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Short-time existence of the α -Dirac-harmonic map flow and applications

Jürgen Jost and Jingyong Zhu

Max Planck Institute for Mathematics in the Sciences, Leipzig, Germany

ABSTRACT

In this paper, we discuss the general existence theory of Dirac-harmonic maps from closed surfaces via the heat flow for α -Dirac-harmonic maps and blow-up analysis. More precisely, given any initial map along which the Dirac operator has nontrivial minimal kernel, we first prove the short time existence of the heat flow for α -Diracharmonic maps. The obstacle to the global existence is the singular time when the kernel of the Dirac operator no longer stays minimal along the flow. In this case, the kernel may not be continuous even if the map is smooth with respect to time. To overcome this issue, we use the analyticity of the target manifold to obtain the density of the maps along which the Dirac operator has minimal kernel in the homotopy class of the given initial map. Then, when we arrive at the singular time, this density allows us to pick another map which has lower energy to restart the flow. Thus, we get a flow which may not be continuous at a set of isolated points. Furthermore, with the help of small energy regularity and blow-up analysis, we finally get the existence of nontrivial α -Dirac-harmonic maps ($\alpha \geq 1$) from closed surfaces. Moreover, if the target manifold does not admit any nontrivial harmonic sphere, then the map part stays in the same homotopy class as the given initial map.

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1. Introduction

Motivated by the supersymmetric nonlinear sigma model from quantum field theory, see [1], Dirac-harmonic maps from spin Riemann surfaces into Riemannian manifolds were introduced in [2]. They are generalizations of the classical harmonic maps and harmonic spinors. From the variational point of view, they are critical points of a conformal invariant action functional whose Euler-Lagrange equations are a coupled elliptic system consisting of a second order equation and a Dirac equation.

It turns out that the existence of Dirac-harmonic maps from closed surfaces is a very difficult problem. Different from the Dirichlet problem, even if there is no bubble, the nontriviality of the limit is also an issue. Here, a solution is considered trivial if the spinor part ψ vanishes identically. So far, there are only a few results about Dirac-

CONTACT Jürgen Jost jjost@mis.mpg.de Max Planck Institute for Mathematics in the Sciences, Inselstrasse 22, 04103 Leipzig, Germany.

harmonic maps from closed surfaces, see [3-5] for uncoupled Dirac-harmonic maps (here uncoupled means that the map part is harmonic; by an observation of Bernd Ammann and Johannes Wittmann, this is the typical case) based on index theory and the Riemann-Roch theorem, respectively. In an important contribution [6], Wittmann investigated the heat flow introduced in [7] and showed the short-time existence of this flow; for reasons that will become apparent below this is not as easy as for other parabolic systems. The problem has also been approached by linking and Morse-Floer theory. See [8, 9] for one dimension and [10] for the two dimensional case.

In critical point theory, the Palais-Smale condition is a very strong and useful tool. It fails, however, for many of the basic problems in geometric analysis, and in particular for the energy functional of harmonic maps from spheres [11]. Therefore, it is not expected to be true for Dirac-harmonic maps. To overcome this problem for harmonic maps, Sacks-Uhlenbeck [12] introduced the notion of α -harmonic maps where the integrand in the energy functional is raised to a power $\alpha > 1$. These α -harmonic maps then satisfy the Palais-Smale condition. However, when we analogously introduce α-Dirac-harmonic maps, the Palais-Smale condition fails due to the following existence result for uncoupled α -Dirac-harmonic maps, which directly follows from the proof of Theorem 4.1.

Theorem 1.1. For a closed spin surface M and a closed manifold N, consider a homotopy class $[\phi]$ of maps $\phi: M^m \to N^n$ for which $[\dim_{\mathbb{H}}(\ker \not D_{\phi})]_{\mathbb{Z}_0}$ is non-trivial. Assume that $\phi_0 \in [\phi]$ is an α -harmonic map. Then there is a real vector space V of real dimension 4 such that all $(\phi_0, \psi), \psi \in V$, are α -Dirac-harmonic maps.

To overcome this issue, in [8, 9], the authors add an extra nonlinear term to the action functional of Dirac-geodesics. As for the two dimensional case [10], we even cannot directly prove the Palais-Smale condition for the action functional of perturbed Dirac-harmonic maps into non-flat target manifolds. Instead, we are only able to prove it for perturbed α -Dirac-harmonic maps, and then approximate the α -Dirac-harmonic map by a sequence of perturbed α -Dirac-harmonic maps. However, in this approach, it is not easy to control the energies of the perturbed α -Dirac-harmonic maps, which are constructed by a Min-Max method over increasingly large domains in the configuration space.

Due to these two problems, in this paper, we would like to use the heat flow method to get the existence of Dirac-harmonic maps from closed surfaces to general manifolds where the harmonic map type equation is parabolized and the first order Dirac equation is carried along as an elliptic side constraint [7]. As already mentioned, the short-time existence of the heat flow for Dirac-harmonic map was proved by Wittmann [6]. He constructed the solution to the constraint Dirac equation by the projector of the Dirac operator along maps. By assuming that the Dirac operator along the initial map has nontrivial minimal kernel, he showed that the kernel would stay minimal for small time in the homotopy class of the initial map. This minimality implies a uniform bound for the resolvents and the Lipschitz continuity of the normalized Dirac kernel along the flow. This Lipschitz continuity makes the Banach fixed point theorem available. If one follows this approach, the first issue is how to deal with the kernel jumping problem. Observe that if the Dirac operators converge at the jumping time, the symmetry of the spectrum of Dirac operator guarantees that the limiting Dirac operator has odd dimensional kernel. Therefore, it is natural to try to extend Wittmann's short time existence to the odd dimensional case. However, the eigenvalues in this case may split at time $t\!=\!0$. Then the projector may not be continuous even if the Dirac operator is smooth with respect to time along the flow (see [13]), which means that the Lipschitz continuity of the kernel is not available in general. To overcome this issue, we need the density mentioned in the abstract, which gives us a piecewise smooth flow.

As for the convergence, it is sufficient to control the energy of the spinor field because the energy of the map decreases along the flow. To do so, one can impose a restriction on the energy of the initial map as in [14] and get the existence of Dirac-harmonic maps when the initial map has small energy. Alternatively, we use another type flow, that is, the heat flow for α -Dirac-harmonic maps (also called α -Dirac-harmonic map flow in the literatures). Our motivation comes from the successful application of this flow to the Dirichlet problem [15]. Different from there, we cannot uniquely solve the constraint equation. Moreover, our equations of the flow are different. We never write the constraint equation in the Euclidean space \mathbb{R}^q . Instead, we just solve it in the target manifold N. Last, our flow is not unique due to the absent of a boundary. Instead, only a weak uniqueness is available. Consequently, we need prove the fact that the flow takes value in the target manifold N in a different way. Eventually, we shall obtain the following results on the general existence of Dirac-harmonic maps.

Theorem 1.2. Let M be a closed spin surface and (N, h) a real analytic closed manifold. Suppose there exists a map $u_0 \in C^{2+\mu}(M,N)$ for some $\mu \in (0,1)$ such that $\dim_{\mathbb{H}} \ker \not D^{u_0} = 1$. Then there exists a nontrivial smooth Dirac-harmonic map (Φ, Ψ) satisfying $E(\Phi) \leq E(u_0)$ and $||\Psi||_{L^2} = 1$.

Furthermore, if (N, h) does not admit any nontrivial harmonic sphere, then the map part Φ is in the same homotopy class as u_0 and (Φ, Ψ) is coupled if the energy of the map is strictly bigger than the energy minimizer in the homotopy class $[u_0]$.

Remark 1.3. Our result can at least keep the possibility of the existence of coupled solutions while other solutions produced in the literatures are all uncoupled. The analyticity of the target manifold is a sufficient condition which is used to get the density mentioned in the abstract. In fact, it is easy to see from the proof that we only need the density of the following set

$$Y := \{e \in (m_0^{\alpha_i}, +\infty) | \text{ there exists at least one map } u \text{ such that } \dim_{\mathbb{H}} \ker \mathcal{D}^u = 1 \text{ and } E^{\alpha_i}(u) = e\}$$
 (1.1)

at the α_i -energy minimizer $m_0^{\alpha_i}$ in the homotopy class $[u_0]$ for a sequence $\alpha_i \setminus 1$ as $i \to \infty$.

In [16], Wittmann discussed the density of those maps along which all the Dirac operators have minimal kernel. In particular, we have the following corollary.

Corollary 1.4. Let M be a closed spin surface and (N, h) a real analytic closed manifold. We also assume that

- 1. *M* is connected, oriented and of positive genus;
- 2. N is connected. If N is even-dimensional, then we assume that it is non-orientable.

Then there exists a nontrivial smooth Dirac-harmonic map.

The rest of paper is organized as follows: In Section 2, we recall some definitions, notations and lemmas about Dirac-harmonic maps and the kernel of Dirac operator. In Section 3, under the minimality assumption on the kernel of the Dirac operator along the initial map, we prove the short time existence, weak uniqueness and regularity of the heat flow for α -Dirac-harmonic maps. In Section 4, we prove the existence of α -Dirac-harmonic maps and Theorem 1.2. In the Appendix, we solve the constraint equation and prove Lipschitz continuity of the solution with respect to the map.

2. Preliminaries

Let (M, g) be a compact surface with a fixed spin structure. On the spinor bundle ΣM , we denote the Hermitian inner product by $\langle\cdot,\cdot\rangle_{\Sigma M}$. For any $X\in\Gamma(TM)$ and $\xi\in$ $\Gamma(\Sigma M)$, the Clifford multiplication satisfies the following skew-adjointness:

$$\langle X \cdot \xi, \eta \rangle_{\Sigma M} = -\langle \xi, X \cdot \eta \rangle_{\Sigma M}. \tag{2.1}$$

Let ∇ be the Levi-Civita connection on (M, g). There is a connection (also denoted by ∇) on ΣM compatible with $\langle \cdot, \cdot \rangle_{\Sigma M}$. Choosing a local orthonormal basis $\{e_{\beta}\}_{\beta=1,2}$ on M, the usual Dirac operator is defined as $\partial := e_{\beta} \cdot \nabla_{\beta}$, where $\beta = 1, 2$. Here and in the sequel, we use the Einstein summation convention. One can find more about spin geometry in [17].

Let ϕ be a smooth map from M to another compact Riemannian manifold (N, h) of dimension $n \ge 2$. Let ϕ^*TN be the pull-back bundle of TN by ϕ and consider the twisted bundle $\Sigma M \otimes \phi^* TN$. On this bundle there is a metric $\langle \cdot, \cdot \rangle_{\Sigma M \otimes \phi^* TN}$ induced from the metric on ΣM and ϕ^*TN . Also, we have a connection $\tilde{\nabla}$ on this twisted bundle naturally induced from those on ΣM and ϕ^*TN . In local coordinates $\{y^i\}_{i=1,\dots,n}$ the section ψ of $\Sigma M \otimes \phi^* TN$ is written as

$$\psi = \psi_i \otimes \partial_{y^i}(\phi),$$

where each ψ^i is a usual spinor on M. We also have the following local expression of $\tilde{\nabla}$

$$\tilde{\nabla \psi} = \nabla \psi^i \otimes \partial_{v^i}(\phi) + \Gamma^i_{ik}(\phi) \nabla \phi^j \psi^k \otimes \partial_{v^i}(\phi),$$

where Γ^i_{jk} are the Christoffel symbols of the Levi-Civita connection of N. The Dirac operator along the map ϕ is defined as

$$D := e_{\alpha} \cdot \tilde{\nabla}_{e_{\alpha}} \psi = D \psi^{i} \otimes \partial_{y^{i}}(\phi) + \Gamma^{i}_{ik}(\phi) \nabla_{e_{\alpha}} \phi^{j}(e_{\alpha} \cdot \psi^{k}) \otimes \partial_{y^{i}}(\phi), \tag{2.2}$$

which is self-adjoint [11]. Sometimes, we use $\not D_{\phi}$ to distinguish the Dirac operators defined on different maps. In [2], the authors introduced the functional

$$L(\phi, \psi) := \frac{1}{2} \int_{M} (|d\phi|^{2} + \langle \psi, \not D\psi \rangle_{\Sigma M \otimes \phi^{*}TN})$$

$$= \frac{1}{2} \int_{M} h_{ij}(\phi) g^{\alpha\beta} \frac{\partial \phi^{i}}{\partial x^{\alpha}} \frac{\partial \phi^{j}}{\partial x^{\beta}} + h_{ij}(\phi) \langle \psi^{i}, \not D\psi^{j} \rangle_{\Sigma M}.$$
(2.3)

They computed the Euler-Lagrange equations of *L*:

$$\tau^{m}(\phi) - \frac{1}{2} R_{lij}^{m} \langle \psi^{i}, \nabla \phi^{l} \cdot \psi^{j} \rangle_{\Sigma M} = 0, \tag{2.4}$$

where $\tau^m(\phi)$ is the *m*-th component of the tension field [11] of the map ϕ with respect to the coordinates on N, $\nabla \phi^l \cdot \psi^j$ denotes the Clifford multiplication of the vector field $\nabla \phi^l$ with the spinor ψ^j , and R^m_{lij} stands for the component of the Riemann curvature tensor of the target manifold N. Denote

$$\mathcal{R}(\phi,\psi) := \frac{1}{2} R^m_{lij} \langle \psi^i, \nabla \phi^l \cdot \psi^j \rangle_{\Sigma M} \partial_{y^m}.$$

We can write (2.4) and (2.5) in the following global form:

$$\begin{cases}
\tau(\phi) = \mathcal{R}(\phi, \psi), \\
\not D\psi = 0,
\end{cases} (2.6)$$

and call the solutions (ϕ, ψ) Dirac-harmonic maps from M to N.

With the aim to get a general existence scheme for Dirac-harmonic maps, the following heat flow for Dirac-harmonic maps was introduced in [7]:

$$\begin{cases}
\partial_t u = \tau(u) - \mathcal{R}(u, \psi), & \text{on } (0, T) \times M, \\
\not D^u \psi = 0, & \text{on } [0, T] \times M.
\end{cases}$$
(2.7)

When M has boundary, the short time existence and uniqueness of (2.8)–(2.9) was also shown in [7]. Furthermore, the existence of a global weak solution to this flow in dimension two under some boundary-initial constraint was obtained in [14]. In [15], to remove the restriction on the initial maps, the authors refined an estimate about the spinor in [7] as follows:

Lemma 2.1. [15] Let M be a compact spin Riemann surface with boundary ∂M , N be a compact Riemann manifold. Let $u \in W^{1,2\alpha}(M,N)$ for some $\alpha > 1$ and $\psi \in W^{1,p}(M,\Sigma M \otimes u^*TN)$ for $1 , then there exists a positive constant <math>C = C(p,M,N,||\nabla u||_{L^{2\alpha}})$ such that

$$||\psi||_{W^{1,p}(M)} \le C(||\not D\psi||_{L^p(M)} + ||\mathcal{B}\psi||_{W^{1-1/p,p}(\partial M)}).$$
 (2.8)

Motivated by this lemma, they considered the α -Dirac-harmonic flow and got the existence of Dirac-harmonic maps. For a closed manifold M, the situation is much more complicated because the kernel of the Dirac operator is a linear space. If the Dirac operator along the initial map has one dimensional kernel, Wittmann proved the short time existence on M whose dimension is $m \equiv 0, 1, 2, 4 \pmod{8}$.

By [18], we can isometrically embed N into \mathbb{R}^q . Then (2.6)–(2.7) is equivalent to following system:

$$\begin{cases}
\Delta_{g} u = II(du, du) + Re(P(S(du(e_{\beta}), e_{\beta} \cdot \psi); \psi)), \\
\partial \psi = S(du(e_{\beta}), e_{\beta} \cdot \psi),
\end{cases} (2.9)$$

where II is the second fundamental form of N in \mathbb{R}^q , and

$$S(du(e_{\beta}), e_{\beta} \cdot \psi) := (\nabla u^{A} \cdot \psi^{B}) \otimes II(\partial_{z^{A}}, \partial_{z^{B}}), \tag{2.10}$$

$$Re(P(S(du(e_{\beta}), e_{\beta} \cdot \psi); \psi)) := P(S(\partial_{z^{C}}, \partial_{z^{B}}); \partial_{z^{A}}) Re(\langle \psi^{A}, du^{C} \cdot \psi^{B} \rangle). \tag{2.11}$$

Here $P(\xi; \cdot)$ denotes the shape operator, defined by $\langle P(\xi; X), Y \rangle = \langle A(X, Y), \xi \rangle$ for $X, Y \in \Gamma(TN)$ and Re(z) denotes the real part of $z \in \mathbb{C}$. Together with the nearest point projection:

$$\pi: N_{\delta} \to N,$$
 (2.12)

where $N_{\delta} := \{z \in \mathbb{R}^q | d(z, N) \leq \delta\}$, we can rewrite the evolution equation (2.8) as an equation in \mathbb{R}^q .

Lemma 2.2. [6, 7] A tuple (u, ψ) , where $u : [0, T] \times M \to N$ and $\psi \in \Gamma(\Sigma M \otimes u^*TN)$, is a solution of (2.8) if and only if

$$\partial_t u^A - \Delta u^A = -\pi_{RC}^A(u) \langle \nabla u^B, \nabla u^C \rangle - \pi_R^A(u) \pi_{RD}^C(u) \pi_{EF}^C(\psi^D, \nabla u^E \cdot \psi^F)$$
 (2.13)

on $(0, T) \times M$, for A = 1, ..., q. Here we denote the A-th component function of u: $[0,T] \times M \to N \subset \mathbb{R}^q$ by $u^A: M \to \mathbb{R}$, write $\pi_B^A(z)$ for the B-th partial derivative of the A-th component function of $\pi: \mathbb{R}^q \to \mathbb{R}^q$ and the global sections $\psi^A \in \Gamma(\Sigma M)$ are defined by $\psi = \psi^A \otimes (\partial_A \circ u)$, where $(\partial_A)_{A=1,\ldots,q}$ is the standard basis of $T\mathbb{R}^q$. Moreover, ∇ and $\langle \cdot, \cdot \rangle$ denote the gradient and the Riemannian metric on M, respectively.

For future reference, we define

$$F_1^A(u) := -\pi_{BC}^A(u) \langle \nabla u^B, \nabla u^C \rangle, \tag{2.14}$$

$$F_2^A(u,\psi) := -\pi_R^A(u)\pi_{BD}^C(u)\pi_{EF}^C(\psi^D, \nabla u^E \cdot \psi^F). \tag{2.15}$$

Note that for $u \in C^1(M, N)$ and $\psi \in \Gamma(\Sigma M \otimes u^*TN)$ we have

$$II(du_{p}(e_{\alpha}), du_{p}(e_{\alpha}))) = -F_{1}^{A}(u)|_{p}\partial_{A}|_{u(p)},$$
(2.16)

$$\mathcal{R}(\phi, \psi)|_{p} = -F_{2}^{A}(u, \psi)|_{p} \partial_{A}|_{u(p)}$$
 (2.17)

for all $p \in M$, where $\{e_{\alpha}\}$ is an orthonormal basis of T_{pM} .

Next, for every T > 0, we denote by X_T the Banach space of bounded maps:

$$X_T := B([0, T]; C^1(M, \mathbb{R}^q)),$$
 (2.18)

$$||u||_{X_T} := \max_{A=1,\dots,q} \sup_{t \in [0,T]} (||u^A(t,\cdot)||_{C^0(M)} + ||\nabla u^A(t,\cdot)||_{C^0(M)}). \tag{2.19}$$

For any map $v \in X_T$, the closed ball with center v and radius R in X_T is defined by

$$B_R^T(\nu) := \{ u \in X_T | ||u - \nu|| \le R \}.$$
 (2.20)

We denote by $P^{u_t, v_s} = P^{u_t, v_s}(x)$ the parallel transport of N along the unique shortest geodesic from $\pi(u(x,t))$ to $\pi(v(x,s))$. We also denote by P^{u_t,v_s} the inducing mappings

$$(\pi \circ u_t)^* TN \to (\pi \circ \nu_s)^* TN, \tag{2.21}$$

$$\Sigma M \otimes (\pi \circ u_t)^* TN \to \Sigma M \otimes (\pi \circ v_s)^* TN \tag{2.22}$$

and

$$\Gamma_{C^1}(\Sigma M \otimes (\pi \circ u_t)^*TN) \to \Gamma_{C^1}(\Sigma M \otimes (\pi \circ \nu_s)^*TN).$$
 (2.23)

Now, let us define

$$\Lambda(u_t) = \sup\{\tilde{\Lambda}|\operatorname{spec}(\not \mathbb{D}^{\pi \circ u_t}) \setminus \{0\} \subset \mathbb{R} \setminus (-\tilde{\Lambda}(u_t), \tilde{\Lambda}(u_t))\}$$
 (2.24)

and $\gamma_t(x):[0,2\pi]\to\mathbb{C}$ as

$$\gamma_t(x) := \frac{\Lambda(u_t)}{2} e^{ix}. \tag{2.25}$$

In general, we also denote by γ the curve $\gamma(x):[0,2\pi]\to\mathbb{C}$ as

$$\gamma(x) := \frac{\Lambda}{2} e^{ix} \tag{2.26}$$

for some constant Λ to be determined. Then the orthogonal projection onto $\ker(\mathcal{D}^{\pi \circ u_t})$, which is the mapping

$$\Gamma_{L^2}(\Sigma M \otimes (\pi \circ u_t)^*TN) \to \Gamma_{L^2}(\Sigma M \otimes (\pi \circ u_t)^*TN),$$
 (2.27)

can be written by the resolvent by

$$s \mapsto -\frac{1}{2\pi i} \int_{\gamma_{\star}} R(\lambda, \not\!\!\!D^{\pi \circ u_t}) s d\lambda,$$
 (2.28)

where $R(\lambda, \not\!\!D^{\pi \circ u_t}): \Gamma_{L^2} \to \Gamma_{L^2}$ is the resolvent of $\not\!\!D^{\pi \circ u_t}: \Gamma_{W^{1,2}} \to \Gamma_{L^2}$.

Finally, the following density lemma is very useful for us to extend the flow beyond the singular time.

Lemma 2.3. [16] Let M be a closed spin surface and (N, h) a real analytic closed manifold. Suppose there exists a map $u_0 \in C^{2+\mu}(M,N)$ for some $\mu \in (0,1)$ such that $\dim_{\mathbb{H}} \ker \mathcal{D}^{u_0} = 1$. Then the kernel of \mathcal{D}^u is minimal for generic $u \in [u_0]$, i.e., for a C^{∞} -dense and C^1 -open subset of $[u_0]$.

3. The heat flow for α -Dirac-harmonic maps

In this section, we will prove the short-time existence of the heat flow for α -Dirac-harmonic maps. Since we are working on a closed surface M, we cannot uniquely solve the Dirac equation in the following system:

$$\begin{cases}
\partial_t u = \frac{1}{(1+|\nabla u|^2)^{\alpha-1}} (\tau^{\alpha}(u) - \frac{1}{\alpha} \mathcal{R}(u, \psi)), \\
\mathbb{D}^u \psi = 0.
\end{cases}$$
(3.1)

The short time existence and its extension are the obstacles. This system (if it converges) leads to a α -Dirac-harmonic map which is a solution of the system

$$\tau^{\alpha}(u) := \tau((1+|du|^2)^{\alpha}) = \frac{1}{\alpha}\mathcal{R}(u,\psi)$$

$$\mathcal{D}^{\mu}\psi = 0.$$
(3.2)

and equivalently a critical point of functional

$$L^{\alpha}(u,\psi) = \frac{1}{2} \int_{M} (1 + |du|^{2})^{\alpha} + \frac{1}{2} \int_{M} \langle \psi, \not D^{u} \psi \rangle_{\Sigma M \otimes \phi^{*} TN}, \tag{3.3}$$

where τ is the tension field.

3.1. Short time existence

As in Section 2, we now embed N into \mathbb{R}^q . Let $u:M\to N$ with $u=(u^A)$ and denote the spinor along the map u by $\psi = \psi^A \otimes (\partial_A \circ u)$, where ψ^A are spinors over M. For any smooth map $\eta \in C_0^\infty(M,\mathbb{R}^q)$ and any smooth spinor field $\xi \in C_0^\infty(\Sigma M \otimes \mathbb{R}^q)$, we consider the variation

$$u_t = \pi(u + t\eta), \psi_t^A = \pi_B^A(u_t)(\psi^B + t\xi^B),$$
 (3.4)

where π is the nearest point projection as in Section 2. Then we have

Lemma 3.1. The Euler-Lagrange equations for L^{α} are

$$\Delta u^{A} = -2(\alpha - 1) \frac{\nabla_{\beta\gamma}^{2} u^{B} \nabla_{\beta} u^{B} \nabla_{\gamma} u^{A}}{1 + |\nabla u|^{2}} + \pi_{BC}^{A}(u) \langle \nabla u^{B}, \nabla u^{C} \rangle$$

$$+ \frac{\pi_{B}^{A}(u) \pi_{BD}^{C}(u) \pi_{EF}^{C}(u) \langle \psi^{D}, \nabla u^{E} \cdot \psi^{F} \rangle}{\alpha (1 + |\nabla u|^{2})^{\alpha - 1}}$$
(3.5)

and

$$\partial \psi^A = \pi^A_{BC}(u) \nabla u^B \cdot \psi^C. \tag{3.6}$$

Proof. Suppose (u, ψ) is a critical point of L^{α} , then for the variation (3.5) we have

$$\frac{dL^{\alpha}(u_{t},\psi_{t})}{dt}\bigg|_{t=0} = \alpha \int_{M} (1+|\nabla u|^{2})^{\alpha-1} \langle \nabla u^{A}, \pi_{B}^{A} \nabla \eta^{B} + \pi_{BC}^{A} \nabla u^{C} \eta^{B} \rangle
+ \int_{M} \langle \partial \psi^{A}, \pi_{B}^{A} \xi^{B} + \pi_{BC}^{A} \pi_{D}^{C} \psi^{B} \eta^{D} \rangle,
=: I + II.$$
(3.7)

Then the lemma directly follows from the following computations.

$$\begin{split} I &= \alpha \int_{M} (1 + |\nabla u|^{2})^{\alpha - 1} \langle \nabla u^{A}, \nabla \eta^{A} \rangle + \alpha \int_{M} (1 + |\nabla u|^{2})^{\alpha - 1} \pi_{BC}^{A} \langle \nabla u^{B}, \nabla u^{C} \rangle \eta^{A} \\ &= -\alpha \int_{M} (1 + |\nabla u|^{2})^{\alpha - 1} \Delta u^{A} \eta^{A} - \alpha (\alpha - 1) \int_{M} (1 + |\nabla u|^{2})^{\alpha - 2} \langle \nabla |\nabla u|^{2}, \nabla u^{A} \rangle \eta^{A} \\ &= -\alpha \int_{M} (1 + |\nabla u|^{2})^{\alpha - 1} (\Delta u^{A} + 2(\alpha - 1) \frac{\nabla_{\beta \gamma}^{2} u^{B} \nabla_{\beta} u^{B} \nabla_{\gamma} u^{A}}{1 + |\nabla u|^{2}} - \pi_{BC}^{A} (u) \langle \nabla u^{B}, \nabla u^{C} \rangle) \eta^{A}. \\ &II &= \int_{M} \langle \partial \psi^{A} - \pi_{BC}^{A} \nabla u^{B} \cdot \psi^{C}, \xi^{A} \rangle + \int_{M} \pi_{B}^{A} \pi_{BD}^{C} \langle \psi^{D}, \partial \psi^{C} \rangle \eta^{A} \\ &= \int_{M} \langle \partial \psi^{A} - \pi_{BC}^{A} \nabla u^{B} \cdot \psi^{C}, \xi^{A} \rangle + \int_{M} \pi_{B}^{A} \pi_{BD}^{C} \langle \psi^{D}, \partial \psi^{C} - \pi_{EF}^{C} \nabla u^{E} \cdot \psi^{F} \rangle \eta^{A} \\ &+ \int_{M} \pi_{B}^{A} \pi_{BD}^{C} \langle \psi^{D}, \pi_{EF}^{C} \nabla u^{E} \cdot \psi^{F} \rangle \eta^{A}. \end{split}$$

Lemma 3.1 implies that (3.1)–(3.2) is equivalent to

$$\begin{cases}
\partial_{t}u^{A} = \Delta u^{A} + 2(\alpha - 1) \frac{\nabla_{\beta\gamma}^{2} u^{B} \nabla_{\beta} u^{B} \nabla_{\gamma} u^{A}}{1 + |\nabla u|^{2}} - \pi_{BC}^{A}(u) \langle \nabla u^{B}, \nabla u^{C} \rangle \\
- \frac{\pi_{B}^{A}(u) \pi_{BD}^{C}(u) \pi_{EF}^{C}(u) \langle \psi^{D}, \nabla u^{E} \cdot \psi^{F} \rangle}{\alpha (1 + |\nabla u|^{2})^{\alpha - 1}}
\end{cases}$$

$$(3.8)$$

Now, let us state the main result of this subsection.

Theorem 3.2. Let M be a closed surface, and N a closed n-dimensional Riemannian manifold. Let $u_0 \in C^{2+\mu}(M,N)$ for some $0 < \mu < 1$ with $\dim_{\mathbb{H}} \ker(\not \mathbb{D}^{u_0}) = 1$ and $\psi_0 \in \ker(\not \mathbb{D}^{u_0})$ with $||\psi_0||_{L^2} = 1$. Then there exists $\epsilon_1 = \epsilon_1(M,N) > 0$ such that, for any $\alpha \in (1,1+\epsilon_1)$, the problem (3.1)–(3.2) has a solution (u,ψ) with

$$\begin{cases}
||\psi_t||_{L^2} = 1, & \forall t \in [0, T], \\
u|_{t=0} = u_0, \psi|_{t=0} = \psi_0.
\end{cases}$$
(3.9)

satisfying

$$u \in C^{2+\mu, 1+\mu/2}(M \times [0, T], N)$$
 (3.10)

and

$$\psi \in C^{\mu,\mu/2}(M \times [0,T], \Sigma M \otimes u^*TN) \cap L^{\infty}([0,T]; C^{1+\mu}(M)). \tag{3.11}$$

for some T > 0.

Proof.

Step 1: Solving (3.9)–(3.10) in \mathbb{R}^q .

In this step, we want to find a solution $u: M \times [0, T] \to \mathbb{R}^q$ and $\psi_t: M \to \Sigma M \otimes (\pi \circ u_t)^*TN$ of (3.9)–(3.10) with the initial values (3.11). We first give a solution to (3.10) in a neighborhood of u_0 . For any T > 0, we can choose ϵ , δ and R as in the Appendix such that

$$u(x,t) \in N_{\delta} \tag{3.12}$$

and

$$d^{N}((\pi \circ u)(x,t),(\pi \circ \nu)(x,s)) < \epsilon < \frac{1}{2}\operatorname{inj}(N)$$
(3.13)

for all $u, v \in B_R^T := B_R^T(\bar{u}_0) = \{u \in X_T | ||u - \bar{u}_0||_{X_T} \le R\} \cap \{u|_{t=0} = u_0\}, x \in M \text{ and } t, s \in [0, T], \text{ where } \bar{u}_0(x, t) = u_0(x) \text{ for any } t \in [0, T]. \text{ If } R \text{ is small enough, then by Lemma 5.5, we have}$

$$\dim_{\mathbb{K}} \ker(\not \!\!\!D^{\pi \circ u_t}) = 1 \tag{3.14}$$

and there exists $\Lambda = \frac{1}{2}\Lambda(u_0)$ such that

$$\{\operatorname{spec}(\not\!\!\!D^{\pi\circ u_t})\cap [-\Lambda,\Lambda]\}=1\tag{3.15}$$

for any $u \in B_R^T$ and $t \in [0, T]$, where $\Lambda(u_0)$ is a constant such that spec($\not \! D^{u_0}$) \ $\{0\} \subset \mathbb{R} \setminus [-\Lambda(u_0), \Lambda(u_0)]$. Furthermore, for $\psi_0 \in \ker(\not \! D^{u_0})$ with $||\psi_0||_{L^2} = 1$, Lemma 5.7 implies that

$$\sqrt{\frac{3}{4}} \le ||\tilde{\psi}_1^{u_t}||_{L^2} \le 1 \tag{3.16}$$

for any $u \in B_{R_1}^T$ and $t \in [0,T]$, where $\tilde{\psi}^{u_t} = P^{u_0,u_t}\psi = \tilde{\psi}_1^{u_t} + \tilde{\psi}_2^{u_t}$ with respect to the decomposition $\Gamma_{L^2} = \ker(\not \!\! D^{\pi\circ u_t}) \oplus (\ker(\not \!\! D^{\pi\circ u_t}))^\perp$ and $R_1 = R_1(R,\epsilon,u_0) > 0$.

$$V_{\kappa}^T := \{ v \in C^{1+\mu,\frac{1+\mu}{2}}(M \times [0,T]) |||v||_{C^{1+\mu,\frac{1+\mu}{2}}} \leq \kappa, v|_{M \times \{0\}} = 0 \}.$$

Then, there exists $\kappa_{R_1} := \kappa(R_1) > 0$ such that

$$u_0 + v \in B_{R_1}^T, \forall v \in V_{\kappa}^T, \forall \kappa \le \kappa_{R_1}.$$
 (3.17)

Now, we denote $\kappa_0 := \kappa_{R_1}$ and $V^T := V_{\kappa_0}^T$.

For every $v \in V^T$, $u_0 + v \in B_{R_1}^T$, Lemma 5.8 gives us a solution $\psi(v + u_0)$ to the constraint equation. Since $v + u_0 \in C^{1+\mu}(M)$, by L^p regularity [6] and Schauder estimate [7], we have

$$||\psi(\nu+u_0)||_{C^{1+\mu}(M)} \le C(\mu, M, N, \kappa_0, ||u_0||_{C^{1+\mu}(M)}). \tag{3.18}$$

For any 0 < t, s < T, we also have

$$\begin{split} \partial (\psi(v+u_0)(t) - \psi(v+u_0)(s)) \\ &= -\Gamma(\pi \circ (v+u_0)(t)) \nabla(\pi \circ (v+u_0)(t)) \psi(v+u_0)(t) \\ &+ \Gamma(\pi \circ (v+u_0)(s)) \nabla(\pi \circ (v+u_0)(s)) \psi(v+u_0)(s) \\ &= -\Gamma(\pi \circ (v+u_0)(t)) \nabla(\pi \circ (v+u_0)(t)) (\psi^v(t) - \psi(v+u_0)(s)) \\ &- \Gamma(\pi \circ (v+u_0)(t)) (\nabla(\pi \circ (v+u_0)(t)) - \nabla(\pi \circ (v+u_0)(s))) \psi(v+u_0)(t) \\ &- (\Gamma(\pi \circ (v+u_0)(t)) - \Gamma(\pi \circ (v+u_0)(s))) \nabla(\pi \circ (v+u_0)(s)) \psi(v+u_0)(s), \end{split}$$

that is,

where denotes a multi-linear map with smooth coefficients. For any $\lambda \in (0,1)$, by the Sobolev embedding, L^p -regularity in [6] and Lemma 5.8, we have

$$||\psi(\nu+u_{0})(t)-\psi(\nu+u_{0})(s)||_{C^{2}(M)} \leq C(\lambda,M,N,\kappa_{0},||u_{0}||_{C^{1}(M)})(||\nu(t)-\nu(s)||_{L^{\infty}(M)}+||d\nu(t)-d\nu(s)||_{L^{\infty}})) \leq C(\lambda,M,N,\kappa_{0},||u_{0}||_{C^{1}(M)})|t-s|^{\mu/2}.$$
(3.19)

Therefore,

$$||\psi(\nu+u_0)||_{C^{\mu,\mu/2}(M)} \le C(\mu,M,N,\kappa_0,||u_0||_{C^1(M)}). \tag{3.20}$$

Now, when $\alpha - 1$ is sufficiently small, for the $(\nu + u_0, \psi(\nu + u_0))$ above, the standard theory of linear parabolic systems (see [19]) implies that there exists a unique solution $v_1 \in C^{2+\mu,1+\mu/2}(M \times [0,T],\mathbb{R}^q)$ to the following Dirichlet problem:

$$\begin{cases} \partial_{t}w^{A} &= \Delta_{g}w^{A} + 2(\alpha - 1)\frac{\nabla_{\beta\gamma}^{2}w^{B}\nabla_{\beta}(v + u_{0})^{B}\nabla_{\gamma}(v + u_{0})^{A}}{1 + |\nabla(v + u_{0})|^{2}} \\ &+ \pi_{BC}^{A}(v + u_{0})\langle\nabla(v + u_{0})^{B}, \nabla(v + u_{0})^{C}\rangle \\ &+ \frac{(\pi_{B}^{A}\pi_{BD}^{C}\pi_{EF}^{C})(v + u_{0})\langle\psi^{D}(v + u_{0}), \nabla(v + u_{0})^{E} \cdot \psi^{F}(v + u_{0})\rangle}{\alpha(1 + |\nabla(v + u_{0})|^{2})^{\alpha - 1}}, \\ &+ \Delta_{g}u_{0}^{A} + 2(\alpha - 1)\frac{\nabla_{\beta\gamma}^{2}u_{0}^{B}\nabla_{\beta}(v + u_{0})^{B}\nabla_{\gamma}(v + u_{0})^{A}}{1 + |\nabla(v + u_{0})|^{2}}, \end{cases}$$
(3.21)
$$w(\cdot, 0) = 0.$$

satisfying

$$||v_1||_{C^{2+\mu,1+\mu/2}(M\times[0,T])} \le C(\mu,M,N)(||v_1||_{C^0(M\times[0,T])} + ||u_0||_{C^{2+\nu}(M)} + \kappa_0). \tag{3.22}$$

Since $v_1(\cdot, 0) = 0$, we have

$$||v_1||_{C^0(M\times[0,T])} \le C(\mu, M, N)T(||v_1||_{C^0(M\times[0,T])} + ||u_0||_{C^{2+\nu}(M)} + \kappa_0). \tag{3.23}$$

By taking T > 0 small enough, we get

$$||\nu_1||_{C^0(M\times[0,T])} \le C(\mu,M,N)T(||u_0||_{C^{2+\nu}(M)} + \kappa_0). \tag{3.24}$$

Then the interpolation inequality in [20] implies that $v_1 \in V^T$ for T > 0 sufficiently small. For such v_1 , we have $\psi(v_1 + u_0)$ satisfying (3.20) and (3.22). Replacing $(v, \psi(v + u_0))$ in (3.23)–(3.24) by $(v_1, \psi(v_1 + u_0))$, then we get $v_2 \in V^T$. Iterating this procedure, we get a solution v_{k+1} of (3.23)–(3.24) with $(v, \psi(v + u_0))$ replacing by $(v_k, \psi(v_k + u_0))$, which satisfies

$$||\psi(\nu_{k+1} + u_0)||_{C^{\mu,\mu/2}(M)} \le C(\mu, M, N, \kappa_0, ||u_0||_{C^1(M)}). \tag{3.25}$$

and

$$||\nu_{k+1}||_{C^{2+\mu,1+\mu/2}(M\times[0,T])} \le C(\mu,M,N)(||u_0||_{C^{2+\nu}(M)} + \kappa_0). \tag{3.26}$$

By passing to a subsequence, we know that v_k converges to some u in $C^{2,1}(M \times [0,T])$ and $\psi^{v_k+u_0}$ converges to some ψ in $C^0(M \times [0,T])$. Then it is easy to see that (u,ψ) is a solution of (3.9)–(3.10) with $u(\cdot,0)=u_0$ and $\psi(\cdot,0)=\psi_0$.

Step 2: u(x, t) takes value in N for any $(x, t) \in M \times [0, T]$.

Suppose $u \in C^{2,1}(M \times [0,T],\mathbb{R}^q)$ and $\psi \in C^{\mu,\mu/2}(M \times [0,T],\Sigma M \otimes (\pi \circ u)^*TN) \cap L^{\infty}([0,T];C^{1+\mu}(M))$ satisfy (3.9)–(3.10). In the following, we write $||\cdot||$ and $\langle\cdot,\cdot\rangle_g$ for the Euclidean norm and scalar product, respectively. Similarly, we write $||\cdot||_g$ and $\langle\cdot,\cdot\rangle_g$ for the norm and inner product of (M,g), respectively. We define

$$\rho: \mathbb{R}^q \to \mathbb{R}^q \tag{3.27}$$

by $\rho(z) = z - \pi(z)$ and

$$\varphi: M \times [0, T] \to \mathbb{R} \tag{3.28}$$

by $\varphi(x,t) = ||\rho(u(x,t))||^2 = \sum_{A=1}^q |\rho^A(u(x,t))|^2$. A direct computation yields

$$\left(\frac{\partial}{\partial t} - \Delta\right) \varphi(x, t) = -2 \sum_{A=1}^{q} \left|\left|\nabla(\rho^{A} \circ u)(x, t)\right|\right|_{g}^{2}
+ 2 \langle \rho \circ u, -\pi_{B}^{A}(u) F_{1}^{B}(u) \rangle
+ \frac{2}{\alpha (1 + \left|\nabla u\right|^{2})^{\alpha - 1}} \langle \rho \circ u, \rho_{B}^{A}(u) F_{2}^{B}(u, \psi) \rangle
+ \frac{4(\alpha - 1)}{1 + \left|\nabla u\right|^{2}} \langle \rho \circ u, \nabla_{\beta \gamma}^{2} u^{C} \nabla_{\beta} u^{C} \nabla_{\gamma} u^{B} \rho_{B}^{A}(u) \rangle,$$
(3.29)

where F_1^A and F_2^A are defined in (2.17) and (2.18), respectively.

Since $\rho \circ u \in T_{\pi \circ u}^{\perp} N$ and $(d\pi)_u : \mathbb{R}^q \to T_{\pi \circ u} N$, we have

$$\langle \rho \circ u, -\pi_R^A(u)F_1^B \rangle = \langle \rho \circ u, \rho_R^A(u)F_2^B \rangle = 0.$$
 (3.30)

Together with

$$\frac{4(\alpha - 1)}{1 + |\nabla u|^{2}} \langle \rho \circ u, \nabla_{\beta \gamma}^{2} u^{C} \nabla_{\beta} u^{C} \nabla_{\gamma} u^{B} \rho_{B}^{A}(u) \rangle
\leq 4(\alpha - 1) ||u||_{C^{2}(M)} ||\rho \circ u|| ||\nabla(\rho \circ u)||
\leq 2(\alpha - 1) (||u||_{C^{2}(M)}^{2} \varphi + ||\nabla(\rho \circ u)||^{2}),$$
(3.31)

we get $\left(\frac{\partial}{\partial t} - \Delta\right) \varphi(x,t) \leq C \varphi$, where $C = C(||u||_{C^{2,1}(M \times [0,T])})$. Since $\varphi(x,t) \geq 0$ and $\varphi(x,0) = 0$ for any $(x,t) \in M \times [0,T]$, we conclude $\varphi = 0$ on $M \times [0,T]$. We have shown that $u(x,t) \in N$ for all $(x,t) \in M \times [0,T]$.

Finally, by using the ϵ -regularity (see Lemma 3.7 below), we conclude that

$$u \in C^{2+\mu, 1+\mu/2}(M \times [0, T], N)$$
 (3.32)

and

$$\psi \in C^{\mu,\mu/2}(M \times [0,T], \Sigma M \otimes (\pi \circ u)^*TN) \cap L^{\infty}([0,T]; C^{1+\mu}(M)). \tag{3.33}$$

Since the equations for α-Dirac-harmonic maps are invariant under multiplying the spinor by elements of \mathbb{H} with unit norm, by uniqueness we always mean uniqueness up to multiplication of the spinor by such elements. This kind of uniqueness for the Diracharmonic map flow was proved by the Banach fixed point theorem in [6]. However, we cannot apply the fixed point theorem to the α -Dirac-harmonic map flow. Therefore, it is interesting to consider the uniqueness of the α-Dirac-harmonic map flow from closed surfaces. By considering the evolution inequality of $||u_1 - u_2||_{C^0(M)}$, we can prove the following uniqueness which is weaker than that in [6] because when the quaternions h_a are different, we can no longer bound the C^0 -norm of the difference of the maps.

Theorem 3.3. For any given T > 0, let (u_1, ψ_1) and (u_2, ψ_2) be two solutions to (3.1)with the constraint (3.11) and $u_1, u_2 \in C^{2+\mu, 1+\mu/2}(M \times [0, T], N)$. Then there exists a time $T_1 > 0$, which depends on R and the $C^{1+\mu,\frac{1+\mu}{2}}$ norms of u_1 and u_2 , such that $u_1,u_2 \in$ $B_R^{T_1}$ and

$$\psi_1(x,t) = h_1(t)\psi(u_a(x,t)), \psi_2(x,t) = h_2(t)\psi(u_a(x,t))$$
(3.34)

for some $h_1(t), h_1(t) \in \mathbb{H}$ with unit length, where $\psi(u(x,t))$ is defined by (5.36). Furthermore, if $h_1(t) = h_2(t)$ on $[0, T_2]$ for some $T_2 \leq T_1$, then $(u_1, \psi_1) \equiv (u_2, \psi_2)$ on $M \times [0, T_2]$.

Proof. By the assumptions, we have

$$||u_a(\cdot,t) - u_0||_{C^0(M)} \to 0, ||\nabla u_a(\cdot,t) - \nabla u_0||_{C^0(M)} \to 0$$
 (3.35)

for a=1, 2. Therefore, for small enough T_1 , $u_1, u_2 \in B_R^{T_2}(\bar{u}_0)$. Since $\dim_{\mathbb{H}}(\not D^{u_a})=1$ for a = 1, 2, there exist $h_a(t) \in \mathbb{H}$ such that

$$\psi_a(x,t) = \psi(u_a(x,t))h_a(t) \tag{3.36}$$

for all $t \in [0, \tilde{T}]$, where $\psi(u(x, t))$ is defined by (5.36). Moreover, $h_a(t)$ is of unit length since $||\psi_a||_{L^2(M)} = ||\psi(u_a)||_{L^2} = 1$.

Now, let us consider the uniqueness of the flow. First, by subtracting the equations of u_1 and u_2 and multiplying by $u_1 - u_2$, we have

$$\frac{1}{2}\partial_{t}|u_{1}-u_{2}|^{2} - \frac{1}{2}\Delta|u_{1}-u_{2}|^{2} + |\nabla(u_{1}-u_{2})|^{2}$$

$$= 2(\alpha-1)\left\langle \frac{\nabla_{\beta\gamma}^{2}u_{1}^{i}\nabla_{\beta}u_{1}^{i}\nabla_{\gamma}u_{1}}{1+|\nabla u_{1}|^{2}} - \frac{\nabla_{\beta\gamma}^{2}u_{2}^{j}\nabla_{\beta}u_{2}^{j}\nabla_{\gamma}u_{2}}{1+|\nabla u_{2}|^{2}}, u_{1}-u_{2}\right\rangle$$

$$-\left\langle II(\nabla u_{1},\nabla u_{1}) - II(\nabla u_{2},\nabla u_{2}), u_{1}-u_{2}\right\rangle$$

$$-\left\langle R(\psi_{1},\nabla u_{1}\cdot\psi_{1}) - R(\psi_{2},\nabla u_{2}\cdot\psi_{2}), u_{1}-u_{2}\right\rangle.$$
(3.37)

In the sequel, we will estimate the terms on the right-hand side of the inequality (3.40).

$$\begin{aligned} &2(\alpha-1)\left\langle \frac{\nabla_{\beta\gamma}^{2}u_{1}^{i}\nabla_{\beta}u_{1}^{i}\nabla_{\gamma}u_{1}}{1+|\nabla u_{1}|^{2}} - \frac{\nabla_{\beta\gamma}^{2}u_{2}^{j}\nabla_{\beta}u_{2}^{j}\nabla_{\gamma}u_{2}}{1+|\nabla u_{2}|^{2}}, u_{1} - u_{2}\right\rangle \\ &= 2(\alpha-1)\left\langle \frac{\nabla_{\beta\gamma}^{2}(u_{1}^{i}-u_{2}^{i})\nabla_{\beta}u_{1}^{i}\nabla_{\gamma}u_{1}}{1+|\nabla u_{1}|^{2}}, u_{1} - u_{2}\right\rangle \\ &+ 2(\alpha-1)\left\langle \nabla_{\beta\gamma}^{2}u_{2}^{i}\nabla_{\beta}u_{1}^{i}\nabla_{\gamma}u_{1}\left(\frac{1}{1+|\nabla u_{1}|^{2}} - \frac{1}{1+|\nabla u_{2}|^{2}}\right), u_{1} - u_{2}\right\rangle \\ &+ 2(\alpha-1)\left\langle \frac{\nabla_{\beta\gamma}^{2}u_{2}^{i}\nabla_{\gamma}u_{1}}{1+|\nabla u_{2}|^{2}}(\nabla_{\beta}u_{1}^{i} - \nabla_{\beta}u_{2}^{i}), u_{1} - u_{2}\right\rangle \\ &+ 2(\alpha-1)\left\langle \frac{\nabla_{\beta\gamma}^{2}u_{2}^{i}\nabla_{\beta}u_{2}^{i}}{1+|\nabla u_{2}|^{2}}(\nabla_{\gamma}u_{1} - \nabla_{\gamma}u_{2}), u_{1} - u_{2}\right\rangle \\ &\leq 2(\alpha-1)\left\langle \frac{\nabla_{\beta\gamma}^{2}u_{1}^{i}\nabla_{\gamma}u_{1}}{1+|\nabla u_{1}|^{2}}, u_{1} - u_{2}\right\rangle \\ &+ C(\alpha-1)|\nabla(u_{1} - u_{2})||u_{1} - u_{2}|, \end{aligned} \tag{3.38}$$

where we used $u_1, u_2 \in C^{2+\mu, 1+\mu/2}(M \times [0, T], N)$. Similar, by the triangle inequality, we get

$$|\langle II(\nabla u_1, \nabla u_1) - II(\nabla u_2, \nabla u_2), u_1 - u_2 \rangle|$$

$$\leq C|u_1 - u_2|^2 + C|\nabla(u_1 - u_2)||u_1 - u_2|$$
(3.39)

and

$$\begin{aligned} & |\langle R(\psi_1, \nabla u_1 \cdot \psi_1) - R(\psi_2, \nabla u_2 \cdot \psi_2), u_1 - u_2 \rangle| \\ & \leq C|u_1 - u_2|^2 + C|\nabla(u_1 - u_2)||u_1 - u_2| + C|\psi_1 - \psi_2||u_1 - u_2|. \end{aligned}$$
(3.40)

Based on these estimates, (3.40) becomes

$$\frac{1}{2}\partial_{t}|u_{1}-u_{2}|^{2} - \frac{1}{2}\Delta|u_{1}-u_{2}|^{2}
\leq 2(\alpha-1)\left\langle \frac{\nabla_{\beta\gamma}^{2}(u_{1}^{i}-u_{2}^{i})\nabla_{\beta}u_{1}^{i}\nabla_{\gamma}u_{1}}{1+|\nabla u_{1}|^{2}}, u_{1}-u_{2}\right\rangle - |\nabla(u_{1}-u_{2})|^{2}
+ C|u_{1}-u_{2}|^{2} + C|\nabla(u_{1}-u_{2})||u_{1}-u_{2}| + C|\psi_{1}-\psi_{2}||u_{1}-u_{2}|.$$
(3.41)

Next, we want to bound those terms in the right-hand side of (3.44) by $|u_1 - u_2|^2$ and $|\nabla u_1 - \nabla u_2|^2$. Since $u_1, u_2 \in B_R^{T_2}(\bar{u}_0)$, there is a unique geodesic between $u_1(x,t)$

and $u_2(x,t)$ for any $(x,t) \in M \times [0,T_2]$. Now, for any $(x,t) \in P := \{x \in M \times T_2 : x \in M \in T_2 : x \in M \in T_2 \}$ $[0, T_2]|u_1(x,t) \neq u_2(x,t)\}$, we define

$$u_s(x,t) := \exp_{u_1(x,t)}(sv(x,t)) = \exp_{u_1(x)}(sV(x,t)/|V(x,t)|)$$
(3.42)

where $s \in [0, |V(x,t)|], V(x,t) := \exp_{u_1(x,t)}^{-1} u_2(x,t)$ and |V(x,t)| denotes the norm of V(x, t) in the tangent space $T_{u_1(x,t)}N$. Then we can estimate $\nabla^2(u_1-u_2)$ as follows:

$$\nabla^{2}_{\beta\gamma}(u_{2} - u_{1})(x, t) = \nabla^{2}_{\beta\gamma}u_{|V(x, t)|}(x, t) - \nabla^{2}_{\beta\gamma}u_{0}(x, t)
= \int_{0}^{|V(x, t)|} \frac{d}{ds} \nabla^{2}_{\beta\gamma}u_{s}(x, t)
\leq \sup_{[0, |V(x, t)|] \times P} \left| \frac{d}{ds} \nabla^{2}u_{s} \right| d^{N}(u_{1}(x, t), u_{2}(x, t))
\leq C|u_{1}(x, t) - u_{2}(x, t)|,$$
(3.43)

where we used the Lemma 5.1 in the Appendix. Hence, we can rewrite (3.44) as

$$\frac{1}{2}\partial_{t}|u_{1}-u_{2}|^{2} - \frac{1}{2}\Delta|u_{1}-u_{2}|^{2} \\
\leq 2(\alpha-1)\left\langle \frac{\nabla_{\beta\gamma}^{2}(u_{1}^{i}-u_{2}^{i})\nabla_{\beta}u_{1}^{i}\nabla_{\gamma}u_{1}}{1+|\nabla u_{1}|^{2}}, u_{1}-u_{2}\right\rangle - |\nabla(u_{1}-u_{2})|^{2} \\
+ C|u_{1}-u_{2}|^{2} + C|\nabla(u_{1}-u_{2})||u_{1}-u_{2}| + C|\psi_{1}-\psi_{2}||u_{1}-u_{2}| \\
\leq C|u_{1}-u_{2}|^{2} + C|\psi_{1}-\psi_{2}||u_{1}-u_{2}|, \tag{3.44}$$

where we used Young's inequality. It remains to bound $|\psi_1 - \psi_2|$ by $|u_1 - u_2|$. To that end, we use the Lemma 5.8 and (3.39) as follows:

$$|\psi_{1} - \psi_{2}| = |h_{1}\psi(u_{1}) - h_{2}\psi_{2}(u_{2})|$$

$$= |\psi(u_{1}) - \psi(u_{2})|$$

$$\leq ||u_{1} - u_{2}||_{C^{0}(M)},$$
(3.45)

where we used $h_1 = h_2$ in the second equality.

Last, it is easy to see $(u_1\psi_1)\equiv (u_2,\psi_2)$ by considering the following evolution inequality

$$\partial_t ||u_1 - u_2||_{C^0(M)}^2 \le C||u_1 - u_2||_{C^0(M)}^2$$
(3.46)

with
$$u_1(\cdot, 0) = u_2(\cdot, 0)$$
.

3.2. Regularity of the flow

In this subsection, we will give some estimates on the regularity of the flow. Let us start with the following estimate of the energy of the map part.

Lemma 3.4. Suppose (u, ψ) is a solution of (3.1)–(3.2) with the initial values (3.11). Then there holds

$$E^{\alpha}(u(t)) + 2\alpha \int_{0}^{t} \int_{M} (1 + |\nabla u|^{2})^{\alpha - 1} |\partial_{t} u|^{2} = E^{\alpha}(u_{0}), \tag{3.47}$$

where $E^{\alpha}(u) := \frac{1}{2} \int_{M} (1 + |\nabla u|^{2})^{\alpha}$. Moreover, $E^{\alpha}(u(t))$ is absolutely continuous on [0, T]and non-increasing.

Proof. N ote that (3.1) can be written as:

$$(1 + |\nabla u|^{2})^{\alpha - 1} \partial_{t} u = \operatorname{div}((1 + |\nabla_{u}|^{2})^{\alpha - 1} \nabla u) - (1 + |\nabla_{g} u|^{2})^{\alpha - 1} A(du, du) - \frac{1}{\alpha} \operatorname{Re}(P(\mathcal{A}(du(e_{\beta}), e_{\beta} \cdot \psi); \psi)).$$
(3.48)

Multiplying the inequality above by $\partial_t u$ and using

$$0 = \int_{0}^{t} \int_{M} \left\langle \psi, \frac{d}{dt} \not D \psi \right\rangle$$

$$= \int_{0}^{t} \int_{M} \left\langle \psi, \not D(\partial_{t}\psi) + e_{\gamma} \cdot \psi^{i} \otimes R_{ijk}^{m} \partial_{t} u^{j} du^{k}(e_{\gamma}) \right\rangle \partial_{y^{m}} \rangle$$

$$= \int_{0}^{t} \int_{M} R_{mijk} \left\langle \psi^{m}, \nabla u^{k} \cdot \psi^{i} \right\rangle \partial_{t} u^{j}$$

$$= \int_{0}^{t} \int_{M} \left[\left\langle S(\partial_{y^{m}}, \partial_{y^{j}}), S(\partial_{y^{i}}, \partial_{y^{k}}) \right\rangle_{\mathbb{R}^{q}} - \left\langle S(\partial_{y^{m}}, \partial_{y^{k}}), S(\partial_{y^{i}}, \partial_{y^{j}}) \right\rangle_{\mathbb{R}^{q}} \right]$$

$$= \left\langle \psi^{m}, \nabla u^{k} \cdot \psi^{i} \right\rangle \partial_{t} u^{j}$$

$$= 2 \int_{0}^{t} \int_{M} \left\langle S(\partial_{y^{m}}, \partial_{y^{j}}), S(\partial_{y^{i}}, \partial_{y^{k}}) \right\rangle_{\mathbb{R}^{q}} Re(\left\langle \psi^{m}, \nabla u^{k} \cdot \psi^{i} \right\rangle) \partial_{t} u^{j}$$

$$= 2 \int_{0}^{t} \int_{M} \left\langle Re(P(\mathcal{A}(du(e_{\beta}), e_{\beta} \cdot \psi); \psi)), \partial_{t} u^{j} \right\rangle,$$

$$(3.49)$$

we get

$$\int_{0}^{t} \int_{M} (1 + |\nabla u|^{2})^{\alpha - 1} |\partial_{t} u|^{2} = \int_{0}^{t} \int_{M} \langle \operatorname{div}((1 + |\nabla u|^{2})^{\alpha - 1} \nabla u), \partial_{t} u \rangle
= -\int_{0}^{t} \int_{M} \langle (1 + |\nabla_{g} u|^{2})^{\alpha - 1} \nabla u, \partial_{t} \nabla u \rangle
= -\frac{1}{2\alpha} \int_{0}^{t} \frac{d}{dt} \int_{M} (1 + |\nabla u|^{2})^{\alpha},$$
(3.50)

which directly gives us the lemma.

Consequently, we can also control the spinor part along the heat flow of the α -Diracharmonic map.

Lemma 3.5. Suppose (u, ψ) is a solution of (3.1)–(3.2) with the initial values (3.11). Then for any $p \in (1, 2)$, there holds

$$||\psi(\cdot,t)||_{W^{1,p}(M)} \le C, \forall t \in [0,T],$$
 (3.51)

where $C = C(p, M, N, E^{\alpha}(u_0))$.

Proof. The lemma directly follows from Lemma 3.4 and the following lemma:

Lemma 3.6. Let M be a closed spin Riemann surface, N be a compact Riemann manifold. Let $u \in W^{1,2\alpha}(M,N)$ for some $\alpha > 1$ and $\psi \in W^{1,p}(M,\Sigma M \otimes u^*TN)$ for $1 , then there exists a positive constant <math>C = C(p,M,N,||\nabla u||_{L^{2\alpha}})$ such that

$$||\psi||_{W^{1,p}(M)} \le C(||\not D\psi||_{L^p(M)} + ||\psi||_{L^p(M)}).$$
 (3.52)



This lemma follows from applying Lemma 2.1 to $\eta\psi$, where η is a cutoff function.

To get the convergence of the flow, we also need the following ϵ -regularity.

Lemma 3.7. Suppose (u, ψ) is a solution of (3.1)–(3.2) with the initial values (3.11). Given $\omega_0 = (x_0, t_0) \in M \times (0, T]$, denote

$$P_R(\omega_0) := B_R(x_0) \times [t_0 - R^2, t_0]. \tag{3.53}$$

Then there exist three constants $\epsilon_2 = \epsilon_2(M, N) > 0, \epsilon_3 = \epsilon_3(M, N, u_0) > 0$ and C = $C(\mu, R, M, N, E^{\alpha}(u_0)) > 0$ such that if

$$1 < \alpha < 1 + \epsilon_2$$
, and $\sup_{[t_0 - 4R^2, t_0]} E(u(t); B_{2R}(\omega_0)) \le \epsilon_3$, (3.54)

then

$$\sqrt{R}||\psi||_{L^{\infty}(P_{p}(\omega_{0}))} + R||\nabla u||_{L^{\infty}(P_{p}(\omega_{0}))} \le C \tag{3.55}$$

and for any $0 < \beta < 1$,

$$\sup_{\left[t_{0}-\frac{R^{2}}{4},t_{0}\right]}||\psi(t)||_{C^{1+\mu}(B_{R/2}(x_{0}))}+||\nabla u||_{C^{\beta,\beta/2}(P_{R/2}(\omega_{0}))}\leq C(\beta). \tag{3.56}$$

Moreover, if

$$\sup_{M} \sup_{[t_0 - 4R^2, t_0]} E(u(t); B_{2R}(\omega_0)) \le \epsilon_3, \tag{3.57}$$

then

$$||u||_{C^{2+\mu,1+\mu/2}\left(M\times\left[t_0-\frac{R^2}{8},t_0\right]\right)}+||\psi||_{C^{\mu,\mu/2}\left(M\times\left[t_0-\frac{R^2}{8},t_0\right]\right)}+\sup_{\left[t_0-\frac{R^2}{8},t_0\right]}||\psi(t)||_{C^{1+\mu}(M)}\leq C. \tag{3.58}$$

Since M is closed, x_0 has to be an interior point of M. Therefore, our Lemma is just a special case of the Lemma 3.4 in [15]. So we omit the proof here.

4. Existence of α -Dirac-harmonic maps

In this section, we will prove Theorem 1.2 by the following theorem on the existence of α -Dirac-harmonic maps for $\alpha > 1$.

Theorem 4.1. Let M be a closed spin surface and (N, h) a real analytic closed manifold. Suppose there exists a map $u_0 \in C^{2+\mu}(M,N)$ for some $\mu \in (0,1)$ such that $\dim_{\mathbb{H}} \ker \not \mathbb{D}^{u_0} = 1$. Then for any $\alpha \in (1, 1 + \epsilon_1)$, there exists a nontrivial smooth α -Diracharmonic map $(u_{\alpha}, \psi_{\alpha})$ such that the map part u_{α} stays in the same homotopy class as u_0 and $||\psi_{\alpha}||_{L^{2}} = 1$.

Proof of Theorem 4.1. By Theorem 2.3 in [21], all the following α -Dirac-harmonic maps are smooth. Let us denote the energy minimizer by

$$m_0^{\alpha} := \inf\{E^{\alpha}(u)|u \in W^{1,2\alpha}(M,N) \cap [u_0]\},$$
 (4.1)

where $[u_0]$ denotes the homotopy class of u_0 . If u_0 is a minimizing α -harmonic map, it follows from Lemma 3.4 that (u_0, ψ_0) is an α -Dirac-harmonic map for any $\psi_0 \in$

ker $\not D^{u_0}$. If $E^{\alpha}(u_0) > m_0^{\alpha}$, then Theorem 3.2 gives us a solution

$$u \in C^{2+\mu, 1+\mu/2}(M \times [0, T), N)$$
 (4.2)

and

$$\psi \in C^{\mu,\mu/2}(M \times [0,T), \Sigma M \otimes u^*TN) \cap \bigcap_{0 < s < T} L^{\infty}([0,s]; C^{1+\mu}(M)). \tag{4.3}$$

to the problem (3.1)–(3.2) with the initial values (3.11).

By Lemma 3.4, we know

$$\int_{M} (1 + |\nabla u|^{2})^{\alpha} \le E^{\alpha}(u_{0}). \tag{4.4}$$

Then it is easy to see that, for any $0 < \epsilon < \epsilon_3$, there exists a positive constant $r_0 = r_0(\epsilon, \alpha, E^{\alpha}(u_0))$ such that for all $(x, t) \in M \times [0, T)$, there holds

$$\int_{B_{r_0}(x)} |\nabla u|^2 \le CE^{\alpha}(u_0)^{1/\alpha} r_0^{1-\frac{1}{\alpha}} \le \epsilon.$$
 (4.5)

Therefore, by Theorem 3.2 and Lemma 3.7, we know that the singular time can be characterized as

$$Z = \{ T \in \mathbb{R} | \lim_{t_i \nearrow T} \dim_{\mathbb{H}} \ker \mathcal{D}^{u_{t_i}} > 1 \}$$

$$\tag{4.6}$$

and there exists a sequence $\{t_i\} \nearrow T$ such that

$$(u(\cdot,t_i),\psi(\cdot,t_i)) \to (u(\cdot,T),\psi(\cdot,T)) \text{ in } C^{2+\mu}(M) \times C^{1+\mu/2}(M)$$

$$\tag{4.7}$$

and

$$||\psi(\cdot,T)||_{L^2} = 1. \tag{4.8}$$

If $Z=\emptyset$, then, by Theorem 3.2, we can extend the solution (u,ψ) beyond the time T by using $(u(\cdot,T),\psi(\cdot,T))$ as new initial values. Thus, we have the global existence of the flow. For the limit behavior as $t\to\infty$, Lemma 3.4 implies that there exists a sequence $\{t_i\}\to\infty$ such that

$$\int_{M} \left| \partial_{t} u \right|^{2} (\cdot, t_{i}) \to 0. \tag{4.9}$$

Together with Lemma 3.7, there is a subsequence, still denoted by $\{t_i\}$, and an α -Diracharmonic map $(u_{\alpha}, \psi_{\alpha})$ such that $(u(\cdot, t_i), \psi(\cdot, t_i))$ converges to $(u_{\alpha}, \psi_{\alpha})$ in $C^2(M) \times C^1(M)$ and $||\psi_{\alpha}||_{L^2} = 1$.

If $Z \neq \emptyset$ and $T \in Z$, let us assume that $E^{\alpha}(u(\cdot,T)) > m_0^{\alpha}$ and $(u(\cdot,T),\psi(\cdot,T))$ is not already an α -Dirac-harmonic map. We extend the flow as follows: By Lemma 2.3, there is a map $u_1 \in C^{2+\mu}(M,N)$ such that

$$m_0^{\alpha} < E^{\alpha}(u_1) < E^{\alpha}(u(\cdot, T)) \tag{4.10}$$

and

$$\dim_{\mathbb{H}} \ker \mathcal{D}^{u_1} = 1. \tag{4.11}$$

Thus, picking any $\psi_1 \in \ker \mathcal{D}^{u_1}$ with $||\psi_1||_{L^2} = 1$, we can restart the flow from the new initial values (u_1, ψ_1) . If there is no singular time along the flow started from (u_1, ψ_1) ,

then we get an α -Dirac-harmonic map as in the case of $Z = \emptyset$. Otherwise, we use again the procedure above to choose (u_2, ψ_2) as initial values and restart the flow. This procedure will stop in finitely or infinitely many steps.

If infinitely many steps are required, then there exist infinitely many flow pieces $\{u_i(x,t)\}_{i=1,\ldots,\infty}$ and $\{T_i\}_{i=1,\ldots,\infty}$ such that

$$E^{\alpha}(u_{i}(t)) + 2\alpha \int_{0}^{t} \int_{M} (1 + |\nabla u|^{2})^{\alpha - 1} |\partial_{t} u|^{2} = E^{\alpha}(u_{i}), \forall t \in (0, T_{i}), \tag{4.12}$$

where $u_i(\cdot,0)=u_i\in C^{2+\mu}(M,N)$. If the T_i are bounded away from zero, then there is $\{t_i\}$ such that (4.9) hold for $t_i \in (0, T_i)$. Therefore, we have an α -Dirac-harmonic map as before. If $T_i \to 0$, then we look at the limit of $E^{\alpha}(u_i)$. If the limit is strictly bigger than m_0^{α} , we again choose another map satisfying (4.10) and (4.11) as a new starting point. If the limit is exactly m_0^{α} , then we choose $\{t_i\}$ such that $t_i \in (0, T_i)$ for each i. By Lemma 3.7, $u_i(t_i)$ converges in $C^2(M) \times C^1(M)$ to a minimizing α -harmonic map u_{α} . If $\not D^{u_{\alpha}}$ has minimal kernel, then for any $\psi \in \ker \not D^{u_{\alpha}}$, (u_{α}, ψ) is an α -Dirac-harmonic map as we showed in the beginning of the proof. If D^{μ_x} has non-minimal kernel, we use the decomposition of the twisted spinor bundle through the \mathbb{Z}_2 -grading $G \otimes id$ (see [3]). More precisely, for any smooth variation $(u_s)_{s \in (-\epsilon, \epsilon)}$ of u_0 , we split the bundle $\Sigma M \otimes u_s^* TN$ into $\Sigma M \otimes u_s^* TN = \Sigma^+ M \otimes u_s^* TN \oplus \Sigma^- M \otimes u_s^* TN$, which is orthogonal in the complex sense and parallel. Consequently, for any $\psi_0 \in \ker \mathcal{D}^{\mu_0}$, we have

$$(\not\!\!D^{u_0}\psi_0^+,\psi_0^+)_{L^2} = (\not\!\!D^{u_0}\psi_0^-,\psi_0^-)_{L^2} = 0 \tag{4.13}$$

for $\psi_0 = \psi_0^+ + \psi_0^-$, where $\psi_0^\pm = \psi_\pm \otimes u_0^*TN$ and $\psi_\pm \in \Sigma^\pm$. Therefore, $\psi_s^\pm := \psi_\pm \otimes u_s^*TN$ are smooth variations of ψ_0^\pm , respectively, such that

$$\frac{d}{dt}\Big|_{t=0} (\not\!\!{D}^{u_s} \psi_s^{\pm}, \psi_s^{\pm})_{L^2} = 0. \tag{4.14}$$

By taking $u_0 = u_\alpha$ and $\psi_0 = \psi_\alpha \in \ker \mathcal{D}^{u_\alpha}$, the first variation formula of L^α implies that $(u_{\alpha}, \psi_{\alpha}^{\pm})$ are α -Dirac-harmonic maps (see Corollary 5.2 in [3]). In particular, we can choose ψ_{α} such that $||\psi_{\alpha}^{+}||_{L^{2}} = 1$ or $||\psi_{\alpha}^{-}|| = 1$.

If it stops in finitely many steps, there exists a sequence $\{t_i\}$ and some $0 < T_k \le +\infty$ such that

$$\lim_{t_i \nearrow T} (u(\cdot, t_i), \psi(\cdot, t_i)) \to (u_\alpha, \psi_\alpha) \text{ in } C^2(M) \times C^1(M), \tag{4.15}$$

where $(u_{\alpha}, \psi_{\alpha})$ either is an α -Dirac-harmonic map or satisfies $E^{\alpha}(u_{\alpha}) = m_{0}^{\alpha}$. And in the latter case, u_{α} is a minimizing α -harmonic map. Then we can again get a nontrivial α -Dirac-harmonic map as above.

By Theorem 4.1, for any $\alpha > 1$ sufficiently close to 1, there exists an α -Dirac-harmonic map $(u_{\alpha}, \psi_{\alpha})$ with the properties

$$E^{\alpha}(u_{\alpha}) \le E^{\alpha}(u_0), ||\psi_{\alpha}||_{L^2} = 1$$
 (4.16)

and

$$||\psi_{\alpha}||_{W^{1,p}(M)} \le C(p, M, N, E^{\alpha}(u_0))$$
 (4.17)

for any $1 . Then it is natural to consider the limit behavior when <math>\alpha$ decreases to 1. Since the blow-up analysis was already well studied in [15], we can directly prove Theorem 1.2.

Proof of Theorem 1.2. By Theorem 4.1, we have a sequence of smooth α-Dirac-harmonic maps $(u_{\alpha_k}, \psi_{\alpha_k})$ with (4.16) and (4.17), where $\alpha_k \setminus 1$ as $k \to \infty$. Then, by Theorem 2.1 in [15], there is a constant $\epsilon_0 > 0$ and a Dirac-harmonic map

$$(\Phi, \Psi) \in C^{\infty}(M, N) \times C^{\infty}(M, \Sigma M \otimes \Phi^* TN)$$

such that

$$(u_{\alpha_k}, \psi_{\alpha_k}) \to (\Phi, \Psi) \text{ in } C^2_{loc}(M \setminus S) \times C^1_{loc}(M \setminus S),$$
 (4.18)

where

$$S := \left\{ x \in M \middle| \liminf_{\alpha_k \to 1} E(u_{\alpha_k}; B_r(x)) \ge \frac{\epsilon_0}{2}, \forall r > 0 \right\}$$

$$(4.19)$$

is a finite set.

Now, taking $x_0 \in \mathcal{S}$, there exists a sequence $x_{\alpha_k} \to x_0, \lambda_{\alpha_k} \to 0$ and a nontrivial Diracharmonic map $(\phi, \xi) : \mathbb{R}^2 \to N$ such that

$$(u_{\alpha_k}(x_{\alpha_k} + \lambda_{\alpha_k}x), \lambda_{\alpha_k}^{\alpha_k - 1} \sqrt{\lambda_{\alpha_k}} \psi_{\alpha_k}(x_{\alpha_k} + \lambda_{\alpha_k}x)) \to (\phi, \xi) \text{ in } C^2_{loc}(\mathbb{R}^2), \tag{4.20}$$

as $\alpha \to 1$. Choose any $p^* > 4$, by taking $p = \frac{2p^*}{2+p^*}$ in (4.17), we get

$$||\psi_{\alpha_k}||_{L^{p^*}(M)} \le C(p^*, M, N, E^{\alpha_k}(u_0))$$
 (4.21)

and

$$||\xi||_{L^4(D_R(0))} = \lim_{\alpha_k \to 1} \lambda_{\alpha_k}^{\alpha_k - 1} ||\psi_{\alpha_k}||_{L^4(D_{\lambda_{\alpha_k} R}(x_{\alpha_k}))} \leq \lim_{\alpha_k \to 1} C ||\psi_{\alpha_k}||_{L^{p^*}(M)} (\lambda_{\alpha_k} R)^{2\left(\frac{1}{4} - \frac{1}{p^*}\right)} = 0. \quad (4.22)$$

Thus, $\xi=0$ and ϕ can be extended to a nontrivial smooth harmonic sphere. Since $||\psi_{\alpha}||_{L^2}=1$, the Sobolev embedding implies that $||\Psi||_{L^2(M)}=\lim_{\alpha_k\to 1}||\psi_{\alpha}||_{L^2(M)}=1$. Therefore, (Φ,Ψ) is nontrivial. Furthermore, if (N,h) does not admit any nontrivial harmonic sphere, then

$$(u_{\alpha_k}, \psi_{\alpha_k}) \to (\Phi, \Psi) \text{ in } C^2(M) \times C^1(M).$$
 (4.23)

Therefore, Φ is in the same homotopy class as u_0 .

5. Appendix

In Section 3, we used some convenient properties of the elements in $B_R^T(\bar{u}_0)$. Those properties were already discussed in [6]. However, the function space used there is $B_R^T(v_0)$, where $v_0(x,t) = \int_M p(x,y,t)u_0(y)dV(y)$, because the solution there is the unique fixed point of the following integral representation over $B_R^T(v_0)$

$$Lu(x,t) := v_0(x,t) + \int_0^t \int_M p(x,y,t-\tau)(F_1(u_\tau) + F_2(u_\tau,\psi(u_\tau)))dV(y)d\tau$$
 (5.1)

where p is the heat kernel of M, F_1 and F_2 are defined as in (2.17) and (2.18), respectively. Our proof for the short-time existence is different from there, and the space

 $B_R^T(\bar{u}_0)$ is more natural and convenient in our situation. Therefore, we cannot directly use the statement in [6]. Although the space is changed, the proofs of those nice properties are parallel. In fact, one can see from the following that to make the elements in $B_R^T(\bar{u}_0)$ satisfy nice properties (5.11) and (5.12), it is sufficient to choose R small, namely, T is independent of R. This is the biggest advantage. In the following, we will give the precise statement of the properties we need in Section 3 and proofs for the most important lemmas.

For every T > 0, we consider the space $B_R^T(\bar{u}_0) := \{u \in X_T | ||u - \bar{u}_0||_{X_T} \le R\} \cap$ $\{u|_{t=0}=u_0\}$ where $\bar{u}_0(x,t)=u_0(x)$ for any $t\in[0,T]$. To get the necessary estimate for the solution of the constraint equation, we will use the parallel transport along the unique shortest geodesic between $u_0(x)$ and $\pi \circ u_t(x)$ in N. To do this, we need the following lemma which tells us that the distances in N can be locally controlled by the distances in \mathbb{R}^q .

Lemma 5.1. [6] Let $N \subset \mathbb{R}^q$ be a closed embedded submanifold of \mathbb{R}^q with the induced Riemannian metric. Denote by A its Weingarten map. Choose C>0 such that $||A|| \leq C$, where

$$||A|| := \sup\{||A_{\nu}X|||\nu \in T_{p}^{\perp}N, X \in T_{p}N, ||\nu|| = 1, ||X|| = 1, p \in N\}.$$
 (5.2)

Then there exists $0 < \delta_0 < \frac{1}{C}$ such that for all $0 < \delta \le \delta_0$ and for all $p, q \in N$ with $||p-q||_2 < \delta$, it holds that

$$d^{N}(p,q) \le \frac{1}{1 - \delta C} ||p - q||_{2}, \tag{5.3}$$

where we denote the Euclidean norm by $||\cdot||_2$ in this section.

In the following, we will choose δ and R to ensure the existence of the unique shortest geodesics between the projections of any two elements in $B_R^T(\bar{u}_0)$. By the definition of $B_R^T(\bar{u}_0)$, we have

$$||u(x,t) - \bar{u}_0(x,t)||_2 = ||u(x,t) - u_0(x)||_2 \le R$$
 (5.4)

for all $(x, t) \in M \times [0, T]$. Then taking any $R \leq \delta$, we get

$$d(u(x,t),N) \le ||u(x,t) - u_0(x)||_2 \le \delta \tag{5.5}$$

for all $(x,t) \in M \times [0,T]$. Therefore, $u(x,t) \in N_{\delta}$. In particular, $\pi \circ u$ is N-valued, and

$$||(\pi \circ u)(x,t) - u_0(x)||_2 \le ||(\pi \circ u)(x,t) - u(x,t)||_2 + ||u(x,t) - u_0(x)||_2 \le 2\delta.$$
 (5.6)

Now, we choose $\epsilon > 0$ with $2\epsilon < \operatorname{inj}(N)$ and δ such that

$$\delta < \min\left\{\frac{1}{4}\delta_0, \frac{1}{4}\epsilon(1 - \delta_0 C)\right\} \tag{5.7}$$

where $\delta_0, C > 0$ are as in Lemma 5.1. From (5.6), we know that for all $u, v \in B_R^T(\bar{u}_0)$, it holds that

$$||(\pi \circ u)(x,t) - (\pi \circ v)(x,s)||_2 \le 4\delta < \delta_0.$$
 (5.8)

Then Lemma 5.1 and (5.7) imply that

$$d^{N}((\pi \circ u)(x,t),(\pi \circ v)(x,s)) \leq \frac{1}{1-\delta_{0}C}||(\pi \circ u)(x,t)-(\pi \circ v)(x,s)||_{2}$$

$$\leq \frac{1}{1-\delta_{0}C}4\delta < \epsilon < \frac{1}{2}inj(N).$$
(5.9)

To summarize, under the choice of constants as follows:

$$\begin{cases} \epsilon > 0, & \text{s.t. } 2\epsilon < \text{inj}(N), \\ \delta > 0, & \text{s.t. } \delta < \min\left\{\frac{1}{4}\delta_0, \frac{1}{4}\epsilon(1 - \delta_0 C)\right\}, \\ R \le \delta, \end{cases}$$
 (5.10)

we have shown that

$$u(x,t) \in N_{\delta} \tag{5.11}$$

and

$$d^{N}((\pi \circ u)(x,t),(\pi \circ v)(x,s)) < \epsilon < \frac{1}{2}\operatorname{inj}(N)$$
 (5.12)

for all $u, v \in B_R^T(\bar{u}_0), x \in M$ and $t, s \in [0, T]$.

Using the properties (5.11) and (5.12), we can parallelly prove two important estimates as in [6]. One is for the Dirac operators along maps.

Lemma 5.2. Choose ϵ , δ and R as in (5.10). If $\epsilon > 0$ is small enough, then there exists C = C(R) > 0 such that

$$||((P^{\nu_s, u_t})^{-1} \not\!\!D^{\pi \circ u_t} P^{\nu_s, u_t} - \not\!\!D^{\pi \circ \nu_s}) \psi(x)|| \le C||u_t - \nu_s||_{C^0(M, \mathbb{R}^q)} ||\psi(x)||$$
 (5.13)

for any $u, v \in B_R^T(\bar{u}_0), \psi \in \Gamma_{C^1}(\Sigma M \otimes (\pi \circ \nu_s)^*TN), x \in M \text{ and } t, s \in [0, T].$

Proof. We write $f_0 := \pi \circ \nu_s, f_1 := \pi \circ u_t$ and define the C^1 map $F : M \times [0,1] \to N$ by

$$F(x,t) := \exp_{f_0(x)}(t \exp_{f_0(x)}^{-1} f_1(x))$$
(5.14)

where exp denotes the exponential map of the Riemannian manifold N. Note that $F(\cdot,0)=f_0, F(\cdot,1)=f_1$ and $t\mapsto F(x,t)$ is the unique shortest geodesic from $f_0(x)$ to $f_1(x)$. We denote by

$$\mathcal{P}_{t_1,t_2} = \mathcal{P}_{t_1,t_2}(x) : T_{F(x,t_1)}N \to T_{F(x,t_2)}N$$
 (5.15)

the parallel transport in F^*TN with respect to ∇^{F^*TN} (pullback of the Levi-Civita connection on N) along the curve $\gamma_x(t) := (x,t)$ from $\gamma_x(t_1)$ to $\gamma_x(t_2), x \in M, t_1, t_2 \in [0,1]$. In particular, $\mathcal{P}_{0,1} = P^{\nu_s, u_t}$. Let $\psi \in \Gamma_{C^1}(\Sigma M \otimes (f_0)^*TN)$. We have

$$((\mathcal{P}_{0,1})^{-1} \not\!{D}^{f_1} \mathcal{P}_{0,1} - \not\!{D}^{f_0}) \psi$$

$$= (e_{\alpha} \cdot \psi^i) \otimes (((\mathcal{P}_{0,1})^{-1} \nabla_{e_{\alpha}}^{f_1^*TN} \mathcal{P}_{0,1} - \nabla_{e_{\alpha}}^{f_0^*TN}) (b_i \circ f_0))$$
(5.16)

where $\psi = \psi^i \otimes (b_i \circ f_0)$, $\{b_i\}$ is an orthonormal frame of TN, ψ^i are local C^1 sections of ΣM , and $\{e_\alpha\}$ is an orthonormal frame of TM.

$$\Theta_{i}(x,t) := \mathcal{P}_{0,t}(x)(b_{i} \circ f_{0})(x). \tag{5.17}$$

For each $t \in [0,1]$ we define the functions $T_{ij}(\cdot,t) := T_{ii}^{\alpha}(\cdot,t)$ by

$$(\mathcal{P}_{0,t})^{-1}((\nabla_{e_{\alpha}}^{F^*TN}\Theta_i)(x,t)) = \sum_j T_{ij}^{\alpha}(x,t)(b_j \circ f_0)(x). \tag{5.18}$$

So far, we only know that the T_{ij} are continuous. In the following, we will perform some formal calculations and justify them afterwards. By a straightforward computation, we have

$$\begin{aligned} ||((\mathcal{P}_{0,1})^{-1} \nabla_{e_{x}}^{f_{1}^{*}TN} \mathcal{P}_{0,1} - \nabla_{e_{x}}^{f_{0}^{*}TN})(b_{i} \circ f_{0})(x)||_{h}^{2} \\ &= ||(\mathcal{P}_{0,1})^{-1} ((\nabla_{e_{x}}^{F^{*}TN} \Theta_{i})(x,1)) - (\mathcal{P}_{0,0})^{-1} ((\nabla_{e_{x}}^{F^{*}TN} \Theta_{i})(x,0))||_{h}^{2} \\ &= ||\sum_{j} T_{ij}(x,1)(b_{j} \circ f_{0})(x) - \sum_{j} T_{ij}(x,0)(b_{j} \circ f_{0})(x)||_{h}^{2} \\ &= \sum_{j} (T_{ij}(x,1) - T_{ij}(x,0))^{2} \\ &= \sum_{j} \left(\int_{0}^{1} \frac{d}{dt} |_{t=r} T_{ij}(x,t) dr \right)^{2}. \end{aligned}$$
(5.19)

Therefore we want to control the first time-derivative of the T_{ij} . Equation (5.18) implies that these time-derivatives are related to the curvature of F^*TN . More precisely, for all $X \in \Gamma(TM)$ we have

$$\frac{d}{dt} \Big|_{t=r} \left((\mathcal{P}_{0,t})^{-1} \left((\nabla_X^{F^*TN} \Theta_i)(x,t) \right) \right) \\
= \frac{d}{dt} \Big|_{t=0} \left((\mathcal{P}_{0,t+r})^{-1} \left((\nabla_X^{F^*TN} \Theta_i)(x,t+r) \right) \right) \\
= \frac{d}{dt} \Big|_{t=0} \left((\mathcal{P}_{0,r})^{-1} (\mathcal{P}_{r,r+t})^{-1} \left((\nabla_X^{F^*TN} \Theta_i)(x,t+r) \right) \right) \\
= (\mathcal{P}_{0,r})^{-1} \frac{d}{dt} \Big|_{t=0} \left((\mathcal{P}_{r,r+t})^{-1} \left((\nabla_X^{F^*TN} \Theta_i)(x,t+r) \right) \right) \\
= (\mathcal{P}_{0,r})^{-1} \left((\nabla_{\frac{\partial}{\partial t}}^{F^*TN} \nabla_X^{F^*TN} \Theta_i)(x,r) \right). \tag{5.20}$$

Now, let us justify the formal calculations (5.19) and (5.20). Combining the definition of Θ_i as parallel transport and a careful examination of the regularity of F we deduce that $\left(\nabla_{\frac{\partial}{\partial t}}^{F^*TN}\nabla_X^{F^*TN}\Theta_i\right)(x,r)$ exists. Then (5.20) holds. Together with (5.18), we know that the T_{ij} are differentiable in t. Therefore (5.19) also holds. We further get

$$\nabla_{\frac{\partial}{\partial t}}^{F^*TN} \nabla_X^{F^*TN} \Theta_i = R^{F^*TN} \left(\frac{\partial}{\partial t}, X \right) \Theta_i + \nabla_X^{F^*TN} \nabla_{\frac{\partial}{\partial t}}^{F^*TN} \Theta_i - \nabla_{\left[\frac{\partial}{\partial t}, X\right]}^{F^*TN} \Theta_i
= R^{F^*TN} \left(\frac{\partial}{\partial t}, X \right) \Theta_i = R^{TN} \left(dF \left(\frac{\partial}{\partial t} \right), dF(X) \right) \Theta_i,$$
(5.21)

since $\nabla_{\frac{\partial}{\partial t}}^{F^*TN}\Theta_i = 0$ by the definition of Θ_i and $[\frac{\partial}{\partial t}, X] = 0$.

This implies

$$\sum_{j} \left(\frac{d}{dt} \Big|_{t=r} T_{ij}(x,t) \right)^{2} = \left\| \frac{d}{dt} \right|_{t=r} ((\mathcal{P}_{0,t})^{-1} ((\nabla_{e_{x}}^{F^{*}TN} \Theta_{i})(x,t))) \right\|_{h}^{2}$$

$$= \left\| \left(\nabla_{\frac{\partial}{\partial t}}^{F^{*}TN} \nabla_{e_{x}}^{F^{*}TN} \Theta_{i} \right) (x,r) \right\|_{h}^{2}$$

$$= \left\| R^{TN} (dF_{(x,r)} \left(\frac{\partial}{\partial t} \right), dF_{(x,r)} (e_{\alpha})) \Theta_{i}(x,r) \right\|_{h}^{2}$$

$$\leq C_{1} \left\| dF_{(x,r)} (\partial_{t}) \right\|_{h}^{2} \left\| dF_{(x,r)} (e_{\alpha}) \right\|_{h}^{2},$$
(5.22)

where C_1 only depends on N.

In the following we estimate $||dF_{(x,r)}(\partial_t)||_h$ and $||dF_{(x,r)}(e_\alpha))||_h$. We have

$$dF_{(x,r)}(\partial_t|_{(x,r)}) = \frac{\partial}{\partial t}|_{t=r}(\exp_{f_0(x)}(t\exp_{f_0(x)}^{-1}f_1(x))) = c'(r), \tag{5.23}$$

where $c(t) := \exp_{f_0(x)}(t \exp_{f_0(x)}^{-1}f_1(x))$ is a geodesic in N. In particular, c' is parallel along c and thus $||c'(r)||_h = ||c'(0)||_h = ||\exp_{f_0(x)}^{-1}f_1(x)||_h$. Therefore, we get

$$||dF_{(x,r)}(\partial_t)||_h = ||\exp_{f_0(x)}^{-1}f_1(x)||_h \le d^N(f_0(x),f_1(x)) \le C_2||u_t - v_s||_{C^0(M,\mathbb{R}^q)}, \tag{5.24}$$

where we have used Lemma 5.1 and the Lipschitz continuity of π . Moreover, there exists $C_3(R) > 0$ such that $||dF_{(x,r)}(e_\alpha))||_h \le C_3(R)$ for all $(x,r) \in M \times [0,1]$.

We have shown

$$\sum_{i} \left(\frac{d}{dt} |_{t=r} T_{ij}(x,t) \right)^{2} \le C_{1} C_{2}^{2} C_{3}(R)^{2} ||u_{t} - v_{s}||_{C^{0}(M,\mathbb{R}^{q})}^{2}$$
(5.25)

for all (x, t). Combining this with (5.16) and (5.19), we complete the proof. \Box The other one is for the parallel transport.

Lemma 5.3. Choose ϵ , δ and R as in (5.10). If $\epsilon > 0$ is small enough, then there exists $C = C(\epsilon) > 0$ such that

$$||P^{\nu_s, u_0} P^{u_t, v_s} P^{u_0, u_t} Z - Z|| \le C||u_t - v_s||_{C^0(M, \mathbb{R}^q)} ||Z||$$
(5.26)

for all $Z \in T_{u_0(x)}N$, $u, v \in B_R^T(\bar{u}_0)$, $x \in M$ and $t, s \in [0, T]$.

Consequently, we also have

Lemma 5.4. Choose ϵ , δ and R as in (5.10). For $u, v \in B_R^T(\bar{u}_0)$, $s, t \in [0, T]$, the operator norm of the isomorphism of Banach spaces

$$P^{\nu_s, u_t}: \Gamma_{W^{1,p}}(\Sigma M \otimes (\pi \circ \nu_s)^* TN) \to \Gamma_{W^{1,p}}(\Sigma M \otimes (\pi \circ u_t)^* TN)$$
 (5.27)

is uniformly bounded, i.e. there exists C = C(R, p) such that

$$||P^{\nu_s, u_t}||_{L(W^{1,p}, W^{1,p})} \le C \tag{5.28}$$

for all $u, v \in B_R^T(\bar{u}_0), x \in M$ and $t, s \in [0, T]$.

The proofs of these two lemmas only depend on the existence of the unique shortest geodesic between any two maps in $B_R^T(\bar{u}_0)$, which was already shown in (5.12). Therefore, we omit the detailed proof here. Besides, by Lemma 5.2, one can immediately prove the following Lemma by the Min-Max principle as in [6].

Lemma 5.5. Assume that $\dim_{\mathbb{K}} \ker(\mathcal{D}^{u_0}) = 2l - 1$, where $l \in \mathbb{N}$ and

$$\mathbb{K} = \begin{cases} \mathbb{C}, & \text{if } m = 0, 1 \pmod{8}, \\ \mathbb{H}, & \text{if } m = 2, 4 \pmod{8}. \end{cases}$$
 (5.29)

Choose ϵ , δ and R as in Lemma 5.2. If R is small enough, then

$$\dim_{\mathbb{K}} \ker(\not \!\!\! D^{\pi \circ u_t}) = 1 \tag{5.30}$$

and there exists $\Lambda = \frac{1}{2}\Lambda(u_0)$ such that

$$\{\operatorname{spec}(\not \!\!\!D^{\pi \circ u_t}) \cap [-\Lambda, \Lambda]\} = 1 \tag{5.31}$$

and $t \in [0, T]$, where $\Lambda(u_0)$ any $u \in B_R^T(\bar{u}_0)$ constant such that spec(\mathbb{D}^{u_0}) \ $\{0\} \subset \mathbb{R} \setminus (-\Lambda(u_0), \Lambda(u_0))$.

Once we have the minimality of the kernel in Lemma 5.5, we can prove the following uniform bounds for the resolvents, which are important for the Lipschitz continuity of the solution to the Dirac equation.

Lemma 5.6. Assume we are in the situation of Lemma 5.5. We consider the resolvent $R(\lambda, \not D^{\pi \circ u_t}): \Gamma_{L^2} \to \Gamma_{L^2}$ of $\not D^{\pi \circ u_t}: \Gamma_{W^{1,2}} \to \Gamma_{L^2}$. By the L^p estimate (see Lemma 2.1 in [6]), we know the restriction

$$R(\lambda, \not D^{\pi \circ u_t}) : \Gamma_{L^p} \to \Gamma_{W^{1,p}}$$
 (5.32)

is well-defined and bounded for any $2 \le p < \infty$. If R > 0 is small enough, then there exists C = C(p, R) > 0 such that

$$\sup_{|\lambda| = \frac{\Lambda}{2}} ||R(\lambda, @@D^{\pi \circ u_t})||_{L(L^p, W^{1,p})} < C$$
(5.33)

for any $u \in B_R^T(\bar{u}_0), t \in [0, T]$.

Now, by the projector of the Dirac operator, we can construct a solution to the constraint equation whose nontrivialness follows from the following lemma.

Lemma 5.7. In the situation of Lemma 5.5, for any fixed $u \in B_R^T(\bar{u}_0)$ and any $\psi \in$ $\ker(\not D^{u_0})$ with $||\psi||_{L^2}=1$, we have

$$\sqrt{\frac{1}{2}} \le ||\tilde{\psi}_1^{u_t}||_{L^2} \le 1,\tag{5.34}$$

where $\tilde{\psi}^{u_t} = P^{u_0, u_t} \psi = \tilde{\psi}_1^{u_t} + \tilde{\psi}_2^{u_t}$ $ition \ \Gamma_{L^2} = \ker(\cancel{p}^{\pi \circ u_t}) \oplus (\ker(\cancel{p}^{\pi \circ u_t}))^{\perp}$ with respect to decompos-

In Section 3, to show the short-time existence of the heat for α -Dirac-harmonic maps, we need the following Lipschitz estimate.

Lemma 5.8. Choose δ as in (5.10), ϵ as in Lemmas 5.2 and 5.3, R as in Lemmas 5.5 and 5.6. For any harmonic spinor $\psi \in \ker(\mathcal{D}^{u_0})$, we define

$$\bar{\psi}(u_t) := \tilde{\psi}_1^{u_t} = -\frac{1}{2\pi i} \int_{\gamma} R(\lambda, \not\!\!\!D^{\pi \circ u_t}) \sigma(u_t) d\lambda \tag{5.35}$$

for any $u \in B_R^T(\bar{u}_0)$, where γ is defined in the Section 2 with $\Lambda = \frac{1}{2}\Lambda(u_0)$. In particular,

 $\bar{\psi}(u_t) \in \ker(\not D^{\pi \circ u_t}) \subset \Gamma_{C^0}(\Sigma M \otimes (\pi \circ u_t)^*TN)$. We write

$$\psi(u_t) := \psi(u(\cdot, t)) = \frac{\bar{\psi}(u_t)}{||\bar{\psi}(u_t)||_{r^2}}.$$
 (5.36)

Let $\psi^A(u_t)$ be the sections of ΣM such that

$$\psi(u_t) = \psi^A(u_t) \otimes (\partial_A \circ \pi \circ u_t) \tag{5.37}$$

for A=1,...,q. Then there exists $C=C(R,\epsilon,\psi_0)>0$ such that

$$||P^{u_t, v_s} \bar{\psi}(u_t)(x) - \bar{\psi}(u_t)(x)|| \le C||u_t - v_s||_{C^0(M, \mathbb{R}^q)}$$
(5.38)

and

$$||\psi^{A}(u_{t})(x) - \psi^{A}(v_{s})(x)|| \le C||u_{t} - v_{s}||_{C^{0}(M, \mathbb{R}^{d})}$$
(5.39)

for all $u, v \in B_R^T(\bar{u}_0), A = 1, ..., q, x \in M$ and $s, t \in [0, T]$.

Proof. Using the following resolvent identity for two operators D_1 , D_2

$$R(\lambda, D_1) - R(\lambda, D_2) = R(\lambda, D_1) \circ (D_1 - D_2) \circ R(\lambda, D_2),$$
 (5.40)

we have

$$\begin{split} P^{u_{t}, v_{s}} \bar{\psi}(u_{t}) - \bar{\psi}(u_{t}) \\ &= -\frac{1}{2\pi i} \left(\int_{\gamma} R(\lambda, P^{u_{t}, v_{s}} \not D^{\pi \circ u_{t}}(P^{u_{t}, v_{s}})^{-1}) P^{u_{t}, v_{s}} P^{u_{0}, u_{t}} \psi_{0} \right. \\ &- \int_{\gamma} R(\lambda, \not D^{\pi \circ v_{s}}) P^{u_{0}, v_{s}} \psi_{0}) \\ &= -\frac{1}{2\pi i} \int_{\gamma} R(\lambda, P^{u_{t}, v_{s}} \not D^{\pi \circ u_{t}}(P^{u_{t}, v_{s}})^{-1}) (P^{u_{t}, v_{s}} P^{u_{0}, u_{t}} \psi_{0} - P^{u_{0}, v_{s}} \psi_{0}) \\ &- \frac{1}{2\pi i} \int_{\gamma} (R(\lambda, P^{u_{t}, v_{s}} \not D^{\pi \circ u_{t}}(P^{u_{t}, v_{s}})^{-1}) - R(\lambda, \not D^{\pi \circ v_{s}})) P^{u_{0}, v_{s}} \psi_{0} \\ &= -\frac{1}{2\pi i} \int_{\gamma} R(\lambda, P^{u_{t}, v_{s}} \not D^{\pi \circ u_{t}}(P^{u_{t}, v_{s}})^{-1}) (P^{u_{t}, v_{s}} P^{u_{0}, u_{t}} \psi_{0} - P^{u_{0}, v_{s}} \psi_{0}) \\ &- \frac{1}{2\pi i} \int_{\gamma} (R(\lambda, P^{u_{t}, v_{s}} \not D^{\pi \circ u_{t}}(P^{u_{t}, v_{s}})^{-1}) \circ (P^{u_{t}, v_{s}} \not D^{\pi \circ u_{t}}(P^{u_{t}, v_{s}})^{-1} - \not D^{\pi \circ v_{s}}) \circ \\ &R(\lambda, \not D^{\pi \circ v_{s}})) P^{u_{0}, v_{s}} \psi_{0}, \end{split}$$

$$(5.41)$$

where γ is defined in (2.29) with $\Lambda = \frac{1}{2}\Lambda(u_0)$. Therefore, for p large enough, we get

$$\begin{split} &||P^{u_{t},v_{s}}\bar{\psi}(u_{t})(x)-\bar{\psi}(u_{t})(x)||\leq C_{1}||P^{u_{t},v_{s}}\bar{\psi}^{u_{t}}-\bar{\psi}^{v_{s}}||_{W^{1,p}(M)}\\ &\leq C_{2}||\int_{\gamma}R(\lambda,P^{u_{t},v_{s}}\not{D}^{\pi\circ u_{t}}(P^{u_{t},v_{s}})^{-1})(P^{u_{t},v_{s}}P^{u_{0},u_{t}}\psi_{0}-P^{u_{0},v_{s}}\psi_{0})||_{W^{1,p}(M)}\\ &+C_{2}||\int_{\gamma}(R(\lambda,P^{u_{t},v_{s}}\not{D}^{\pi\circ u_{t}}(P^{u_{t},v_{s}})^{-1})\circ(P^{u_{t},v_{s}}\not{D}^{\pi\circ u_{t}}(P^{u_{t},v_{s}})^{-1}-\not{D}^{\pi\circ v_{s}})\circ\\ &R(\lambda,\not{D}^{\pi\circ v_{s}}))P^{u_{0},v_{s}}\psi_{0}||_{W^{1,p}(M)}\\ &\leq C_{2}\int_{\gamma}||R(\lambda,P^{u_{t},v_{s}}\not{D}^{\pi\circ u_{t}}(P^{u_{t},v_{s}})^{-1})(P^{u_{t},v_{s}}P^{u_{0},u_{t}}\psi_{0}-P^{u_{0},v_{s}}\psi_{0})||_{W^{1,p}(M)}\\ &+C_{2}\int_{\gamma}||(R(\lambda,P^{u_{t},v_{s}}D^{\pi\circ u_{t}}(P^{u_{t},v_{s}})^{-1})\circ(P^{u_{t},v_{s}}\not{D}^{\pi\circ u_{t}}(P^{u_{t},v_{s}})^{-1}-\not{D}^{\pi\circ v_{s}})\circ\\ &R(\lambda,D^{\pi\circ v_{s}}))P^{u_{0},v_{s}}\psi_{0}||_{W^{1,p}(M)} \end{split}$$

Now, we estimate all the terms in the right-hand side of the inequality above. First, by Lemmas 5.6 and 5.4, we know that all the resolvents above are uniformly bounded. Next, by Lemma 5.2, we have

$$||P^{u_t,v_s} \not\!\!\!D^{\pi \circ u_t} (P^{u_t,v_s})^{-1} - \not\!\!\!D^{\pi \circ v_s}||_{L(W^{1,p},L^p)} \le C(R)||u_t - v_s||_{C^0(M,\mathbb{R}^q)}.$$
 (5.43)

Finally, by Lemma 5.3, we obtain

$$||P^{u_t, v_s} P^{u_0, u_t} \psi_0 - P^{u_0, v_s} \psi_0||_{L^p} \le C(\epsilon, \psi_0) ||u_t - v_s||_{C^0(M, \mathbb{R}^q)}.$$
(5.44)

Putting these together, we get (5.38).

Next, we want to show the following estimate which is very close to (5.39).

$$||\bar{\psi}^{A}(u_{t})(x) - \bar{\psi}^{A}(v_{s})(x)|| \le C(R, \epsilon, \psi_{0})||u_{t} - v_{s}||_{C^{0}(M, \mathbb{R}^{q})}.$$
 (5.45)

In fact, we have

$$\begin{split} &||\bar{\psi}^{A}(u_{t})(x) - \bar{\psi}^{A}(v_{s})(x)|| \\ &\leq ||\bar{\psi}(u_{t})(x) - \bar{\psi}(v_{s})(x)||_{\Sigma_{x}M\otimes\mathbb{R}^{q}} \\ &\leq ||P^{u_{t},v_{s}}\bar{\psi}(u_{t})(x) - \bar{\psi}(v_{s})(x)||_{\Sigma_{x}M\otimes\mathbb{R}^{q}} + ||P^{u_{t},v_{s}}\bar{\psi}(u_{t})(x) - \bar{\psi}(u_{t})(x)||_{\Sigma_{x}M\otimes\mathbb{R}^{q}} \\ &= ||P^{u_{t},v_{s}}\bar{\psi}(u_{t})(x) - \bar{\psi}(v_{s})(x)||_{\Sigma_{x}M\otimes T_{(\pi^{o}v_{s}(x))}N} + ||P^{u_{t},v_{s}}\bar{\psi}(u_{t})(x) - \bar{\psi}(u_{t})(x)||_{\Sigma_{x}M\otimes\mathbb{R}^{q}} \\ &\leq C(R,\epsilon,\psi_{0})||u_{t} - v_{s}||_{C^{0}(M,\mathbb{R}^{q})} + ||P^{u_{t},v_{s}}\bar{\psi}(u_{t})(x) - \bar{\psi}(u_{t})(x)||_{\Sigma_{x}M\otimes\mathbb{R}^{q}}. \end{split}$$

It remains to estimate the last term in the inequality above. To that end, let $\gamma(r) :=$ $\exp_{(\pi \circ u_t)(x)}(r \exp_{(\pi \circ u_t)(x)}^{-1}(\pi \circ u_t(x))), r \in [0,1],$ be the unique shortest geodesic of N from $(\pi \circ u_t)(x)$ to $(\pi \circ v_s)(x)$. Let $X \in T_{\gamma(0)}N$ be given and denote by X(r) the unique parallel vector field along γ with X(0) = X. Then we have

$$P^{u_t, v_s} X - X = X(1) - X(0) = \int_0^1 \frac{dX}{dr} \bigg|_{r=\xi} d\xi = \int_0^1 II(\gamma'(r), X(r)) dr.$$
 (5.46)

Therefore,

$$||P^{u_t, v_s}X - X||_{\mathbb{R}^q} \le C_1 \sup_{r \in [0, 1]} ||\gamma'(r)||_N \sup_{r \in [0, 1]} ||X(r)||_N = C_1 ||\gamma'(0)||_N ||X||_N$$
(5.47)

where II is the second fundamental form of N in \mathbb{R}^q and C_1 only depends on N. Using (5.9) and the Lipschitz continuity of π we get

$$||\gamma'(0)||_{N} \le d^{N}((\pi \circ u_{t})(x), (\pi \circ \nu_{s})(x)) \le C_{2}||u_{t}(x) - \nu_{s}(x)|||_{\mathbb{R}^{q}}$$
(5.48)

and

$$||P^{u_t, v_s} X - X||_{\mathbb{P}^q} \le C_3 ||u_t(x) - v_s(x)||_{\mathbb{P}^q} ||X||_{N}.$$
(5.49)

This implies

$$||P^{u_t, v_s} \bar{\psi}(u_t)(x) - \bar{\psi}(u_t)(x)||_{\Sigma : M \otimes \mathbb{R}^q} \le C(R, \epsilon, \psi_0) ||u_t(x) - v_s(x)||_{\mathbb{R}^q}.$$
 (5.50)

Hence, (5.45) holds.

Now, using (5.38) and (5.45), we get

$$\begin{split} &||\psi^{A}(u_{t})(x)-\psi^{A}(v_{s})(x)||=||\frac{\bar{\psi}^{A}(u_{t})(x)}{||\bar{\psi}(u_{t})||_{L^{2}}}-\frac{\bar{\psi}^{A}(u_{t})(x)}{||\bar{\psi}(v_{s})||_{L^{2}}}-\frac{\bar{\psi}^{A}(u_{t})(x)}{||\bar{\psi}(v_{s})||_{L^{2}}}-\frac{\bar{\psi}^{A}(u_{t})(x)}{||\bar{\psi}(v_{s})||_{L^{2}}}-\frac{\bar{\psi}^{A}(v_{s})(x)}{||\bar{\psi}(v_{s})||_{L^{2}}}||\\ &\leq \frac{\bar{\psi}^{A}(u_{t})(x)}{||\bar{\psi}(u_{t})||_{L^{2}}||\bar{\psi}(v_{s})||_{L^{2}}}|||\bar{\psi}(v_{s})||_{L^{2}}-||\bar{\psi}(u_{t})||_{L^{2}}|+\frac{1}{||\bar{\psi}(v_{s})||_{L^{2}}}||\bar{\psi}^{A}(u_{t})(x)-\bar{\psi}^{A}(v_{s})(x)||\\ &=\frac{\bar{\psi}^{A}(u_{t})(x)}{||\bar{\psi}(v_{s})||_{L^{2}}||\bar{\psi}(v_{s})||_{L^{2}}}||\bar{\psi}^{A}(u_{t})(x)-\bar{\psi}^{A}(v_{s})(x)||\\ &\leq \frac{\bar{\psi}^{A}(u_{t})(x)}{||\bar{\psi}(u_{t})||_{L^{2}}||\bar{\psi}(v_{s})||_{L^{2}}}||P^{u_{t},v_{s}}\bar{\psi}(u_{t})-\bar{\psi}(v_{s})||_{L^{2}}+\frac{1}{||\bar{\psi}(v_{s})||_{L^{2}}}||\bar{\psi}^{A}(u_{t})(x)-\bar{\psi}^{A}(v_{s})(x)||\\ &\leq \left(\frac{\bar{\psi}^{A}(u_{t})(x)}{||\bar{\psi}(u_{t})||_{L^{2}}||\bar{\psi}(v_{s})||_{L^{2}}}+\frac{1}{||\bar{\psi}(v_{s})||_{L^{2}}}\right)C(R,\epsilon,\psi_{0})||u_{t}-v_{s}||_{C^{0}(M,\mathbb{R}^{q})}. \end{split}$$

Then the inequality (5.39) follows from Lemma 5.7 and (5.45). This completes the proof.

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