An Architecture Extension for Efficient Geometry Processing

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Talk Outline

- Motivation---why enhance the MIPS architecture
- Background on 3D graphics geometry operations and current MIPS architecture
- What are the enhancements?
- Performance and cost
- Summary



Current 3D Rendering Limited by Geometry Processing

- Front-end Geometry and Lighting operations
 - ◆ General-purpose processors: 0.5 2 M polygons/s. Eg. R5K (1998,200MHz), PIII (1999,500MHz).
- Back-end: Rendering
 - ◆ Graphics processors: 6 8 M polygons/s. Eg. ATI Rage 128(1999), 3Dfx Voodoo3(1999).
- A solution: dedicated hardware --- highperformance, but expensive.
 Eg. Sony Emotion Engine



Our Solution

- Enhance the MIPS architecture to improve 3D geometry performance : MIPS-3D[™] ASE (Application Specific Extension) includes 13 new instructions
- Lower cost than dedicated geometry hardware
- Main processor improvements are leveraged
 - ◆ technology/speed
 - parallelism/pipelining



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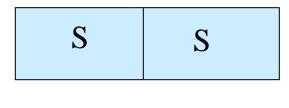
Geometry and Lighting Operations

- Vertex transformation (matrix multiplication)
- Clip-check (compare and branch)
- Transform to screen coordinates (perspective division using reciprocal)
- Lighting: infinite and local (normalization using reciprocal square root)



Already in the MIPS Architecture

- S Single FP format (32 bits)
- D Double FP format (64 bits)
- PS- Paired-Single, two singles





- Floating point operations
 - ◆ MUL (S, D, PS)
 - ◆ ADD (S, D, PS)
 - MADD (S, D, PS) (multiply-add)
 - ◆ RECIP (S, D)
 - ◆ RSQRT (S, D)



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ADDR: for Vertex Transformation

$$\begin{bmatrix} x & y & z & w \end{bmatrix} * \begin{bmatrix} m0 & m4 & m8 & m12 \\ m1 & m5 & m9 & m13 \\ m2 & m6 & m10 & m14 \\ m3 & m7 & m11 & m15 \end{bmatrix} = \begin{bmatrix} x^t & y^t & z^t & w^t \end{bmatrix}$$

$$Eg. \ x^t = m0x + m1y + m2z + m3w$$

MUL.PS FP10, FP0, FP8

MADD.PS FP11, FP10, FP1, FP9

 $FP11 = [m1y+m3w \mid m0x+m2z]$

ADDR

Reorganize register to enable add ADD.PS ...

ADDR.PS FP11, FP?, FP11

FP11 = [-- | m1y+m3w+m0x+m2z]



Clip Check (Compare)

Is the vertex within the viewing pyramid?

$$x >= -w$$
, $x <= w$
 $y >= -w$, $y <= w$
 $z >= -w$, $z <= w$
Set 6 Condition Code (CC) bits

Observation: Can use magnitude compares.

$$\begin{vmatrix} |x| <= |w| \\ |y| <= |w| \\ |z| <= |w|$$
 Set only 3 CC bits



CABS: for Clip Check Compare

Transformed $[w \mid z]$ $[y \mid x]$ in FP registers

```
PUU.PS to get [w | w]

NEG.PS to get [-w | -w]
C.NGE.PS !(y >= -w)? !(x >= -w)?
C.NGE.S !(z >= -w)?
C.LE.PS y<=w? x<=w?
C.LE.S z<=w?

CABS.LE.PS |y|<=|w|?, |x|<=|w|?
CABS.LE.PS |w|<=|w|?, |z|<=|w|?
```



BC1ANY4F: for Clip Check Branch

- Without absolute compare, need 6 branch instructions to check the 6 CC bits.
- With absolute compare, need 3 branch instructions to check the 3 CC bits.
- New MIPS-3D[™] ASE instruction --BC1ANY4F, a single branch instruction that
 checks 4 CC bits.



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Perspective Division and Normalization

- In MIPS V architecture
 New MIPS-3D™ ASE
 - ◆ RECIP
 - ◆ RSQRT
- Full precision
- Long latency
- Not fully pipeline-able
- Only S and D formats

- New MIPS-3D[™] ASE instructions:
 - ◆ RECIP1
 - ◆ RECIP2
 - ◆ RSQRT1
 - ◆ RSQRT2
- Reduced & full precision
- Pipeline-able
- PS format



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Implementation Cost

- Die Area (of the Ruby processor)
 - ◆ Implementation of PS adds 6-8% to FP die area.
 - ◆ MIPS-3D[™] ASE adds 3% to the floating point die area. (FP is less than 15% of the total die area).
- Logic/pipeline complexity
 - ◆ ADDR, CABS, BC1ANY4F, etc. minimal impact on both die area and FP pipeline logic.
 - ◆ RECIP1, RSQRT1 128 word lookup tables contribute to most of the 3% die area increase.



Other Instruction Sets

- 3DNow! -- enhance 3D graphics and multimedia
 - ◆ 2-packed FP SIMD (PS)
 - ◆ PFACC accumulate
 - ◆ PFRCP, PFRCPIT1, PFRCPIT2 - reciprocal
 - PFRSQRT, PFRSQIT1 reciprocal square root
 - ◆ PF2ID, PI2FD convert

- AltiVec
 - ◆ 4 SIMD (32-bits)
 - vrefp, vnmsubfp, vmaddfpreciprocal
 - vrsqrtefp, etc reciprocal square root
 - vcmpbfp bounds compare
 - vcfsx, vctsxs convert



Performance: Number of Instructions

Note: Inner-loop instructions=cycles

	No PS + No MIPS- 3D TM ASE	PS + No MIPS- 3D TM ASE	PS + MIPS- 3D TM ASE
Transform (matrix transform + clip + perspective divide)	29	28	20
Transform + complex lighting	90	67	49



Experiment/Coding Assumptions

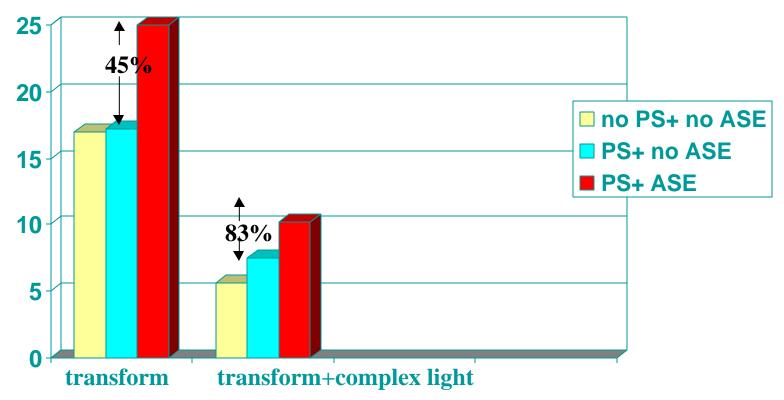
- FP pipeline has 4-cycle data dependency
- Loop interleaves computations of 2 vertices
- Transform constants locked in cache
- Vertex co-ordinates are pre-fetched from memory to cache, every loop iteration
- Code uses full precision reciprocal and reduced precision reciprocal square-root



Performance: M polygons/s

Using today's high-end desktop processor frequency---500MHz

M polygons/s





Summary

- MIPS-3D[™] ASE adds thirteen instructions to the current MIPS 64-bit architecture
- Low cost (3% die area)
- Increases polygons/sec count by 45% for the transform code
- Increases polygons/sec count by 36% -- 83% for the transform+complex light code



Appendix:Vertex Transformation Code

FP0--FP7 hold m0--m15 in pair-single FP8, FP9 hold x,y,z,w in pair-single

MUL.PS FP10,FP8,FP0 FP10 <-- m1*y | m0*x MUL.PS FP11,FP8,FP2 FP11 <-- m5*y | m4*x MUL.PS FP12,FP8,FP4 FP12 <-- m9*y | m8*x MUL.PS FP13,FP8,FP6 FP13 <-- m13*y | m12*x MADD.PS FP10.FP10.FP9.FP1 FP10 <-- m3*w+m1*y | m2*z+m0*x MADD.PS FP11,FP11,FP9,FP3 FP11 <-- m7*w+m5*y | m6*z+m4*x MADD.PS FP12,FP12,FP9,FP5 FP12 <-- m11*w+m9*y | m10*z+m8*x MADD.PS FP13,FP13,FP9,FP7 FP13 <-- m15*w+m13*y | m14*z+m12*x

PLL.PS FP14,FP11,FP10 PUU.PS FP15,FP11,FP10 PLL.PS FP16,FP13,FP12 PUU.PS FP17,FP13,FP12 ADD.PS FP8, FP15,FP14 ADD.PS FP9,FP17,FP16

Replace with

ADDR.PS FP8,FP11,FP10 ADDR.PS FP9,FP13,FP12 FP8 <-- m4x+m5y+m6z+m7w | m0x+m1y+m2z+m3w

FP9 <-- m12x+m13y+m14z+m15w |

m8x+m9y+m10z+m11w



Appendix: The 13 MIPS-3D™ ASE Instructions

Type	Mnemonic	Valid Formats	Description
Arithmetic	ADDR	PS	Floating point reduction add
	MULR	PS	Floating point reduction multiply
	RECIP1	S, D, PS	Reciprocal first step – reduced precision
	RECIP2	S, D, PS	Reciprocal second step – enroute to full precision
	RSQRT1	S, D, PS	Reciprocal square root first step – reduced precision
	RSQRT2	S, D, PS	Reciprocal square root second step
Format Conversion	CVT.PS.PW	PW	Convert a pair of 32-bit fixed point integers to a pair-single floating point value
	CVT.PW.PS	PS	Convert a paired-single floating point value to a pair of 32-bit fixed point integer values
Compare	CABS	S, D, PS	Magnitude compare of floating point values
Branch	BC1ANY2F		Branch if either one of two (consecutive) CC bits is F
	BC1ANY2T		Branch if either one of two (consecutive) CC bits is T
	BC1ANY4F		Branch if any one of four (consecutive) CC bits is F
	BC1ANY4T		Branch if any one of four (consecutive) CC bits is T