approximation results

In this section, we design approximation algorithms for optimization versions of Roman \{2\}-domination and double Roman domination problems based on the approximation result known for MINIMUM DOMINATION problem, which is given below.

## MINIMUM DOMINATION

Instance: A simple, undirected graph $G=(V, E)$.
Solution: Minimum cardinality dominating set $D$ of $G$.
Measure: Cardinality of $D$.
The minimum Roman $\{2\}$-domination and the minimum double Roman domination problems are defined as follows.
MINIMUM ROMAN \{2\}-DOMINATION PROBLEM (MR2DP)
Instance: A simple, undirected graph $G=(V, E)$.
Solution: An R2DF of $G$.
Measure: Weight of R2DF.

## MINIMUM DOUBLE ROMAN DOMINATION PROBLEM (MDRDP)

Instance: A simple, undirected graph $G=(V, E)$.
Solution: A DRDF of G.
Measure: Weight of DRDF.
Now, we propose a $2(1+\ln (\Delta+1))$-approximation algorithm for MR2DP.
The following approximation result has been obtained in [6] for MINIMUM DOMINATION problem.

Theorem 14 ([6]). The MINIMUM DOMINATION problem in a graph with maximum degree $\Delta$ can be approximated with an approximation ratio of $1+\ln (\Delta+1)$.

By Theorem 14, let APPROX-DOM-SET be an approximation algorithm that gives a dominating set $D$ of a graph $G$ such that $|D| \leq(1+\ln (\Delta+1)) \gamma(G)$, where $\Delta$ is the maximum degree of the graph $G$.

Next, we propose an algorithm APPROX-R2D to compute an approximate solution of MR2DP problem. In our algorithm, first we compute a dominating set $D$ of the input graph $G$ using the approximation algorithm APPROX-DOM-SET. Next, we construct a triple $T_{r}$ in which every vertex in $D$ will be
assigned with weight 2 and the remaining vertices will be assigned with weight 0 .

Now, let $T_{r}=\left(D^{\prime}, \emptyset, D\right)$ be the triple obtained by using the APPROX-R2D algorithm. It can be easily seen that every vertex $v \in V$ is assigned with weight either 0 or 2 . Since $D$ is a dominating set of $G$, every vertex $v \in D^{\prime}$ with weight 0 is adjacent to a vertex $u \in D$ with weight 2 . Thus, $T_{r}$ gives an R2DF of $G$.

```
Algorithm 1: APPROX-R2D(G)
    Input: A simple, undirected graph \(G\).
    Output: A Roman 2-dominating triple \(T_{r}\) of \(G\).
        1: \(D \leftarrow\) APPROX-DOM-SET( \(G\) )
        2: \(T_{r} \leftarrow(V \backslash D, \emptyset, D)\)
        3: return \(T_{r}\).
```

We note that the algorithm APPROX-R2D computes a Roman 2-dominating triple $T_{r}$ of the given graph $G$ in polynomial time. Hence, we have the following result.
Theorem 15. The MR2DP in a graph with maximum degree $\Delta$ can be approximated with an approximation ratio of $2(1+\ln (\Delta+1))$.

Proof. Let $D$ be the dominating set produced by the algorithm APPROX-DOM-SET, $T_{r}$ be the Roman \{2\}-dominating triple produced by the algorithm APPROX-R2D and $W_{r}$ be the weight of $T_{r}$.

It can be observed that $W_{r}=2|D|$. It is known that $|D| \leq(1+\ln (\Delta+1)) \gamma(G)$. Therefore, $W_{r} \leq 2(1+\ln (\Delta+$ 1) $) \gamma(G)$. Since $\gamma(G) \leq \gamma_{\{R 2\}}(G)$ [4], it follows that $W_{r} \leq 2(1+\ln (\Delta+1)) \gamma_{\{R 2\}}(G)$.

Similar to Algorithm 1, we propose an approximation algorithm namely, APPROX-DRD, which produces a double Roman dominating quadruple as follows.

## Algorithm 2: APPROX-DRD(G)

Input: A simple, undirected graph $G$.
Output: A double Roman dominating quadruple $Q_{r}$ of $G$. 1: $D \leftarrow$ APPROX-DOM-SET( $G$ ) 2: $Q_{r} \leftarrow(V \backslash D, \emptyset, \emptyset, D)$ 3: return $Q_{r}$.

We also note that the algorithm APPROX-DRD computes a double Roman dominating quadruple $Q_{r}$ of a given graph $G$ in polynomial time. Hence, the following theorem holds.

Theorem 16. The MDRDP in a graph with maximum degree $\Delta$ can be approximated with an approximation ratio of $3(1+\ln (\Delta+1))$.

Proof. The proof is obtained with similar arguments as in Theorem 15.

We have the following corollaries of Theorems 15 and 16, respectively.

Corollary 1. MR2DP problem for bounded degree graphs is in $A P X$.

Corollary 2. MDRDP problem for bounded degree graphs is in $A P X$.

## 7. Conclusion

In this article, we have shown that the decision versions of Roman $\{2\}$-domination and the double Roman domination problems are NP-complete for some subclasses of bipartite graphs. Next, we have shown that R2DF and DRDF problems are linear time solvable for bounded tree-width graphs, threshold graphs and chain graphs. We have also given polynomial time approximation algorithms for MR2DP and MDRDP. In future work, one can investigate the algorithmic complexity of R2DP and DRDP for other subclasses of bipartite graphs and chordal graphs. Since, the MINIMUM DOMINATION problem is APX-hard for bounded degree graphs, the intuition suggests that MR2DP and the MDRDP could be APX-hard. Hence, determining whether or not MR2DP and MDRDP are APX-hard for bounded degree graphs remains open.

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