# A New Decision Making Approach for Indirect Left Turn Treatments by Utilizing Decision Assistance Curves 

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# A NEW DECISION MAKING APPROACH FOR INDIRECT LEFT TURN TREATMENTS BY UTILIZING DECISION ASSISTANCE CURVES 

 bySunil Gyawali

## A DISSERTATION

Presented to the Faculty of The Graduate College at the University of Nebraska In Partial Fulfillment of Requirements For the Degree of Doctor of Philosophy

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# A NEW DECISION MAKING APPROACH FOR INDIRECT LEFT TURN TREATMENTS BY UTILIZING DECISION ASSISTANCE CURVES 

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This study developed decision assistance curves (DAC) for unconventional intersections, including median U-turns (MUT), continuous flow intersections (CFI), and jughandle intersections, based on their operational performance relative to a conventional intersection. An economic analysis was performed to compute the net present value (NPV) of benefits and the benefit to cost ratio (B/C) with the development of a spreadsheet tool. The DAC classified the region of optimal performance of isolated unconventional intersections. For 5\% left turn traffic conditions, MUT was warranted for all volume criteria. For $10 \%$ and $15 \%$ left turn traffic conditions, jughandle was warranted for the major street approach traffic volumes greater than or equal to 2200 vph , and greater than 1800 vph , respectively. However, the warranty decreased with the increase of minor streets for all of the conditions except at balanced and nearly balanced conditions under $10 \%$ left turn traffic. For $10 \%$ and $15 \%$ left turn traffic conditions with an unbalanced flow, CFI was warranted for major street approach traffic volumes greater than or equal to 2200 vph , and greater than 1800 vph , respectively. The warranty expanded with the increase of minor street approach traffic volumes. The standard signalized intersection with left turn permitted was warranted for minor street approach traffic volumes less than 200 vph and the major street approach traffic volumes of 700 vph to 1350 vph . The high presence of trucks favored the use of CFI. Additionally, a case
study performed on a 24 -hour rural pattern volume indicated the highest NPV of benefits and the highest $\mathrm{B} / \mathrm{C}$ related to new MUT construction. Though the MUT-retrofit had the highest NPV, since the construction cost of MUT-retrofit was high, a jughandle-retrofit was found to have the highest $\mathrm{B} / \mathrm{C}$. In this manner, the developed method provided an integrated decision support system utilizing both operational performance and economic aspects as an improved method over the current practice. Some possible extensions of study were also recommended as further studies.

## DEDICATION

To my parents Laxman and Sita Jnawali, and to my beloved wife Bandita Parajuli who inspired me to pursue a Ph. D.

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## CHAPTER 1

## INTRODUCTION AND OBJECTIVE

### 1.1 General Background

The prevalent problem of traffic congestion has caused the waste of billions of gallons of fuel, time, and money (Grant, Bowen, Day, Winick, Bauer, Chavis \& Trainor, 2011). The 2012 Urban Mobility Report stated that the cost of traffic congestion was $\$ 121$ billion in 2011. This estimation was based on the travel delay of 5.5 billion hours, 2.9 billion gallons of wasted fuel, the production of 56 billion pounds of carbon dioxide $\left(\mathrm{CO}_{2}\right)$, and truck congestion costs of $\$ 27$ billion. In addition, about $40-50 \%$ of all nonrecurring congestion was associated with traffic incidents, and for every dollar of congestion costs, the related crash cost was $\$ 1.84$ in large cities (Crashes vs. CongestionWhat's the cost to Society, 2008). This scenario reflects a strong need for measures to mitigate traffic congestion. Highway intersections are key components of the transportation network, and they experience significant traffic congestion due to the competing needs of the traffic on different intersection approaches. Conventional measures to reduce highway traffic congestion may not be sufficient to alleviate existing adverse traffic conditions at intersections. Therefore, there is a need to investigate the development and implementation of unconventional intersection designs in order to cope with the congestion issue by overcoming the inefficiency of conventional intersections and maintaining better traffic mobility.

### 1.2 Study Intersections

This study was an attempt to investigate the use of the following three types of unconventional intersections also known as indirect left turn intersections: median U-turn (MUT), continuous flow intersection (CFI), and jughandle, a standard signalized intersection with a left turn permitted along a major street, to assess their usefulness in different traffic volume conditions.

A common feature of these three types of unconventional intersections is the treatment of the left turn maneuver, diverting left turning traffic from through traffic. This process can be effective at easing the operation of an intersection system by redistributing demands over sub-intersections and the core intersection, and by reducing the cycle length of the traffic signal. The key objective is to eliminate the protected left turn phase on the approaches to ameliorate signal operation, which can potentially minimize intersection delay.

### 1.2.1 Median U-Turn (MUT)

The median U-turn (MUT), as shown in figure 1.1, is comprised of one signalized intersection and two median crossovers or openings. The median openings, depending on the situation, can be STOP controlled or signal controlled. The signalized intersection is only used for major and minor street through movements, and hence operates with a two phase signal. The left turning traffic move with through movement through the signalized intersection, then divert towards the exclusive left turn lane at the median openings, and finally perform a U-turn. This kind of geometric and signal configuration is expected to improve the intersection by reducing delay, stops, and conflicts, providing better
progression for the through traffic on the major street, and increasing the capacity of the intersection (Hummer, 1998(A); Techbrief: Synthesis of Median U-Turn Intersection Treatment, 2007).


Figure 1.1 A typical median U-turn

### 1.2.2 Continuous Flow Intersection (CFI)

The continuous flow intersection (CFI) shown in figure 1.2 is comprised of five intersections, including one main signalized intersection and four other signalized crossover intersections. Left turning traffic is diverted through a displaced left turn lane 300-400 feet ahead of the intersection and merged with the minor street at crossover intersections. Hence, the main signalized intersection is only for through traffic and operates with two signal phases. This kind of geometric and signal configuration is
expected to reduce delay, travel time, fuel consumption, and pollution (Techbrief: Displaced Left-Turn Intersection, 2009).


Figure 1.2 A typical continuous flow intersection

### 1.2.3 Jughandle

Jughandle intersections use ramps to divert left-turning vehicles from the main street. Left turns from the minor street are allowed. The signalized intersection operates for through vehicles from the major street, through vehicles from the minor street, and left-turning vehicles from the minor street. The crossovers are generally YIELD controlled. The FHWA Tech Brief on Traffic Performance of Three Typical Designs of New Jersey Jughandle Intersections (2007) mentioned three types of jughandles: (1) forward/forward (F/F), (2) forward/reverse (F/R), and (3) reverse/reverse
$(R / R)$. Figure 1.3 depicts a typical $R / R$ jughandle. A jughandle is expected to reduce delay and increase the capacity of an intersection (TechBrief: Traffic Performance of Three Typical Designs of New Jersey jughandle Intersections, 2007).


Figure 1.3 A typical R/R jughandle

### 1.2.4 Standard Signalized Intersection with Left Turn Permitted along Major Street

This is a minor deviation on a standard signalized intersection. In this intersection, the left turn movements along the major street are permitted (figure 1.4). This intersection is included in the study to test if the intersection's operation can be improved
by removing the protected left turn phase along major streets in order to judge the possibility of avoiding the implementation of unconventional intersections.


Figure 1.4 A typical standard signalized intersection with permitted left turns at major street

### 1.3 Problem Statement

From the literature review and current state of practice included in Chapter 2 and Chapter 3 of this dissertation, it can be inferred that a reliable decision support system is needed for the selection of optimal types of unconventional intersection treatments. Some
of the major problems identified on the current status of studies is described in the following section.

### 1.3.1 Lack of Transferability and Failure to provide an Integrated Decision Support System

The literature review indicates that there are a lot of studies that deal with microsimulation based performance analysis of unconventional intersections (Goldbat, Mier and Fredman, 1994; Hummer and Boone, 1995; Dorothy, Maleck and Nolfe, 1997; Topp and Hummer, 2005; Pittasringkam, 2005; Tarko, Inerowicz, Lang and Villwock, 2008; Tarko, Azam and Inerowicz, 2010; Kivlins and Naudzuns, 2011; Chang, Lu and Xiangfeng, 2011; Chowdhury, 2011; Smith, 2011; El Esawey and Sayed, 2014). These studies have compared the magnitude of performance measures like delay, travel time, number of stops, etc., with the conventional intersection on certain criteria of volumes, lane configurations, and controls. They quantified the benefits of unconventional intersections based on the comparison of performance measures. Firstly, there is always a transferability problem with pure micro-simulation based results and also with the statistical models developed based on micro-simulation to transfer them to a new situation because of issues like the need of re-calibration, the need of excessive time for performing simulation, and reporting the decision choice for a large set of data. Secondly, these studies were performed like case specific studies, and they failed to provide any integrated general decision support system for different types of unconventional intersections providing some specific thresholds.

### 1.3.2 Based on too Simplistic Performance Measures

While planning for the implementation of unconventional intersections, the decision-making criteria to select an appropriate alternative, while considering limiting factors such as traffic volumes, truck percentage, geometry, etc., plays a very important role. At present, few decision assistance tools are available that perform planning-level analysis and are capable of providing a hierarchical order of unconventional intersections based on their performance. The literature indicates that these tools use critical lane volume analysis (CLV) to evaluate the performance of intersections in the form volume to capacity (V/C) ratio (Asokan, Bared, Jagannathan, Hughes, Cicu and Illota, 2010; Kirk, Jones and Statmatadias, 2011; Stamatiadis, kirk, Agrawal and Jones, 2011; Stamatadias, Kirk and Agrawal, 2012; Sangster and Rakha, 2014). The drawback for such tools is that the volume to capacity ratio is a very simplistic performance measure. It does not take into account other factors like travel delay. The volume to capacity ratios are not easily understood by decision makers or the general public, and hence cannot be effectively used to communicate the results. Also, the volume to capacity ratios cannot be monetized to perform a benefit to cost analysis for the selected unconventional intersections.

### 1.3.3 Need of Accountancy of Cost and Benefit

The accountancy of the cost and benefit aspect during the decision-making process for the selection of a suitable unconventional intersection is very necessary. This area is also neglected in the existing method of evaluating unconventional intersections. It could be that a certain type of unconventional intersections for a given situation may
have some operational or safety benefits, but the cost of implementation is so high that its use may not be economically justified. Some studies have used the cost and benefit aspect and have calculated the benefit to cost (B/C) ratio or the net present value of cost (NPV) (Boddapatti, 2008; Martin, Islam, Best and Sharma, 2012). However, they either dealt with certain types of intersections only or used a combined form of unconventional treatments for specific situations. The methods of these studies do not suffice for the purpose of developing a decision support system for broad conditions.

### 1.4 Context of Study

As mentioned in section 1.2, this study included only three types of unconventional intersections: MUT, CFI, and jughandle, and a standard signalized intersection with a left turn permitted along a major street. The study considered only fully actuated signal control operations on all of these intersections, including a simple standard signalized intersection. Pedestrians were not included in this study, but this study methodology can be easily extended to explicitly account for operational impacts of pedestrians. Furthermore, this study was limited to full MUT with no left turns at the signalized intersection and un-signalized (STOP controlled) median openings, a signalized CFI with a single controller, and a jughandle with un-signalized (YIELD controlled) crossovers. The study analyzed a rural intersection with a four-lane major street and two-lane minor streets. A tool was developed to work on multiple sets of criteria so that it can be applicable for any locations. The methodology developed from this study can be easily extended for different conditions of volumes, different types of intersections, and urban settings.

Highway Capacity Software (HCS) was used in this study to compute the performance of multiple intersections. The benefits of using HCS as a screening tool are listed below.

1. HCS is faster than micro-simulation in generating estimates of performance measures.
2. HCS is based on multiple studies conducted throughout the United States. HCS uses results from these studies to generate appropriate calibration factors to calibrate itself for existing operating conditions. As an example, the gap acceptance threshold for heavy vehicles can be selected from the appropriate table to model given field conditions. These thresholds are a result of multiple validation and calibration studies.
3. HCS produces several important performance measures, such as delay and stops, which can be easily understood and monetized.

This study used the operational performance analysis in the development of DAC as well as in the development of tools for economic analysis. The past studies have indicated that unconventional intersections have less conflict points than standard signalized intersections, and they do not pose any major safety concerns for traffic and pedestrians. This conclusion can inferred from the literatures included in Chapter 2 of the dissertation, such as "Information and Geometric Design Guidance Regarding Boulevards, Directional Crossovers, and Indirect ('Michigan') Left Turns" (1995), Kach (1992), FHWA Techbrief: Displaced Left-turn Intersection (2009), Jagannathan and Bared (2005), Jagannathan, Gimbel, Bared, Hughes, Persuad and Lyon (2006), etc.

Additionally, intersection safety in itself is a very vast area of study and could be considered as a separate topic of study. In this backdrop, this dissertation limited its scope on operational performance only.

### 1.5 Objectives

The study carried the following specific objectives:

1. Evaluate the operation of three unconventional intersections such as MUT, CFI, and jughandle, and deviation of standard signalized intersections macroscopically.
2. Develop decision assistance curves that can provide decision support for the selection of suitable intersection types and the quantification of the performance for the selected intersections under defined volume criteria
3. Monetize the benefits and costs, and perform an economic analysis based on marginal costs associated with each intersection type in comparison to a standard signalized intersection
4. Develop a spreadsheet tool that can operate under a user's defined criteria and provide decision assistance for the selection of a suitable unconventional intersection type

### 1.6 Contributions

With an objective to build a reliable decision support system for unconventional intersections, this study featured some uniqueness in the present trend of relevant studies and thrived to contribute more in this sector. These features are described in detail as follows:

1. A distinct and new approach in the existing trend of study

This study adopted clustering methods (Discriminant Analysis) to classify the intersections according to the optimal performance on the grid of major and minor street approach traffic volumes. This is a first time that the Discriminant Analysis is used in the study of unconventional intersections. Furthermore, the development of contour plots in the meshgrid of volumes to indicate the delay benefits or loss (trends and specific values) of intersections for any volumes is also a new concept. It is evident from the literature review included in Chapter 2 that this kind of methodology has never been applied on any of the past studies regarding unconventional intersections.
2. Development of decision assistance curves (DAC) as a decision support system for decision makers

This study was focused on developing DAC using a measure of effectiveness computed from a macro level of analysis. DAC are capable of allocating suitable alternatives according to the performance for any criteria of volume. At the same time, the contour plots can provide the delay loss or saving for that selected alternative for any volume condition. Hence, the decision maker can obtain assistance in selecting the alternative as well as quantifying the loss or benefit at any volume condition for a selected intersection. These kinds of curves have never been developed so far by any of the studies related to unconventional intersections.

## 3. Consideration of cost and benefit

This study considered the cost and benefit aspect with the inclusion of operational benefits or costs, construction costs, and operation and maintenance costs throughout the life cycle period of an intersection. The economic analysis was incorporated on the spreadsheet tool "SILCC," which is capable of performing LCCA to provide the NPV and B/C of each alternative based on marginal values of cost and benefits. The integrated tool will avail users with an economic performance from which intersections can be categorized according to the hierarchy of cost effectiveness. Some literatures have used the cost based approach on the selection of alternatives (Boddapatti, 2008; Martin et al., 2012). However, Bodapatti (2008) was focused on MUT and its deviations, and Martin et al. (2012) has done more engineering analysis for specific projects comprised of combinations of alternatives. There are no studies which have integrated all of the aspects to provide an economic performance in terms of NPV benefits or the B/C ratio separately for CFI, MUT, and Jughandle, so that the hierarchical order of performance can be developed under a multiple set of criteria as SILCC does.

### 1.7 Dissertation Organization

This dissertation is organized into eight chapters. This chapter, "Introduction and Objectives," deals with the general background of unconventional intersections, the problem statement, the scope, and the objectives and contribution of the study. Chapter 2 contains a review of related past studies regarding the operation, safety, and cost of unconventional intersections. Chapter 3 deals with the condition of existing practices,
especially the guidelines for the implementation of unconventional intersections and related costs. Chapter 4 deals with an operational analysis of these unconventional intersections. Chapter 5 is concerned with the delay sensitivity of these unconventional intersections with respect to multiple volume conditions. Chapter 6 deals with an economic analysis, including cost estimation, the monetization of cost, a life cycle cost analysis, and the development of a spreadsheet tool. Chapter 7 is the last chapter, which is comprised of a conclusion based on the study's findings and recommendations for further research.

## CHAPTER 2

## LITERATURE REVIEW

This chapter is focused on the description of past studies, their methods of evaluation, and their performance related to the development and implementation of unconventional intersections based on a literature review. The literature review is comprised of three major components: (1) the description of existing tools to evaluate unconventional intersections, (2) their performance in terms of operation and safety, and (3) costs related to unconventional intersections. Limited by the scope of this study, the focus is on the MUT, CFI, and jughandle unconventional intersections.

### 2.1 Existing Tools to Evaluate Unconventional Intersections

An extensive search found that there are three types of tools developed for evaluating unconventional intersections including MUT, CFI, and jughandle. The following sections detail the names and descriptions of these tools.

### 2.1.1 Intersection Design Alternative Tool (IDAT)

This tool was developed by a research team at the University of Kentucky. It is available for download from the CATS lab website at the Kentucky Transportation Centre upon registration. The main purpose of this tool is to provide decision assistance for engineers and planners for the selection of alternative designs based on capacity constraints (Kentucky Transportation Centre, accessed 2014). The program accepts input of peak-hour traffic and pedestrian volumes, and can work for 12 different alternative designs including CFI, MUT, and jughandle. It evaluates intersections in terms of right-of-way, safety, and ability to accommodate access management techniques (Kentucky

Transportation Centre, accessed 2014). A detailed description is also provided in a paper by Stamatiadis et al. (2012) and in a report by Stamatiadis et al. (2011). The operational evaluation procedure has utilized critical lane volume analysis (CLVA) or critical movement analysis (CMA) (Stamatiadis et al., 2011; Stamatadias et al., 2012; Kirk et al., 2011). CMA for signalized intersections represents the sum of the critical volumes assigned for each signal phase of that intersection (Kirk et al., 2011). For two-way stop control, it uses the critical approach traffic volume, which is equivalent to critical volume for signalized intersections. The threshold for a particular intersection is fixed based on the plot of intersection control delay and critical volume. The critical thresholds determined for signalized intersections was $1,400 \mathrm{vph}$ (vehicles per hour), $1,200 \mathrm{vph}$ for all way stop control, 900 vph for two way stop control, and $1,000 \mathrm{vph}$ for roundabouts (Kirk et al., 2011).

### 2.1.2 Alternative Intersection Selection Tool (AIST)

The AIST was developed by the Federal Highway Administration (FHWA) in 2009. The tool used the CLVA approach to approximate the capacity as the sum of critical movements at an intersection per lane based on input of peak hour volumes (Asokan, Bared, Jagannathan, Hughes, Cicu and Illota, 2010). The tool can evaluate six types of intersections: (1) conventional intersections, (2) displaced left turn or continuous flow intersections (partial and full), (3) restricted crossing U-turns, (4) median U-turns (partial and full), (5) quadrant roadway intersections, and (6) roundabouts. The tool was later updated and expanded to include additional alternatives and was renamed the

Capacity Analysis for Planning of Junctions (CAP-X) (Alternative Intersections by John Sangster, accessed on 2014).

### 2.1.3 Capacity Analysis and Planning of Junctions (CAP-X)

The CAP-X was developed by the FHWA in partnership with the Transportation Systems Institute at the University of South Florida in 2011. It is the updated form of AIST. The tool is available for download from the Transportation System Institute (TSI) website upon registration. Sangster and Rakha (2014) have done extensive analysis of the CAP-X tool and consider it a highly functional planning level tool. However, they have emphasized this tool's need for validation. Sangster and Rakha (2014) have also documented the formulation of critical sum equations used in the tool and have demonstrated the operational limitations of intersections as predicted by this tool. The critical sum method determines the most governing movement at any time during a signal cycle, which sums the demands for critical movements in the sequence and determines a total value for demand at intersections in vehicles per hour per lane. This software is capable of assessing six different intersection designs and five different interchange designs, including CFI and MUT. The authors indicated that CAP-X does not apply adjustment factors for lane utilization or adjustment factors for saturation flow rate for turning movements, and doesn't allow variability in the end time of opposing left turn phases. The authors also stated that CAP-X software does not include jughandle intersections. Similarly, the authors indicated that CAP-X neglects the additional volumes added by the minor street left-turn movements.

From above literatures about existing tools for unconventional intersections, it can be inferred that these tools used a critical lane volume analysis method to analyze the performance of unconventional intersections. Furthermore, it can be also observed that these tools have not used the cost and benefit aspect of these intersections. The currency and efficiency of these tools can be improved by going more in-depth into the performance analysis part and using the effect of the cost and benefit aspect in the selection criteria of the intersections.

### 2.2 Operation and Safety Performance Related to Median U-Turn (MUT)

As described in the preceding chapter, the two-legged MUT is comprised of a core signalized intersection and two median openings. The left turning vehicles from minor and major streets weave toward the exclusive left turn lane to approach the median opening and finally perform a U-turn. The traffic operational phenomenon regarding this maneuver, and the safety and operational performance of the system, are described in detail in the following subsections.

### 2.2.1 Median Opening and Operation Related to U-Turn Maneuver

The two-legged MUT is constructed with two median openings along the major street. The MUT can be implemented with signalized or un-signalized openings (Techbrief: Synthesis of MUT Intersection Treatment, 2009). To avoid stopping on the through lane, the exclusive left-turn lanes are provided in advance of the median openings (AASHTO Green Book, 2011). The width of the median depends on the type of U-turn maneuver and type of vehicle. The values are provided in the AASHTO Green Book (2011) and a Michigan DOT report, "Information and Geometric Design Guidance

Regarding Boulevards, Directional Crossovers, and Indirect ('Michigan') Left-Turns." The median on a four-lane arterial should have a width of 60 ft . to accommodate a tractor-semitrailer combination of trucks as the design vehicle (AASHTO Green Book, 2011; Rodgerts, Ringert, Koonce, Bansen, Nguyen, McGill, Stewart, Sugget, Neuman, Antonucci, Hardym, and Courage, 2004). The minimum design of the median openings are also provided in the AASHTO Green Book (2011) and MDOT guidelines. The U-turn opening will benefit from signalization if the geometry is perfect and signal progression can be maintained. If the geometry is not perfect, stop signs work best for U-turn openings (Dorothy, Maleck and Nolf, 1997). The signal at the median opening should accommodate a maximum queue to avoid spill overs (Rodgerts et al., 2004). The provision of median openings along the segment between intersections helps to maintain the good capacity and level of service of downstream signalized intersections, rather than making vehicles U-turn from downstream signalized intersections (Guo, Liu, Liu and Deng, 2011). There will be less delay experienced if U-turns are allowed through median openings before downstream signalized intersections as opposed to direct left turns. Drivers prefer making right turns, followed by U-turns (RTUT), at median openings rather than signalized intersections (Liu, Lu, Pirinccioglu and Sokolow, 2006). It also helps to reduce travel time (Liu and Lu, 2007). Although a study (Kai, Ning and Chendong, 2007) mentioned that the application of an exclusive left turn lane at the median opening may not be good in some conditions, such as when there is a slow operating speed and high volume, it cannot be omitted because of its safety aspect (Chen, Qi and

Liu, 2014). The existing method to evaluate median openings and the U-turn maneuver are described based on past literature.

### 2.2.1.1 Estimation of U-Turn Capacity and Delay

The Highway Capacity Manual (HCM, 2010) has adopted Harder's model as a procedure to estimate the capacity of minor stream movement at an un-signalized, two way stop controlled (TWSC) intersection. In Harder's model, the capacity of minor movement is expressed as a function of conflicting flow rate, critical gap, and follow-up time for minor movement. The model is expressed below (HCM, 2010).

$$
\begin{equation*}
C_{p, x}=\frac{V_{c . x} e^{-\frac{v_{c, x} t_{c, x}}{3600}}}{1-e^{-\frac{v_{c, x} t_{f, x}}{3600}}} \tag{2.1}
\end{equation*}
$$

Where,

$$
\begin{aligned}
& \mathrm{C}_{\mathrm{p}, \mathrm{x}}=\text { Potential capacity of movement } \mathrm{x}(\mathrm{veh} / \mathrm{h}), \\
& \mathrm{V}_{\mathrm{c} \cdot \mathrm{x}}=\text { Conflicting flow rate for movement } \mathrm{x}(\mathrm{veh} / \mathrm{h}), \\
& \mathrm{t}_{\mathrm{c}, \mathrm{x}}=\text { Critical headway for minor movement }(\mathrm{s}), \text { and } \\
& t_{f, x}=\text { Follow-up headway for minor movement } \mathrm{x}(\mathrm{~s}) .
\end{aligned}
$$

The HCM (2010) also provides the method to compute the critical gap and follow-up time. The critical gap depends on the base critical headway, the adjustment factors for heavy vehicles and heavy vehicle percentage, the adjustment factor for grade
and percent grade, and the adjustment for intersection geometry. Similarly, the follow-up time depends on the base follow-up time and the adjustment factor for heavy vehicles and heavy vehicle percentage. The HCM offers the tables to provide base critical headway and base follow-up headway values for TWSC.

Studies (Liu, John, Hu and Sokolow, 2008; Liu et al., 2006; Al Maseid, 1999) have utilized this concept when determining the capacity of the U-turn maneuver at median openings. In this context, Al Maseid (1999) used empirical and gap acceptance approaches to estimate the capacity of U-turn openings. He collected data in the country of Jordan in two sets: first, for capacity estimation models, and second, for critical gap and move up time models. He developed linear and exponential capacity models, where capacity was a function of conflicting flow. He also expanded his linear model to account for the flow per lane. Al Maseid developed a delay equation where the total delay was the function of the conflicting flow and a linear model for critical gap, which was the function of the average total delay and the conflicting traffic stream. In the move up time model, the move up time was the function of average total delay. The equations are expressed as follows (Al Maseid, 1999):

$$
\begin{align*}
C & =1,545-790 e^{\frac{q}{3600}}  \tag{2.2}\\
T D & =6.6 e^{\frac{q}{1,200}} \tag{2.3}
\end{align*}
$$

Where,
C = Capacity of U-Turn movement (vph),
$\mathrm{q}=$ Conflicting traffic flow (vph), and
$\mathrm{TD}=$ Average total delay for U -Turning vehicles at median opening(s).

Al Masaeid (1999) compared the capacity from his equation with the capacity from Siegloch's equation (based on gap acceptance approach). The results were similar with a 95\% confidence level. However, other literature (Liu, 2006; Liu et al., 2008) has criticized these equations for use in the U.S., because that study was based on data collected in Jordan. Similarly, Liu (2006) and Liu et al. (2008) estimated the potential capacity for U-turn movement at median openings on multilane highways by performing an estimation of the critical gap and follow-up time for U-turning passenger cars at median openings. They collected data from six selected median openings in Tampa Bay, Florida. The critical gap for U-turns was estimated by using the maximum likelihood method and the follow-up time predicted by the linear regression equation developed in this study. The capacity estimation was done using Harder's equation. The mean critical headways were estimated as 6.9 and 6.4 s for narrow median openings (median nose width $\leq 21 \mathrm{ft} . \mathrm{m}$ ) and wide median openings (median nose width $\geq 21 \mathrm{ft}$ ) openings (Liu, 2006; Liu and Lu, 2007; Liu et al., 2008). The study found that median width is a significant parameter affecting capacity, such that the U-turn movement on wide medians has a larger potential capacity than a U-turn movement with narrow median openings. The study further tested Harder's models with the capacity obtained from field data using Kyte's method (Kyte, Clemow, Mahfood, Lall and Khisty, 1991). The results showed that Harder's model provided reasonable capacity estimates for U-turn movements at
median openings. Later in 2012, Liu, Qu, Yu, Wang, and Cao also developed a VISSIM simulation model for U-turns at un-signalized intersections. They collected behavioral features such as priority rule, lane selection, and turning speed of U-turns from field studies at ten sites. They compared the capacity calculated from a calibrated VISSIM model with the HCM method and field-measured capacity. They found that the VISSIM simulation yielded mean absolute percentage errors of $17.6 \%$ and $20.7 \%$ for four-lane and six-lane roadways, respectively.

Recently, Obaidat and Elayan (2013) studied gap acceptance behavior of drivers at four U-turn openings in four-lane divided highways in Jordan, and developed models. The first model was developed to estimate the time gap accepted by drivers. In the model, the time gap accepted by drivers was the function of the driver's age, gender, and waiting time. The second model was developed to estimate the probability of accepting the gap. In this model, the turning choice was the function of accepted gap lengths, driver's age, driver's gender, and waiting time. The models showed that the accepted gap length decreased with waiting time and the presence of a male driver. It increased with the presence of an older age group. The turning function decreased with the presence of a young age group, but increased with the length of gap, waiting time, and presence of male drivers. In the same context, Yang (2002) studied the capacity estimation of U-turn movements at median openings using CORSIM to quantify the relationship between the capacity and conflicting flow rate for the U-turn maneuver. The study showed that there is an exponential relationship between the potential capacity and conflicting traffic volumes. The obtained relationship was consistent with the curves drawn based on the

HCM 2000. The number of through lanes increased the U-turn capacity. Although the quantitative effects were not provided, the study also mentioned that distance between the U-turn bay and a downstream intersection has effect on potential capacity. Similarly, Jenjiwattanakul, Sano, and Nishiuchi (2013) evaluated the HCM 2010 gap acceptance model and proposed the adjustment method based on a volume to capacity ratio. They adjusted the potential capacities by increasing the capacity of one stream and decreasing the capacity of the other stream, so that the volume to capacity ratio of conflicting traffic and U-turn traffic was equal. They plotted a graph showing field capacity against the capacity estimated by the gap acceptance model, and against the capacity adjusted by balancing the volume to capacity ratio. They found that these were equivalent. The capacity estimation by the gap acceptance model was found to be systematically overestimating or underestimating the field capacity. Shihan and Mohammed (2009) used a U-SIM model to investigate the effect of five parameters: (1) gap acceptance behavior, (2) gap forcing behavior, (3) effect of opposing and advancing turning flow, (4) difference between left turn and U-turn behavior, and (5) median storage lanes. The median opening was of the bi-directional type. The result showed that with the increase in the U-turn percentage of the opposing traffic stream, the delay of U-turning vehicles in the advancing approach decreases. The study mentioned that gap forcing behavior may persist in median U-turns. This result will have an effect on safety and traffic performance. The total delay, average delay, and average queue length per vehicle were found to be positively affected by increased flow levels. The study mentioned that the U -
turn maneuver is more complicated than the left turn maneuver because the drivers need larger gaps to complete the maneuver.

Al-Omari and Al-Akhras (2014) developed a delay model for un-signalized MUT at suburban four-lane divided highways. They collected data during the a.m., noon, and p.m. peak periods on sunny days with dry pavement conditions. The developed model for average turning traffic stop delay ( $\mathrm{s} / \mathrm{veh}$ ) showed that turning traffic volume and conflicting traffic volume are significant parameters in predicting the delay. Both parameters have a positive effect on the log value of delay. Regarding the use of different U-turn capacity models, Aldian and Taylor (2001) studied the suitability of traffic models to calculate U-turn capacity. They estimated gap acceptance and move-up time by reducing field data. They tested the capacity with five different models: Tanner's formula, the National Association of Australian State Roads Authorities' (NAASRA) model, the random platoon Tanner's formula, the modified random platoon Tanner's formula, and Siegloch's method. Using the Chi-square test between estimated capacity and the observed capacity, they found that the Tanner's formula can very reliably determine U-turn capacity.

### 2.2.1.2 Effect on Traffic Flow

Regarding the effect of U-turns on traffic, Ben-Edigbe, Rahaman, and Jailani (2013) conducted a study about kinematic waves to estimate and compare volume and density per directional flow at and before midblock facilities. They collected volume, headway, speed, and vehicle type data for eight weeks for both directional flows at two sites in Malaysia. Based on empirical analysis of the collected data, they concluded that
because of the speed reduction, traffic flow rate will precede kinematic waves. Traffic safety is correlated to kinematic waves, and significant positive kinematics were found at the exit lanes. The U-turning movement at midblock induces shockwaves. Rahaman, Ben-Edigbe, and Hassan (2012) studied the extent of traffic shockwave velocity propagation induced by U-turn facilities on roadway segments, and estimated traffic shockwave velocity propagations for U-turn lanes. The results indicated that the shockwaves produced due to deceleration and diverging are less severe than the shockwaves produced by acceleration and merging. They indicated that shockwaves produced by U-turn facilities can cause traffic crashes. Similarly, Combidino, and Lim (2010) modelled U-turn traffic flow using a cellular automata model called Nagel Schreckenberrg (NaSch), which is based on microscopic control of car speed and driver behavior. They also checked the model prediction against empirical observations of U turn traffic. In conclusion, the authors mentioned that U-turns promote the interaction of cars. Although some studies have shown that U-turns provide decreased congestion and increased flow compared to left turns, this study suggested that this could be possible only if there is low car flow and less lane changing maneuvers. At high traffic densities, U-turns make the situation worse instead of reducing congestion. The study recommended using lane separators as a measure to promote minimal traffic interactions. Cellular automaton was also used by Fan, Jia, Li, Tian, and Yan (2013) to study the characteristics of traffic flow at non-signalized T-shaped intersections with U-Turn movements. They found that the average control delay is a good practical means of measuring the performance of an intersection. If the inflow rate is high, U-turns can
increase both the range and degree of congestion. U-turn movements in different directions have an asymmetric effect on traffic conditions. Similarly, Carter, Hummer, Foyle, and Philips (2005) studied the operational and safety effects of U-turns at standard signalized intersections. They measured vehicle headway in an exclusive left turn lane at 14 signalized intersections. The regression analysis of saturation flow data showed a $1.8 \%$ saturation flow rate loss for every $10 \%$ increase in U-turn percentage in the left turn lane. There was an additional $1.5 \%$ saturation loss for every $10 \%$ increase in U-turns if the U-turning movement was opposed by right turn overlap from the cross street. A study has also indicated that a full median opening is less safe than a directional median opening, but will produce less delay than a directional median opening (Qi, Chen, Liu, and Wang, 2014).

### 2.2.2 Weaving of Right Turn Followed by U-Turn (RTUT) Maneuver and Optimal Location of Median Opening

The left-turning vehicle from the cross street in MUTs requires multilane changing after it enters the main street and before it U-turns from the median opening. This process is called weaving, and the entire movement is called right turn followed by U-turn (RTUT) (Zhou, Lu, Yang, Dissanayake, and Williams, 2002). RTUT is comprised of following four steps (Zhou et al. 2002):

1. Stopping at a cross street, waiting for a gap, and turning right when a gap is available;
2. Accelerating into the through lane, weaving to the left turn lane, and deceleration to stop at U-turn;
3. Waiting for suitable gap to make U-turn; and
4. Accelerating to get to the operating speed of through vehicles.

The optimal location of the median opening from the main signalized intersection is specified as 660 ft . (AASHTO Green Book, 2011). MDOT advises that the optimal spacing of a median opening from the main intersection is $660 \mathrm{ft} . \pm 100 \mathrm{ft}$. (Information and Geometric Design Guidance Regarding Boulevards, Directional Crossovers, and Indirect ['Michigan'] Left-Turns, accessed 2014; Hughes, Jagannathan, Sengupta, and Hummer, 2010). Hughes et al. (2010) mentions that the longer the spacing distance of the median opening with respect to the main intersection, the higher the travel time, but there will be less of a probability of main road queues blocking the median opening. A long distance will allow more time for the driver to see and read signs. Hence, there should be a tradeoff between the disadvantage due to additional travel time and the advantage due to the prevention of a spillback effect with the main intersection. The operational aspects related to the weaving associated with the RTUT maneuver and the optimal location of the median opening as presented by past literature are described in detail in following subsections.

### 2.2.2.1 Weaving of Right Turn Followed by U-Turn (RTUT) Maneuver

The weaving maneuver in urban and sub-urban arterials where signal spacing is less than 2.0 miles differs from freeway weaving, as the traffic flow is dominated by platoons and interruptions from traffic signals (Zhou, Hsu, Lu, and Wright, 2003). Hence, RTUT is executable on the availability of acceptable gaps between platoons, and only random arrivals or stragglers may be affected by RTUT (Zhou et al., 2003). Weaving
speed is positively correlated with weaving length (Zhou et al., 2003). The models developed by Shahia and Choupanib (2009) indicate that the weaving speed of U-turning vehicles is positively affected by free flow speed, weaving length, and volume ratio, which is the ratio of the flow rate of vehicles that move freely in every lane to the flow rate of vehicles that are subjected to an access specific lane. Similarly, the weaving time of U-turning vehicles is affected positively by weaving length and total volume of weaving section, and negatively affected by volume ratio and free flow speed. The delay effect of RTUT as modelled by Zhou et al. (2002) indicates the significance of the twodirectional through traffic flow rate, split, and flow rate of RTUT. Likewise, total volumes, RTUT volumes, split, and speed limit affect travel time. Travel time is negatively correlated with speed limit. It is also in agreement with a travel time model developed by Liu and Lu (2007), which indicates that the travel time at weaving sections while making a RTUT increased with offset and decreased with speed. Liu and Lu (2007) also indicate that the travel time is less on four-lane roadways than six or more lane roadways. Zhou et al. (2002) also related drivers' selection of the RTUT maneuver against direct left turning with an empirical relationship, which indicated that it is affected positively with a combination of left-turn inflow rate and major road through traffic flow rate, but negatively affected by a split. The study also indicated that travel time performance for the RTUT maneuver is better compared to that of a direct left turn under moderate and high traffic volumes. Drivers prefer to use the RTUT maneuver rather than make a direct left turn under moderate to high traffic volumes (Zhou et al. 2002). In the same context, Lu, Dissanayake, Zhou, Yang and Williams (2001) found that
the RTUT maneuver increased with the major traffic flow rate and left turn flow rate from major roads. Based on empirical models developed using data collected from ten sites, delay and travel time related to the RTUT maneuver were found to be less than that related to direct left turns. There was less speed reduction on the major street due to RTUT as opposed to a direct left turn, and the running time of RTUT was found to increase linearly with weaving distance. The before and after study conducted by Lu et al. (2001) indicated $15-22 \%$ less delay related to RTUT when RTUT was forced by placing directional median openings downstream instead of allowing them for direct left turning. A similar conclusion was obtained in a study by Yang and Zhou (2004), which indicated that for a higher through volume, the delay and travel time would increase at a faster rate for a direct left turn rather than a RTUT movement. The same study also indicated that RTUT movement can perform better for a wide range of traffic conditions. In an attempt to evaluate U-turns as an alternative to a direct left turn, Liu et al. (2006) found that the RTUT maneuver at a median opening produced 24 seconds less delay than a direct left turn for 6-8 lane roadways. The average running time of a RTUT depends on the offset between the driveway and the downstream median opening, and decreases with the speed limit of the major road. The percentage of drivers selecting RTUT increases with the upstream through traffic, left turn volume from the major street, and total left-turning volume at the driveway.

### 2.2.2.2 Optimal Location of Median Opening

The optimal weaving length minimizes the average waiting delay of the U-turning vehicle at the median opening. This is possible when a RTUT vehicle arrives at a median
opening at the time the last vehicle in the platoon of opposite traffic passes the median opening (Zhou et al., 2003). A deterministic model that estimates the optimal weaving length as developed by Zhou et al. (2003) is expressed below:

$$
\begin{equation*}
L=\frac{-\left(1-.082 \Delta t+\frac{21.5}{v}\right)+\sqrt{\left(1-0.082 \Delta t+\frac{21.5}{v}\right)^{2}+7.05 \frac{\Delta t}{v}}}{\frac{0.164}{v}} \tag{2.4}
\end{equation*}
$$

Where,
$\mathrm{L}=$ Optimal weaving length,
$\Delta t=$ Term expressed as a function of offset of upstream and downstream signal timing, whole section length, distance between driveway and upstream signalized intersection and posted speed limit, and $\mathrm{v}=$ speed limit.

The above equation indicates that the optimal weaving length is governed by (1) the offset of signal timing between upstream and downstream signals, (2) the distance between upstream and downstream signalized intersections, (3) the distance between the subject driveway and the upstream signalized intersection, and (4) the posted speed limit.

For a RTUT maneuver, Lu, Pirinccioglu, and Pernia (2005) related the offset distance between driveway exits and downstream U-turn median openings to crash and conflict rates. The developed model in the study indicated a positive correlation between
the location of the median opening and the crash rate. The details of this literature will be dealt in the safety literature review of MUT. Similarly, Liu and Lu (2007) evaluated the offset of a U-turn bay and upstream driveway based on crash data analysis and travel time analysis. Based on safety and operational performance, the study identified the minimum offset for a U-turn bay located at median opening as 350 ft . and 450 ft . for four-lane and 6-8 lane roadways.

### 2.2.3 Operational Performance of MUT

The major objective behind the implementation of unconventional intersection treatments, including MUT, is the expected improvement of the operation of existing conventional intersections (Hughes et al., 2010). MUT is thought to have more operational benefits compared to other intersections, but under specific traffic conditions. For example, Hummer (1998-B) mentioned that MUT is applicable in arterials as an intersection treatment for low-to-medium left turns from the arterial, low-to medium left turns from a minor street, any minor street through volume, and at the availability of minimum right of way 30 ft . wide. In this context, this subsection discusses the operational performance of MUT compared to conventional intersections or other unconventional intersections, the criteria and conditions of traffic parameters at which the MUT operates at a better level, and the condition and criteria at which MUT cannot be a good alternative based on the literature review. Review notes of prominent literature that is directly related to operational performance of MUT are shown in table 2.1, table 2.2, table 2.3, table 2.4 , and table 2.5 .

### 2.2.3.1 Travel Efficiency of MUT

In this subsection, the performance of MUT in terms of travel time, stops, and average network speed are discussed based on past literature. In this context, Hummer and Boone (1995) studied the travel efficiency of MUT by comparing its travel time performance with conventional intersections and other unconventional intersections, such as a continuous green T-intersection (CGT) and Bowtie in terms of travel time and percentage of stops and stop delay. The study indicated that MUT is more travel efficient at a through volume range between 400 and 700 vph . The MUT displayed superior performance in terms of overall travel time and stops in terms of through volume, but at the expense of travel time and stopped delay for left-turning traffic, which were inferior to a conventional intersection. Boone and Hummer (1995) validated the use of CORSIM for an operational performance evaluation of MUT using a larger saturation flow rate as a calibrating parameter. The travel time and delay obtained from the simulation matched satisfactorily with observed site value. Later, Reid and Hummer (1999) used CORSIM to compare the performance of a MUT with signalized median openings to a superstreet and a conventional two way left turn lane (TWLTL) design. The MUT decreased the system travel time by $17.25 \%$ as compared to a conventional intersection, and the average speed of an arterial was found to be $24.74 \%$ faster than a conventional intersection. However, the average number of stops per vehicle increased by $5.56 \%$. Compared to a superstreet, MUT performed better in terms of average speed and average number of stops per vehicle. However, the system travel time was slightly higher than that of superstreet. Again in 2001, Reid and Hummer compared the performance of seven unconventional
intersections, including a MUT with conventional intersections. He considered seven intersections comprised of these major and minor street configurations: $4 \times 4$ ( 2 nos.), one 4x2 (1 nos.), 6x4 (1 nos.), 6x2 (1 nos.), and 8x4 (2 nos.). Compared to conventional intersections, the most MUT could reduce the total time was $27.94 \%$. However, MUT increased the total time in some intersections, and the highest increase of all seven intersections was $8.57 \%$. Similarly, the highest average percent of stops that MUT could decrease compared to conventional intersections was $20.97 \%$, however, it increased the highest average percent of stops in some intersections, the highest being by $28.4 \%$. This result clearly shows that MUT can perform better in terms of travel efficiency, but not in terms of stops compared to conventional intersections. Similarly, Henderson and Statamatiadis (2001) studied the travel efficiency of MUT along a principal urban arterial in Kentucky. The study used CORSIM to evaluate different alternatives, including signal optimization for the existing intersection, the addition of a lane, and the implementation of MUT. A set of four intersections were studied for the implementation of MUT, and the results indicated a significant improvement on the operation of the network. Considering the whole system, speed increased by 2.4 mph and the move to total time ratio increased to 0.41 . The MUTs were implemented at an additional two intersections, resulting in a total system-wide effect of a speed increase of 3.6 mph and a move to total time ratio increase by $26 \%$ (0.44).

The travel efficiency of MUT was also praised in a study by Bared and Kaisar (2002). They compared a partial MUT where direct left turns from minor streets were allowed with a conventional intersection that had single and dual left turn lanes. The
study found an abrupt rise in travel time savings, from 10 to $40 \mathrm{~s} / \mathrm{vehicle}$ with 600 vph entering the flow with $10 \%$ left turns compared to a conventional intersection with a single left turn lane. The travel time saved by MUT rose to $60 \mathrm{~s} / \mathrm{veh}$ icle for $20 \%$ leftturning volume at 600 vph entering flow compared to a conventional intersection with a single left turn lane. The travel time saved by MUT was smaller at a total entering flow of 5500 vph to 6600 vph , but larger saving starts from 6600 vph for $20 \%$ left-turning volume as compared to a conventional intersection with dual left turn lanes. The average travel time for U-turning traffic was $20 \mathrm{~s} / \mathrm{veh}$ to $30 \mathrm{~s} / \mathrm{veh}$ higher because of circuitous movement. The average proportion of stops was $20 \%$ to $40 \%$ lower for MUT for $10 \%$ left-turning traffic and for $20 \%$ left-turning traffic. A noticeable reduction starts at about $4,500 \mathrm{vph}$, compared to a conventional intersection with a single left turn lane. Similarly, a report developed for the Community Planning Association (COMPASS) of Southwest Idaho (2008) indicated that MUT can reduce travel time by $2 \%$ to $20 \%$ during non-peak hour traffic and $6 \%$ to $21 \%$ during peak hours. However, the performance of MUT for stop varies with $20 \%$ reduction to $70 \%$ increment during non-peak hours and $30 \%$ increment during peak hours. Tarko et al. (2010) indicated that MUT lowered travel time significantly compared to a conventional intersection at saturated condition. Similarly, Kivlins and Naudzuns (2011) indicated that MUT could reduce the vehicle waiting time by $73 \%$. They also indicated that the left turn lanes on an arterial intersection of a MUT intersection can produce a $90 \%$ shorter congestion length at the end of green signal phase than a conventional intersection.

A study (Martin, Islam, Best, and Sharma, 2012) also evaluated MUT in combination with other alternatives. That particular study, about the US 290 Corridor, led to the development of three alternatives. Alternative 1 was a combination of MUT, CFI, and traditional improvements, such as the addition of lanes. Alternative 2 was the combination of MUT and CFI. Alternative 3 was combination of MUT, CFI, and a superstreet. They used a VISSIM simulation to calculate project annual delay savings and travel time for the existing year 2010 and the future years 2015 and 2020. The results showed that Alternative 1 and Alternative 2 have significant travel time savings during the peak hour: $50 \%$ and $45 \%$ for year 2010, $45 \%$ and $30 \%$ for year 2015, and $28 \%$ and $33 \%$ for year 2020. Similarly, Pirdavani, Brijs, Bellmans and Wets (2011) estimated travel time and compared it with conventional intersections. They used a raised U-turn facility that restricted a left turn from the major street, and through and left from minor street movements. They modelled travel time based on several scenarios of the offset distance of the U-turn with a signalized intersection, traffic volume on minor and major approaches, as well as left turn percentages using AIMSUN. The results indicated that travel time for the U-turn facility for the through maneuver was always less compared to a conventional intersection. However, for left-turning vehicles on the major street, the travel time for the U-turn facility was slightly higher than a conventional intersection, but it was still less for left-turning vehicles from the minor street. Regarding the MUT with a signalized median opening, Dorothy et al. (1997) found that for $10 \%$ of left-turning volumes, MUT with a signalized median opening had lower travel time by $20 \mathrm{~s} /$ vehicle,
$40 \mathrm{~s} /$ vehicle, and $150 \mathrm{~s} /$ vehicle at $30 \%, 50 \%$ and $70 \%$ mainline saturation, respectively, than two way left turn lanes.

### 2.2.3.2 Capacity and Delay Efficiency of MUT

The reduction in the signal phases at the core intersection of MUT is explained as the reason it has an increased capacity compared to a conventional intersection (FHWA Tech brief: Synthesis of MUT Intersection Treatment, 2009). Savage (1974), and Synthesis of MUT Intersection Treatment (2007) indicated that the use of directional median openings can increase the capacity by $20 \%$ - $50 \%$. Jagnnnathan (2007) also stated that MUT on four or six-lane roads increases the intersection capacity by $20 \%$ to $50 \%$ more than a two-way left turn lane intersection.

Hughes et al. (2010) mentioned that MUT can increase the throughput $15 \%$ to 40\% more than conventional intersections. Similarly, the Community Planning Association (COMPASS) of Southwest Idaho (2008) indicated that MUT can increase capacity by $50 \%$ or more compared to a conventional double left turn intersection. Similarly, Zhao, Ma, Head, and Yang (2014) measured the improvement in intersection capacity with five types of MUT with signalized median openings, including (1) a MUT with left turn prohibition from the major street, (2) a MUT with left turn prohibition from the minor street, (3) a through movement prohibition from the minor street, (4) a left turn prohibition from the major street and through movements from the minor street (5) a left turn and through movement prohibition from the minor street and (6) a left turn prohibition from the major street and through movements from the minor street. All the MUTs performed better than a conventional intersection, especially under high traffic

Table 2.1 Operational performance of MUT (Part I)

| Literature | Intersection Type | Delay | Speed | Stop | Travel Time |
| :---: | :--- | :--- | :--- | :--- | :--- |

Table 2.2 Operational performance of MUT (Part II)

| Literature | Intersection Type | Intersection Capacity with respect to Conventional Intersection | Stop | Travel Time |
| :---: | :---: | :---: | :---: | :---: |
| Bared and Kaisar (2002) | MUT (with minor street left turning allowed) |  | The average proportion of stops was 20 to $40 \%$ lower for MUT for $10 \%$ and $20 \%$ left turning traffic and for $20 \%$ left turning noticeable reduction started at about $4,500 \mathrm{vph}$ compared to conventional intersection with single left turn lane. | The travel time saving rised from 10 to 40 s/vehicle for $10 \%$ left turning volume at 600 vph entering flow than ordinary intersection with single left turn lane. |
|  |  |  |  | The travel time saving increased to 60 s/vehicle for $20 \%$ left turning volume at 600 vph entering flow than ordinary intersection with single left turn lane. |
|  |  |  |  | The travel time saving was smaller at total entering flow of 5500 vph to 6600 vph and larger saving starts from $66,00 \mathrm{vph}$ for $20 \%$ left turning volume than ordinary intersection with dual left turn lane. |
|  |  |  |  | Average travel time for U-Turning traffic was 20 to $30 \mathrm{~s} / \mathrm{veh}$ higher because of circuitous movement. |
| $\begin{aligned} & \text { COMPASS } \\ & (2008) \end{aligned}$ | MUT, CFI, jughandle | MUT can increase 50\% or more capacity than a comparable double left turn | MUT operates with 20\% reduction to $70 \%$ increment during non-peak hours and 2\% reduction to $30 \%$ increment during peak hours | Travel time can be reduced by $2-20 \%$ during non-peak hours and by $6-21 \%$ during peak hours |

Table 2.3 Operational performance of MUT (Part III)
$\left.\left.\begin{array}{|c|c|l|l|l|}\hline \text { Literature } & \text { Intersection Type } & \begin{array}{c}\text { Intersection Capacity with } \\ \text { respect to Conventional } \\ \text { Intersection }\end{array} & \text { Delay } & \\ \hline \begin{array}{c}\text { Dorothy et al. } \\ \text { (1997) }\end{array} & \text { MUT } & & & \text { Travel Time }\end{array}\right] \begin{array}{l}\text { For 10\% left-turning volumes, MUT } \\ \text { with signalized median opening has } \\ \text { lower travel time by 20 s/vehicle, 40 } \\ \text { s/vehicle and 150 s/vehicle at } 30 \%, \\ 50 \% \text { and 70\% mainline saturation, } \\ \text { respectively than two way left turn } \\ \text { lanes. }\end{array}\right]$

Table 2.4 Operational performance of MUT (Part IV)

| Literature | Intersection Type | Intersection Capacity with respect to Conventional Intersection | Delay | Travel Time |
| :---: | :---: | :---: | :---: | :---: |
| Tarko et al. (2010) | CFI, jughandle and MUT |  | At total intersection volume from the range 1,000 vph to $3,000 \mathrm{vph}$, the intersection delay range related to a conventional intersection was 25 to 70 $\mathrm{s} / \mathrm{veh}$ and the intersection delay range related to MUT was 20 to $55 \mathrm{~s} / \mathrm{veh}$. | MUT $r r$  <br> travel lowered  <br> significantly time <br> conventional  <br> intersection at <br> saturated condition.  |
| Hughes et al. (2010) (FHWA AIIR) | CFI, jughandle, MUT | MUT increased throughput of 15 to $40 \%$ than conventional intersection. |  |  |
| Autey et al.(2010) | MUT |  | MUT with un-signalized median opening performs better or at least equivalent to signalized MUT. |  |
|  |  |  | For light volumes (up to 1100 vph ), un-signalized MUTs performance is very good on balanced condition. |  |
|  |  |  | Both MUTs with signalized and un-signalized median opening can't accommodate heavy left turning volume and high approach traffic volume. |  |
| Kivlins and Naudzuns (2011) | MUT | MUT ensures good intersection capacity for left turning traffic flows on both arterial and cross street. | MUT ensures $73 \%$ less vehicle waiting time than arterial. |  |

Table 2.5 Operational performance of MUT (Part V)

| Literature | Intersection <br> Type | Intersection Capacity with <br> respect to Conventional <br> Intersection | Delay | Travel Time |
| :---: | :---: | :---: | :---: | :---: |
| El Esawey and Sayed <br> (2011), El Esawey and <br> Sayed (2011b) | MUT | The capacity of MUT intersection <br> was about $8 \%$ to $10 \%$ higher than <br> that of the conventional <br> intersection. |  |  |

demand. The average and highest improvements in capacity were $21 \%$ and $62.6 \%$, respectively. The study also concluded that type 3 and type 4 MUTs are not good MUT alternatives.

A study by Henderson and Stamatiadis (2001) about the implementation of MUT along a principal urban arterial in Kentucky indicated that the average and total delay time for the whole system decreased by $28 \%$ and $24 \%$ with the implementation of MUT at four intersections. Again, with the implementation of MUT on two additional intersections, the average delay and total delay were decreased by $36 \%$ and $32 \%$, respectively. Martin et al. (2012) found that the delay savings for the peak hour, when calculated for the existing year 2010 and using the MUT/CFI alternative, was $61 \%$, and the delay savings for the MUT/CFI/superstreet alternative was $65 \%$. Further, the savings for the MUT/CFI alternative and MUT/CFI/superstreet alternative for 2015 was $49 \%$ and $45 \%$, respectively. Finally, the delay savings calculated for 2020 for these alternatives were $23 \%$ and $17 \%$, respectively. In his thesis, Hilderband (2007) indicated that at major street volumes of 1000,2000 and 3000 vph and minor street volumes of 626 vph , MUT reduced delay by $82 \%, 98 \%$ and $99 \%$, respectively. Tarko et al. (2010) indicated that at total intersection volume from the range $1,000 \mathrm{vph}$ to $3,000 \mathrm{vph}$, the intersection delay range related to conventional intersections was 25 to $70 \mathrm{~s} / \mathrm{veh}$, and the intersection delay range related to MUT was 20 to 55 s/veh. A study by Autey, Sayed, and El Esawey (2010) indicated that un-signalized MUTs exhibit lower delay than signalized MUTs, but neither could accommodate an approach traffic volume of more than 1500 vph with $20 \%$
left turn traffic for a balanced traffic flow. They mentioned that the un-signalized MUTs are the best choice for light volumes (up to 1100 vph ) for balanced traffic flow conditions. They concluded that the un-signalized MUT will always perform better than or at least equivalent to signalized MUT for both balanced and un-balanced traffic flow conditions. For unbalanced traffic flow conditions, they also mentioned that both type of MUT can accommodate only light to moderate traffic volumes. They are not recommended for heavy left turning traffic conditions.

El Esawey and Sayed (2011a) and El Esawey and Sayed (2011b) assessed the performance of two types of MUT against the conventional four legged intersection. Type 1 MUT prohibits left-turning traffic only from major and minor streets and is pretimed signal controlled at the core intersection. Type 2 MUT prohibits all movement of the minor street and the left turn only movement of the major street. The core intersection is not controlled with a signal. They used Synchro to optimize the signal and VISSIM for simulation, and tested the performance of the three intersections, including a conventional intersection under balanced and unbalanced traffic flow conditions in terms of average intersection control delay and overall capacity of the intersection. The result indicated that Type 1 MUT performed better than Type 2 MUT. Type 2 MUT was beneficial only in very low demand approach traffic volumes and left turning volumes. The capacity of Type 2 MUT was lower than a conventional intersection by $27 \%$ under balanced volume conditions. However, the capacity of Type 1 MUT with signalized and un-signalized median openings was $8 \%$ to $10 \%$ higher than a conventional intersection.

Under unbalanced conditions, the Type 2 MUT exhibited higher delays in most cases except at a very light volume for the cross street. Type 1 MUT outperformed all other intersections in terms of exhibiting the lowest delay. For two traffic conditions with $20 \%$ and $30 \%$ left turning traffic, Type 1 MUT with un-signalized median openings reduced delay from 3 to $6 \mathrm{~s} / \mathrm{veh}$ to $8 \mathrm{~s} / \mathrm{veh}$. Similarly, Topp and Hummer (2005) compared the operations between traditional MUT designs at median openings along an arterial to the new MUT design that has median openings on the minor street. They used CORSIM for the simulation. The results found that the MUT with median openings at the cross street provides better operation in terms of stops, total time, and delay for most of volume combinations. They mentioned that the cross street can better accommodate left turns from a median opening because of the capacity available due to low volume. This also decreases the likelihood of stopping and queue interference with heavy traffic flow.

### 2.2.4 Safety Performance of MUT

A MUT intersection possesses a total of 16 conflict points, including 12 merging/diverging conflict points, 0 crossing (left turn) conflict points, and 4 other crossing points, compared to four-legged standard signalized intersection, which has 32 conflict points (Kivlins and Naudzuns , 2011). This indicates that MUT should have safety benefits compared to conventional intersections. In this section, the safety performance of MUT is described based on past studies. The literature review notes from prominent literature that deals directly with MUT-related safety are shown in table 2.6 and table 2.7.
"Information and Geometric Design Guidance Regarding Boulevards, Directional Crossovers, and Indirect ('Michigan') Left Turns" (1995) indicated that MUTs result in a reduction of $60.6 \%$ total crashes, $74.6 \%$ injury crashes, $17.1 \%$ rear end crashes, $95.5 \%$ angle crashes, and $60.6 \%$ sideswipe crashes. Similarly, Kach (1992) did a comparative crash study between directional (MUT) and bi-directional signalized intersections with an objective to establish directional crossovers as a safety treatment. He studied about 15 directional signalized intersections and 30 bi-directional signalized intersections. The study identified key types of crash reduction for signalized directional intersections: angle straight by $53.1 \%$, rear end left turn by $9.3 \%$, sideswipe opposite by $0.3 \%$, and head-on left turn by $35.4 \%$. However, the treatment increased some crashes as fixed object by $7 \%$ and rear end by $91.4 \%$. In sum, the total crash reduction was $48.91 \%$, and total crash gained was $21.8 \%$. The equivalent overall crash reduction was $27.11 \%$. The result of the study showed significant reduction in total, angle and right turn, and left turn collisions. Similarly, the result also indicated significant reduction in fatal and injury collisions. Based on analysis of data collected data over 115 median openings including 105 median openings in urban arterials and 12 median openings in rural arterials, Potts, Harwood, Torbic, Richard, Gluck, Levinson, Garvey, and Ghebrial (2004) estimated average of 0.41 U -Turn plus left-turn accidents per median openings per year in urban arterial and 0.2 accidents per median opening per year in rural arterial. U-Turns represent $58 \%$ of the total median opening movement and the left turn represents $42 \%$ of the median opening movement. The study found no major safety concern on the un-
signalized median opening. The study also found existence of major road angle collision, major road rear end collision, cross street collision, and other or unknown collision. In terms of MUT median opening, the cross street collision is not applicable.

Mallah (2011) developed guidelines for the full opening median treatment at an unsignalized intersection using predicted conflict rate as the safety measures. They collected segment geometric data, traffic volumes and traffic conflict data. They calculated conflict rates both from observations and from the model prediction. In the developed conflict rate models, the prediction of direct left turn conflict was positively governed with major road traffic volume in one direction, major road traffic volume in the opposite direction, the direct left turn volume, left turn in driveway volume and left turn in opposite driveway volume. Similarly, Qi et al. (2014) investigated the operational and safety impacts of directional median openings on urban roadways with the help crash analysis and simulation-based study. They found from the crash analysis that full median openings pose more safety and operational hazards, and hence should be avoided. To maintain good safety conditions, a sufficient median width is very necessary. From the simulation study, it was found that when a full median opening is converted to a directional median opening, crossing conflicts will be greatly reduced, but there will be a slight increase in lane change conflict. In his dissertation, Liu (2006) evaluated the operational effects of U-turn movement on multilane roadways by gathering the crash histories of 179 roadway segments in central Florida. In order to complete the RTUT movement, the types of crashes during weave as explained by the study were angle/right
turn crashes, sideswipe crashes, and rear end crashes. The study found that the crash rate at weaving sections decreases with the increase of the separation distance and travel time. Carter et al. (2005) analyzed the crashes of 78 intersections, 24 of which had problems with U-turns. No collisions were found in 65 sites. The remaining 13 sites had 0.33 to 3 collisions/year. U-turn collisions were high for the sites with dual left turn lanes, protected right turn overlap, or high left turn and conflicting right turn traffic. Pirinccioglu, Lu, Liu, and Sokolow (2006) evaluated the safety of RTUT on four-lane arterials at signalized and un-signalized median openings by collecting data from 16 sites. Nine types of conflict were used; five of them were related to RTUT and four of them were related to direct left turns. The study at signalized intersections indicated that a direct left turn produced two times more conflict per hour than RTUT, but the conflict rate that takes volume into account was 5\% higher for RTUT than direct left turns. RTUT-related conflicts were less severe than direct left turn related conflicts. The study at median opening sites indicated $10 \%$ more direct left turn related conflict per hour than RTUT-related conflicts. The conflict rate (per 1,000 vph), which takes traffic volumes into account, was $62 \%$ higher for RTUT than direct left turn. RTUT-related conflicts were less severe than direct left turn related conflicts. Lu et al. (2005) did a safety evaluation of RTUT and direct left turns at signalized intersections by comparing traffic conflicts. Nine types of conflict were studied, and five of them were related to RTUT movements while the rest related to direct left turns. They used two types of conflict rates: conflict per hour and conflicts per thousand vehicles. The comparison showed

RTUT generates three times less conflicts than direct left turn in terms of conflict per hour. The conflict rate per volume showed that RTUT had 35\% less conflicts than the direct left turn on six- or eight-lane roads. Overall severity related to RTUT conflicts were $37 \%$ lower than that of the direct left turn. Regarding conflict modeling, Agarwal (2011) estimated pedestrian safety at intersections using simulations and SSAM. He found that the conflict patterns of MUT intersections are similar to that of conventional signalized intersections.

Xu (2001) studied the safety effects of RTUT at directional median openings by conducting a before-and-after period crash analysis. The study found that RTUT can reduce the total number of crashes by $24 \%$ and injury/fatality crashes by $32 \%$ compared to direct left turns for six-lane divided arterials. Liu and Lu (2007) evaluated the offset of U-turn bays and upstream driveways based on crash data analysis and travel time analysis. The crash analysis was performed over 179 selected roadway segments, and travel time data was collected at 29 selected sites in Tampa Bay, Florida. The study mentioned that RTUT-related crashes involve angle/right turn crashes, sideswipe crashes, and rear end crashes. The model developed for crash rates on four-lane and 6-8 lane roadways (crashes $/ \mathrm{mvm}$ ) indicated that the crash rate will increase if the U -turn bay is located at a signalized intersection rather than a median opening. The crash rate was significantly affected by the offset between the driveway and U-turn bay. Based on safety and operational performance, the study also identified the minimum offset for U-turn bays located at a median opening as 350 ft . and 450 ft . for four-lane and 6-8 lane
roadways. The minimum offsets were 500 ft . and 750 ft . for a U -turn at a signalized intersection on 6-8 lane roadways.

Mauga and Kaseko (2010) evaluated the safety effect of access management features in the midblock section while considering two types of median treatments: raised medians and two-way left turn lanes. The study indicated that each reduction of one median opening per mile resulted in a crash reduction of $4.7 \%$. There has also been a study about the safety effects of length of left turn lanes at un-signalized median openings. In this context, Chen et al. (2014) developed a relationship between crash modification factors and relative length of left turn lane at un-signalized median openings with respect to the AASHTO Greenbook. The relation showed that the shorter the length of left turn lane, the higher the crash modification factor.

The public perception of the use of MUT was studied by Strickland (2012). On the basis of public comments received by the Cobb County Department of Transportation (CCDOT), the majority of the public have accepted the MUT design. However, there were some comments against the use of MUT, which were people who were either skeptical about the innovative intersection strategy or did not like the additional distance the left turning traffic have to travel due to the MUT design. The author concluded his study by emphasizing the need to educate the general public about these new designs.

Table 2.6 Safety performance of MUT (Part I)

| Literature | Alternative Intersection | Safety Performance |
| :---: | :---: | :---: |
| "Information and Geometric Design Guidance Regarding Boulevards, Directional Crossovers, and Indirect ('Michigan') Left Turns" (1995) | MUT | Reduction in total crash was 60.6\%. |
|  |  | Reduction in injury crash was $74.6 \%$. |
|  |  | Reduction in rear end crash was $17.1 \%$. |
|  |  | Reduction in sideswipe crash was $95.5 \%$ and $60.6 \%$ of sideswipe crashes. |
| Kach (1992) | MUT | Reduction in angle straight was $53.1 \%$. |
|  |  | Reduction in rear end left turn crash was $9.3 \%$. |
|  |  | Reduction in sideswipe opposite crash was $0.3 \%$. |
|  |  | Reduction in head on left turn crash was $35.4 \%$. |
|  |  | Increment in fixed object crash was 7\%. |
|  |  | Increment in rear end crash was $91.4 \%$. |
|  |  | The total crash reduction was $48.91 \%$, total crash gained was $21.8 \%$ and the equivalent overall crash reduction was $27.11 \%$. |
| Potts et al. (2004) | MUT Median Opening | Average of 0.41 U-turn plus left-turn accidents per median openings per year in urban arterial and 0.2 accidents per median opening per year in rural arterial were estimated. U-turns represent $58 \%$ of the total median opening movement and the left turn represents $42 \%$ of the median opening movement. |
| Carter et al. (2005) | MUT Median Opening | U-turn collisions were high for the sites with dual left turn lanes, protected right turn overlap, or high left turn and conflicting right turn traffic. |

Table 2.7 Safety performance of MUT (Part II)

| Literature | Alternative Intersection | Safety Performance |
| :---: | :---: | :---: |
| Pirinccioglu et al. (2006) | MUT Median Opening | The study at signalized intersection indicated that direct left turn produce two times more conflict per hour than RTUT. RTUT-related conflicts were less severe than direct left turn related conflicts. The study at median opening sites indicated $10 \%$ more direct left turn related conflict per hour than RTUT related conflicts. The conflict rate (per 1,000 vph) was $62 \%$ higher for RTUT than direct left turns. |
| Lu et al. (2005) | MUT (RTUT Movement) | The comparison showed RTUT generates 3 times less conflicts than direct left turn in terms of conflict per hour than direct left turn. In terms of conflict rate considering volume, RTUT showed $35 \%$ lower conflict than direct left turn on six or eight lane roads. Overall severity related to RTUT conflicts were $37 \%$ lower than that of direct left turn. |
| $\mathrm{Xu}(2001)$ | MUT (RTUT <br> Movement) | RTUT reduced the total crash by $24 \%$ and injury/fatal crash by $32 \%$ than direct left turn for six lane divided arterials. |
| Mauga and Kaseko (2010) | Median opening | Each reduction of one median opening per mile would result in crash reduction by $4.7 \%$. |
| Chen et al. (2014) | Median Opening | Shorter the length of left turn lane higher is the crash modification factor. |

### 2.3 The Operation and Safety Performance Related to Continuous Flow

## Intersections (CFI)

As described in preceding chapter, the CFI operates with one main intersection and four other crossover intersections. All the intersections are signalized. The operational and safety effect brought by reduced traffic signal phases, the provision of the displaced left turn lane, and the effect of the whole system are described in the following subsections.

### 2.3.1 Operational Performance of CFI

Like other unconventional intersections, CFI is applied as an intersection treatment to improve safety and operation. However, the extent of improvements is based on certain traffic conditions. For example, according to the alternative selection criteria developed by Hummer (1998-B), when based on left turn volume from urban and suburban arterials, CFI is applicable for all traffic volume conditions of left turns from arterials, left turns from minor streets, minor street through traffic, and the availability of two 40 ft . by 300 ft . right-of-way rectangles. In this context, this subsection deals with the operational performance of CFI compared to conventional intersections or other conventional intersections under different criteria or conditions. The review notes of prominent literature that are directly related to the operational performance of CFI are shown in table 2.8, table 2.9 , table 2.10 , and table 2.11 .

### 2.3.1.1 Travel Efficiency of CFI

Travel efficiency represents travel time, average speed, and stops related to the operation of CFI. In this context, Tarko et al. (2008) studied the safety and operational impacts of unconventional intersections. They used VISSIM for operation performance evaluation. The study showed that at total intersection volume levels of $1730 \mathrm{vph}, 2250$ vph, and 3110 vph, CFI reduced stops by $35.56 \%, 7.5 \%$, and $60.17 \%$, respectively. Reid and Hummer (2001) compared the travel time of unconventional intersections, including CFI, by performing a simulation with traffic signals with optimal cycle length using peak hours, off peak hours, and peak hours with $15 \%$ added volume levels. The unconventional intersections were found to have lower travel time than conventional designs. Similarly, Yang, Chang, Rahwanji, and Lu (2013) studied CFI to identify queue spillback locations and develop a set of planning stage models. They also compared the operational performance of CFI to that of conventional intersections. The reductions in total travel time (hour) were $15.1 \%$ and $14.7 \%$ in the morning and evening peaks. The average number of stops per vehicle was reduced by $6.3 \%$ and $7.8 \%$ at the morning and evening peaks.

### 2.3.1.2 Capacity and Delay and Other Operational Efficiency of CFI

Goldbat et al. (1994) studied the effectiveness CFIs operating under multiphase actuated control. They used a TRAFNETSIM simulation model to compare both conventional and unconventional designs. The result showed that CFI performed better than conventional intersections at capacity, when the demand exceeded capacity, and
with the presence of heavy left-turners such that they required left turn protection. It was found that the demand of 2000 vph on each approach exceeded the capacity of conventional designs by $20 \%$. The capacity of CFI was exceeded on all approaches at a demand level of 3000 vph , but the capacity at this demand level was $50 \%$ higher than that of conventional intersection. A similar type of conclusion was reached by Berkowitz, Mier, Walter, Bragd (1997) in a study of CFI, which indicated that CFI can accommodate $50 \%$ more traffic than a conventional three-legged intersection design at a demand level of $3,000 \mathrm{vph}$. Simulations showed that CFI delay was $1 / 5$ of conventional intersection delay. Mean speed of CFI was approximately twice the speed at conventional intersection. The signal efficiency increased by at least $80 \%$ and fuel consumption and emissions were reduced by $1 / 3$ or more. "Techbrief: Displaced Left turn Intersection" (2009) indicated that a full CFI can increase $30 \%$ throughput over a conventional intersection under fully balanced opposing flow in mainlines, and $25 \%$ throughput with unbalanced main line volumes. For partial CFI, the increase in throughput was $10 \%$ for unbalanced flows and 20\% for balanced flows.

The delay reduction capabilities of CFIs as assessed by Pitaksringkam (2005) using VISSIM simulation modeling concluded that queue and delay could be decreased by $64 \%$ and $61 \%$ respectively during PM peak hours as compared to conventional intersections. Cheong et al. (2008) assessed the operational performance of CFI, parallel flow intersections (PFI), and upstream signalized crossover (USC) intersections. The average delay comparison of through only and left-turn only traffic concluded that CFI
outperformed other intersections except for some traffic conditions. For example, in balanced conditions, the average delay of through traffic for PFI was smaller than CFI under low traffic volume ( 1000 vph ) conditions, and almost similar under a moderate traffic volume level (1500 vph). Liu, Zhang, and Yang (2012) studied CFI for urban roads, evaluating CFI with a VISSIM simulation. In terms of delay, CFI reduced $42 \%$ to $86 \%$ delay with respect to conventional intersections. The CFI through vehicle queue length decreased by $28 \%$ to $83 \%$, and the left-turning queue length decreased from $36 \%$ to $6 \%$. Under high or oversaturated traffic status, the traffic benefits of the CFI tended to be steady. Similarly, in their study about integrated computer system analysis, selection, and evaluation of unconventional intersections, Chang et al. (2011) developed wellcalibrated VISSIM simulation models of CFI and diverging diamond interchange (DDI). They assessed operational performance under various constraints and traffic conditions, and concluded that the average intersection delay for both CFI and DDI depended on the congestion level of each sub-intersection and the ratio of maximum queue length to available bay length. Jagannathan and Bared (2004) also studied the design and operational performance of three types of CFI, including crossovers on all approaches (Type A), crossovers on the major street approach (Type B) and crossovers on one approach of the major street (Type C), over a wide distribution of traffic flow conditions under pre-timed signal settings. The result of the study found a $48 \%$ to $50 \%$ delay reduction for Type A, $58 \%$ to $71 \%$ delay reduction for Type B and $19 \%$ to $90 \%$ delay reduction for Type C. El Esawey and Sayed (2007) compared the performance of four
legged CFI and upstream signalized crossover (USC). They found that CFI has a higher capacity than conventional intersections by $90 \%$. Similarly, USC has a $50 \%$ higher capacity than conventional intersections. Taberno and Sayed (2006) did a performance comparison of upstream signalized crossovers with a conventional intersection using VISSIM and found that USC can handle high traffic volumes with low overall delay.

Kaisar, Edara, Rodriguez, and Chery (2011) compared the performance of a signalized and un-signalized roundabout, a continuous flow intersection (CFI), and parallel flow intersection (PFI) as alternatives to the conventional four legged intersection. They used AIMSUN and VISSIM models to evaluate these intersections under three different level of volume; low, medium, and high entrance volumes. The CFI produced the lowest delay at medium $(3,000 \mathrm{vph}$ to $4,000 \mathrm{vph})$ and high $(4,500 \mathrm{vph}$ to $6,000 \mathrm{vph})$ volumes. The roundabout performed well at low (1,000 vph to $2,500 \mathrm{vph}$ ) volume. However, the overall performance was still better with CFI over all alternatives as it maintained level of service (LOS) C throughout all volume levels. Chang et al. (2011) developed deterministic queuing models for CFI and DDI. They also found that for CFI or DDI, the average intersection was dependent on the congestion level of each sub-intersection and the ratio of the maximum queue length to available bay length at each bottle-neck location. They categorized the level of impacts of queue on intersection delay at different locations. For example, for a two legged CFI, the prioritized queue locations were: (1) the through queue between the main and crossover intersection, (2) the left turn queue between the main and crossover intersection, (3) the left turn queue at

Table 2.8 Operational performance of CFI (Part I)

| Literature | Intersection Type | Stop | Travel Time |
| :---: | :---: | :--- | :--- |
| Reid and <br> Hummer <br> (2001) | CFI and other types of <br> Unconventional <br> Intersections |  | The unconventional intersections were found to have lower travel <br> time than conventional designs. |
| Tarko et <br> al. (2008) | CFI | At total intersection volume levels of <br> 1730 vph, 2250 vph and 3110 vph, <br> CFI reduces stop by 35.56\%, $7.5 \%$ <br> and 60.17\% |  |
| Yang et al. <br> (2013) | CFI | The average number of stops per <br> vehicle was reduced by $6.3 \%$ and <br> $7.8 \%$ at morning and evening peak <br> times. | The reductions in total travel time (hour) were $15.1 \%$ and $14.7 \%$ <br> in the morning and evening peak times. |

Table 2.9 Operational performance of CFI (Part II)

| Literature | Intersection Type | Intersection Capacity with respect to Conventional Intersection | Delay and Queue | Speed | Fuel <br> Consump tion and Emissions |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Glodbatt et al. (1994) | CFI | At demand level of 2000 vph , approach exceeded the capacity of conventional design by $20 \%$. | The delay of CFI was $1 / 5$ of conventional intersection. | Mean speed was approximatel y twice the speed at conventional intersection. | Fuel consumpti on and emissions were reduced by $1 / 3$ or more. |
|  |  | At the demand level of 3000 vph , but the capacity of CFI was $50 \%$ higher than conventional intersection. |  |  |  |
|  |  | Signal efficiency increased at least by $80 \%$. |  |  |  |
| FHWA <br> Displaced Left turn Intersection (2009) | CFI | Full CFI can increase 30\% throughput over conventional intersections under fully balanced opposing flow in mainlines and $25 \%$ throughput with unbalanced main line volumes. For partial CFI, the increase in throughput is $10 \%$ for unbalanced flows and $20 \%$ for balanced flows. |  |  |  |
| $\begin{gathered} \text { Pitaksringkam } \\ (2005) \end{gathered}$ | CFI |  | Queue and delay could be decreased by $64 \%$ and $61 \%$ respectively during PM peak hour as compared to those of unconventional intersection. |  |  |

Table 2.10 Operational performance of CFI (Part III)

| Literature | Intersection Type | Intersection Capacity with respect to Conventional Intersection | Delay and Queue | Fuel Consumption and Emissions |
| :---: | :---: | :---: | :---: | :---: |
| $\underset{\text { (2012) }}{\substack{\text { Liu et al. }}}$ | CFI |  | CFI reduced 42 to $86 \%$ delay with respect to conventional intersection. The through vehicle of queue length decreases by 28 to $83 \%$ and left turning queue length of CFI decreases 36 to $6 \%$. |  |
| Jagannathan and Bared (2004) | CFI (Type A: Crossovers on all approaches, Type B: Crossovers on major street approach, Type C: <br> Crossover on one approach of major street |  | Type A: Reduction in delay was 48 to $50 \%$, Type B: Reduction in delay was 58 to $71 \%$, Reduction in delay in Type C: 19 to $90 \%$ |  |
| $\begin{gathered} \hline \text { El Esawey } \\ \text { and Sayed } \\ (2007) \\ \hline \end{gathered}$ | CFI and Upstream Signalized Crossover (USC) | CFI has higher capacity than conventional intersections by $90 \%$. |  |  |
| Autey et al. (2013) | MUT, CFI, Upstream Signalized Crossover (USC) and Double Crossover Intersection (DXI) | CFI showed 99\% higher capacity than conventional intersection where as USC and DXI showed $50 \%$. |  |  |
| Yang et al. (2013) | CFI |  | The performance comparison between CFI and conventional intersections showed 34.2\% reduction in average delay per vehicle (sec) in morning peak and $35.1 \%$ in afternoon peak. | CFI was found helpful in view point of fuel consumption and vehicle emission. |

Table 2.11 Operational performance of CFI (Part IV)

| Literature | Intersection Type | Intersection Capacity with respect <br> to Conventional Intersection | Delay and Queue | Fuel Consumption and Emissions |
| :--- | :---: | :---: | :--- | :--- |
| Park and Rakha |  |  |  | CFI could result in energy savings of <br> (2010) |
| CFI (from VISSIM) and $11 \%$ (from |  |  |  |  |
| INTEGRATION), respectively. The |  |  |  |  |
| decrease in HC, CO, and NOx |  |  |  |  |
| emissions ranged from $1 \%$ to $6 \%$. |  |  |  |  |

each crossover intersection, and (4) the through and left turn queue on the conventional legs. Autey, Sayed, and El Esawey (2013) studied four unconventional intersections: MUT, CFI, USC and DXI. The CFI outperformed all the intersections under most balanced and un-balanced volume levels. CFI showed $99 \%$ higher capacity than conventional intersections. USC and DXI had about 50\% more capacity than conventional intersections. The impact of increasing the left turning volume was more prominent in conventional intersections than these unconventional intersections.

Caroll and Lahusen (2013) developed a deterministic model to study the operational effects of CFI. The model showed that a displaced left turn lane (DLTL) plays a vital role in the optimal design of CFI. Some other non-geometric elements, like speed, also have an effect on operation, but not as much as a DLTL. DLTL also controls the maximum available signal phase time of left-turning movement. Traffic volume demand is a major control over DLTL length. The authors expressed that the deterministic models can provide a more accurate and time effective result in finding the optimal design for DLTL. Yang et al. (2013) studied CFI to identify queue spillback locations and develop a set of planning stage models. They developed four equations for four types of queue at full CFI with deterministic equations and using a simulation experiment. Using experimental data, they also identified the correlation between the total delay and queue length $(\mathrm{QL})$ ratio at each critical location. The mean and variance of average delay grows exponentially when the average QL ratio increased. The QL ratio is the ratio of bay length to queue length. Average delay increases linearly with the
increase of total demand. Under a high congested volume, the critical lane volume could be a more reliable indicator of delay than total volume. Type 1 queue was the through queues at the major intersection. Type 2 queue was the left-turn queues at the crossover intersection. Type 3 queue was the left-turn queues at the major intersection. Type 4 queue was the through queues at the crossover intersection. They used the QL ratio to identify queue spillback locations. The performance comparison between CFI and conventional intersections showed a $34.2 \%$ reduction in average delay per vehicle (sec) in the morning peak hours and $35.1 \%$ in the afternoon peak hours.

The CFI is also helpful from the viewpoint of fuel consumption and vehicle emission. A study by Park and Rakha (2010) indicated that the use of CFI could result in energy savings of $5 \%$ (from VISSIM) and $11 \%$ (from INTEGRATION). In the case of emissions, the decrease in $\mathrm{HC}, \mathrm{CO}$, and $\mathrm{NO}_{\mathrm{x}}$ emissions ranged from $1 \%$ to $6 \%$. This study also indicated that CFI reduced fuel use and $\mathrm{CO}_{2}$ emissions at both low and high demand levels of left-turn movements.

### 2.3.2 Safety Performance of CFI and Effect of Signing and Markings

The two-legged CFI possesses 30 conflict points compared to 32 conflict points in a conventional intersection (FHWA Techbrief: Displaced Left-turn Intersection, 2009). Hence, it can be thought that CFI would reduce crashes. This section includes a safetyrelated literature review about CFI. The review notes from prominent literature related to the safety performance of CFI are also shown table 2.12 and table 2.13.

A safety study of CFI in Baton Rouge indicated a $24 \%$ reduction in total crashes and a $19 \%$ reduction in fatal and injury crashes (FHWA Techbrief: Displaced Left-turn Intersection, 2009). In terms of the service of unconventional intersections to pedestrians, Jagannathan and Bared (2005) studied CFI in terms of design methodologies for pedestrian access and related pedestrian signal timings. They conducted simulations for pedestrian traffic performance of three CFI models, optimized timing for vehicular traffic. Case A was the four-legged CFI model, Case B was the two-legged CFI model, and Case C was the three-legged CFI with a displaced left turn at one side of the major street. The result from the simulation indicated that the maximum average delay experienced by any pedestrian while crossing the intersection legs with a speed of $4 \mathrm{ft} / \mathrm{s}$ were $37 \mathrm{~s}, 46 \mathrm{~s}$, and 44 s for Case A, Case B, and Case C, respectively. The maximum average delay per stop experienced by pedestrians while crossing the intersection legs with a speed of $4 \mathrm{ft} / \mathrm{s}$ were $15 \mathrm{~s}, 28 \mathrm{~s}$, and 26 s , which are equivalent to LOS B, C, and C for Cases A, B, and C, respectively. The maximum average delay for pedestrians for diagonal crossing across two legs of CFI at a speed of $4 \mathrm{ft} / \mathrm{s}$ were $34 \mathrm{~s}, 55 \mathrm{~s}$, and 26 s for Case A, Case B, and Case C, respectively. The average delay per stop for pedestrians crossing diagonally across two legs of the CFI at a speed of $4 \mathrm{ft} / \mathrm{s}$ were $11 \mathrm{~s}, 20 \mathrm{~s}$, and 18 s, which are equivalent to LOS B for Case A, Case B, and Case C, respectively. All pedestrians were serviced within two cycles of signal timing for all cases. Yahl (2013), in his thesis, studied the safety effects of CFI through a before-and-after study. Data from five sites in four different states were used for study using the naïve method, the naïve
with traffic factors method, and the comparison group method. The results indicated a decrease in collisions in Baton Rouge, LA, but there was an increase in collisions in the after period for the rest of the test sites. From the overall site analysis, it was found that fatal and injury collisions, rear end, and sideswipe collisions increased, while angle and other collisions decreased. The study also recommended that agencies should consider using CFI as a congestion treatment, although the safety effects are negative or neutral. The study recommended adjusting the design elements of CFI to minimize the additional crashes.

A safety study conducted by Park and Rakha (2010) regarding CFI indicated that a large number of unsafe maneuvers during the early use of CFI could be due to drivers' unfamiliarity. The study showed a $50 \%$ reduction in unsafe maneuvers by the end of first year of use. The researchers have suggested implementing a proper signing plan and information campaign as a solution to this problem. The AASHTO Green Book (2011) has suggested the use of signing, visual cues, and education to provide guidance for intersection users. Similarly, in Thomson and Hummer's study (2001) about the safe implementation of unconventional intersections, they emphasized signing plans and efficient public information campaigns as a measure to fulfill the ad-hoc and priori expectancy of the drivers to maintain safety. Similarly, Inman (2009) conducted a simulator study to compare alternative signing and marking options. Three strategies for navigation signing were evaluated: overhead signing and two different ground-mounted sign alternatives. The results showed that the ground-mounted signing treatment that
included a "Keep Left" advance sign was as effective as an overhead navigation sign. FHWA (2008) has published a summary report regarding the evaluation of sign and marking alternatives for displaced left turn (DLT) lane intersections with three main purposes. The first purpose is to "inform recommendations for signing DLT crossovers," the second is to "inform recommendations for mitigation of stop line overruns on minor street approaches to DLTS," and the third is to see "the extent to which naive drivers are able to navigate a DLT for the first time." The study concluded that advance signing is important and that overhead signing may not be more effective than ground-mounted signs. It does not mean that overhead signs should not be considered; it means that in some cases ground-mounted signs could be sufficient. The report mentioned that minor street approaches to DLT were not the problem. There were KEEP CLEAR markings applied, but whether the absence of overruns was due to this sign or not was not certain. The study mentioned that there was no driver confusion when drivers confronted the DLT for the first time.

### 2.4 The Operation and Safety Performance Related to Jughandles

As described in preceding chapter, the jughandle operates with one main intersection and two other crossover intersections. Reverse/reverse (R/R) jughandles have reverse ramps to divert left-turning vehicles. The main intersection is signalized and the crossovers are YIELD controlled. The operational and safety effect brought by this intersection modification are described in flowing subsections.

Table 2.12 Safety performance of CFI (Part I)

| Literature | Alternative Intersection | Safety Performance and Behavior |
| :---: | :---: | :--- |
| $\begin{array}{c}\text { Techbrief: } \\ \text { Displaced Left- } \\ \text { turn Intersection } \\ (2009)\end{array}$ | CFI |  | \(\left.\begin{array}{l}The two legged CFI possess 30 conflict points compared 32 conflict points in a conventional <br>

intersection. A safety study of CFI in Baton Rouge indicated 24\% reduction in total crashes <br>
and 19 \% reduction in fatal and injury crashes.\end{array}\right]\)

Table 2.13 Safety performance of CFI (Part II)

| Literature | Alternative Intersection | Safety Performance and Behavior |
| :---: | :---: | :--- |
| Thomson and Hummer (2001) | CFI | The safe implementation of unconventional intersections emphasized <br> on signing plans and efficient public information campaigns as a <br> measure to fulfill the adhoc and priori expectancy of the drivers to <br> maintain safety. |
| AASHTO (2011) | CFI | AASHTO suggests the need of signing, visual cues, and education to <br> provide guidance for intersection users. |

### 2.4.1 Operational Performance of Jughandles

Jughandles are thought to be suitable as an intersection treatment for high volume arterials with moderate to low left turning volume (Toolbox on Intersection Safety and Design, 2004; Hummer, 1998; Rodgerts et al., 2004). It is applicable for all volumes of minor street through traffic. Hummer and Reid (1999) further added that jughandles were suitable for arterials with high through volume, moderate to low left turn volume, narrow right of way, and the distances between signals should be long so that additional right-ofway and other costs for the ramp do not exceed the savings. The extent of performance was based on certain traffic conditions that are discussed below based on the information provided by past literature. The review notes of prominent literature that are directly related to the operational performance of jughandles are shown in table 2.14 and table 2.15.

Rodegerdts et al. (2004) indicated that jughandles have potential to reduce the overall travel time, but they do not reduce travel time and stops for left-turning vehicles compared to conventional intersections. "Techbrief: Traffic Performance of Three Typical Designs of New Jersey Jughandle Intersections" (2007) indicated that the delayg reduction capability of jughandles depend on the type of configuration and geometrics. The result showed that the forward/forward (F/F), reverse/reverse (R/R), and forward/reverse ( $\mathrm{F} / \mathrm{R}$ ) jughandles will reduce the average intersection delays compared to conventional intersections by $15-35 \%, 20-40 \%$, and $25-40 \%$, respectively. Similarly, they
have higher intersection capacities compared to conventional intersections for saturated conditions in the range of $20-25 \%, 25-30 \%$ and $25-40 \%$. Jughandles performed well in terms of travel time and number of stops per vehicle compared to conventional intersections only for near saturated conditions. The vehicular capacity of left turn volumes in the major road decreases with ramp offsets such that offset length reduction from 450 ft . to 230 ft . reduces the left-turn capacity on the major road approach by approximately $30 \%$. The performance of jughandles may depend on the control of crossovers as well. In this context, Chowdhury (2011) evaluated a New Jersey jughandle intersection (NJJI) with and without pre-signals. The study indicated that NJJI with presignals can improve operations under high volume conditions without degrading the condition at low volume. The NJJI without pre-signals performed slightly better than NJJI with pre-signals and conventional intersections under low overall volume condition. The NJJI alternative with pre-signals increased intersection capacity by $45 \%$ over conventional intersections. Both types of NJJI reduced $\mathrm{HC}, \mathrm{CO}$, and NO emissions from conventional intersections. Regarding fuel consumption, the mileage per gallon on average were 13.8, 14.7 and 14.8 for conventional intersections, NJJI without pre-signals, and NJJI with pre-signals, respectively. Regarding the use of jughandles to improve arterial corridor congestion, Furtado, Tencha and Devos (2003) did a study on suitable methods for the improvement of McKnight Boulevard in Calgary for medium term (2015) and long term (2038) under certain sets of constraints. They studied six alternatives for improvement, including a jughandle ramp at key intersections. The
analysis showed that the implementation of a jughandle (4 \& 6 lanes) can improve existing conditions and perform better than a conventional six-lane alternative in terms of travel time, signal delay, average speed, and LOS at AM and PM peak hour conditions for eastbound and westbound through traffic along McKnight Boulevard. The signal delay, travel time, and average speed were $139 \mathrm{~s}, 265 \mathrm{~s}$, and $20 \mathrm{~km} / \mathrm{h}$, respectively, for the eastbound AM peak hour in existing conditions. Similarly, the signal delay, travel time, and average speed were $140 \mathrm{~s}, 287 \mathrm{~s}$, and $23 \mathrm{~km} / \mathrm{h}$, respectively, for the westbound PM peak hour. With the implementation of a jughandle (four lanes) in the year 2015, signal delay, travel time, and average speed will be $33 \mathrm{~s}, 126 \mathrm{~s}$, and $43 \mathrm{~km} / \mathrm{h}$, respectively, for the eastbound PM peak hour; and $45 \mathrm{~s}, 154 \mathrm{~s}$, and $42 \mathrm{~km} / \mathrm{h}$ for the westbound PM peak hour. The same performance measures will be $46 \mathrm{~s}, 140 \mathrm{~s}$, and $39 \mathrm{~km} / \mathrm{h}$ for the eastbound PM peak hour, and $38 \mathrm{~s}, 147 \mathrm{~s}$, and $44 \mathrm{~km} / \mathrm{h}$ for the westbound PM peak hour, in the year 2038 with the implementation of a jughandle (six lanes). These values were better than the conventional six-lane alternative. Similarly, the LOS at year 2038 achieved through the use of a jughandle at 4th Street West were C and B, compared to F and D with the conventional alternative for AM and PM peak hours. The LOS at Center Street were B and B with a jughandle, compared to F and E for a conventional alternative for AM and PM peak hours, respectively. Similarly, the LOS at Edmonton Trail were B and B with a jughandle, compared to F and E for a conventional alternative for AM and PM peak hours.

Table 2.14 Operational performance of jughandle (Part I)

| Literature | Intersection Type | $\begin{gathered} \text { Intersection Capacity } \\ \text { with respect to } \\ \text { Conventional Intersection } \end{gathered}$ | Delay and Queue | Travel Efficiency | Fuel <br> Consumption <br> and <br> Emissions |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Rodegerdts et al. (2004) | Jughandle |  |  | Jughandles do not reduce stops for left turning vehicles compared to conventional intersections. They have potential to reduce the overall travel time but they do not reduce travel time as compared to the conventional intersections. |  |
| Techbrief: Traffic <br> Performance of Three Typical Designs of New Jersey jughandle Intersections (2007) | Jughandle : <br> Forward/Forward (F/F), <br> Reverse/Reverse ( $\mathrm{R} / \mathrm{R}$ ) and Forward/Reverse ( $\mathrm{F} / \mathrm{R}$ ) | Jughandles have higher intersection capacities compared to conventional intersections for saturated conditions in the range 2025\% (F/F), 25-30\% (R/R) and 25-40\% (F/R). | Jughandles reduce the average intersection delays compared to conventional intersections by $15-35 \%$ ( $\mathrm{F} / \mathrm{F}$ ), 20-40\% (R/R), and $25-40 \%$ ( $\mathrm{F} / \mathrm{R}$ ), respectively. | Jughandles performed well in terms of travel time and number of stops per vehicle compared to conventional intersections only for near saturated conditions. |  |
|  |  | The vehicular capacity of left turn volumes on the major road decreases with ramp offsets such that offsets length reduction from 450 ft . to 230 ft . reduces the left-turn capacity on the major road approach by approximately $30 \%$. |  |  |  |

Table 2.15 Operational performance of jughandle (Part II)

| Literature | Intersection Type | Intersection Capacity <br> with respect to <br> Conventional <br> Intersection | Delay and Queue | Travel <br> Efficiency | Fuel Consumption and Emissions |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | The NJJI alternative with <br> Chowdhury <br> (2011) | New Jersey jughandle <br> Intersection (NJI) with <br> and without pre-signals | intersection capacity by <br> $45 \%$ over conventional <br> intersection. | NJJI reduce HC, CO and NO emissions <br> than conventional one. Regarding fuel <br> consumption, the mileage per gallon in <br> an average were 13.8,14.7 and 14.8 for <br> conventional, NJJI without pre-signals <br> and NJJI with pre-signals respectively. |

### 2.4.2 Safety Performance of Jughandles

A study (Jagannathan et al., 2006) indicated that a four-legged signalized intersection with two forward jughandle ramps has a total of 26 conflict points. The four- legged signalized intersection with one forward and one reverse jughandle ramps has a total of 25 conflict points, and the four-legged signalized intersection with two reverse jughandle ramps has total of 24 conflict points. Smith (2013) indicated that a forward ramp intersecting the cross street plus a forward ramp curving left to intersect the mainline jughandle would produce 20 diverge/merge conflicts, 4 crossing (left) conflicts, and 4 crossing (angle) conflicts to total about 28 conflicts, compared to the 32 conflicts of conventional four-legged intersection and 26 conflicts of a Type A jughandle. Jagannathan et al. (2006) indicated that conventional intersections had more head-on, left turn, fatal plus injury, and property damage only crashes compared to NJJIs. Within jughandles, the reverse/reverse jughandle was found to have the lowest rate of angle and left turn crashes per million vehicle miles. The forward jughandles were found have the highest overall rate of crashes per million vehicle miles travelled, which was about 1.3 to 1.4 times the other two types, forward-reverse jughandle and reverse-reverse jughandle. There were significant differences in pedestrian injuries between conventional intersections and NJJIs. Agarwal (2011) developed a conflict model concerning pedestrian safety for signalized and un-signalized intersections using a Surrogate Safety Assessment Model (SSAM) to quantify the conflicts. For a F/F jughandle, separate models were developed for ramp sections and intersections. For the ramp, the pedestrian

Table 2.16 Safety performance of jughandle

| Literature | Alternative Intersection | Safety Performance and Behavior |
| :---: | :---: | :---: |
| Jagannathan et al. (2006) | Jughandles | A four-legged signalized intersection with two forward jughandle ramps has total of 26 conflict points. The four-legged signalized intersection with one forward and one reverse jughandle ramps has total of 25 conflict points, and the four-legged signalized intersection with two reverse jughandle ramps has a total of 24 conflict points. |
|  |  | The reverse-reverse jughandle was found to have lowest rate of angle and left turn crashes per million vehicle miles. The forward jughandles were found have highest overall rate of crashes per million vehicle miles travelled, which was about 1.3 to 1.4 times the other two types, $\mathrm{F} / \mathrm{R}$ jughandles and $\mathrm{R} / \mathrm{R}$ jughandle. There were significant differences in pedestrian injuries between conventional intersections and NJJIs. |
| Smith (2013) | Jughandles | The forward ramp intersecting the cross street plus forward ramp curving left to intersect the mainline jughandle would produce 20 diverge/merge conflicts, 4 crossing (left) conflicts, and 4 crossing (angle) conflicts, to a total about 28 conflicts compared to 32 conflicts of conventional four-legged intersection and 26 conflicts of a Type A jughandle. |
| Agarwal (2011) | Jughandles | For jughandle (F/F), separate models were developed for ramp section and intersection. For the ramp, the pedestrian vehicle conflict was found to be positively affected by turn percentage, and conflict volume. Similarly, the pedestrian vehicle conflict for jughandle intersections was found to be positively affected by conflict volume, number of lanes, and turn percentage. The minor approach was found to have more pedestrian vehicle conflicts. |

vehicle conflict was found to be positively affected by the turn percentage and conflict volume. Similarly, the pedestrian vehicle conflict for jughandle intersections was found to be positively affected by conflict volume, number of lanes, and turn percentage. The minor approach was found to have more pedestrian vehicle conflicts. The review notes from prominent literature related to the safety performance of jughandles are shown table 2.16.

### 2.5 Summary of Literature Review about the Performance of Unconventional

## Intersections

From the literature review about the performance of unconventional intersections, it can be inferred that all three types of intersections have superior performance in the view point of operation and safety compared to unconventional intersection. However, the degree of performance was found largely dependent on the volume condition, movement type, and their individual types. Particularly, the operational performance of MUT was very good overall, but at the cost of the performance of its left turn movements compared to conventional intersections as well as other types of unconventional intersections. The performance of MUT was not always superior to other intersections regarding number of stops. Similarly, the performance of CFI was better than other intersections, especially under high traffic condition and when the flow on different approaches was not balanced. Under low traffic conditions, CFI could be outperformed by other types of unconventional intersections. Similarly, the performance of a jughandle was good under high overall volume conditions and low left turn volume conditions.

Overall, the literature indicated that the unconventional intersections are safer than conventional intersections.

### 2.6 Economic Aspects of Unconventional Intersections

This section includes a review of literatures related to construction cost and its related elements, delay pricing and pricing of fuel consumption and emissions. The information from these literatures is utilized for the economic analysis that is described in a later chapter of this dissertation.

### 2.6.1 Construction Cost

In their paper, Berkowitz et al. (1997) have indicated that the cost of CFI was $\$ 638,000$ based on a site in Mexico; $\$ 6,000,000$ based on a site on Brooklyn, NY; and $\$ 4.4$ million based in Baton Rouge, LA. The preliminary analysis by KLD associates and Francisco Mier indicated that the cost of a CFI is three times the cost of a conventional intersection. COMPASS of Southwest Idaho (2008) mentioned that the total cost of CFI was $\$ 8.55$ million based on a site in Salt Lake City, including construction costs of $\$ 4$ million, construction engineering cost of $\$ 300,000$, a preliminary engineering cost of $\$ 1$ million, and a right of way cost of $\$ 3.25$ million. Hildebrand (2007) indicated in his thesis that the estimated cost of a CFI was $\$ 5,221,064.02$, which was $49 \%$ higher than the estimated cost of a conventional intersection. He indicated that the cost of a jughandle was $\$ 3,238,125$, which was $7.3 \%$ lower than a conventional intersection. He also indicated that the cost of MUT was $\$ 4,681,201.11$, which was $34.1 \%$ higher than a conventional intersection. The "Intersection Improvement Study Phase 2 Report" from
the Town of Cary indicated a total MUT project cost of $\$ 3.9$ million. In his thesis,
Boddapati (2008) indicated that the cost of an un-signalized MUT crossover was
$\$ 951,818$ based on bid prices of the Missouri Department of Transportation in the year 2007. A summary of the cost of unconventional intersections collected from different sources are presented in table 2.17.

Table 2.17 Cost of unconventional intersections

| Intersection Type | Source | Cost of Construction |
| :---: | :---: | :---: |
| CFI | Berkowitz et al. (1997) | \$638,000 (in Mexico) |
|  |  | \$6,000,000 (Brooklyn, NY) |
|  |  | 3 times the conventional intersection (Preliminary analysis by KLD Associates and Francisco Mier) |
|  |  | The total cost of CFI was $\$ 4.4$ million (Baton Rouge, LA) |
|  | COMPASS (2008) | The total cost of CFI was $\$ 8.55$ million (Salt Lake City) including construction cost of $\$ 4$ million, construction engineering cost of \$ 300,000, preliminary engineering cost of $\$ 1$ million, and right of way cost of $\$ 3.25$ million. |
|  | Hilderband (2007)-Thesis | The estimated cost of CFI was $\$ 5,221,064.02$ (49.\% higher than conventional) |
| Jughandle | Hilderband (2007)-Thesis | The cost of jughandle was $\$ 3,238,125$ (7.3\% lower than conventional). |
| MUT | Hilderband (2007)-Thesis | The MUT costs \$4,681, 201.11 (34.1\% higher than conventional). |
|  | Intersection Improvements Study Phase 2 report (Town of Cary) | Project cost of MUT was \$3.9 Million. |
|  | Boddapati (2008) | The cost of un-signalized median U-turn cross over was $\$ 951,818$ based on bid prices of MODOT for year 2007. |

### 2.6.2 Delay Pricing

The price of delay is a governing factor for the estimation of monetized intersection operational benefit or cost. Price of delay varies on the locations and time. In this context, the prices estimated by Kawamura (1999) for urban areas based on the data collected in California by interviewing the truck drivers were $\$ 23.4 / \mathrm{hr}$ and $\$ 32 / \mathrm{hr}$. From a similar study based on California, Brownstone, Ghos, Golob, Kazimi and Amelsfort (2002) estimated the median value of driver willingness to pay to reduce commute time as approximately $\$ 30 / \mathrm{hr}$ for morning peak hour. In a study about performance evaluation of CHART (Coordinated Highways Action Response Team), Chang, Liu, Lin and Zhou (2003) have used average delay price as $\$ 14.34 /$ hour. It was a study based on Maryland. Similarly, the 2012 Urban Mobility report has indicated the average cost of time as \$16.79/hr.

### 2.6.3 Price of Fuel and Emissions

Regarding the price of fuel, the American Automobile Association (AAA), in its website about fuel gauge report, indicated the unit prices of diesel and petrol averaged throughout the year 2012 for Nebraska as $\$ 3.704$ /gallon for petrol and $\$ 3.956 /$ gallon for diesel. The unit price of $\mathrm{CO}_{2}$ indicated by 2010 Annual Supplement to National Institute of Standards and Technology (NIST) Handbook published by the U.S. Department of Energy was $\$ 0.02 / \mathrm{kg}$. Similarly, a technical paper by Bishop, Stedman, Peterson, Hosick and Guenther (1993) indicated the unit price of CO as $\$ 200 /$ ton. Muller and Mendelson
(2009) indicated the unit prices for $\mathrm{NO}_{\mathrm{x}}$ and $\mathrm{VOC}_{\mathrm{s}}$ as $\$ 180 /$ ton/year and $\$ 250 /$ ton/year considering median damage cost.

### 2.6.4. Life Cycle Cost Analysis (LCCA) and Benefit Cost (B/C) Ratio of

## Unconventional Intersections

Very little literature (Boddapati, 2008; Martin et al., 2012) was found dealing with economic analysis of unconventional intersections considering their future performance. Additionally, these studies were more concerned with particular type of unconventional intersection or the set of unconventional intersections for a particular project. In this context, Boddapati (2008) did a life cycle cost analysis of type 2 median crossover, MUT with signalized crossover and MUT with unsignalized crossover, to calculate the annual equivalent costs for a 20-year life cycle period. He considered travel time cost as the user's cost. Based on annual equivalents, he found that type 2 median crossover was good for a low volume major street. An unsignalized MUT was found to be good for medium volumes. A signalized MUT was found to be good for higher volumes. Similarly, Martin et al. calculated benefit-cost on three alternatives comprising of unconventional intersections: (i) a combination of MUT, CFI, and traditional improvements as addition of turn lanes, etc, and (ii) a combination of MUT and CFI. He considered construction costs and delay savings related to alternatives. They estimated B/C for existing year 2010, future year 2015, and future year 2020. They found that both alternatives had higher B/C than a no build condition.

### 2.7 Brief Summary of Inferences obtained from Literature Review Chapter

In summary, the literature review of past studies provided the information about the principles used in existing tools to evaluate unconventional intersections, operational and safety performance of unconventional intersections, and the economic aspect of unconventional intersections. From the information about the principles used in existing tools, we realized that their method of analysis can be improved. The detailed operational analysis, computation of a monetizable measure of effectiveness, and the use of cost and benefit aspects in the evaluation of unconventional intersections would certainly improve the present level of methodology adopted for evaluation on these tools. It was also found that the economic aspect of unconventional intersections is still not well studied. This information suggested adoption of these aspects in this study. Similarly, on the performance aspect, the literature was found to be more concentrated on microsimulation based operational evaluation and comparison of performance measures to differentiate the performance of unconventional intersections with conventional intersections or between different types of unconventional intersections. The performances of unconventional intersections are explained to be dependent on large range conditions. However, no literature was found to have developed any generalized decision criteria to select the most suitable intersection type out of several alternatives. This backdrop in past studies also supplied the clue for this study to look into this aspect.

## CHAPTER 3

## STATE OF PRACTICE

Email queries were sent to state agencies to collect information about existing research and practices pursued by different U.S. states, especially about guidelines for the implementation, related costs, and user's feedback concerning unconventional intersection treatments. This chapter includes a description of the information collected from different state agencies. The information is also tabulated in table 3.1 and table 3.2.

### 3.1 Missouri Department of Transportation (MODOT)

The responder from MODOT explained that the capacity- and turning movementbased decisions are the main criteria for the implementation of CFIs and jughandles. The responder also mentioned that they had success regarding the CFI designs in the St. Louis area, but were not sure of the reason behind the installation. MODOT has implemented ten median U-turns or J-turns to date. These were designed to tackle the angle crashes in their retrofit projects or four-lane designs. The before-and-after study indicated that there was a tremendous reduction in angle crashes, but an increase in sideswipe crashes with the use of MUT. MODOT's policy for the implementation of directional median openings with downstream U-turns (slight modification MUTs), is based on Section 233.2 At-Grade Intersection with Stop and Yield Control, and subsection 233.2.6 of the MODOT Engineering Policy Guide. The cost to install a J-turn (deviation of MUT) varied by location and geometry, but was about less than $\$ 400,000$ per intersection according to their experience with the Central District. These intersections include
lengthy acceleration and deceleration lanes as well. According to the responder, the feedback for jughandles was not positive. The responder also indicated that these designs were not well received by all and it would take time before they are accepted by the majority.

### 3.2 Michigan Department of Transportation (MDOT)

According to the responder from MDOT, Michigan did not use CFI or jughandle designs, and instead used the Michigan indirect left. MDOT had a detailed report about directional crossovers (MUTs), Michigan's preferred left turn strategy. According to the report, the capacity problem due to interlocking left turns within the bi-directional crossovers at major street intersections led to the concept of using directional crossovers. MDOT has implemented 700 directional crossovers on their state highway system. In terms of capacity, the study conservatively showed $20 \%$ to $50 \%$ capacity improvement. The report also included the detailed operational analysis, safety analysis, and the design of the directional left turn strategy. In terms of safety, a report from Michigan State University indicated a $31 \%$ crash reduction in the entire highway system and a $42 \%$ crash reduction in the places where bi-directional crossovers were replaced with directional crossovers. Overall, MDOT appears to have detailed documents about their implementation of MUT designs. The cost of construction, as indicated in the report for directional strategy, was $\$ 120,000 /$ pair.

### 3.3 Iowa Department of Transportation (IOWA DOT)

IOWA DOT did not have any special policies regarding unconventional intersections. IOWA DOT tried to install MUTs, but could not due to public's reception of the proposal. The public expressed concerns that J-turns would bring new problems or continue to have the same crash problems as before. It could be dangerous for buses, as they make U-turns from median openings, and would not be helpful for roads that are used by semi-trailers.

### 3.4 Virginia Department of Transportation (VDOT)

VDOT did not have special policies. It constructed a jughandle on Route 460. A jughandle was chosen because it could be constructed within the pre-existing VDOT right of way (ROW), and it improved the signal timing operation of the intersection. The bid estimate of the project was $\$ 982,910$, however, it included work associated with the closure of three additional cross-overs. The work that was included in the cost estimate, but was not related to the construction of the jughandle, was less than $10 \%$.

### 3.5 Kentucky Transportation Cabinet (KYTC)

The Kentucky Transportation Cabinet (KYTC) did not have a policy about the implementation of unconventional intersections. However, the Kentucky Transportation Center at the University of Kentucky has developed a design tool that helps determine the feasibility and lane configurations of different type of intersections. It did not have a cost estimate for intersections because they vary by location, size, and complexity.

### 3.6 North Carolina Department of Transportation (NCDOT)

North Carolina's general state of practice is to find anything that works to resolve traffic safety and operation problems. Their Congestion Management section reviews each project to determine the best operation for the corridor/intersection. There is no specific policy as projects are judged on an individual basis. However, they are looking to implement more superstreets on their critical corridors to maintain acceptable LOS and travel time. North Carolina does not consider jughandles for treatments anymore. North Carolina has not implemented CFIs, but is planning to implement them in near future. The responder indicated that NCDOT did not have any formal cost estimations. To retrofit existing intersections into superstreets, they estimated about $\$ 1.2$ million per single location, which includes two U-turn locations, the median treatment at the main intersection, and four signals. The public's opinion was generally negative before, and positive afterward.

### 3.7 New York State Department of Transportation (NYSDOT)

Their practice is based on NYSDOT intersection design and policy stated by its Highway Design Manual Chapter 5: Basic Design. Section 5.9.1.3 states that unconventional intersections need special consideration and treatment and should be developed in consultation with the Regional Transportation Systems Operations Engineer. The layout, applicability, design features, safety performance, and operational performance are based on FHWA's Signalized Intersections: Informational Guide.

Table 3.1 State of practice (Part I)

| State Agencies | Contacte d <br> Persons | Intersection Types |  |  | Cost | User's Response |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | CFI | MUT | Jughandle |  |  |
| MoDOT | John P. <br> Miller | Capacity and turning movement | Capacity analysis considering weaving movements | Capacity and turning movement | Variation with location and geometry (J-turn: \$400,000 according to the experience in central district) | Not positive, takes time to be accepted by majority |
|  |  |  | (233.2.6, MoDOT Engineering Policy Guide) |  |  |  |
| MDOT | Imad Gedaoun | Not used | They have developed a guideline: Directional Crossovers, Michigan Preferred Left Turn Strategy | Not used | \$120,000/pair (MUTs) | N/A |
| NCDOT | James <br> Dunlop | In plan to implement. No specific policy, general practice to resolve traffic safety and operational problems | Superstreets | Doesn't consider jughandle as treatment | No formal estimate is available. | Negative at the beginning but, positive afterwards |
|  |  |  | No specific policy, general practice to resolve traffic safety and operational problem |  | Superstreet retrofitting: 1.2 million/intersection (2 Uturn locations, median treatment at main intersections and four signals) |  |
| $\begin{gathered} \text { NYSDO } \\ \mathrm{T} \end{gathered}$ | Rick Wilder | Based on NYSDOT intersection design and policy stated by NYSDOT Highway Design Manual Chapter 5- Basic Design. Consultation with Regional Transportation Systems Operations Engineer. |  |  | No standard cost for unconventional intersection. It depends on available right of way, number of lanes, local construction costs, whether or not closed design is needed and the work zone traffic control. |  |
|  |  | The layout applicability, safety and operational performance are based on FHWA's Signalized Intersection: Informational Guide. |  |  |  |  |

Table 3.2 State of practice (Part II)

| State agencies | Contacted Persons | Intersection Types |  |  | Cost | User's Response |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | CFI | MUT | Jughandle |  |  |
| IOWA DOT | John Narigon | N/A | Iowa DOT tried to seek place to install MUTs but it couldn't do that due to public's reception of the project. | The overall cost of proposed J-turn (a deviation of MUT) was $\$ 557,300$. | N/A | Public expressed their concerns that J-turn would bring new problems or continue to have the same crash problem as before. It could be dangerous for buses, as they do U-turn from median opening. It wouldn't be helpful for the roads that are used by semitrailers. |
| VDOT | George T. <br> Rogerson Jr. | N/A | N/A | No specific guidelines. VDOT constructed one jughandle because of availability of right of way. Additionally, it improved signal operation of intersection. | Bid estimate: \$982,910 (including work associated with closure of 3 additional crossovers) | No feedback. Assumption was made that public accepted the facility. |
| Kentucky Transportation Cabinet (KYTC) | Brent A. Sweger | No specific policy. University of Kentucky has developed a design tool that provides assistance in deciding the proper type of unconventional intersections. |  |  | N/A | Not known about MUT, CFI and jughandle. However, the public responses for roundabout and double crossover diamond interchange were positive. |
| State Highway Administration, Maryland (SHAM) ) | Minseo k. Kim | No specific policy. General criteria based on delay, v/c ratio, queue length, travel time, etc.), right of way, environmental impact, construction cost, engineering judgment and experience along with human factors knowledge in addressing any potential safety concerns. |  |  | N/A | N/A |

Section 5.9.1.3 also states that jughandles are applied in the locations where operational and safety concerns preclude left turns from the median lane.

### 3.8 State Highway Administration, Maryland (SHAM)

The State Highway Administration, Maryland reported that there is no specific policy about the implementation of unconventional intersections except the general criteria based on delay, volume to capacity ratio, queue length, right of way, environmental impact, construction cost, engineering judgment, and experience, along with human factors in addressing any potential safety concerns.

### 3.9 Brief Summary of Inferences obtained from Current State of Practice

The current state of practice regarding the unconventional intersection indicated that the majority of states do not have specific guidelines for the implementation of unconventional intersection treatments. Most state DOTs were found to follow the method of practices of general signalized intersections, such as performing traffic engineering studies for specific locations to determine the feasibility, using engineering judgment, looking at the construction cost, etc. This information along with the information from literature review directed this study towards the remedy of deficiencies in the method of current studies and practices. The idea of developing a decision support system, as mentioned in the objective of this study, was generated looking at these deficiencies in existing studies and current state of practices.

## CHAPTER 4

## OPERATIONAL ANALYSIS

This chapter includes the procedure applied in the operational analysis of standard four-legged signalized intersections, standard four-legged signalized intersections with left turn permitted along the major street, and three types of unconventional intersections: MUT, CFI, and jughandle. The operational analysis includes the volume database creation, the use of HCS for delay estimation, and a subsequent estimate of fuel consumption and emissions, which are described in detail in the following sections.

### 4.1 Levels and Magnitude of Fixed and Variable Parameters

Prior to the computation of the measures of effectiveness (MoEs), it was necessary to consider the reasonable magnitude of fixed parameters that represented the local condition of Nebraska or standard practices in the U.S., and fix the level of variable parameters. The fixed parameters were speed and some specific geometric-related parameters. The variable parameters were volumes both of major streets and minor streets, truck percentages for both major streets and minor streets, the directional split for major streets, and the turn percentage of major streets.

### 4.1.1 Fixed Parameters

(A) Speed: Since this study is focused on rural roads, the operating speed at the intersections and crossovers were considered to reflect the speed condition of rural roads of Nebraska. The Nebraska Minimum Design Standards (2008) specify the design speed
of 60 mph for rural major arterials in the state highway system. Similarly, it has a specified design speed of 40 mph to 50 mph for rural other arterials, 40 mph to 50 mph for rural collectors, and 30 mph to 50 mph for rural local roads in the local roads and streets system. To represent these speed conditions of rural roads in Nebraska, the operating speed of major streets was fixed at 45 mph , and the operating speed of minor streets was fixed at 35 mph . The speed of traffic at the reverse ramp of the jughandle was kept fixed at 30 mph based on the study described in "Techbrief: Traffic Performance of Three Typical Designs of New Jersey Jughandle Intersections" (2007).
(B) Offset of Median Openings and Geometry related to Median Openings for MUT: The offset of median openings was fixed at 660 ft . based on the suggestion of past literature (AASHTO Green Book, 2011; "Information and Geometric Design Guidance Regarding Boulevards, Directional Crossovers, and Indirect ['Michigan'] Left Turns", 1995; Potts et al., 2004). The median width was kept fixed at 60 ft . to accommodate a tractor-semitrailer combination of trucks as the design vehicle as prescribed by past literature (AASHTO Green Book, 2011; Rodgerts et al., 2004).
(C) Offset of Crossovers for Jughandles: For jughandles, the offsets of crossovers were considered 170 ft . along major streets and 150 ft . along minor streets as shown in a typical diagram of the geometry of a R/R jughandle in "Techbrief: Traffic Performance of Three Typical Designs of New Jersey jughandle Intersections" (2007).
(D) Geometric Features of CFI: The offset of east and west crossovers were considered 350 ft . from the central signalized intersection. This was based on the study by Armstrong (2014).

### 4.1.2 Variable Parameters

(A) Volume: The bi-directional volume beginning from 50 vph to 2400 vph at the increment of 50 mph was considered. There were a total of 48 different bi-directional volume levels for the major street. For the minor street, one directional volume, from 25 vph to 250 vph , was considered at the increment of 25 vph . Since the split for the minor street was kept constant at 0.5 , both directional volumes for the minor street were equal. There were ten different unidirectional volume levels for the minor street. Since the right turn movement was to be excluded from the analysis, no volume was generated for the right turn movements for all four intersections.
(B) Truck Percentage (TP): Three levels of truck percentage were considered: $2 \%$, $5 \%$, and $10 \%$. The same truck percentages were considered for both major and minor streets.
(C) Balance Factor (BF): The balance factor is related to the ratio of approach traffic volume to total approach traffic volume. Three levels of balance factor along the eastbound direction of the major street were considered: $0.5,0.6$, and 0.7 . The balance factor of the minor street was kept fixed at 0.5.
(D) Left Turn Percentage (LTP): Three levels of left turn percentage were considered for major streets, those being $5 \%, 10 \%$, and $15 \%$. The left turn percentage of the minor street was kept fixed at $5 \%$.

Based on directional splits (balance factor) and turn percentage, an origindestination (O-D) volume database for all volume combinations was constructed for all four types of intersections: a standard signalized intersection, MUT, CFI, jughandles, and a standard signalized intersection with left turn permitted along the major street. The combination of all these levels of variable parameters produced a total of 12,960 combinations for each intersection.

### 4.2 Estimation of Delay

Delay estimation was done using HCS $2010^{\circledR}$ Streets version 6.5. The networks were coded to represent the whole system of each individual intersection. For example, MUT has two STOP controlled median openings and one central signalized intersection, CFI has four signalized crossovers and one central signalized intersection, and the jughandle has four crossovers, including two YIELD controlled crossovers and one central signalized intersection. The fully actuated signal control was assumed for all four intersection types. The details are described in following subsections.

### 4.2.1 Standard Signalized Intersection

The standard signalized intersection consists of two through lanes, one exclusive left turn lane, and one exclusive right turn lane in an approach. Since the right turn movement was not considered for analysis, it was not included in the lane configuration
coding in HCS $2010^{\circledR}$. The intersection operates under a fully actuated eight-phase signal control with protected left turn movements, as shown in figure 4.1. The maximum green times for all the movements were kept at 50 s , and minimum green times were left at the default 10 s . The yellow change time was changed to 3 s . The base saturation flow rate was kept at $1800 \mathrm{pc} / \mathrm{h} / \mathrm{ln}$. The speed was set to 45 mph for the major street and 35 mph for the minor street. Respective heavy vehicle percentages for each volume combination were set.


Figure 4.1 Phases and lane configuration of standard signalized intersection

### 4.2.2 MUT

The MUT consists of two through lanes and one exclusive right turn lane. Since the right turn movement was not considered for analysis, it was not included in the lane configuration coding in HCS 2010 ${ }^{\circledR}$. The central signalized intersection operates under fully-actuated two phase signal control, allowing through movement of the major and minor streets. The median openings are STOP controlled. During network coding in HCS $2010{ }^{\circledR}$ Streets, the un-signalized median opening was coded as equivalent to a signalized intersection, while a U-turn was coded as a permitted left turn (see fig. 4.2). This permitted left turning movement will try to sneak through the gaps of opposing traffic that were provided with continuous green time throughout the cycle. To return the volumes toward the direction of U-turns, a right turn lane (northbound for west crossover and southbound for east crossover) was introduced with an equal volume to the left turn lane. Since HCS $2010^{\circledR}$ Streets does not support a single right turn lane, a same bound dummy through movement was added with zero volume. The right turn movements were allowed to turn right on red (RTOR). The central signalized intersection was coded as two phase signals. This coding technique was adopted from Armstrong (2014). However, unlike Armstrong's coding, the signal control was made fully actuated in this study. The maximum green times for all the movements were kept at 50 s and the minimum green times were left at the default 10 s . The yellow change time was changed to 3 s . The base saturation flow rate was kept at $1800 \mathrm{pc} / \mathrm{h} / \mathrm{ln}$. The speed was set to 45 mph for the major street and 35 mph for the minor street. The respective heavy vehicle percentages for each
volume combination were set. The input of the left turn equivalency factor was replaced by the approximate U-turn equivalency factor (Armstrong, 2014), which was calculated based on the effects of the radius of travel path using equation 4.1 from HCM 2010.

$$
f_{R}=\frac{1}{1+\frac{5.61}{R}}
$$

Where,

$$
\begin{aligned}
f_{R}= & \text { U-Turn Equivalency factor }=\text { Adjustment factor to account for the effect of } \\
& \text { travel path radius } \\
\mathrm{R}= & \text { Radius of travel path }
\end{aligned}
$$

For median openings, the U-turn equivalency factor was calculated using a 60 ft . turn radius. The default values of critical headway and follow up headway for a permitted left turn were also replaced with values for $U$ - turn movement calculated using the following equations from HCM 2010 for $0 \%$ grade and no adjustment factor for intersection geometry.

$$
\begin{align*}
& t_{c, x}=t_{c, \text { base }}+t_{c, H V} P_{H V} \\
& t_{f, x}=t_{f, \text { base }}+t_{f, H V} P_{H V}
\end{align*}
$$

Where,

$$
t_{c, x}=\text { critical headway }
$$

$t_{c, \text { base }}=$ base critical headway,
$t_{c, H V}$ and $t_{f, H V}=$ adjustment factor for heavy vehicles,
$P_{H V}=$ proportion of heavy vehicles for movement,
$t_{f, x}=$ follow up headway, and
$t_{f, \text { base }}=$ base follow up headway

The base critical headway for a U-turn from the major street can be obtained with table 4.1, based on HCM 2010. In this study, 6.9 s was chosen considering the narrow turn and four lanes. The adjustment factor for heavy vehicles for critical headway is 2 for a major street with two or three lanes in each direction (HCM 2010). The proportion of heavy vehicles for the movement corresponded to the truck percentage. Similarly, the base follow-up headway for U-turns can be obtained by table 4.2 , which is based on HCM 2010. The adjustment factor for heavy vehicles for follow-up headway was 1 for a major street with two or three lanes in each direction (HCM 2010).


Figure 4.2 Equivalent phases and lane configuration of MUT considered in network coding in HCS $2010^{\circledR}$ Streets

### 4.2.3 CFI

CFI is comprised of one central signalized intersection and four signalized crossovers. While coding the movements of east and west crossovers (see fig. 4.3), the left turns at crossovers were coded as right turns. Since HCS $2010{ }^{\circledR}$ Streets

Table 4.1 Base critical headway values from HCM 2010 Exhibit 19-10

| Vehicle Movement | Base Critical Headway (s) |  |  |
| :---: | :---: | :---: | :---: |
|  | Two Lanes | Four Lanes | Six Lanes |
| Left turn from Major | 4.1 | 4.1 | 5.3 |
| U-turn from Major | N/A | 6.4 (wide) | 5.6 |
|  | Right turn from Minor | 6.2 |  |
| Through traffic on <br> Minor | 1-stage: 6.5 | 1-stage: 6.5 | 1-stage: 6.5 |
|  | 2-stage, Stage I: 5.5 | 2-stage, Stage I: 5.5 | 2-stage, <br> Stage I: 5.5 |
|  | 2-stage, Stage I: 5.5 | 2-stage, Stage I: 5.5 | 2-stage, <br> Stage I: 5.5 |
|  | 1-stage: 7.1 | 1-stage: 7.5 | 1-stage: 6.4 |
|  | 2-stage, Stage I: 6.1 | 2-stage, Stage I: 6.5 | 2-stage, <br> Stage I: 7.3 |
|  | 2-stage, Stage I: 6.1 | 2-stage, Stage I: 6.5 | 2-stage, <br> Stage I: 6.7 |

Table 4.2 Base follow up headway values from HCM 2010 Exhibit 19-11

| Vehicle Movement | Base Follow-Up Headway (s) |  |  |
| :---: | :---: | :---: | :---: |
|  | Two Lanes | Four Lanes | Six Lanes |
| Left turn from Major | 2.2 | 2.2 | 3.1 |
| U-turn from Major | N/A | 2.5 (wide) | 2.3 |
|  | 3.3 | 3.1 (narrow) | 3.3 |
| Right turn from minor | 4.0 | 4.0 | 4.0 |
| Through traffic on <br> Minor | 1-stage: 7.1 | 1-stage: 7.5 | 1-stage: 6.4 |
| Left turn from Minor |  |  |  |

does not support a single right turn lane, a same bound dummy through movement was added with zero volume. Similarly, the left crossover movements at north and south crossovers were coded as right turn movement in the central signalized intersection. The
default value of the right turn equivalency factor in HCS $2010{ }^{\circledR}$ Streets was replaced with the left turn equivalency factor to compensate for the left and right turns trading roles. This coding technique was adopted from Armstrong (2014). However, unlike Armstrong's coding, the signal control was made fully actuated. The maximum green times for all the movements were kept at 50 s and minimum green times were left at the default 10 s . The yellow change time was changed to 3 s . The base saturation flow rate was kept at $1800 \mathrm{pc} / \mathrm{h} / \mathrm{ln}$. The speed was set to 45 mph for the major street and 35 mph for the minor street. Respective heavy vehicle percentages for each volume combination were set.

### 4.2.4 Jughandles

The R/R jughandle has ramps forming crossovers at major and minor street segments. The ramps facilitate the flow of left turn traffic from major street approaches. The network coding of a jughandle intersection in HCS $2010^{\circledR}$ Streets is shown in figure 4.4. The right turns from ramps at minor street crossovers were coded as permitted left turns. The tradeoff was made by setting the critical headway and follow-up time of permitted left turn movement as that of right turn movement. The critical headway and follow up times were calculated using equations 4.2 and 4.3, and the respective values of base critical headway and follow up times were chosen from tables 4.1 and 4.2. The base critical headway was chosen to be 6.9 s , as it was the movement that originated from a four-lane road, and the follow-up headway was chosen to be 3.3 s . To return the volume from permitted left-turn movements toward the original direction, right turn movements


Figure 4.3 Equivalent phases and lane configuration of CFI considered in network coding in HCS $2010^{\circledR}$ Streets
with equal volume were coded at both crossovers. Since HCS $2010{ }^{\circledR}$ Streets does not support a single right turn lane, a same bound dummy through movement was added with zero volume at both crossovers. The right turn movements at both crossovers were allowed to turn right on red (RTOR). The central signalized intersection was coded to operate with a three phase signal. For volume balancing purposes, both left turn movements from the major street were treated as RTOR movement at the central signalized intersection. The signal control was made fully actuated. The maximum green times for all the movements were kept at 50 s and minimum green times were left at the
default 10 s . The yellow change time was changed to 3 s . The base saturation flow rate was kept at $1800 \mathrm{pc} / \mathrm{h} / \mathrm{ln}$. The speed was set to 45 mph for the major street and 35 mph for the minor street. Respective heavy vehicle percentages for each volume combination were set.


Figure 4.4 Equivalent phases and lane configurations of jughandle considered in network coding in HCS $2010^{\circledR}$ Streets

### 4.2.5 Standard Signalized Intersection with Left Turn Permitted along Major Street

There are some criteria that govern the need of left turn permission in signalized intersection. The Signal Timing Manual (Rodegerdts et al., 2008) has provided a chart that explains the potential need of left turn phase adopted from Manual of Traffic Signal Design (1999). Similarly, Asante, Ardekani, and Williams (1994) have developed plots that can identify the need of left turn permission based on left turn volume, opposing speed and number of opposing lanes. The standard signalized intersection with left turn permitted consists of one shared left turn and through lane, one through only lane, and one exclusive right turn lane in an approach. Minor street approach has same configuration as that of standard signalized intersection. Since the right turn movement was not considered for analysis, it was not included in the lane configuration coding in HCS $2010^{\circledR}$. The intersection operates under a fully actuated eight-phase signal control with protected left turn movements, as shown in figure 4.5. The maximum green times for all the movements were kept at 50 s , and minimum green times were left at the default 10 s . The yellow change time was changed to 3 s . The base saturation flow rate was kept at $1800 \mathrm{pc} / \mathrm{h} / \mathrm{ln}$. The speed was set to 45 mph for the major street and 35 mph for the minor street. Respective heavy vehicle percentages for each volume combination were set. The critical headway and follow up times were calculated using equations 4.2 and 4.3, and the respective values of base critical headway and follow up times were chosen from tables 4.1 and 4.2 for left turn from major. The base critical headway was chosen to
be 4.1 s , as it was the movement that originated from a four-lane road, and the follow-up headway was chosen to be 2.2 s .


Figure 4.5 Phases and lane configuration of standard signalized intersection with left turn permitted along major street

### 4.2.6 Delay Results for Median Openings of MUT and Crossovers at Minor Streets of Jughandles from HCS $2010{ }^{\text {® }}$ Streets

Careful observation of the HCS output confirmed that there was an error in the HCS $2010^{\circledR}$ Streets calculation of the delay at median openings and crossovers at the jughandle's minor street. As an example of this error, a screen shot of movement results
from HCS $2010^{\circledR}$ Streets output for MUT is shown in figure 4.6. If we observe the capacity of westbound left movement as shown in the figure 4.6 , it is higher than the saturation flow of the left turn lane, which is not true according to the original relationship between capacity and saturation flow. The problem was reported to the developer of HCS $2010^{\circledR}$ Streets. The developer responded that it would be corrected in the next version of HCS $2010^{\circledR}$ Streets.

| Movement Group Results | EB |  |  | WB |  |  | NB |  |  | SB |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Approach Movement | L | T | R | L | T | R | L | T | R | L | T | R |
| Assigned Movement |  | 2 |  | 1 | 6 |  |  | 8 | 18 |  |  |  |
| Adjusted Flow/ Rate (v), veh/h |  | 1051 |  | 71 | 1016 |  |  |  |  |  |  |  |
| Adjusted Saturation Flow Rate (s), veh/h/ln |  | 1632 |  | 222 | 1632 |  |  |  |  |  |  |  |
| Queue Service Time ( $g_{\mathrm{z}}$ ), 5 |  | 0.0 |  | 0.0 | 0.0 |  |  |  |  |  |  |  |
| Cycle Queue Clearance Time ( $g$ :), 5 |  | 0.0 |  | 0.0 | 0.0 |  |  |  |  |  |  |  |
| Green Ratio ( $g / C$ ) |  | 1.00 |  | 1.00 | 1.00 |  |  |  |  |  |  |  |
| Capacity (c), veh/h |  | 3264 |  | 986 | 3264 |  |  |  |  |  |  |  |
| Volume-to-Capacity Ratio ( $X$ ) |  | 0.322 |  | 0.072 | 0.311 |  |  |  |  |  |  |  |
| Available Capacity (cs), veh/h |  | 17305 |  | 1941 | 17305 |  |  |  |  |  |  |  |
| Back of Queue (Q), veh/In (50th percentile) |  |  |  |  |  |  |  |  |  |  |  |  |
| Queue Storage Ratio (RQ) (50th percentile) |  |  |  |  |  |  |  |  |  |  |  |  |
| Uniform Delay ( $d_{1}$ ), 5 /veh |  | 0.0 |  | 0.0 | 0.0 |  |  |  |  |  |  |  |
| Incremental Delay (dz), s/veh |  | 0.0 |  | 0.0 | 0.0 |  |  |  |  |  |  |  |
| Initial Queue Delay ( d ), , s/veh |  | 0.0 |  | 0.0 | 0.0 |  |  |  |  |  |  |  |
| Control Delay (d). s/veh |  |  |  |  |  |  |  |  |  |  |  |  |
| Level of Service (LOS) |  |  |  |  |  |  |  |  |  |  |  |  |
| Approach Delay, s/veh / LOS |  |  |  |  |  |  |  |  |  |  |  |  |
| Intersection Delay, s/veh / LOS |  |  |  |  |  |  |  |  |  |  |  |  |

Figure 4.6 Screen shot of a part of HCS $2010^{\circledR}$ Streets result for median opening of MUT

Since similar methods have been applied for delay calculation of both median openings and crossovers at the minor street of a jughandle, it was necessary to correct the delay for both locations. To calculate the delay at median openings and crossovers at the
minor street of a jughandle, a method based on queuing theory was applied, and is described in the following section.

### 4.2.7 Delay for Median Openings of MUT and Crossovers at the Minor Street of a Jughandle Based on Queuing Theory

The delay for the system comprised of Poisson arrivals and the Exponential service served by a single server can be computed by a $\mathrm{M} / \mathrm{M} / 1$ queuing concept. The discrete random variable $\mathrm{X}(\mathrm{t})$ is said to have a Poisson distribution with a parameter of $\lambda>0$, if the probability mass function (pmf) is given by the following expression (Hillier, Lieberman, Nag and Basu, 2010).

$$
P\{X(t)=n\}=\left\{\frac{\lambda^{n} \times e^{-\lambda}}{n!}\right\}
$$

Where,

$$
\begin{aligned}
& P\{X(t)=n\}=\text { Probability mass function, } \\
& \lambda=\text { rate parameter, and } \\
& \mathrm{n}=0,1,2,3 \ldots
\end{aligned}
$$

The expected value $\mathrm{E}(\mathrm{X})$ and variance $\operatorname{Var}(\mathrm{X})$ for the Poisson distribution are both equal to rate parameter $\lambda$. The random variable $\lambda$ is said to have an exponential distribution with parameter if its probability density function (pdf) has the following expression (Banks, Carson II, Nelson and Nicol, 2009).

$$
f(t ; \lambda)=\lambda \times e^{-\lambda t}
$$

for $t \geq 0$ and

$$
\mathrm{f}(\mathrm{t} ; \lambda)=0
$$

for $t<0$

The total system delay based on the $\mathrm{M} / \mathrm{M} / 1$ concept is the sum of queue delay and the server's delays as expressed by the following equation (Hillier et al., 2010).

$$
W_{s}=\frac{\lambda}{\mu \times(\mu-\lambda)}+\frac{1}{\mu}
$$

Where,
$W_{s}=$ Total system delay,
$\lambda=$ Arrival flow rate, and
$\mu=$ Departure flow rate

The departure flow rates for the median opening and crossover are the same as the capacity of the opening or ramp junction. This is based on opposing flow, critical gap, and follow-up headway as provided by the HCM 2010 equation (equation 2.1 of this dissertation) to compute capacity of stop-controlled movement using a gap acceptance model. The follow-up headway and critical gap were calculated based on HCM equations 19-30 and 19-31 (equations 4.2 and 4.3 of this dissertation) for the respective values of

U-turn movement at median openings of MUT and right turn movement at the crossovers of a jughandle.

### 4.2.8 Delay and LOS at Signalized Intersections

HCM 2010 has provided the stepwise flow chart for the delay and LOS calculation in exhibit 18-11 for a pre-timed and actuated signal. Figure 4.7 shows the procedure for an actuated signal. Step 1 to step 4 includes the calculations of adjusted flow rate and adjusted saturation flow rate. In this study, while using HCS $2010{ }^{\circledR}$ Streets, all the saturation flow rate adjustment factors were left at default values. Since effective green time and cycle length is not known at first for an actuated signal, the estimation of the green interval duration is an iterative process. This process is described in detail in "Chapter 31: Signalized Intersections: Supplemental" of HCM 2010. According to chapter 31, the initial estimate of green interval duration for a fully actuated signal is equal to the maximum green time. The process goes through several steps until it calculates the green extension time. Finally, it computes green interval duration from average phase duration through several steps after the green extension time is calculated. The process repeats until the difference between the estimated green interval duration and the computed green interval converges by less than 0.1 s . After reaching this convergence, the actual proportion of vehicles arriving during the green phase, the phase duration, and the volume to capacity ratio are calculated. Finally, delay and LOS are computed.


Figure 4.7 HCM method of computing delay and LOS for Actuated Signal adopted from HCM 2010

The control delay for a given lane group is the sum of uniform delay $\left(d_{1}\right)$, incremental delay $\left(d_{2}\right)$, and initial queue delay $\left(d_{3}\right)$. HCM 2010 defines the uniform delay (equation 4.8) as the average delay per vehicle due to uniform arrivals, and incremental delay (equation 4.9) is the average delay per vehicle due to random arrivals.

The initial queue delay refers to unmet demand in the previous time period; it is $0 \mathrm{~s} / \mathrm{veh}$ in this study.

$$
\begin{align*}
& d_{1}=\frac{0.5 C(1-g / C)^{2}}{1-\left[\min (1, X)^{g} / C\right]} \\
& d_{2}=900 T\left[\left(X_{A}-1\right)+\frac{8 k I X_{A}}{C_{A} T}\right]
\end{align*}
$$

Where,

$$
\begin{aligned}
& C=\text { cycle length, } \\
& g=\text { effective green time for lane group, } \\
& X=\text { volume to capacity ratio }(\mathrm{v} / \mathrm{c}) \text { or degree of saturation for lane group, } \\
& T=\text { duration of analysis period (h), } \\
& k=\text { incremental delay factor that is dependent on controller settings, } \\
& I=\text { upstream filtering/metering adjustment factor, } \\
& C_{A}=\text { lane group capacity }(\text { veh } / \mathrm{h}), \text { and } \\
& X_{A}=\text { lane group v/c ratio or degree of saturation. }
\end{aligned}
$$

Since the actuated signal phase has the ability to adapt its green interval duration to serve the demand on a cycle-by-cycle basis, the K factor should be taken into account for actuated signal operations, which is expressed in the following equations:

$$
K=\left(1-2 K_{\min }\right)\left(v / C_{a}-0.5\right)+K_{\min } \leq 0.50
$$

$$
\begin{gather*}
K_{\min }=-0.375+0.354 P T-0.0910 P T^{2}+0.0089 P T^{3} \geq 0.04 \\
C_{a}=3600 \frac{g_{a} s N}{C} \\
g_{a}=G_{\max }+Y+R_{C}-l_{1}-l_{2}
\end{gather*}
$$

Where,
$C_{a}=$ available capacity for lane group served by an actuated phase (veh/h),
$K_{\text {min }}=$ minimum incremental delay factor,
$P T=$ passage Time,
$g_{a}=$ available effective green time,
$s=$ saturation flow rate,
$N=$ number of lanes,
$C=$ cycle length,
$G_{\max }=$ maximum green interval,
$Y=$ yellow interval,
$R_{C}=$ red clearance interval,
$l_{1}=$ start-up lost time, and
$l_{2}=$ end lost time

The levels of service (LOS) were computed using LOS thresholds established for the automobile mode at signalized intersections listed in Exhibit 18-4 of the HCM 2010.

The operation involved in the permitted left turn movement in an exclusive lane is also provided in "Chapter 31: Signalized Intersections: Supplemental" of HCM 2010. Two effective green times are associated with permitted left turn movement. These are the effective green time for permitted left turn operation $\left(g_{p}\right)$, and the effective green time associated with permitted left turn green time that is not blocked by an opposing queue $\left(g_{u}\right)$. The saturation flow rate for permitted left turn operation is provided in equation 3197 of HCM 2010 can be expressed as follows:

$$
S_{p}=\frac{v_{0} e^{-v_{0} t_{c g} / 3600}}{1-e^{-v_{0}}{ }^{t_{f h} / 3600}}
$$

Where,

$$
\begin{aligned}
& S_{p}=\text { saturation flow rate of permitted left turn movement, } \\
& v_{0}=\text { opposing demand of flow rate } \\
& t_{c g}=\text { critical Headway }=4.5 \mathrm{sec}, \text { and } \\
& t_{f h}=\text { follow up headway }=2.5 \mathrm{sec}
\end{aligned}
$$

This is adjusted with saturation flow rate adjustment factors to compute the saturation flow rate for lane groups with a permitted left turn operation in an exclusive lane. This saturation flow rate is ultimately used in the estimation of the capacity of permitted left turn operations in an exclusive lane.

### 4.2.9 HCS Batch Run

As mentioned in previous sections, the combinations of different levels of variable parameters created 12,960 total combinations for each of the four intersections. The network files were run in batch mode with the developed codes to compute delay. Ten random combinations were picked and run again manually as a quality check. The delay obtained from the manual run of networks was found to exactly match the delay obtained from the batch run aided by code.

### 4.3 Estimation of Fuel Consumption

The AASHTO Red Book (2010) provides a table that gives fuel consumption in gallons per minute of delay $\left(\mathrm{gal}_{\mathrm{c}, \mathrm{min}}\right)$ by vehicle type, such as small car, big car, SUV, 2axle single unit vehicle, 3-axle single unit vehicle, and combo, according to free-flow speed. This table was utilized for the computation of fuel consumption at intersections and crossovers. Six vehicle categories were combined to form two categories: cars and heavy vehicles. The $\operatorname{gal}_{c, \min }$ of the car vehicle type is the average $\mathrm{gal}_{\mathrm{c}, \min }$ values of small cars, big cars, and SUVs. Similarly, the $\operatorname{gal}_{\mathrm{c}, \min }$ of heavy vehicles is the average $\mathrm{gal}_{\mathrm{c}, \min }$ values of 2-axle single unit vehicles, 3-axle single unit vehicles, and combos. Table 4.3 shows the $\mathrm{gal}_{\mathrm{c}, \text { min }}$ of cars and heavy vehicles computed by this method. To compute fuel consumption, the delay ( $\mathrm{s} / \mathrm{veh}$ ) for each intersection was separately converted to delay in vehicle minutes for cars and trucks. The vehicle minute delay of cars and trucks are multiplied with respective $\operatorname{gal}_{\mathrm{c}, \text { min }}$ from table 4.3 to get fuel consumption by each vehicle
type. The free flow speeds were assumed to be 45 mph for the major street and 35 mph for the minor street.

Table 4.3 Fuel consumption (gallons) per minute of delay by vehicle type based on the

> AASHTO Red Book (2010)

| Free Flow Speed (mph) | Small Cars | Heavy Vehicles (Trucks) |
| :---: | :---: | :---: |
| 20 | 0.02 | 0.12 |
| 25 | 0.02 | 0.16 |
| 30 | 0.03 | 0.19 |
| 35 | 0.03 | 0.23 |
| 40 | 0.03 | 0.26 |
| 45 | 0.04 | 0.30 |
| 50 | 0.04 | 0.34 |
| 55 | 0.05 | 0.37 |
| 60 | 0.06 | 0.41 |
| 65 | 0.06 | 0.45 |
| 70 | 0.07 | 0.49 |
| 75 | 0.08 | 0.53 |

A table in the AASHTO Red Book (2010) that provides the fuel consumption in gallons per mile for auto and trucks with respect to the operating speed was referenced to calculate fuel consumption from travel delay related to MUT and jughandles. Fuel consumption in gallons was estimated considering a 45 mph operating speed for MUT to travel from the intersection to median openings and vice versa, 30 mph for a jughandle
ramp, and 45 mph along the major street. The values from the AASHTO Red Book (2010) table are also in table 4.4.

Table 4.4 Fuel consumption related to operating speed

| Speed (mph) | Gallons per Mile |  |
| :---: | :---: | :---: |
|  | Autos | Trucks |
| 5 | 0.117 | 0.053 |
| 10 | 0.075 | 0.316 |
| 15 | 0.061 | 0.254 |
| 20 | 0.054 | 0.222 |
| 25 | 0.05 | 0.204 |
| 30 | 0.047 | 0.191 |
| 35 | 0.045 | 0.182 |
| 40 | 0.044 | 0.176 |
| 45 | 0.042 | 0.170 |
| 50 | 0.041 | 0.166 |
| 55 | 0.041 | 0.163 |
| 60 | 0.040 | 0.160 |
| 65 | 0.039 | 0.158 |

### 4.4 Estimation of Emissions

This study estimated four major types of vehicular emissions: carbon monoxide (CO), oxides of nitrogen $\left(\mathrm{NO}_{\mathrm{x}}\right)$, volatile oxygen compounds (VOCs), and carbon dioxide $\left(\mathrm{CO}_{2}\right)$. Cobian, Henderson, Sudeshna, Nuworsoo, and Sullivan (2009) developed the factors to convert fuel consumption in gallons to gram units of emissions, like $\mathrm{CO}, \mathrm{NO}_{\mathrm{x}}$ and VOCs. These factors are 69.9 gram/gallon for $\mathrm{CO}, 13.6 \mathrm{gram} / \mathrm{gallon}$ for $\mathrm{NO}_{\mathrm{x}}$, and 16.2 gram/gallon for VOCs. Similarly, the U.S. Department of Energy has published a
document called "Instructions for Form EIA-1605: Voluntary Reporting of Greenhouse Gases" in 2007, which relates $\mathrm{CO}_{2}$ emissions in grams with petrol and diesel fuel consumption. The conversion factor for petrol consumption to $\mathrm{CO}_{2}$ emissions is 17.59 gram/gallon, and the conversion factor for diesel consumption to $\mathrm{CO}_{2}$ emissions is 22.37 gram/gallon. The conversions are shown in table 4.5.

Table 4.5 Relationship between fuel consumption and emissions

| Emissions | Relationship with Fuel Consumption | Source of <br> Information |
| :---: | :--- | :--- |
| CO | Fuel consumption (gallon) $* 69.9$ <br> gram/gallon | }$(2009)$ |
| $\mathrm{NO}_{\mathrm{x}}$ | Fuel consumption (gallon) <br> gram/gallon |  |
| VOCs | Fuel consumption (gallon) $* 16.6$ <br> gram/gallon | Fuel consumption (Petrol) (gallon)*17.59 <br> gram/gallon + Fuel consumption (Diesel) |
| (gallon)*22.37 gram/gallon |  |  | | Instruction for |
| :--- |
| form EIA-1605: |
| Voluntary <br> Reporting of <br> Greenhouse Gases <br> (2007) |

### 4.5 Brief Summary of Chapter

In this chapter, the operational performance of all the study intersections was performed. The control delay for signalized crossovers was computed by batch processing the networks coded in HCS $2010^{\circledR}$ Streets and queueing theory was used for computing delay at unsignalized crossovers such as median openings of MUT and
north/south crossovers of jughandle. The fuel consumption was calculated utilizing the factors from AASHTO Red Book. Similarly, the emissions were calculated out of fuel consumption utilizing the conversion factors from different literature. As a final product, the delay, fuel consumption, and emissions were calculated for each Origin-Destination (OD). These performance measures were utilized in the economic analysis included in later chapters.

## CHAPTER 5

## SENSITIVITY ANALYSIS

This chapter deals with the relative delay performance of unconventional intersections under different approach traffic volumes with respect to each other and standard signalized intersections. It includes descriptions of different types of plots used to develop decision assistance curves (DAC), which allocate the volume regions where the performance of each type of intersections can be optimal.

### 5.1 Decision Assistance Curves (DAC) - Classification

DAC refer to the boundary lines that allocate areas of optimal performance of unconventional intersections produced on plots with the major street and minor street approach traffic volumes on the X and Y axes. The development of DAC includes two steps described in the following subsections.

### 5.1.1 Clusters

The total intersection delay of all three unconventional intersections was compared with each other for all 12,960 combinations. The intersection producing the minimal delay was chosen for each combination. Since the minimal delay from the comparison was always less than the intersection delay of a standard signalized intersection, the standard intersection delay was excluded. The allowance for left turn permission is governed by some criteria. For this study, this criterion was fixed according to the plot developed by Asante et al. (1993). For two opposing lanes and a 45 mph opposing speed limit, the plots provided in Asante et al. (1993) indicated the limiting
condition of left turning vehicles as 35 vph . Hence, for a standard signalized intersection with left turn permitted along the major street, the delay results for any case with one or both of major street left turn with volumes exceeding or equal to 35 vph were omitted. The group scatter plots were developed while taking the major street approach traffic volumes, minor street approach traffic volumes, and group based on four types of intersections that produced the minimal delay into account. The scatter plot showed the clusters of each intersection in reference to the X axis as the major street approach traffic volume and the Y axis as the minor street approach traffic volume. An example scatter plot showing the clusters of each unconventional intersection is shown in figure 5.1. In figure 5.1, the four intersections MUT, CFI, jughandle, and a standard signalized intersection with left turn permitted along the major street are clustered in three different locations in the plot of major street approach traffic volume ( X axis ) and minor street approach traffic volume (Yaxis).

### 5.1.2 Application of Classifier and Development of the Equations for DAC

To separate the regions for the clusters developed as explained in section 5.1.1, the Quadratic Discriminate Analysis (QDA) was performed. The QDA was chosen over Linear Discriminant Analysis (LDA) because of three main reasons: (1) QDA allows more flexibility for covariance matrix for each class, (2) the boundary lines as observed from scatter plots were not linear, and (3) QDA classified the clusters very accurately, which can be observed from table 5.2. The DAC plots were done based on a QDA that defined the areas where the delay performance of each intersection was optimal. The


Figure 5.1 Example scatter plot showing clusters at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$
equations for the DAC developed from QDA are shown in tables 5.2 through 5.7. These equations follow the form of equation 5.1.

$$
Z=K+\left[X_{1}, X_{2}\right] \times \boldsymbol{L}+\left[X_{1}, X_{2}\right] \times \boldsymbol{Q} \times\left[X_{1}, X_{2}\right]^{T}
$$

Where,
$\mathrm{Z}=$ quadratic classifier,
$\mathrm{K}=$ constant,
$\mathrm{L}=$ linear coefficient matrix,
$\mathrm{Q}=$ quadratic coefficient matrix,
$\mathrm{X}_{1}=$ total major street approach traffic volume, and
$\mathrm{X}_{2}=$ total minor street approach traffic volume

The performance of the classifier was tested using the following performance table (table 5.1). The precision and accuracy were calculated using equations 5.2 and 5.3. The precision and accuracy of each classification are shown in tables 5.2 through 5.7. These six tables also show the re-substitution error, which is the difference between the original and predicted classification.

Table 5.1 Performance evaluation of classifier

|  |  | Conditions |  |
| :---: | :---: | :---: | :---: |
| Classifier | Prediction that a particular <br> unconventional intersection is optimal | True prediction <br> that a particular <br> unconventional <br> intersection is <br> optimal | False prediction <br> that a particular <br> unconventional <br> intersection is <br> optimal. |
|  | Prediction that a particular <br> unconventional intersection is not <br> optimal | False prediction <br> that a particular <br> unconventional <br> intersection is not <br> optimal | True prediction <br> that a particular <br> unconventional <br> intersection is not <br> optimal |

Accuracy
$=\frac{\text { Number of true predicted optimality }+ \text { Number of true predicted non optimality }}{\text { Total numbers }} 5.2$

Precision
$=\frac{\text { Number of true predicted optimality }+ \text { Number of true predicted non optimality }}{\text { Number of true predicted optimality }+ \text { Number of false predicted optimality }} 5.3$

Table 5.2 Equations of DAC (Part I)

| Coefficients |  |  |  | Combin ations | Correspon ding Figure | Corresponding | Resubsti | $\begin{array}{r} \text { Precis } \\ \text { Acc } \end{array}$ | on and racy |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| K | L | Q |  |  | $\underset{\text { A }}{\text { Appendix }}$ |  | Error | $\begin{gathered} \hline \text { Precision } \\ (\%) \\ \hline \end{gathered}$ | Accuracy (\%) |
| 3.34 | -0.02 | $3.44 \mathrm{E}-05$ | -1.07E-04 | $B F=0.5$, <br> LTP=10 <br> $\%$ and <br> $\mathrm{TP}=2 \%$ | Figure A. 4 | LT-Permitted Threshold | 0.008 | 99 | 99.17 |
|  | -0.04 | -1.07E-04 | $1.27 \mathrm{E}-03$ |  |  |  |  |  |  |
| 817.6 | -0.69 | $1.44 \mathrm{E}-04$ | $2.26 \mathrm{E}-05$ |  |  | Jughandle Threshold | 0.008 | 100 | 99.17 |
|  | -0.11 | $2.26 \mathrm{E}-05$ | $9.39 \mathrm{E}-06$ |  |  |  |  |  |  |
| 2.58 | -0.02 | 4.13E-05 | -1.27E-04 | $\mathrm{BF}=0.6$, <br> LTP=10 <br> $\%$ and <br> $\mathrm{TP}=2 \%$ | Figure A. 5 | LT-Permitted Threshold | 0.006 | 100 | 99.38 |
|  | -0.06 | $-1.27 \mathrm{E}-04$ | $1.48 \mathrm{E}-03$ |  |  |  |  |  |  |
| 652.70 | -0.55 | $1.18 \mathrm{E}-04$ | $9.22 \mathrm{E}-06$ | $\mathrm{TP}=2 \%$ |  | Jughandle <br> Threshold | 0.021 | 99 | 97.92 |
|  | -0.05 | $9.22 \mathrm{E}-06$ | $6.82 \mathrm{E}-06$ |  |  |  |  |  |  |
| 6.90 | -0.05 | $9.90 \mathrm{E}-05$ | -2.00E-04 | $\mathrm{BF}=0.7$, <br> LTP $=10$ <br> \% and <br> TP=2\% | Figure A. 6 | LT-Permitted Threshold | 0.002 | 100 | 99.79 |
|  | -0.03 | -2.00E-04 | $1.58 \mathrm{E}-03$ |  |  |  |  |  |  |
| 795.14 | -0.67 | $1.40 \mathrm{E}-04$ | 3.42E-05 |  |  | Jughandle | 0.01 | 99 | 98.96 |
|  | -0.17 | $3.42 \mathrm{E}-05$ | $4.44 \mathrm{E}-05$ |  |  | Threshold |  |  |  |
| -746.32 | 0.64 | -1.37E-04 | 7.86E-07 |  |  | MUT+LT- | 0.017 | 85 | 98.33 |
|  | 0.00 | 7.86E-07 | -5.50E-06 |  |  | Permitted Threshold |  |  |  |

Table 5.3 Equations of DAC (Part II)

| Coefficients |  |  |  | Combin ations | Corresp onding | Correspondi | Resubstitu | Precis | n and acy |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| K | L | Q |  |  | $\begin{gathered} \text { Appendi } \\ \text { x A } \\ \hline \end{gathered}$ | Figure | tion Error | Precision (\%) | Accuracy (\%) |
| 0.97 | -0.02 | $5.28 \mathrm{E}-05$ | -3.82E-05 | $\mathrm{BF}=0.5$, <br> LTP=15 <br> \% and <br> $\mathrm{TP}=2 \%$ | Figure A. 7 | LT-Permitted | 0.015 | 99 | 98.54 |
|  | 0.00 | -3.82E-05 | $1.66 \mathrm{E}-04$ |  |  | Threshold |  |  |  |
| 90.75 | -0.08 | $1.73 \mathrm{E}-05$ | $3.12 \mathrm{E}-06$ |  |  | Jughandle | 0.008 | 99 | 99.17 |
|  | -0.02 | 3.12E-06 | $1.70 \mathrm{E}-06$ |  |  | Threshold |  |  |  |
| 1.34 | -0.03 | $9.29 \mathrm{E}-05$ | -7.39E-05 | $\mathrm{BF}=0.6$, <br> LTP=15 <br> \% and <br> TP=2\% | Figure A. 8 | LT-Permitted Threshold | 0.004 | 100 | 99.58 |
|  | 0.00 | -7.39E-05 | $2.49 \mathrm{E}-04$ |  |  |  |  |  |  |
| 934.23 | -0.49 | 8.10E-05 | $1.00 \mathrm{E}-04$ |  |  | CFI | 0.002 | 100 | 99.79 |
|  | -1.5 | $1.23 \mathrm{E}-04$ | $1.00 \mathrm{E}-03$ |  |  | Threshold |  |  |  |
| 96.69 | -0.09 | $1.86 \mathrm{E}-05$ | $5.62 \mathrm{E}-06$ |  |  | Jughandle <br> Threshold | 0.033 | 99 | 96.88 |
|  | -0.03 | 5.62E-06 | $7.65 \mathrm{E}-06$ |  |  |  |  |  |  |
| 2.27 | -0.04 | $1.39 \mathrm{E}-04$ | -8.19E-05 | $\mathrm{BF}=0.7$, <br> LTP=15 <br> $\%$ and <br> $\mathrm{TP}=2 \%$ | Figure A. 9 | LT-Permitted | 0.002 | 100 | 99.79 |
|  | 0.00 | -8.19E-05 | $2.23 \mathrm{E}-04$ |  |  | Threshold |  |  |  |
| -110.91 | 0.10 | -2.22E-05 | $5.84 \mathrm{E}-07$ |  |  | MUT+LT- | 0.017 | 95 | 98.33 |
|  | 0.00 | $5.84 \mathrm{E}-07$ | -1.88E-06 |  |  | Permitted <br> Threshold |  |  |  |
| 240.24 | -0.19 | $3.72 \mathrm{E}-05$ | $2.24 \mathrm{E}-05$ |  |  | CFI <br> Threshold | 0.013 | 99 | 98.75 |
|  | -0.14 | $2.24 \mathrm{E}-05$ | $4.67 \mathrm{E}-05$ |  |  |  |  |  |  |

Table 5.4 Equations of DAC (Part III)

| Coefficients |  |  |  | Combin ations | Correspo nding <br> Figure in <br> Appendix <br> A | Correspondi ng Curves | Resubst itution Error | Precision and Accuracy |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| K | L |  |  |  |  |  |  | Precision (\%) | Accuracy (\%) |
| 617.07 | -0.52 | $1.11 \mathrm{E}-04$ | $1.37 \mathrm{E}-05$ | $\mathrm{BF}=0.5 \text {, }$ <br> LTP $=10$ |  | Jughandle <br> Threshold | 0.006 | 100 | 99.38 |
|  | -0.07 | $1.37 \mathrm{E}-05$ | 5.29E-06 | \% and | A. 13 |  |  |  |  |
| 3.34 | -0.02 | $3.44 \mathrm{E}-05$ | -1.07E-04 | $\mathrm{TP}=5 \%$ |  | LT-Permitted | 0.008 | 99 | 99.17 |
|  | -0.04 | $-1.07 \mathrm{E}-04$ | $1.27 \mathrm{E}-03$ |  |  | Threshold | 0.008 | 9 | 9.17 |
| 452 | -0.03 | $5.51 \mathrm{E}-05$ | -1.41E-04 | F=0.6, |  | LT-Permitted | 0.006 | 100 | 99.38 |
|  | -0.03 | -1.41E-04 | $1.35 \mathrm{E}-03$ | LTP=10 | Figure | Threshold | 0.006 | 100 | 9.38 |
| 466.64 | -0.40 | 8.56E-05 | $5.29 \mathrm{E}-06$ | \% and |  | Jughandle | 0.019 | 99 | 98.13 |
| 466.64 | -0.03 | 5.29E-06 | $5.78 \mathrm{E}-06$ | TP=5\% |  | Threshold |  | 99 | 98.13 |
| 6.90 | -0.05 | $9.90 \mathrm{E}-05$ | $-2.00 \mathrm{E}-04$ | $B F=0.7$, <br> LTP=10 <br> $\%$ and <br> $\mathrm{TP}=5 \%$ | Figure | LT-Permitted | 0.002 | 100 | 99.79 |
|  | -0.03 | -2.00E-04 | $1.58 \mathrm{E}-03$ |  |  | Threshold |  |  |  |
| -507.57 | 0.44 | -9.45E-05 | $1.03 \mathrm{E}-06$ |  |  | MUT+LT- | 0.02 | 86 | 98.13 |
|  | 0.00 | $1.03 \mathrm{E}-06$ | -3.73E-06 |  |  | Permitted <br> Threshold |  |  |  |
| 1007.05 | -0.81 | $1.65 \mathrm{E}-04$ | $4.01 \mathrm{E}-05$ |  |  | CFI <br> Threshold | 0.002 | 100 | 99.79 |
|  | -0.29 | $4.01 \mathrm{E}-05$ | $1.11 \mathrm{E}-04$ |  |  |  |  |  |  |

Table 5.5 Equations of DAC (Part IV)

| Coefficients |  |  |  | Combin ations | Corresp onding |  |  | Preci Acc | on and racy |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| K | L | Q |  |  | $\begin{aligned} & \text { Appendi } \\ & \text { x A } \end{aligned}$ | Curves | tion Error | Precision (\%) | Accuracy (\%) |
| 0.97 | -0.02 | 5.28E-05 | -3.82E-05 | $\mathrm{BF}=0.5$, <br> LTP=15 <br> $\%$ and $\mathrm{TP}=5 \%$ | Figure | LT-Permitted | 0.015 | 99 | 98.54 |
|  | 0.00 | -3.82E-05 | 1.66E-04 |  |  | Threshold |  |  |  |
| 80.05 | -0.07 | $1.53 \mathrm{E}-05$ | $2.85 \mathrm{E}-06$ |  |  | Jughandle | 0.010 | 99 | 98.96 |
|  | -0.02 | $2.85 \mathrm{E}-06$ | $1.98 \mathrm{E}-06$ |  |  |  |  |  |  |
| 1.34 | -0.03 | $9.29 \mathrm{E}-05$ | -7.39E-05 | $\begin{gathered} \mathrm{BF}=0.6, \\ \mathrm{LTP}=15 \\ \%, \mathrm{TP}=5 \\ \% \end{gathered}$ | Figure | LT-Permitted | 0.0042 | 100 | 99.58 |
|  | 0.00 | $-7.39 \mathrm{E}-05$ | $2.49 \mathrm{E}-04$ |  |  | Threshold |  |  |  |
| 491.65 | -0.26 | $4.14 \mathrm{E}-05$ | $7.68 \mathrm{E}-05$ |  |  | CFI Threshold | 0.004 | 100 | 99.5 |
|  | -0.82 | 7.68E-05 | $4.93 \mathrm{E}-04$ |  |  |  |  |  |  |
| -72.87 | 0.07 | -1.45E-05 | -4.36E-07 |  |  | MUT+LT- | 0.021 | 95 | 97.92 |
|  | 0.00 | -4.36E-07 | -2.66E-06 |  |  | Permitted <br> Threshold |  |  |  |
| 2.06 | -0.04 | $1.27 \mathrm{E}-04$ | -9.05E-05 | $\begin{gathered} \mathrm{BF}=0.7, \\ \mathrm{LTP}=15 \\ \%, \mathrm{TP}=5 \\ \% \end{gathered}$ | Figure A. 18 | LT-Permitted | 0.002 | 100 | 99. |
|  | -0.01 | -9.05E-05 | $3.62 \mathrm{E}-04$ |  |  | Threshold |  |  |  |
| 194.09 | -0.16 | $3.17 \mathrm{E}-05$ | $1.72 \mathrm{E}-05$ |  |  | CFI Threshold | 0.013 | 99 | 98.75 |
|  | -0.1 | $1.72 \mathrm{E}-05$ | $2.08 \mathrm{E}-05$ |  |  |  |  |  |  |
| -96.93 | 0.09 | -1.95E-05 | 5.66E-07 |  |  | MUT+LT- | 0.008 | 97 | 99.17 |
|  | 0.00 | 5.66E-07 | -1.02E-06 |  |  | Permitted <br> Threshold |  |  |  |

Table 5.6 Equations of DAC (Part V)

| Coefficients |  |  |  | Combinat ions | Corresp onding <br> Figure in Appendi $\mathbf{x}$ A | Correspondin g Curves | Resubsti tution Error | Precision and Accuracy |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| K | L | Q |  |  |  |  |  | Precision <br> (\%) | Accuracy (\%) |
| 3.34 | -0.02 | $3.44 \mathrm{E}-05$ | -1.07E-04 | $\begin{gathered} \mathrm{BF}=0.5, \\ \mathrm{LTP}=10 \% \\ \text { and } \\ \mathrm{TP}=10 \% \end{gathered}$ | Figure A. 22 | LT-Permitted | 0.008 | 99 | 99.17 |
|  | -0.04 | -1.07E-04 | $1.27 \mathrm{E}-03$ |  |  | Threshold |  |  |  |
| 504.25 | -0.43 | $9.05 \mathrm{E}-05$ | $1.30 \mathrm{E}-05$ |  |  | Jughandle <br> Threshold | 0.017 | 99 | 98.33 |
|  | -0.06 | $1.30 \mathrm{E}-05$ | 5.37E-06 |  |  |  |  |  |  |
| 2.58 | -0.02 | $4.13 \mathrm{E}-05$ | -1.27E-04 | $\begin{aligned} & \mathrm{BF}=0.6, \mathrm{~L} \\ & \mathrm{TP}=10 \%, \\ & \mathrm{TP}=10 \% \end{aligned}$ | Figure A. 23 | LT-Permitted Threshold | 0.006 | 100 | 99.38 |
|  | -0.06 | $-1.27 \mathrm{E}-04$ | 0.0014813 |  |  |  |  |  |  |
| 450.82 | -0.39 | $8.34 \mathrm{E}-05$ | $4.83 \mathrm{E}-06$ |  |  | Jughandle <br> Threshold | 0.023 | 99 | 97.71 |
|  | -0.03 | $4.83 \mathrm{E}-06$ | $1.02 \mathrm{E}-05$ |  |  |  |  |  |  |
| 6.90 | -0.05 | $9.90 \mathrm{E}-05$ | -2.00E-04 | $\begin{aligned} & \mathrm{BF}=0.7, \mathrm{~L} \\ & \mathrm{TP}=10 \%, \\ & \mathrm{TP}=10 \% \end{aligned}$ | Figure A. 24 | LT-Permitted | 0.002 | 100 | 99.79 |
|  | -0.03 | $-2.00 \mathrm{E}-04$ | $1.58 \mathrm{E}-03$ |  |  | Threshold |  |  |  |
| 802.58 | -0.66 | $1.38 \mathrm{E}-04$ | $2.47 \mathrm{E}-05$ |  |  | CFI Threshold | 0.006 | 100 | 99.38 |
|  | -0.16 | $2.47 \mathrm{E}-05$ | $5.20 \mathrm{E}-05$ |  |  |  |  |  |  |
| -510.67 | 0.44 | -9.54E-05 | $1.66 \mathrm{E}-06$ |  |  | MUT+LT- <br> Permitted <br> Threshold | 0.017 | 88 | 98.33 |
|  | -0.01 | $1.66 \mathrm{E}-06$ | -8.65E-07 |  |  |  |  |  |  |

Table 5.7 Equations of DAC (Part VI)

| Coefficients |  |  |  | Combin ations | Correspo nding Figure in Appendix A | Correspondin g Curves | Resubstitu tion Error | Precision and Accuracy |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| K | L | Q |  |  |  |  |  | Precision <br> (\%) | Accurac $\mathrm{y}(\%)$ |
| 0.617 | -0.02 | 5.04E-05 | -4.64E-05 | $\begin{gathered} \mathrm{BF}=0.5, \\ \mathrm{LTP}=15 \\ \% \text { and } \\ \mathrm{TP}=10 \% \end{gathered}$ | $\begin{aligned} & \text { Figure } \\ & \text { A. } 25 \end{aligned}$ | LT-Permitted | 0.013 | 99 | 98.75 |
|  | -0.01 | -4.64E-05 | $2.16 \mathrm{E}-04$ |  |  | Threshold |  |  |  |
| 78.35 | -0.07 | $1.51 \mathrm{E}-05$ | $3.23 \mathrm{E}-06$ |  |  | Jughandle | 0.02 | 99 | 98.13 |
|  | -0.02 | $3.23 \mathrm{E}-06$ | $3.52 \mathrm{E}-06$ |  |  | Threshold |  |  |  |
| 1.33 | -0.03 | $9.29 \mathrm{E}-05$ | -7.39E-05 | $\begin{gathered} \mathrm{BF}=0.6, \\ \mathrm{LTP}=15 \\ \% \text { and } \\ \mathrm{TP}=10 \% \end{gathered}$ | $\begin{aligned} & \text { Figure } \\ & \text { A. } 26 \end{aligned}$ | LT-Permitted Threshold | 0.004 | 100 | 99.58 |
|  | 0.00 | -7.39E-05 | $2.49 \mathrm{E}-04$ |  |  |  |  |  |  |
| 314.8 | -0.20 | $3.57 \mathrm{E}-05$ | $4.51 \mathrm{E}-05$ |  |  | CFI Threshold | 0.006 | 100 | 99.38 |
|  | -0.38 | $4.51 \mathrm{E}-05$ | $1.88 \mathrm{E}-04$ |  |  |  |  |  |  |
| -71.55 | 0.066 | -1.45E-05 | $5.68 \mathrm{E}-07$ |  |  | MUT+LTPermitted Threshold | 0.017 | 95 | 97.92 |
|  | -0.001 | 5.68E-07 | $-2.53 \mathrm{E}-06$ |  |  |  |  |  |  |
| 1.96 | -0.043 | $1.40 \mathrm{E}-04$ | -9.79E-05 | $B F=0.7$, <br> LTP=15 <br> \% and $\mathrm{TP}=10 \%$ | Figure A. 27 | LT-Permitted | 0.0042 | 100 | 99.58 |
|  | 0.008 | -9.79E-05 | $2.45 \mathrm{E}-04$ |  |  | Threshold |  |  |  |
| $\begin{gathered} 159.5 \\ 7 \end{gathered}$ | -0.13 | $2.75 \mathrm{E}-05$ | $1.19 \mathrm{E}-05$ |  |  | CFI Threshold | 0.017 | 99 | 98.33 |
|  | -0.06 | $1.19 \mathrm{E}-05$ | $1.04 \mathrm{E}-05$ |  |  |  |  |  |  |
| 93.16 | -0.08 | 1.88E-05 | -5.34E-07 |  |  | MUT+LT- | 0.010 | 96 | 98.96 |
|  | 0.00 | -5.34E-07 | $3.55 \mathrm{E}-07$ |  |  | Permitted <br> Threshold |  |  |  |

### 5.1.3 Discussion on Developed DAC

The QDA was used to develop the DAC for all 12,960 combinations under 27 combinations of three levels: of balance factor (BF), left turn percentage (LTP), and truck percentage (TP). Each combination of BF, LTP and TP comprises of 480 volume combinations including 48 volume levels of total major street volumes and 10 volume levels of total minor street volumes. Hence, there would be 27 combinations of BF, LTP and TP with each 480 volume combinations with the total of 12960 data sets. The obtained 27 plots with thresholds are included in Appendix A in figure A. 1 to figure A.27. The example study on how to use DAC plots is included in Appendix C. The following patterns were observed from the DAC:

1. For a low percentage of left turns (5\%), MUT performed optimally on all conditions of BF and TP under all levels of major street approach traffic volume and minor street approach traffic volume from a delay-saving standpoint. A standard signalized intersection with left turn permitted along the major street performed optimally in very low minor street approach traffic volumes (less than or equal to 50 vph ) in a linear fashion as shown in the figure 5.2. The range of major street approach traffic volumes where a standard signalized intersection with left turn permitted along the major street appeared in the figures and are shown in table 5.8.
2. For a medium percentage of left turns ( $10 \%$ ) and BF at 0.5 and 0.6 , the threshold between MUT and a jughandle was found to be approximately between 2200 vph and 2400 vph of major street approach traffic volume. However, the threshold flared
toward the left to provide a wide area for the optimal region for the jughandle as minor street approach traffic volume increased. From this, it can be inferred that for this particular condition, a jughandle performed better at high major street volumes (greater than or equal to 2200 vph ), and its performance increased further when the

Table 5.8 Total major street approach traffic volume range for optimality of standard signalized intersection with left turn permitted along the major street

| Combinations | Corresponding <br> Figure in Appendix <br> A | Total Major Street Approach Traffic <br> Volume Ranges for Standard <br> Signalized Intersection with LT- <br> Permitted along Major Street (vph) |
| :---: | :---: | :---: |
| $\mathrm{BF}=0.5, \mathrm{LTP}=$ <br> $5 \%, \mathrm{TP}=2 \%$ | Figure A.1 | $900-1350$ |
| $\mathrm{BF}=0.6, \mathrm{LTP}=$ <br> $5 \%, \mathrm{TP}=2 \%$ | Figure A.2 | $800-1100$ |
| $\mathrm{BF}=0.7, \mathrm{LTP}=$ <br> $5 \%, \mathrm{TP}=2 \%$ | Figure A.3 | $700-950$ |
| $\mathrm{BF}=0.5, \mathrm{LTP}=$ <br> $5 \%, \mathrm{TP}=5 \%$ | Figure A.10 | $900-1350$ |
| $\mathrm{BF}=0.6$, LTP $=$ <br> $5 \%, \mathrm{TP}=5 \%$ | Figure A.11 | $750-1100$ |
| $\mathrm{BF}=0.7, \mathrm{LTP}=$ <br> $5 \%, \mathrm{TP}=5 \%$ | Figure A.12 | $650-950$ |
| $\mathrm{BF}=0.5, \mathrm{LTP}=$ <br> $5 \%, \mathrm{TP}=10 \%$ | Figure A.19 | $850-1350$ |
| $\mathrm{BF}=0.6, \mathrm{LTP}=$ <br> $5 \%, \mathrm{TP}=10 \%$ | Figure A.20 | $750-1100$ |
| $\mathrm{BF}=0.7, \mathrm{LTP}=$ <br> $5 \%, \mathrm{TP}=10 \%$ | Figure A.21 | $700-950$ |

minor street approach traffic volume increased. Jughandle has good performance under high major street volume compared to MUT because the conflicting traffic for diverted left turning traffic of jughandle is the minor street traffic which is lower in volume than conflicting major street traffic for MUT. Under the presence high major street conflicting traffic, when the minor street traffic increases, it adds more left turning vehicles at median opening and hence delay at median openings will increase drastically. However, for jughandle, since minor street traffic doesn't add left turning vehicles, the delay will increase because of increment in conflicting minor street traffic volume but at much lower rate compared to MUT. That is why the optimal region of jughandle expands with the increasing minor street traffic at $10 \%$ left turning condition at balance factors of 0.5 and 0.6 . Still, the higher portion of the region was occupied by MUT, and there was no CFI region for this particular condition. Figure 5.3 represents this pattern. When the balance factor increased to 0.7 for the same left turn percentage (10\%), CFI was introduced to the high major street approach traffic volume (greater than or equal to 2200 vph ) and high minor street approach traffic volume region (greater than or equal to 250 vph ), as shown by figure 5.4. From this, it can be inferred that high left turns on any major street approach traffic volume and high minor street approach traffic volume (greater than or equal to $250 \mathrm{vph})$ conditions favor the application of CFI.
3. For a high percentage of left turns ( $15 \%$ ) and BF at 0.5 , which represents the balance condition under which both approaches on the major street have the same volume of
traffic, the thresholds of the jughandle shifted toward the left, between 1800 vph to 2000 vph major street approach traffic volume. The threshold flared toward the left to provide a wide area for the optimal region for the jughandle as the minor street approach traffic volume increased. From this, it can be inferred that at a balanced condition, the jughandle performed better at high major street volumes (greater than $1800 \mathrm{vph})$ and performed even better when the minor street approach traffic volume increased. The reason behind this pattern is same as the reason behind the pattern at medium left turn percentage (15\%) at balance factors of 0.5 and 0.6. Still, the higher portion of the region was occupied by MUT, and there was no CFI region at this particular condition. Figure 5.5 represents this pattern.

Similarly, when the BF increases from 0.5 to 0.6 , the CFI was introduced in the region of high major street approach traffic volume (greater than 1900 vph ) and high minor street approach traffic volume (greater than or equal to 350 vph ). With a further increase in BF, from 0.6 to 0.7, the optimal region of CFI extended to low minor street approach traffic volume ( 50 vph ). This can be visualized from figure 5.6 and figure 5.7. From this, it can be conferred that under high left turning volumes on both approaches, the unbalanced flow conditions also led to increased left-turning volume at a high major street approach traffic volume, which ultimately favored CFI to serve the high left-turning volume.
4. The performance of a standard signalized intersection with left turn permitted on the major street was found optimal only on very low total major street approach traffic
volume and very low total minor street approach traffic volume for medium and high percentage of left turns. The volume ranges were a minimum of 150 vph to a maximum of 650 vph for the major street approach traffic and a minimum of 50 vph to a maximum of 100 vph for the minor street approach traffic under $10 \%$ left turn traffic conditions. Similarly, the ranges were a minimum of 50 vph to a maximum of 450 vph for the major street approach traffic and a minimum of 50 vph to a maximum of 200 vph for the minor street approach traffic under $15 \%$ left turn traffic conditions.
5. Effect of truck percentage was distinct only at a high left turn percentage (15\%) and a high balance factor (0.7), where high truck percentage favors the increment of the optimal region of CFI. This is clear from figure 5.8, figure 5.9, and figure 5.10. The reason behind this is the high delay causation at median openings of MUT and north-south crossovers of jughandle due to large gap requirement for heavy vehicles. The delay is relatively low as CFI provides exclusive phase for left turning vehicles at crossover displaced left turn lane.
6. From the plots, it can be conferred that the standard signalized intersection was never optimal under studied scenarios. This also implies for all the studied conditions, there exists at least one unconventional intersection or permitted left turn alternative that produces lower delay than conventional signalized intersection. However, it is imperative to look at cost aspect as well while making decision for selection. The cost aspect is included in chapter 6 of this dissertation.


Figure 5.2 Representative DAC at low LTP $(\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%)$


Figure 5.3 DAC for unconventional intersection at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%$ and $\mathrm{TP}=2 \%$


Figure 5.4 DAC for unconventional intersection at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%$ and $\mathrm{TP}=5 \%$


Figure 5.5 DAC for unconventional intersection at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%$ and $\mathrm{TP}=2 \%$


Figure 5.6 DAC for unconventional intersection at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%$ and $\mathrm{TP}=10 \%$


Figure 5.7 DAC for unconventional intersection at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%$ and $\mathrm{TP}=10 \%$


Figure 5.8 DAC for unconventional intersection at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%$ and $\mathrm{TP}=2 \%$


Figure 5.9 DAC for unconventional intersection at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%$ and $\mathrm{TP}=5 \%$


Figure 5.10 DAC for unconventional intersection at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%$ and $\mathrm{TP}=10 \%$

### 5.2 Decision Assistance Curves (DAC)-Contour

From DAC, it is possible to select the optimal choice among three unconventional intersections for any volume criteria. Furthermore, DAC was supplemented with additional information about how to obtain the amount of delay loss or benefit the optimal intersection would have for those volume criteria. This was done by developing two types of contour plots. The first type of contour plot was developed for the highest delay difference between the left turn movement of a standard signalized intersection, and three intersections, including MUT, jughandle, and standard signalized intersections with left turn permitted along the major street, in seconds per vehicle. The second type of contour plot was developed for all four intersections, indicating the total intersection delay difference with respect to a standard signalized intersection in seconds per vehicle. In case of contour, every intersection would have 12960 data sets for 27 combinations of BF, LTP, and TP with one combination comprising 480 volume combinations. Hence, one contour plot represents 480 volume combinations.

### 5.2.1 Contour Plots for Difference in Left Turn Delay

MUT, jughandle, and standard signalized intersections with left turn permitted along the major street were chosen for these plots because the left turning traffic on a MUT and jughandle are expected to have higher delay due to additional travel delay and delay at crossovers. Similarly, a mixed effect is expected in the case of standard signalized intersections with left turn permitted. The plots were developed for the meshgrid of minor approach traffic volume ( 50 vph to 500 vph ) and major approach traffic volume ( 50 vph to 2400 vph ) for 27 combinations of the three levels: balance
factor, truck percentage, and left turn percentage. The two example plots at $0.7 \mathrm{BF}, 15 \%$ LTP, and $10 \%$ TP are shown in figures 5.11 and 5.12 for MUT and jughandle, respectively. The example contour plot for standard signalized intersections with left turn permitted along the major street is shown in figure 5.13. The negative values of the contour represent the delay saving capability of unconventional intersections for left turns compared to a standard signalized intersection. The positive values of contour represent when unconventional intersections have higher delay than a standard signalized intersection.

The contour plots indicated that the left turn delay of critical left turn movement for MUT was always higher than that of a signalized intersection. The delay difference increased at a higher rate for higher major street approach traffic volumes. In the combinations with a high left turning volume, the left turn delay was exceptionally higher at high major approach traffic volumes, even reaching the condition of failure. The condition of failure occurred as the left-turning volumes exceeded the capacity of the U turn openings. In figure 5.11, the condition of failure is indicated by a contour line designated with the value of 9999 . All of the MUT contour plots are included in Appendix A of this dissertation.

Unlike MUT, the contour plot indicated that the critical left turn delay difference between jughandles and standard signalized intersections was less, and even negative, for higher major street and minor street approach traffic volumes, showing less delay or delay-saving conditions for left turn movements. As shown in figure 5.12, there are some circular areas enclosed with a contour of the same magnitude. These areas were formed


Figure 5.11 Contour plot for critical left turn delay difference between MUT and standard signalized intersection at BF=0.7, $\mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure 5.12 Contour plot for critical left turn delay difference between jughandle and standard signalized intersection at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure 5.13 Contour plot for critical left turn delay difference between standard signalized intersection with left turn permitted along major street and standard signalized intersection at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$
when there was no change in delay for that particular volume condition within those areas. For this particular condition of BF, LTP, and TP, the distance between contours at the same intervals was less at high major street approach traffic volume regions than low major street approach traffic volumes, showing the delay change is rapid with the increase of major street approach traffic volume. All the contour plots for the jughandle are included in Appendix A of this dissertation. The contour plot of standard signalized intersections with left turn permitted along the major street indicated negative contour at a very low total major street approach traffic volume, which increased and turned to positive values with the increment of total major street approach traffic volume showing delay saving at very low major street volumes and delay loss when the volume increased. Since left turn permission is allowed for a limited number of left turn volumes depending on the number of lanes in the conflicting road and speed limit of conflicting vehicles, the plots are blank on the higher level of major street approach traffic volume.

### 5.2.2 Contour Plots for Difference in Total Intersection Delay

Contour plots for the difference in total intersection delay were developed for all four intersections. The negative values of the contour represent the delay-saving capability of unconventional intersections and standard signalized intersections with left turn permitted along the major street compared to standard signalized intersections. The positive contour values represent unconventional intersections that have a higher delay than a standard signalized intersection. The example delay difference plots are shown in figures 5.14 through 5.17. The plots indicated that the delay saving capability of MUT decreased with an increasing major street approach traffic volume. Under the presence of


Figure 5.14 Contour plot for total intersection delay difference between MUT and standard signalized intersection at $\mathrm{BF}=0.7$,

$$
\mathrm{LTP}=15 \%, \mathrm{TP}=10 \%
$$



Figure 5.15 Contour plot for total intersection delay difference between CFI and standard signalized intersection at $\mathrm{BF}=0.7$,

$$
\mathrm{LTP}=15 \%, \mathrm{TP}=10 \%
$$



Figure 5.16 Contour plot for total intersection delay difference between jughandle and standard signalized intersection at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure 5.17 Contour plot for total intersection delay difference between standard signalized intersection with left turn permitted along major street and standard signalized intersection at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$
higher left turning volumes, the MUT system fails. The MUT intersection failure is depicted in the contour plot with a value of 999 . The plots also indicated that the delay saving capability of CFI was good for a high major street approach traffic volume under the presence of a high minor street approach traffic volume.

The delay-saving capability of jughandles was also good for a higher major street approach traffic volume, but it decreased with a high minor street approach traffic volume. For that specific condition, the delay-saving capability of jughandles increased with minor street approach traffic volume for low to medium major street approach traffic volumes. The contour plot for standard signalized intersections with left turn permitted along the major street also showed delay saving for the provided condition. The plots are included in Appendix A of this dissertation. The example procedure for how to use DAC-classifier and DAC-contour for decision making about suitable intersections is provided in Appendix B.

### 5.2.3 Delay Performance Information for Projected Volumes from Contour Plot

The contour plots in conjunction with the plot of projected volumes can be used to find delay savings information for projected volumes. This can be more clearly understood by referring to an example of MUT with the contours of total delay difference, shown in figure 5.18 . This is a case when major and minor street approach traffic volumes are increasing at the rate of $2 \%$ annually. The growth rate curves for the growth rate of $1 \%, 2 \%, 3 \%, 4 \%$ and $5 \%$ are also included in Appendix A. Let us consider a case with a major street approach traffic volume of 1600 vph and a minor
street approach traffic volume of 250 vph . Point A, which lies between the contours of magnitude -5 and -6 , represents the particular delay savings of about $5.4 \mathrm{~s} /$ veh for the base year. Now, the delay savings for the projected volume, if both approach traffic volumes increase at the same rate of $2 \%$ annually, can be calculated by extending line OA. The delay savings for the projected volume for the 10th year can be estimated by locating point B in line OA , as shown in figure 5.18. B represents a delay savings of approximately $3.5 \mathrm{~s} / \mathrm{veh}$. Hence, the delay savings for the projected volumes of 1600 vph for the major street and 250 vph for the minor street for the 10th year is $3.5 \mathrm{~s} / \mathrm{veh}$. By projecting line OA to the contour of magnitude 999 , which represents the failure case, it can be observed that if both volumes of approach keep increasing by $2 \%$, MUT will fail in 15.5 years. If the rates of increment of major and minor street approach traffic volumes are different, it is necessary to use different projection plots.

It is possible to find the delay of any volume for any percentage of annual increments in minor street total approach traffic by projecting the line expressed by equation 5.4 originating from the base year point.

$$
\begin{gathered}
\text { Slope of Projection Line }=\frac{Y \times\left(1+\frac{n}{100}\right)-Y}{X \times\left(1+\frac{m}{100}\right)-X} \\
=\frac{Y n}{X m}
\end{gathered}
$$



Figure 5.18 Delay savings for projected volumes (case study: MUT total intersection delay different at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%$,

$$
\mathrm{TP}=10 \%)
$$

Where,
$X=$ total major street approach traffic volume for base year, $\mathrm{Y}=$ total minor street total approach traffic volume for base year, $m=$ the annual percentage increment of major street approach traffic volume, and $\mathrm{n}=$ annual percentage increment of minor street approach traffic volume

### 5.3 Brief Summary of Chapter

This chapter explained the process in the development of DAC utilizing O-D delay obtained from the method as explained in the previous chapter. DAC were developed in the form of plots such as DAC-Classifier plots and DAC-Contour plots. These plots classified the optimal region of delay performance for each intersection as well as quantify the delay savings or loss related to them. This chapter also included the holistic pattern observed from those plots. These plots can act as decision support system during the selection of a suitable intersection. Additionally, this chapter described an easy use of graphical method for the calculation of operational benefits over the life of the intersection.

## CHAPTER 6

## ECONOMIC ANALYSIS

This chapter is comprised five major sections: (1) estimation of marginal agency cost, (2) monetization of marginal user's and non-user's benefits, (3) the life cycle cost analysis (LCCA), (4) the development of a spreadsheet tool to perform LCCA, and (5) a sample case study of LCCA using the spreadsheet tool. The outcome of this chapter will provide marginal net present value (NPV) and benefits to cost ratio (B/C) pertaining to the three unconventional intersections, which can serve as a basis for deciding the optimal alternative of unconventional intersections.

### 6.1 Marginal Agency Cost

The marginal agency cost includes both the marginal agency cost for new construction of unconventional intersections and retrofitting unconventional intersections over standard signalized intersections. The word "marginal" stands for the difference in quantity or cost due to the new construction of unconventional intersections or their retrofits with respect to standard signalized intersections. The marginal agency cost includes the costs of construction, preliminary engineering, and additional operation and maintenance.

The marginal construction quantities for new construction were estimated based on the additional pavement requirement, additional signals and installations with related accessories, and the additional right of way needed for new unconventional intersections as compared to standard signalized intersections. The construction quantities for retrofits
were estimated based on the additional pavement requirement, the removal of existing pavements, additional signals with their installations and related accessories, etc., needed while retrofitting standard signalized intersections. NDOR's latest "English Average Unit Price (AUP) Summary July 2012-June 2013," found on their website under Item History and Info, was referenced for unit price information. The items considered for the quantity estimates and the related unit prices are shown in table 6.1 and table 6.2. The unit price of land (\$4142.5/acre) was calculated by referencing the "United States Land Values 2012 Summary" (2012) published by the United States Department of Agriculture. The unit

Table 6.1 Unit prices of item considered in estimation of construction quantities (Part I)

| Standar ditem no. | Item | Unit | Rate (US <br> \$) | Source <br> of informat ion |
| :---: | :---: | :---: | :---: | :---: |
| 1101 | Concrete Pavement Removal | SY | 6.81 |  |
| 3075.56 | 10" Doweled Concrete Pavement, Class 47 B-3500 (Including Median Opening) | SY | 30.59 | Average Unit Price (AUP), Summary |
| 1010 | Excavation (1.5') | CY | 3.26 |  |
| 1122.01 | Remove Concrete Median Surfacing (6' Median) | SY | 5.90 |  |
| A724.01 | Relocate Traffic Signal | Each | 470.00 |  |
| A006.98 | Vehicle Detector, Type TD-A Performed | Each | 263.69 | $\begin{gathered} \text { July } \\ \text { 2010- } \end{gathered}$ |
| A001.7 | Pull Box, Type PB-7 | Each | 1, 010.00 |  |
| A070.22 | 4 Inch Conduit in Trench | LF | 5.91 | 2013 |
| A072.20 | 4 Inch Conduit in Roadway | LF | 7.83 | (accessed on 2014) |
| A077.26 | 16/C 14 AWG Traffic Signal Cable | LF | 3.98 |  |
| A079.01 | 2/C \#14 AWG Detector Lead-In Cable | LF | 1.46 |  |
| 7320.27 | Traffic Sign and Post | Each | 295.85 |  |

price of real estate land (\$2,590/acre), cropland (\$4,480/acre), irrigable land ( $\$ 6,000 /$ acre ), and non-irrigable land ( $\$ 3,500 /$ acre $)$ were averaged. The preliminary engineering cost (PE) involves expenses for activities from planning to the final design of a project (Turochy, Hoel and Doty, 2001). According to Turochy et al. (2001), most state DOTs consider the PE cost to range from $5 \%$ to $20 \%$ of construction costs depending on the project size and scope. Remaining in that range, this study considered the PE cost to be $10 \%$ of the construction cost. Contingency was assumed to be $20 \%$ of the construction

Table 6.2 Unit prices of item considered in estimation of construction quantities (Part II)

| Standar ditem no. | Item | Unit | Rate (US <br> \$) | Source of information |
| :---: | :---: | :---: | :---: | :---: |
| 7500.22 | Right Arrow Performed Pavement Markings | Each | 420.00 | Average Unit Price (AUP), Summary July 2010-June 2013, NDOR (accessed on 2014) |
| 7500.25 | Through and Left Arrow Performed Pavement Markings | Each | 483.00 |  |
| 3017.4 | Concrete Class 47B-3000 Median Surfacing | SY | 31.05 |  |
| A016.8 | Mast Arm Signal Pole, Type MP-60 | Each | 8,500.00 |  |
| A504.81 | Install Mast Arm Signal Pole | Each | 3,700.00 |  |
| A 703.00 | Relocate Mast Arm | Each | 1,470.00 |  |
| A003.10 | Traffic Signal, Type TS-1 | Each | 493.89 |  |
| A501.00 | Install Traffic Signal, Type TS-1 | Each | 242 |  |
| 7496.05 | 5" Yellow Permanent Pavement Markings | LF | 0.19 |  |
| 7495.55 | 5" White Permanent Pavement Markings | LF | 0.4 |  |
| 7495.12 | 12 " Yellow Permanent Pavement Marking Paint | LF | 0.5 |  |
| N/A | Additional Land | Acre | 4,142.50 | USDA (2012) |

cost with reference to Boddapati (2008). The unit price O\&M for CFI was estimated based on the service requirement for additional signal heads, detectors, signal retiming costs, and power supply costs. Similarly for MUT and jughandle, the unit price of O\&M was fixed based on the cost of landscaping the medians and areas enclosed by the reverse ramps. The agency costs were monetized by multiplying the quantities of each item by their respective unit prices. The computed marginal costs of all three unconventional intersections, considering new construction and retrofits, are shown in table 6.3. Since the marginal cost of the new construction of a standard signalized intersection with left turn permitted along the major street is lower than that of a standard signalized intersection, it is shown as negative value. The marginal cost estimate tables for new construction and retrofits for all four intersections are included in Appendix C.

### 6.2 Marginal User's and Non-User's Benefit and their Monetization

The user's benefit pertains to the savings due to the reduction in delay and fuel consumption when new unconventional intersections or standard signalized intersections with left turn permitted along the major street are constructed instead of signalized intersections, or a standard signalized intersection is retrofitted with an unconventional intersection or a standard signalized intersection with left turn permitted along the major street. Similarly, the non-user's benefit pertains to the savings due to reduction in emissions when new unconventional intersections or standard signalized intersections with left turn permitted along the major street are constructed instead of signalized intersections, or a standard signalized intersection is retrofitted with an unconventional

Table 6.3 Computed marginal cost of unconventional intersections

| Intersection type | Construction Cost + Soft <br> Cost including Contingency <br> (US \$) |  | Operation and Maintenance <br> Cost <br> (US \$) |  |
| :---: | :---: | :---: | :---: | :---: |
|  | New <br> construction | Retrofit | New <br> construction | Retrofit |
| MUT | $36,762.81$ | $680,426.26$ | 2,000 | 2,000 |
| CFI | $279,226.41$ | $439,799.44$ | 24,000 | 2,4000 |
| Jughandle | $64,551.15$ | $64,635.13$ | 2,000 | 2,000 |
| Standard Signalized <br> Intersection with <br> Left Turn Permitted <br> along Major Street | $-10,334.96$ | $1,393.21$ | 0 | 0 |

intersection or with a standard signalized intersection with left turn permitted along the major street. These are calculated by subtracting the amount of each item produced by a standard signalized intersection from the amount of each item produced by these intersections. If the deducted value is negative, it is called the cost or a negative benefit. Unit prices of each benefit were calculated by our own rate analysis or by referencing past literature. The unit price of time (price of delay) was considered as $\$ 16.79 /$ hour as provide by 2012 Urban Mobility report. The unit prices of diesel and petrol were calculated averaging the 2012 average gas price for Nebraska, provided by AAA's Fuel Gauge Report (petrol: $\$ 3.704 /$ gallon, diesel: $\$ 3.956 /$ gallons). The unit price of $\mathrm{CO}_{2}$ $(\$ 0.02 / \mathrm{kg})$ was referenced from the 2010 Annual Supplement to National Institute of

Standards and Technology (NIST) Handbook published by the U.S. Department of Energy. The unit price of CO (\$200/ton) was referenced from a technical paper by Bishop et al. (1993). Similarly, unit prices for $\mathrm{NO}_{\mathrm{x}}\left(\$ 250 /\right.$ ton/year) and $\mathrm{VOC}_{\mathrm{s}}$ (\$180/ton/year) were referenced from Muller and Mendelson (2009) considering median damage cost. The unit prices are also listed in table 6.4. These marginal benefits were monetized by multiplying the quantities with respective unit prices.

Table 6.4 Unit prices of items

| Items | Unit prices | Source of Information |
| :---: | :---: | :--- |
| Delay | $\$ 16.79 /$ hour | 2012 Urban Mobility Report |
| Petrol | $\$ 3.704 /$ Gallons |  |
| Diesel | $\$ 3.956 /$ Gallons |  |
| $\mathrm{CO}_{2}$ | $\$ 0.02 / \mathrm{Kg}$ | U.S. Department of Energy: NIST <br> $(2010)$ |
| CO | $\$ 200 /$ ton | Bishop et al. (1993) |
| $\mathrm{NO}_{x}$ | $\$ 250 /$ ton/year | Muller and Mendelson (2009) |
| $\mathrm{VOC}_{s}$ | $\$ 180 /$ ton/year |  |

### 6.3 Life Cycle Cost Analysis (LCCA)

The LCCA was performed on monetized agency, user's and non-user's marginal costs, to determine the net present value (NPV) and benefit to cost ratio (B/C) of the new
construction and retrofits of the unconventional intersections as well as standard signalized intersections with left turn permitted along the major street. The life cycle period of the retrofits was assumed to be 20 years and the discount rate was assumed to be $3 \%$ with no inflation for each year (Boddapati, 2008). The annual increase of traffic was considered $2 \%$ for major streets and $1 \%$ for minor streets. The delay for each projected volume for a 20-year period was estimated by batch running HCS 2010 Streets ${ }^{\circledR}$. The respective fuel consumption and emissions and their annual costs were estimated. The operation and maintenance cost was assumed to be the same throughout the life cycle period. The NPV was estimated using the following equations:

$$
\begin{aligned}
& \text { NPV of Total } \\
& =\text { NPV of Benefits }- \text { NPV of } O \& M \text { Cost }- \text { Construction Cost } \\
& \text { - PE Cost } \\
& \text { Benefit to Cost Ratio ( } B / C \text { ) } \\
& =\text { NPV of Benefits/\{NPV of O \& M Cost } \\
& + \text { (Construction Cost } \\
& + \text { PE Cost))\} } \\
& \text { NPV of } O \text { \& M Cost } \\
& =\left(\frac{1}{i}\right) \\
& \times\left\{1-\frac{1}{(1+i)^{N}}\right\} \\
& \text { NPV of benefits } \\
& =\sum_{N=0}^{20} P_{N} \\
& \times \frac{1}{(1+i)^{N}}
\end{aligned}
$$

Where,

$$
\begin{aligned}
& \mathrm{N}=\text { life cycle period, } \\
& \mathrm{i}=\text { discount rate }(3 \%) \text {, and } \\
& \mathrm{P}_{\mathrm{N}}=\text { yearly negative or positive benefits }
\end{aligned}
$$

If any retrofits or new unconventional intersections failed due to high demand in any year throughout life cycle period, the NPV of those retrofits were calculated assuming a reduced life cycle period. The reduced life cycle period equals the time period up to which intersection operation is feasible. This case is applicable for MUT and jughandle because they were evaluated with $\mathrm{M} / \mathrm{M} / 1$ queues, where the server's capacity should not be exceeded by demand. It is because the queuing system works until the utilization factor (ratio of demand and service capacity) remains less than 1.

### 6.4 Development of a Spreadsheet Tool to Perform Life Cycle Cost Analysis

This study developed a Microsoft Excel-based tool interfaced with HCS 2012 ${ }^{\circledR}$ that can estimate a measure of effectiveness of operational performance, such as delay, fuel consumption, and emissions, and also can perform the life cycle cost analysis. The spreadsheet tool has four parts of operation: (1) the estimation of delay, fuel, and emissions in conjunction with HCS $2012^{\circledR}$, as well as their projection for each year in the life cycle period of the intersections; (2) the marginal cost estimate of user's and nonuser's benefits with respect to standard signalized intersections and monetization; (3) the estimation and monetization of construction costs, soft costs, and operation and
maintenance costs; and (4) a life cycle cost analysis to estimate the NPV of benefits and the corresponding B/C of MUT, CFI, jughandle, and standard signalized intersections with left turn permitted along the major street. This spreadsheet can function as a decision assistance tool to decide the best unconventional intersection design under a user's defined criteria. The tool is named as "SILCC" (Signalized Intersection Life Cycle Cost Analysis).

### 6.5 A Case Study of LCCA using SILCC

For a case study, the volume pattern for rural roads was developed, following one of the 24-hour data patterns provided by Williams and Ardekani (1996). This pattern is shown in figure 6.1. The delay, fuel consumption, and emissions were estimated corresponding to the 24 hour volume data, using SILCC for the 20 -year life cycle period and the specifications of $10 \%$ truck and $5 \%$ left turning traffic and the default annual increment in traffic ( $2 \%$ on the major street and $1 \%$ for the minor street). Additionally, the default lane configuration of a four-lane major street at 45 mph and a two-lane minor street with at 35 mph were considered. The construction estimate for retrofits and new construction for unconventional intersections along with standard signalized intersections with left turn permitted along the major street that were used were the same as those discussed in section 6.1. The corresponding default rates of items used were as mentioned in previous sections. SILCC provided the results from LCCA as displayed in table 6.5. The result indicated that MUT would have the highest NPV of the net benefits for both cases, but due to the high construction cost of a retrofit, the $\mathrm{B} / \mathrm{C}$ is lower than that of a
jughandle. The ranking of alternatives for retrofits according to their B/C was found to follow the hierarchical order of (1) jughandle, (2) MUT, and (3) CFI. However for new construction, the ranking of alternatives according to $\mathrm{B} / \mathrm{C}$ was found to follow the hierarchical order of (1) MUT, (2) jughandle, (3) CFI. All the unconventional intersections were found to have a $\mathrm{B} / \mathrm{C}$ greater than 1 , indicating that they were more beneficial than standard signalized intersections for this particular condition. Standard signalized intersections with left turn permitted along the major street were not applicable as one or both of left turn volumes along major street during 24 hr period exceeded limiting criteria of left turn permission.


Figure 6.1 Volume pattern for a rural road

Table 6.5 LCCA result for case study

| Cases | LCCA Outcomes | MUT | CFI | Jughandle | Standard <br> Signalized Intersection with Left Turn Permitted along Major Street |
| :---: | :---: | :---: | :---: | :---: | :---: |
| New <br> Construct ion | Net Present Value (NPV) of Marginal Net Benefit (US \$) | $\begin{gathered} 4,331 \\ 748 \end{gathered}$ | $\begin{aligned} & 313, \\ & 233 \end{aligned}$ | 2, 255, 279 | 10,335 |
|  | Marginal Benefit to Cost ratio (B/C) | 66.12 | 1.49 | 24.91 | 0 |
|  |  |  |  |  |  |
| Retrofits | Net Present Value (NPV) of Marginal Net Benefit (US \$) | $\begin{gathered} 3,688 \\ 084 \end{gathered}$ | $\begin{aligned} & 152, \\ & 660 \end{aligned}$ | 2, 255, 195 | -1,393 |
|  | Marginal Benefit to Cost ratio (B/C) | 6.19 | 1.19 | 24.89 | 0 |

### 6.6 Brief Summary of Chapter

This chapter explained the method of performing economic analysis and the development of SILCC utilizing the operational performance computed from the method explained in chapter 4 . The quantity and cost associated with construction and operation were calculated as marginal values deducting the amount associated with standard signalized intersections. The monetization was done using standard unit prices of items from different literature sources. SILCC was used for the life cycle cost analysis. The life cycle cost analysis of a case study provided the hierarchical order of intersections.

## CHAPTER 7

## CONCLUSION AND RECOMMENDATION

This chapter provides the conclusion based on the results obtained from the DAC pattern and economic analysis. It also describes some of the limitations of this study and recommends areas of further study.

### 7.1 Conclusion

This study evaluated standard signalized intersections with left turn permitted along the major street and three types of unconventional intersections: MUT, CFI, and jughandle, comparing their performance with standard signalized intersections. The study at first assessed the intersections based on delay performance, and finally, performed the life cycle cost analysis over the operational benefits, operational cost, cost of construction, and cost of operation and maintenance. Based on delay performance, this study was able to define the DAC that distinguished the region of optimal performance for each type of unconventional intersection. Both graphical plots and thresholds equations were developed and are included in this dissertation. The overall analysis of DAC indicated that MUT is applicable for almost all levels of volume combinations of major and minor street approach traffic volume under the presence of low left-turning traffic (5\%), except at some ranges of major street approach traffic volume under some low minor street volume ranges ( 700 vph to 1350 vph ). Under medium to high leftturning traffic ( $10 \%$ and $15 \%$ ), standard signalized intersections with permitted left turn along the major street performed optimally at low minor street volume (less than or equal
to 200 vph ) and low major street volume (less than 650 vph ). Under medium left turning traffic at balanced and nearly balanced conditions, and under high left-turning traffic at balanced only conditions, the jughandle performed optimally on high major street approach traffic volume (greater than or equal to 2200 vph for $10 \%$ LT and greater than 1800 vph for $15 \% \mathrm{LT}$ ), and its performance got better with increasing minor street approach traffic volume. Under medium to high left-turning traffic, CFI performed optimally for high major street approach traffic volume (greater than or equal to 2200 vph for $10 \% \mathrm{LT}$ and greater than 1800 vph for $15 \% \mathrm{LT}$ ), and the optimal performance region expanded with increasing minor street approach traffic volumes. The jughandle performed optimally for high major street approach traffic volume (greater than or equal to 2200 vph for $10 \%$ LT and greater than 1800 vph for $15 \% \mathrm{LT}$ ) and the optimal performance region expanded with decreasing minor street approach traffic volume at unbalanced flow conditions. CFI's optimal region expanded as the flow became more unbalanced.

Furthermore, to provide flexibility for users to decide on the best unconventional intersection design under multiple sets of conditions, a spreadsheet tool, "SILCC," was developed. SILCC has the ability to estimate the operational performance measure, complete a cost estimate, and perform LCCA. For new construction, a sample case study performed on a 24 -hour rural pattern volume indicated a higher NPV for operational benefits and a higher $\mathrm{B} / \mathrm{C}$ related to MUT compared to all other intersections. However, since the construction cost of a MUT-retrofit is high, the jughandle-retrofit was found to
have the highest B/C, despite the fact that MUT had the highest NPV. The standard signalized intersection with left turn permitted was found not applicable for the provided volume condition.

In this manner, this study developed the decision support system, which can provide integrated decision criteria for unconventional intersections, and developed SILCC that accounts the cost and benefit aspects that were lacking in the existing decision assistance method. The integrated decision criteria provided the volume warrants for the studied unconventional intersections. The other specific conclusions reached by the study are detailed below:

1. The DAC developed based on delay performance favored the use of MUT for all combinations of total approach traffic volumes ranging from 50 vph to 2400 vph on the major street and 50 vph to 500 vph on the minor street under a low percentage of left-turning traffic (5\%), except at some total major street approach traffic volume ranges under very low total minor street approach traffic volume, as shown in table 5.8.
2. For a medium percentage of left turns $(10 \%)$ and BF at 0.5 and 0.6 , the threshold between MUT and a jughandle was found to be between 2200 vph and 2400 vph of major street approach traffic volume. The optimal region for the jughandle increased as minor street approach traffic volume increased. When the balance factor increased to 0.7 for the same left turn percentage (10\%), CFI was introduced to the high major street approach traffic volume
(greater than or equal to 2200 vph ) and high minor street approach traffic volume region (greater than or equal to 250 vph ).
3. For a high percentage of left turns $(15 \%)$ and BF at 0.5 , which represents the balance condition under which both approaches on the major street have the same volume of traffic, the thresholds of the jughandle shifted toward the left, between 1800 vph to 2000 vph major street approach traffic volume. The optimal region for the jughandle increased as the minor street approach traffic volume increased. From this, it can be inferred that at a balanced condition, the jughandle performed better at high major street volumes (greater than $1800 \mathrm{vph})$ and performed even better when the minor street approach traffic volume increased. When the BF increases from 0.5 to 0.6 , the CFI was introduced in the region of high major street approach traffic volume (greater than 1900 vph ) and high minor street approach traffic volume (greater than or equal to 350 vph ). With a further increase in BF , from 0.6 to 0.7 , the optimal region of CFI extended to low minor street approach traffic volume ( 50 vph ). From this, it can be inferred that CFI performed better at high major and minor street approach traffic volumes, and the jughandle performed better at high major street approach traffic volumes and low minor street approach traffic volumes under unbalanced flow conditions.
4. The performance of standard signalized intersections with left turn permitted on the major street was only found to be optimal on very low major street
approach traffic volume and very low minor street approach traffic volume for a medium and high percentage of left turns. The volume ranges were a minimum of 150 vph to a maximum of 650 vph for major street approach traffic and a minimum of 50 vph to a maximum of 100 vph for minor street approach traffic under 10\% left turn traffic conditions. Similarly, the ranges were a minimum of 50 vph to a maximum of 450 vph for major street approach traffic and a minimum of 50 vph to a maximum of 200 vph for minor street approach traffic under 15\% left turn traffic conditions.
5. For the most of volume criteria for all conditions of flow balance, left turn percentage, and truck percentage, MUT was the preferred alternative. It was also found that the conventional signalized intersection with protected left turns was never optimal under studied scenarios. This implies that for all the studied conditions, there exists at least one unconventional intersection or permitted left alternative that produces lower delay than the conventional signalized intersection.
6. Effect of truck percentage was distinct only at a high left turn percentage (15\%) and a high balance factor (0.7), where high truck percentage favors the increment of the optimal region of CFI.
7. Looking at the DAC plots in Appendix A and the DAC equations in tables 5.2 through 5.7 are recommended to gain an accurate understanding of the thresholds.
8. The above criteria are based on delay performance and limited to rural intersections with a four-lane major street at 45 mph and a two-lane minor street at 35 mph . However, this method can be extended for urban intersections as well. To account for the cost in decision making, the SILCC is recommended. Additionally, SILCC can provide a decision based on cost and operational benefits for any criteria that the user wants to assess; it can be used as a decision assistance tool.
9. Both the performance based decision support system and the cost based decision support system tested for low volume condition indicated MUT as most preferred alternative. However, the study also indicated that the marginal cost of MUT retrofit is quite higher than new construction. The economic study showed CFI retrofit expensive than new CFI but by lower degree as compared to MUT.
10. It should be noted that DAC and SILCC provide a decision support system to the decision maker only. It is a decision maker who decides based on prevailing volume condition according to his priorities such as budget allocation, type of treatments (new construction or retrofit), and whether importance is to be given to cost or performance, etc. There are several other factors that may also affect the decision besides the operational performance and cost factors. One of these factors could be the cutoff of access roads due to the implementation of unconventional intersection. It could be a major
hindrance to the local road users both in viewpoint of pedestrians and traffic mobility. Similarly, the availability of additional right of way can sometime be an issue too. Hence, the studied factors are the important factors but not all. The decision maker shouldn't be limited on those factors only.

### 7.2 Recommendation

As mentioned in the previous section, the DAC were developed for rural intersections with a four-lane major street at 45 mph and a two-lane minor street at 35 mph. However, this method can be extended for urban intersections as well and the flexibility to add more controlling variables is available. To use SILCC, the minimum requirement for users is that they should be familiar with the highway capacity manual. The modification of some of the factors also requires the knowledge and skill to run HCS 2010 Street ${ }^{\circledR}$. Codes modification may be needed if SILCC is to be run with a different version than HCS-6.5. Some further studies based on the limitations of this study are recommended as following:

1. It is recommended that this study is extended to develop DAC for other conditions and intersections. Conditions may be intersections in an urban setting, more levels of truck factors, left turn percentage, and balance factor, as well as other types of unconventional intersections. Similarly, SILCC can be extended for other unconventional intersections. The use of the methodology developed for this study will reduce the time and effort of these kinds of studies.
2. A separate study can be conducted to capture the effect of fast growing traffic in future years to see if several alternatives could be optimal one at a time for certain periods in the whole analysis period.
3. It is recommended that a separate detailed study be conducted to develop a method to integrate the weight of all the priorities that a decision maker would consider to decide on an intersection based on the results obtained from the developed decision assistance tools. This would provide further support for the decision maker.
4. It is also recommended that a separate study be conducted to compute crash modification factors related to these intersection treatments and incorporate the safety benefits in the life cycle cost analysis included in SILCC.

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## APPENDIX A DAC PLOTS AND GROWTH CURVES

A.1. Volume Threshold Plots


Figure A.1: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%$ and $\mathrm{TP}=2 \%$


Figure A.2: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%$ and $\mathrm{TP}=2 \%$


Figure A.3: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%$ and $\mathrm{TP}=2 \%$


Figure A.4: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.5$, $\mathrm{LTP}=10 \%$ and $\mathrm{TP}=2 \%$


Figure A.5: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%$ and $\mathrm{TP}=2 \%$


Figure A.6: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%$ and $\mathrm{TP}=2 \%$


Figure A.7: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.5$, $\mathrm{LTP}=15 \%$ and $\mathrm{TP}=2 \%$


Figure A.8: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%$ and $\mathrm{TP}=2 \%$


Figure A.9: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%$ and $\mathrm{TP}=2 \%$


Figure A.10: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%$ and $\mathrm{TP}=5 \%$


Figure A.11: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%$ and $\mathrm{TP}=5 \%$


Figure A.12: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%$ and $\mathrm{TP}=5 \%$


Figure A.13: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%$ and $\mathrm{TP}=5 \%$


Figure A.14: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%$ and $\mathrm{TP}=5 \%$


Figure A.15: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.7$, $\mathrm{LTP}=10 \%$ and $\mathrm{TP}=5 \%$


Figure A.16: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%$ and $\mathrm{TP}=5 \%$


Figure A.17: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%$ and $\mathrm{TP}=5 \%$


Figure A.18: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%$ and $\mathrm{TP}=5 \%$


Figure A.19: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%$ and $\mathrm{TP}=10 \%$


Figure A.20: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%$ and $\mathrm{TP}=10 \%$


Figure A.21: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%$ and $\mathrm{TP}=10 \%$


Figure A.22: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%$ and $\mathrm{TP}=10 \%$


Figure A.23: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%$ and $\mathrm{TP}=10 \%$


Figure A.24: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.7$, $\mathrm{LTP}=10 \%$ and $\mathrm{TP}=10 \%$


Figure A.25: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%$ and $\mathrm{TP}=10 \%$


Figure A.26: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%$ and $\mathrm{TP}=10 \%$


Figure A.27: Volume thresholds for unconventional intersection at $\mathrm{BF}=0.7$, $\mathrm{LTP}=15 \%$ and $\mathrm{TP}=10 \%$

## A. 2 Contour Plots for MUT

## A.2.1 Contour Plots for Critical Left Turn Delay Difference with Standard Signalized Intersection



Figure A. 28 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 29 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 30 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 31 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 32 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 33 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 34 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 35 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$
(Note: 9999 represents failure condition of Median Opening)


Figure A. 36 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$
(Note: 9999 represents failure condition of Median Opening)


Figure A. 37 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 38 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 39 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 40 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 41 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 42 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 43 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$
Note: 9999 represents failure condition of Median Opening


Figure A. 44 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$
(Note: 9999 represents failure condition of Median Opening)


Figure A. 45 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$
(Note: 9999 represents failure condition of Median Opening)


Figure A. 46 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 47 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 48 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A.49 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 50 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 51 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$
(Note: 9999 represents failure condition of Median Opening)


Figure A. 52 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$
(Note: 9999 represents failure condition of Median Opening)


Figure A. 53 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$
(Note: 9999 represents failure condition of Median Opening)


Figure A. 54 Contour plot at $\mathrm{BF}=0.7$, LTP=15 \%, TP=10 \%
(Note: 9999 represents failure condition of Median Opening)
A.2.2. Contour Plot for Total Intersection Delay Difference between MUT and Standard Signalized Intersection


Figure A. 55 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 56 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 57 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 58 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 59 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 60 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 61 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 62 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%$, $\mathrm{TP}=2 \%$
(Note: 999 represents failure condition of Median Opening)


Figure A. 63 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$
(Note: 999 represents failure condition of Median Opening)


Figure A. 64 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 65 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 66 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 67 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 68 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 69 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 70 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$
Note: 999 represents failure condition of Median Opening


Figure A. 71 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$
(Note: 999 represents failure condition of Median Opening)


Figure A. 72 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$
(Note: 999 represent failure condition of Median Opening)


Figure A. 73 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 74 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 75 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 76 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 77 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 78 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 79 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$
(Note: 999 represents failure condition of Median Opening)


Figure A. 80 Contour plot at BF=0.6, LTP=15 \%, TP=10 \%
(Note: 999 represents failure condition of Median Opening)


Figure A. 81 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$
(Note: 999 represents failure condition of Median Opening)
A.2. Contour Plots for Total Intersection Delay Difference of CFI with Standard Signalized Intersection


Figure A.82 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 83 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 84 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 85 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 86 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 87 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 88 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 89 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 90 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 91 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 92 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 93 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 94 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 95 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 96 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 97 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$


Figure A. 98 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$


Figure A. 99 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$


Figure A. 100 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 101 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 102 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 103 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 104 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 105 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 106 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure A. 107 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure A. 108 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$

## A.3. Contour Plots Jughandle

## A.3.1 Contour Plots for Critical Left Turn Delay Difference with Standard Signalized Intersection



Figure A. 109 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A.110 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 111 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A.112Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 113 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 114 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 115 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 116 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 117 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 118 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 119 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 120 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 121 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 122 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 123 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 124 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$


Figure A. 125 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$


Figure A. 126 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$


Figure A. 127 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 128 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 129 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 130 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 131 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 132 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 133 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure A. 134 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure A. 135 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$
A.3.2. Contour Plot for Total Intersection Delay Difference between Jughandle and Standard Signalized Intersection


Figure A. 136 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 137 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 138 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 139 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 140 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 141 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 142 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 143 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 144 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 145 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 146 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 147 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 148 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 149 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 150 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 151 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$


Figure A.152Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$


Figure A. 153 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$


Figure A. 154 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 155 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 156 Contour plot at $\mathrm{BF}=0.7$, $\mathrm{LTP}=5 \%, \mathrm{TP}=10$ \%


Figure A. 157 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 158 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 159 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 160 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure A. 161 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure A. 162 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$

## A. 4 Contour Plots Standard Signalized Intersection with Left Turn Permitted along Major Street

A.4.1 Contour Plot for Critical Left Turn Delay Difference between Standard Signalized Intersection with Permitted LT and Standard Signalized intersection


Figure A. 163 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 164 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 165 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 166 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 167 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 168 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 169 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 170 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 180 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 181 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 182 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 183 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 184 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 185 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 186 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 187 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$


Figure A. 188 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$


Figure A. 189 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$


Figure A. 190 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 191 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 192 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 193 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 194 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 195 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 196 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure A. 197 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure A. 198 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$
A.4.2 Contour Plot for Total Intersection Delay Difference between Standard Signalized Intersection with LT-Permitted and Standard Signalized Intersection


Figure A. 199 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 200 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 201 Contour plot at $\mathrm{BF}=0.7$, $\mathrm{LTP}=5 \%, \mathrm{TP}=2 \%$


Figure A. 202 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 203 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 204 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=2 \%$


Figure A. 205 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 206 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 207 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=2 \%$


Figure A. 208 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 209 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 210 Contour plot at $\mathrm{BF}=0.7$, $\mathrm{LTP}=5 \%, \mathrm{TP}=5 \%$


Figure A. 211 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 212 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 213 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=10 \%, \mathrm{TP}=5 \%$


Figure A. 214 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$


Figure A. 215 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$


Figure A. 216 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=5 \%$


Figure A. 217 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 218 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 219 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=5 \%, \mathrm{TP}=10 \%$


Figure A. 220 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 221 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 222 Contour plot at $\mathrm{BF}=0.7$, $\mathrm{LTP}=10 \%, \mathrm{TP}=10 \%$


Figure A. 223 Contour plot at $\mathrm{BF}=0.5, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure A. 224 Contour plot at $\mathrm{BF}=0.6, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure A. 225 Contour plot at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$

## A.4. The Growth Curves



Figure A. 226 Growth curves for growth rate of $1 \%$


Figure A. 227 Growth curves for growth rate of $2 \%$


Figure A. 228 Growth curves for growth rate of $3 \%$


Figure A. 229 Growth curves for growth rate of $4 \%$


Figure A. 230 Growth curves for growth rate of $5 \%$

## APPENDIX B EXAMPLE USE OF DAC

Consider three volume conditions of major street approach traffic volume at minor street approach traffic volume $=150 \mathrm{vph}$
(1) Major street approach traffic volume $=200 \mathrm{vph}$
(2) Major street approach traffic volume $=1000 \mathrm{vph}$
(3) Major street approach traffic volume $=2000 \mathrm{vph}$
(4) Major street approach traffic volume $=2200 \mathrm{vph}$

In figure $\mathrm{C} .1, \mathrm{~A}$ represents the first condition; B represents the second condition, C represents the third condition, and D represents the fouth condition. From figure C.1, it is clear that A lies on the optimal performance zone of standard signalized intersection with left turn permitted along major street, B lies on the optimal performance zone of MUT, C lies on the optimal performance zone of jughandle, and D lies on the optimal performance zone of CFI.

- If A is observed in figure B.2, it can be found located very near to contour of magnitude 2.9. This indicates that the critical left turn delay of standard signalized intersection with left turn permitted along major street is approximately $2.9 \mathrm{~s} /$ veh lower than that of a standard signalized intersection. If A is observed in figure B.3, it can be found located very near to contour of magnitude -3 . This indicates that the total intersection delay of standard signalized intersection with left turn permitted along major street is approximately $3 \mathrm{~s} / \mathrm{veh}$ lower than that of a standard signalized intersection. It can be inferred that a standard signalized intersection with left turn permitted along major street
has lower total intersection delay as well lower critical left turn delay. It should be noted that DAC can be sued for standard signalized intersection with left turn permission only if they meet the left turn permission requirement.
- If B is observed in figure B.4, one can see it is located between the contours of magnitude 17 and 18.This indicates that the critical left turn delay of MUT is approximately 17.7 s/veh higher than that of a standard signalized intersection. Again, if A is observed in figure B.5, it can be found located between the contours of magnitude -4 and -4.5 . This indicates that the total average intersection delay of MUT is approximately $4.1 \mathrm{~s} / \mathrm{veh}$ lower than that of a standard signalized intersection. It can be inferred that MUT has lower total intersection delay than a standard signalized intersection, but at the expense of a higher left turn delay for critical left turn movements.
- If C is observed in figure B.6, it can be found located very near the contour of magnitude -1 . This indicates that the critical left turn delay of jughandle is approximately $1 \mathrm{~s} / \mathrm{veh}$ lower than that of a standard signalized intersection. Again, if B is observed in figure B.7, it can be found located between the contours of magnitude -4 . This indicates that the total average intersection delay of a jughandle is $4 \mathrm{~s} / \mathrm{veh}$ lower than that of a standard signalized intersection. It can be inferred that a jughandle has lower total intersection delay as well lower critical left turn delay.
- If D is observed in figure B .8 , one can see that it lies between the contours of magnitude 3.5.and -4. This indicates that the total intersection delay of CFI is lower than that of a standard signalized intersection by approximately $3.8 \mathrm{~s} / \mathrm{veh}$.

This information from DAC can help the planner to decide the optimal unconventional intersection, as well as quantify the respective benefits or costs related to delay savings.


Figure B. 1 DAC at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure B. 2 Contour plot for standard signalized intersection with LT-Permitted for critical left turn delay difference at $\mathrm{BF}=0.7$,

$$
\mathrm{LTP}=15 \%, \mathrm{TP}=10 \%
$$



Figure B. 3 Contour plot for standard signalized intersection with LT-Permitted for total average intersection delay difference at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure B. 4 Contour plot for MUT for critical left turn delay difference at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure B. 5 Contour plot for MUT for total average intersection delay difference MUT at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure B. 6 Contour plot for jughandle for critical left turn delay difference at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure B. 7 Contour plot for jughandle for average total intersection delay difference at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$


Figure B. 8 Contour plot for CFI for average total intersection delay difference at $\mathrm{BF}=0.7, \mathrm{LTP}=15 \%, \mathrm{TP}=10 \%$

## APPENDIX C COST

## C.1. Marginal Cost of New Construction

Table C. 1 Marginal cost of new construction of MUT

|  | Standard <br> item no. | Item | Quantity | Unit | Rate | Amount <br> in US <br> Dollars |
| :---: | :---: | :--- | :---: | :---: | :---: | :---: |
|  | 3075.56 | 10 Doweled <br> Concrete Pavement, <br> Clas 47 B-3500 <br> (Including Median <br> Opening) | 399.6 | SY | 30.59 | $12,223.76$ |
|  |  | 1010 | Excavation (1.5') | 199.8 | CY | 3.26 |

Table C. 2 Marginal cost of new construction of CFI Part I

|  | Standard item no. | Item | Quantity | Unit | Rate | Amount in US <br> Dollars |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 3075.56 | 10" Doweled Concrete Pavement, Class 47 B-3500 | 2, 064.6 | SY | 30.59 | $\begin{gathered} 63, \\ 156.11 \end{gathered}$ |
|  | 1010 | Excavation (1.5') | 1, 032.3 | CY | 3.26 | 3,365.3 |
|  | 3017.4 | Concrete Class 47B-3000 <br> Median Surfacing | 0 | SY | 31.05 | 0 |
|  | A016.8 | Mast Arm Signal Pole, Type MP-60 | 8 | Each | 8500 | 68, 000 |
|  | A504.81 | Install Mast Arm Signal Pole | 8 | Each | 3700 | 29,600 |
|  | A003.10 | Traffic Signal, Type TS-1 | 10 | Each | $\begin{gathered} 493.8 \\ 9 \\ \hline \end{gathered}$ | 4,938.9 |
|  | A501.00 | Install Traffic Signal, Type TS-1 | 10 | Each | 242 | 2, 420 |
|  | A001.7 | Pull Box, Type PB-7 | 12 | Each | 1010 | 12, 120 |
|  | A070.22 | 4 Inch Conduit in Trench | 300 | LF | 5.91 | 1, 773 |
|  | A072.10 | 4 Inch Conduit in Roadway | 432 | LF | 7.83 | 3,382 |
|  | A077.26 | 16/C 14 AWG Traffic Signal Cable | 1,800 | Lf | 3.98 | 7, 164 |
|  | A007.08 | Vehicle Detector, Type TDA Performed | 40 | Each | $\begin{gathered} 263.6 \\ 9 \end{gathered}$ | $\begin{gathered} 10, \\ 547.6 \end{gathered}$ |
|  | A079.1 | 2/C \#14 AWG Detector <br> Lead-In Cable | 500 | LF | 1.46 | 730 |
|  | 7320.27 | Traffic Sign and Post (No RTOR and No Left Turn) | 6 | Each | $\begin{gathered} 295.8 \\ 5 \end{gathered}$ | 1,775.1 |
|  | 7500.25 | Left Arrow Performed Pavement Markings | 6 | Each | 483 | 2,898 |

Table C. 3 Marginal cost of new construction of CFI Part II

|  | Standard item no. | Item | Quantity | Unit | Rate | Amount in US Dollars |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 7496.05 | 5" Yellow <br> Permanent Pavement Markings | 2, 800 | LF | 0.19 | 532 |
|  | N/A | Additional Land | 0.58 | Acre | 4, 142.5 | 2, 386.98 |
| Subtotal |  |  |  |  |  | 214, 789.55 |
| ¢ $\substack{0 \\ 0 \\ 0 \\ 0 \\ 0}$ |  | Preliminary Engineering (PE) | 10\% of Subtotal |  |  | 21,478.95 |
|  |  | Contingency | 20\% of Subtotal |  |  | 42, 957.91 |
|  | Total Cost in US Dollar |  |  |  |  | 279, 226.41 |
|  |  | Additional Signal O and M (signal head, detectors, signal retiming, power supply, etc.) | 4 | Per year | 6,000 | 24, 000 |

Table C. 4 Marginal cost of new construction of jughandle

|  | Standar d item no. | Item | Quantity | Unit | Rate | Amount in US <br> Dollars |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1010 | Excavation (1.5') | 652.68 | CY | 3.26 | 2,127.74 |
|  | 3075.56 | 10" Doweled Concrete Pavement, Class 47 B-3500 | 1,305.36 | SY | 30.59 | 39, 930.96 |
|  | 7320.27 | Traffic Sign and Post (Yield Sign, No RTOR and No Left Turn) | 8.00 | Each | 295.85 | 2, 366.80 |
|  | 7495.55 | 5" White Permanent Pavement Markings | 340.00 | LF | 0.40 | 136.00 |
|  | 7496.05 | 5" Yellow Permanent Pavement Markings | 1,280 | LF | 0.19 | 243.20 |
|  | N/A | Additional Land | 1.17 | Acre | 4, 142.50 | 4, 850.03 |
| Subtotal |  |  |  |  |  | 49, 654.73 |
|  |  | Preliminary Engineering (PE) | 10\% Subtotal |  |  | 4,965.47 |
|  |  | Contingency | 20\% of Subtotal |  |  | 9,930.95 |
|  | Total Cost in US Dollar |  |  |  |  | 64, 551.15 |
|  |  | Landscaping of area enclosed by reverse curves | 2 | Per <br> year | 1,000 | 2, 000.00 |

Table C. 5 Marginal cost of standard signalized intersection with left turn permitted

|  |  | Item | Quantity | Unit | Rate | Amount in US Dollars |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 3075.56 | 10" Doweled Concrete Pavement, Class 47 B3500 | -363.00 | SY | 30.59 | -11, 104.70 |
|  | 7320.27 | Traffic Sign and Post (No Left Turn) | 2.00 | Each | 295.85 | 591.70 |
| Subtotal |  |  |  |  |  | -10, 512.47 |
| 苞苞 |  | Preliminary Engineering (PE) | 10\% of Subtotal |  |  | 59.17 |
|  |  | Contingency | 20\% of Subtotal |  |  | 118.34 |
|  | Total Cost in US Dollar |  |  |  |  | -10, 334.96 |

## C.2. Marginal Cost of Retrofit

Table C. 6 Marginal cost of MUT retrofit (Part I)

|  | Standard <br> item no. | Item | Quantity | Unit | Rate | Amount in <br> US Dollars |
| :---: | :---: | :--- | :---: | :---: | :---: | :---: |
| 1101 | Concrete Pavement Removal | $10,778.1$ | SY | 6.81 | $73,398.86$ |  |
| 3075.56 | 10" Doweled Concrete Pavement, <br> Class 47 B-3500 (Including <br> Median Opening) | $11,910.3$ | SY | 30.59 | 364, <br> 336.08 |  |
| 1010 | Excavation (1.5') | $5,955.15$ | CY | 3.26 | $19,413.79$ |  |
| 1122.01 | Remove Concrete Median <br> Surfacing (6' Median) | 2,220 | SY | 5.9 | 13,098 |  |
| A724.01 | Relocate Traffic Signal | 6 | Each | 470 | 2,820 |  |
| A703.00 | Relocate Mast Arm | 4 | Each | 1470 | 5,880 |  |
| A006.98 | Vehicle Detector, Type TD-A <br> Performed | 24 | Each | 263.6 | $6,328.56$ |  |
| A001.7 | Pull Box, Type PB-7 | 12 | Each | 1010 | 12,120 |  |
| A070.22 | 4 Inch Conduit in Trench | 160 | LF | 5.91 | 945.6 |  |
| A072.20 | 4 Inch Conduit in Roadway | 432 | LF | 7.83 | $3,382.56$ |  |
| A077.26 | 16/C 14 AWG Traffic Signal <br> Cable | 500 | Lf | 3.98 | 1,990 |  |
| A079.01 | 2/C \#14 AWG Detector Lead-In <br> Cable | 250 | LF | 1.46 | 365 |  |

Table C. 7 Marginal cost of MUT retrofit (Part II)

|  | Standard item no. | Item | Quantity | Unit | Rate | Amount in US Dollars |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 7320.27 | Traffic Sign and Post (STOP Sign, No RTOR and No Left Turn) | 10 | Each | 295.85 | 2, 958.5 |
|  | 7500.22 | Right Arrow Performed Pavement Marking, Type 3 | 2 | Each | 420 | 840 |
|  | 7500.25 | Through and Left Arrow Performed Pavement Markings | 6 | Each | 483 | 2, 898 |
|  | 7495.55 | 5" White Permanent Pavement Markings | 4, 000 | LF | 0.4 | 1,600 |
|  | 7496.05 | 5" Yellow Permanent Pavement Markings | 8, 000 | LF | 0.19 | 1,520 |
|  | N/A | Additional Land | 2.296 | Acre | 4142.5 | 9, 509.87 |
| Subtotal |  |  |  |  |  | 523, 404.82 |
|  |  | Preliminary Engineering (PE) | 10\% Subtotal |  |  | 52, 340.48 |
|  |  | Contingency | 20\% of Subtotal |  |  | 104, 680.96 |
|  | Total Cost in US Dollar |  |  |  |  | 680, 426.26 |
|  |  | Landscaping of median | 2 | Per year | $\begin{array}{c\|c} r & 1,00 \\ r & 0 \end{array}$ | 2000 |

Table C. 8 Marginal cost of CFI retrofit (Part I)

|  | Standar d item no. | Item | Quantity | Unit | Rate | Amount in US Dollars |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \vec{v}_{0}^{0} \\ & 0 \\ & 0 \\ & 0 \\ & 0 \\ & 0 \\ & 0 \\ & 0 \end{aligned}$ | 1122.01 | Remove Concrete Median Surfacing (6' Median) | 2, 109 | SY | 5.9 | 12, 443.1 |
|  | 3075.56 | 10" Doweled Concrete Pavement, Class 47 B3500 | 3, 196.8 | SY | 30.59 | 97, 790.1 |
|  | 1010 | Excavation (1.5') | 1, 598.4 | CY | 3.26 | 5,210.78 |
|  | 3017.4 | Concrete Class 47B-3000 Median Surfacing | 2, 386.5 | SY | 31.05 | 74, 100.8 |
|  | A016.8 | Mast Arm Signal Pole, Type MP-60 | 8 | Each | 8500 | 68, 000 |
|  | A504.81 | Install Mast Arm Signal Pole | 8 | Each | 3700 | 29, 600 |
|  | A003.10 | Traffic Signal, Type TS-1 | 10 | Each | 493.89 | 4,938.9 |
|  | A501.00 | Install Traffic Signal, Type TS-1 | 10 | Each | 242 | 2, 420 |
|  | A001.7 | Pull Box, Type PB-7 | 12 | Each | 1010 | 12,120 |
|  | A070.22 | 4 Inch Conduit in Trench | 300 | LF | 5.91 | 1,773 |
|  | A072.20 | 4 Inch Conduit in Roadway | 432 | LF | 7.83 | 3,382.56 |
|  | A077.26 | 16/C 14 AWG Traffic Signal Cable | 1, 800 | Lf | 3.98 | 7,164 |
|  | A006.98 | Vehicle Detector, Type TD-A Performed | 40 | Each | 263.69 | 10, 547.6 |
|  | A079.01 | 2/C \#14 AWG Detector Lead-In Cable | 500 | LF | 1.46 | 730 |
|  | 7320.27 | Traffic Sign and Post ( No RTOR and NO Left Turn) | 4 | Each | 295.85 | 1,183.4 |
|  | 7500.25 | Through and Left Arrow Performed Pavement Markings | 4 | Each | 483 | 1,932 |

Table C. 9 Marginal cost of CFI retrofit (Part II)

|  | Standa <br> rd <br> item <br> no. <br> 7 | Item | Quantity | Unit | Rate | Amount in US Dollars |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 苞 | $\begin{gathered} 7495.5 \\ 5 \end{gathered}$ | 5" White Permanent Pavement Markings | 3,800 | LF | 0.4 | 1,520 |
|  | $\begin{gathered} 7496.0 \\ 5 \\ \hline \end{gathered}$ | 5" Yellow Permanent Pavement Markings | 5,600 | LF | 0.19 | 1, 064 |
|  | N/A | Additional Land | 0.58 | Acre | 4, 142.5 | 2,386.98 |
| Subtotal |  |  |  |  |  | 338, 307 |
|  |  | Preliminary Engineering (PE) | 10\% Subtotal |  |  | 33,830.7 |
|  |  | Contingency | 20\% | of Subto |  | 67, 661.5 |
|  | Total Cost in US Dollar |  |  |  |  | 439,799 |
|  |  | Additional Signal O and M (signal head, detectors, signal retiming, power supply, etc.) | 4 | Per year | 6,000 | 24, 000 |

Table C. 10 Marginal cost of jughandle retrofit

| $\begin{aligned} & \tilde{v}_{0}^{0} \\ & 0 \\ & 0 \\ & 0 \\ & 0 \\ & 0 \\ & 0 \\ & 0 \end{aligned}$ | Standard item no. | Item | Quantity | Unit | Rate | $\begin{aligned} & \hline \text { Amount } \\ & \text { in US } \\ & \text { Dollars } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1010 | Excavation (1.5') | 652.68 | CY | 3.26 | 2, 127.74 |
|  | 3075.56 | 10" Doweled Concrete Pavement, Class 47 B3500 | 1,305.36 | SY | 30.59 | $\begin{gathered} 39, \\ 930.96 \\ \hline \end{gathered}$ |
|  | 7320.27 | Traffic Sign and Post (Yield Sign, No RTOR and No Left Turn) | 8.00 | Each | 295.85 | 2, 366.80 |
|  | 7495.55 | 5" White Permanent Pavement Markings | 340.00 | LF | 0.40 | 136.00 |
|  | 7496.05 | 5" Yellow Permanent Pavement Markings | 1,620 | LF | 0.19 | 307.80 |
|  | N/A | Additional Land | 1.17 | Acre | 4,142.50 | 4, 850.03 |
| Subtotal |  |  |  |  |  | $\begin{gathered} 49 \\ 719.33 \end{gathered}$ |
|  |  | Preliminary Engineering (PE) | 10\% Subtotal |  |  | 4, 971.93 |
|  |  | Contingency | 20\% of Subtotal |  |  | 9, 943.87 |
| Total Cost in US Dollar |  |  |  |  |  | $\begin{gathered} 64 \\ 635.13 \end{gathered}$ |
|  |  | Landscaping of area enclosed by reverse curves | 2 | Per year | 1,000 | 2, 000.00 |

Table C. 11 Marginal cost of standard signalized intersection with left turn permitted along major street.

|  |  | Item |  | Quantity | Unit | RateAmount <br> in US <br> Dollars |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

