# On curvature, volume growth and uniqueness of steady Ricci solitons 

Xin Cui<br>Lehigh University

Follow this and additional works at: http:// preserve.lehigh.edu/etd
Part of the Mathematics Commons

## Recommended Citation

Cui, Xin, "On curvature, volume growth and uniqueness of steady Ricci solitons" (2016). Theses and Dissertations. 2562.
http:/ / preserve.lehigh.edu/etd/2562

# On curvature, volume growth and uniqueness of steady Ricci solitons. 

by

Xin Cui

A Dissertation<br>Presented to the Graduate Committee of Lehigh University in Candidacy for the Degree of Doctor of Philosophy<br>in<br>Mathematics

Lehigh University
May 2016

Copyright
Xin Cui

Approved and recommended for acceptance as a dissertation in partial fulfillment of the requirements for the degree of Doctor of Philosophy.

## Xin Cui

On curvature, volume growth and uniqueness of steady Ricci solitons.

## Date

Prof. Huai-Dong Cao,
Dissertation Director, Chair

## Accepted Date

Committee Members

## Xiaofeng Sun

Terrence Napier

Justin Corvino

## Acknowledgments

I would like to express my sincere gratitude to my advisor, Professor HuaiDong Cao. This work could not have been done without his significant inspiration, constant guidance and support.

Many thanks to Professor Xiaofeng Sun, Professor Terrence Napier, Professor Justin Corvino, Professor Don Davis, Professor David Johnson, Professor Joseph Yukich and Professor Wei-Min Huang for their generous helping during my study at Lehigh University.

I also would like to thank my friends Meng Zhu, Qiang Chen,Yingying Zhang, Yashan Zhang, Jianyu Ou, Chih-Wei Chen and Zhuhong Zhang. Also thank my college classmates, Qiang Guang, Xing Wang, Zhilin Ye, Hang Xu, Shi Wang for years of discussion on mathematics.

There are many people whom I wish to thank. In particular, I want to thank Mary Ann Dent and Mary Ann Haller. They are always there whenever I meet a problem. Their help reminds me the feeling of a family. I would like to thank Mr. Dale S. Strohl '58. His generous gift to Lehigh University granted me fellowship scholarship two times. I also would like to show my respect to Mr. Robert E. Zoellner '54. I would like to especially mention that the door is always open at the Zoellner art center, I was able to practice piano at the center although I am not an music major student.

Finally and most importantly, I also would like to thank my parents, Yuanshan Cui and Qiuhua Piao. My father had a dream to be a mathematician and he tried even harder than I do. My mother created chances for me to touch various form of art and never force me to study. Eventually I picked piano by myself. I deeply thank them for their open-mindedness and courage.

## Contents

Abstract ..... 1
1 Preliminary ..... 2
1.1 Definition of Ricci solitons ..... 2
1.2 Curvature equations and inequalities ..... 3
1.3 Basic properties of solitons ..... 5
1.4 Some examples of steady solitons ..... 5
2 Curvature estimates for four- dimensional steady solitons ..... 6
2.1 Background ..... 6
2.2 Main Results ..... 8
2.3 Preliminaries ..... 9
2.4 Case 1: steady soliton with Ric $>0$ ..... 10
2.5 Case 2: steady soliton with $\lim _{x \rightarrow \infty} R(x)=0$ ..... 14
3 Curvature and volume growth of steady Kähler Ricci solitons ..... 23
3.1 Background ..... 23
3.2 Volume growth ..... 24
3.3 Curvature estimates ..... 27
4 Uniqueness under constraints of the asymptotic geometry. ..... 32
4.1 Background ..... 32
4.2 Main Theorem ..... 33
4.3 Preliminary ..... 33
4.4 Calculations ..... 34
4.4.1 Killing vectors of the model metric ..... 34
4.4.2 Shifting preserves the assumption 1 ..... 37
4.4.3 Rigidity of the soliton vector ..... 39
4.4.4 Decay rate of Ricci of the model metric ..... 41
4.4.5 Main Argument ..... 43
Bibliography ..... 45
Vita ..... 52


#### Abstract

This thesis contains my work during my Ph.D. studies at Lehigh University under the guidance of my advisor Huai-Dong Cao. The work is related to objects called Ricci solitons which serve as singularity models of Ricci flow. We are going to study Ricci solitons in this thesis from the following aspects: 1. Curvature properties. 2. Volume growth properties. 3. Uniqueness under constraints of the asymptotic geometry.

We first explore the curvature estimate for four dimensional steady Ricci solitons. The main result is about control of the full curvature tensor Rm by scalar curvature $R$.

We are then going to study curvature and volume growth properties of complete steady Kahler Ricci solitons with positive Ricci curvature. The main result is that volume growth is at least half dimensional and scalar curvature behaves like $\frac{1}{r}$ in average where $r$ is the geodesic distance to some point.

In the third part, we are going to study the uniqueness of the steady Kahler Ricci soliton constructed by Huai-Dong Cao under constraints of the asymptotic geometry. The main result says that it is unique if we ask that the metric tensor be $C^{1}$ close in some sense to the model.


## Chapter 1

## Preliminary

### 1.1 Definition of Ricci solitons

The Ricci flow is a geometric PDE introduced by R. Hamilton in 1982 [37]. It is a nonlinear weakly parabolic system which evolves the metric tensor by its Ricci tensor,

$$
\frac{\partial}{\partial t} g_{i j}=-2 R_{i j}
$$

It is a powerful tool in the study of the geometry of the underlying manifold where this PDE system evolves. For example, it is the primary tool used in G. Perelman's solution of the Poincaré conjecture[51]. It has also been applied by R. Schoen and S. Brendle[5] in the proof of the differentiable sphere theorem.

Singularity analysis is one of the main parts of studying the Ricci flow. Self similar solutions, called Ricci solitons arise during singularity analysis.

Definition 1.1.1. A complete Riemannian manifold $(M, g)$ is called a Ricci soliton, if there exists a complete vector field $V$, such that

$$
R_{i j}+\frac{1}{2} \mathcal{L}_{V} g_{i j}=\lambda g_{i j}
$$

for some constant $\lambda \in \mathbb{R}$.

Based on the sign of $\lambda$, they divide into three types, namely shrinking $(\lambda>0)$, steady $(\lambda=0)$ and expanding $(\lambda<0)$.

Moreover, if $V$ is a gradient vector field, i.e., $V=\nabla f$, then we say it is a gradient Ricci soliton with potential function $f$. In the these we are going to focus on gradient steady solitons $(V=\nabla f, \lambda=0)$

$$
R_{i j}+\nabla_{i} \nabla_{j} f=0
$$

Ricci solitons are natural generalization of Einstein manifolds $(V=0)$. The self similar solution generated by a Ricci soliton often appears as a singularity model, i.e., the parabolic dilation limit of Ricci flow near a singularity. Therefore, the structure of Ricci soliton helps us know more about the Ricci flow near itsp singularity.

### 1.2 Curvature equations and inequalities

Lemma 1.2.1. (Hamilton [39]) Let $\left(M^{n}, g_{i j}, f\right)$ be a complete gradient steady soliton satisfying Eq. (1.1). Then

$$
\begin{gather*}
R=-\Delta f,  \tag{1.1}\\
\nabla_{i} R=2 R_{i j} \nabla_{j} f,  \tag{1.2}\\
R+|\nabla f|^{2}=C_{0}  \tag{1.3}\\
\nabla_{l} R_{i j k l}=R_{i j k l} \nabla_{l} f \tag{1.4}
\end{gather*}
$$

We also collect several equations and inequalities of $R$, Ric and Rm (cf. [39],[54]).
Lemma 1.2.2. Let $\left(M^{n}, g_{i j}, f\right)$ be a complete gradient steady soliton satisfying Eq.
(1.1). Then, we have

$$
\begin{aligned}
\Delta_{f} R & =-2|R i c|^{2} \\
\Delta_{f} R i c & =-2 R_{i j k l} R_{j l} \\
\Delta_{f} R m & =R m * R m
\end{aligned}
$$

where $*$ means linear combinations of contractions between tensors, $\Delta_{f}$ is the $f$ Laplacian operatorp $\Delta-\nabla f \cdot \nabla$.

Lemma 1.2.3. Let $\left(M^{n}, g_{i j}, f\right)$ be a complete gradient steady soliton satisfying Eq. (1.1). Then

$$
\begin{aligned}
\Delta_{f}|R i c|^{2} & \geq 2|\nabla R i c|^{2}-4|R m||R i c|^{2} \\
\Delta_{f}|R m| & \geq-c|R m|^{2} \\
\Delta_{f}|R m|^{2} & \geq 2|\nabla R m|^{2}-C|R m|^{3}
\end{aligned}
$$

Here $c>0$ is some universal constant depending only on the dimension $n$.
Remark 1.2.1. To derive the second differential inequality, one needs to use the Kato inequality $|\nabla| R m||\leq|\nabla R m|$ as shown in [45].

To get nonnegativity of scalar curvature, we will need the following useful result by B.-L. Chen [22].

Proposition 1.2.1. (B.-L Chen [22]) Let $g_{i j}(t)$ be a complete ancient solution to the Ricci flow on a noncompact manifold $M^{n}$. Then the scalar curvature $R$ of $g_{i j}(t)$ is nonnegative for all $t$.

Since gradient steady solitons generate self silimar solutions which are not just ancient but eternal, we have,

Lemma 1.2.4. Let $\left(M^{n}, g_{i j}, f\right)$ be a complete gradient steady soliton. Then it has nonnegative scalar curvature $R \geq 0$.

Remark 1.2.2. In fact, by Proposition 3.2 in [54], either $R>0$ or $\left(M^{n}, g_{i j}\right)$ is Ricci flat.

### 1.3 Basic properties of solitons

Let us compare some previous results for complete gradient shrinking and steady Ricci solitons.

| Properties | Shrinking solitons | Steady solitons |
| :---: | :---: | :---: |
| Potential function growth | $f \sim \frac{1}{4} r^{2},[15]$ | (1) If $R c>0, R$ attains maximum, $c_{1} r-c_{2} \leq-f \leq \sqrt{R_{\max }} r+c_{3},[16]$ |
|  |  | (2)inf $\inf _{y \in \partial B_{r}(x)} f(y) \sim-\sqrt{\Lambda} r,[63]$ |
| Volume growth | (1) $\operatorname{Vol}\left(B_{r}\right) \leq c r^{n},[15]$ | (1)c $\cdot r \leq \operatorname{Vol}\left(B_{p}(r)\right) \leq c \cdot e^{a \sqrt{r}},[44]$ |
|  | (2) $\operatorname{Vol}\left(B_{r}\right) \geq c r,[46]$ |  |
|  | $\begin{aligned} & \text { (3)If } R c \geq 0 \text {, then } \\ & \lim _{r \rightarrow \infty} \frac{\operatorname{Vol}\left(B_{r}\right)}{r^{n}}=0, \end{aligned}$ | (2) If $f$ satisfies a uniform condition, $\operatorname{Vol}\left(B_{r}\right) \leq r^{n}$. [61] |

### 1.4 Some examples of steady solitons

Steady solitons arise as certain Type II singularity models of the Ricci flow. Recall a gradient steady Ricci soliton satisfies

$$
R_{i j}+f_{i j}=0 .
$$

Therefore Ricci flat spaces are steady solitons if we pick our potential function $f$ to be 0 . Indeed, by an argument of Hamilton [39], a compact steady soliton has to be trivial (Ricci flat). Therefore a nontrivial steady soliton is noncompact. Many people have constructed nontrivial steady solitons and we list some of them.

| Space | $\mathbb{R}^{2}$ | $\mathbb{R}^{n}(n \geq 3)$ | $\mathbb{C}^{n}(n \geq 2)$ |
| :--- | :--- | :--- | :--- |
| Metric Ansatz | $S O(2)$ or $U(1)$ | $S O(n)$ | $U(n)$ |
| Potential function | $f=-\ln \cosh (r)$ | $f \sim-c r$ | $f \sim-c r$ |
| Volume Growth | $\operatorname{Vol}\left(B_{r}\right) \sim r$ | $\operatorname{Vol}\left(B_{r}\right) \sim r^{\frac{n+1}{2}}$ | $\operatorname{Vol}\left(B_{r}\right) \sim r^{n}$ |
| Curvature | $R(g)>0$, | $\sec (g)>0$, | $\sec (g)>0$, |
|  | $R=O\left(e^{-2 r}\right)$ | $R=O\left(\frac{1}{r}\right)$ | $R=O\left(\frac{1}{r}\right)$ |
| Found by | R. Hamilton, [38] | R. Bryant, [8] | H.-D. Cao, [11] |

## Chapter 2

## Curvature estimates for fourdimensional steady solitons

### 2.1 Background

A complete Riemannian metric $g_{i j}$ on a smooth manifold $M^{n}$ is called a gradient steady Ricci soliton if there exists a smooth function $f$ on $M^{n}$ such that the Ricci tensor $R_{i j}$ of the metric $g_{i j}$ satisfies the equation

$$
\begin{equation*}
R_{i j}+\nabla_{i} \nabla_{j} f=0 \tag{2.1}
\end{equation*}
$$

The function $f$ is called a potential function of the gradient steady soliton. Clearly, when $f$ is a constant the gradient steady Ricci soliton $\left(M^{n}, g_{i j}, f\right)$ is simply a Ricciflat manifold. Gradient steady solitons play an important role in Hamilton's Ricci flow, as they correspond to translating solutions, and often arise as Type II singularity models. Thus one is interested in possibly classifying them or understanding their geometry.

It turns out that compact steady solitons must be Ricci-flat. In dimension $n=2$, Hamilton [36] discovered the first example of a complete noncompact gradient steady
soliton on $\mathbb{R}^{2}$, called the cigar soliton, where the metric is given by

$$
d s^{2}=\frac{d x^{2}+d y^{2}}{1+x^{2}+y^{2}}
$$

The cigar soliton has potential function $f=-\log \left(1+x^{2}+y^{2}\right)$, positive curvature $R=4 e^{f}$, and is asymptotic to a cylinder at infinity. Furthermore, Hamilton [36] showed that the only complete steady soliton on a two-dimensional manifold with bounded (scalar) curvature $R$ which assumes its maximum at an origin is, up to scaling, the cigar soliton. For $n \geq 3$, Bryant [10] proved that there exists, up to scaling, a unique complete rotationally symmetric gradient Ricci soliton on $\mathbb{R}^{n}$; see, e.g., Chow et al. [28] for details. The Bryant soliton has positive sectional curvature, linear curvature decay and volume growth of geodesic balls $B(0, r)$ on the order of $r^{(n+1) / 2}$. In the Kähler case, Cao [11] constructed a complete $U(m)$-invariant gradient steady Kähler-Ricci soliton on $\mathbb{C}^{m}$, for $m \geq 2$, with positive sectional curvature. It has volume growth on the order of $r^{m}$ and also linear curvature decay. Note that in each of these three examples, the maximum of the scalar curvature is attained at the origin. One can find additional examples of steady solitons, e.g., in [41, 43, 30, 31, 3] etc; see also [14] and the references therein.

In dimension $n=3$, Perelman [52] claimed that the Bryant soliton is the only complete noncompact, $\kappa$-noncollapsed, gradient steady soliton with positive sectional curvature. Recently, Brendle has affirmed this conjecture of Perelman (see [6]; and also [7] for an extension to the higher dimensional case). On the other hand, for $n \geq 4$, Cao-Chen [16] and Catino-Mantegazza [20] proved independently, and using different methods, that any $n$-dimensional complete noncompact locally conformally flat gradient steady Ricci soliton $\left(M^{n}, g_{i j}, f\right)$ is either flat or isometric to the Bryant soliton (the method of Cao-Chen [16] also applies to the case of dimension $n=3$ ). In addition, Bach-flat gradient steady solitons (with positive Ricci curvature) for all $n \geq 3$ [19] and half-conformally flat ones for $n=4$ [25] have been classified respectively.

Inspired by the very recent work of Munteanu-Wang [45], in [17] we studied curvature estimates of four-dimensional complete noncompact gradient steady solitons.

In [45], Munteanu and Wang made an important observation that the curvature tensor of a four-dimensional gradient Ricci soliton $\left(M^{4}, g_{i j}, f\right)$ can be estimated in terms of the potential function $f$, the Ricci tensor and its first derivates. In addition, the (optimal) asymptotic quadratic growth property of the potential function $f$ proved in [15], as well as a key scalar curvature lower bound $R \geq c / f$ shown in [29] are crucial in their work. Even though gradient steady Ricci solitons in general don't share these two special features (cf. [63, 44, 61] and [29, 34]), some of the arguments in [45] can still be adapted to prove certain curvature estimates for two classes of gradient steady solitons.

### 2.2 Main Results

Theorem 2.2.1. Let $\left(M^{4}, g_{i j}, f\right)$ be a complete noncompact 4-dimensional gradient steady Ricci soliton with positive Ricci curvature Ric $>0$ such that the scalar curvature $R$ attains its maximum at some point $x_{0} \in M^{4}$. Then, $\left(M^{4}, g_{i j}\right)$ has bounded Riemann curvature tensor, i.e.

$$
\sup _{x \in M}|R m| \leq C
$$

for some constant $C>0$. If in addition $R$ has at most linear decay, then

$$
\sup _{x \in M} \frac{|R m|}{R} \leq C
$$

Theorem 2.2.2. Let $\left(M^{4}, g_{i j}, f\right)$, which is not Ricci-flat, be a complete noncompact 4-dimensional gradient steady Ricci soliton. If $\lim _{x \rightarrow \infty} R(x)=0$, then, for each $0<a<1$, there exists a constant $C>0$ such that

$$
|R i c|^{2} \leq C R^{a} \quad \text { and } \quad \sup _{x \in M}|R m| \leq C
$$

Suppose in addition $R$ has at most polynomial decay. Then, for each $0<a<1$,
there exists a constant $C>0$ such that

$$
|R m|^{2} \leq C R^{a}
$$

### 2.3 Preliminaries

It follows from Remark 1.2.2 that the constant $C_{0}$ in (1.3) is positive whenever $f$ is a non-constant function (i.e., the steady soliton is non-trivial). By a suitable scaling of the metric $g_{i j}$, we can normalize $C_{0}=1$ so that

$$
\begin{equation*}
R+|\nabla f|^{2}=1 \tag{2.2}
\end{equation*}
$$

In the rest of this chapter, we shall always assume this normalization (2.4).
Combining (2.1) and (2.4), we obtain $-\Delta f+|\nabla f|^{2}=1$. Thus, setting $F=-f$,

$$
\begin{equation*}
\Delta_{f} F=1 \tag{2.3}
\end{equation*}
$$

For gradient steady solitons with positive Ricci curvature Ric>0,
Proposition 2.3.1. (Cao-Chen [16]) Let $\left(M^{n}, g_{i j}, f\right)$ be a complete noncompact gradient steady soliton with positive Ricci curvature Ric $>0$ such that the scalar curvature $R$ attains its maximum $R_{\max }=1$ at some point $x_{0} \in M^{n}$. Then, there exist some constants $0<c_{1} \leq 1$ and $c_{2}>0$ such that $F=-f$ satisfies the estimates

$$
\begin{equation*}
c_{1} r(x)-c_{2} \leq F(x) \leq r(x)+\left|F\left(x_{0}\right)\right|, \tag{2.4}
\end{equation*}
$$

where $r(x)=d\left(x_{0}, x\right)$ is the distance function from $x_{0}$.
Remark 2.3.1. In (2.4), only the lower bound on $F$ requires the assumptions on Ric and $R$. Note that, under the assumption in Proposition 2.3.1, $F(x)$ is proportional to the distance function $r(x)=d\left(x_{0}, x\right)$ from above and below. Throughout the
chapter, we denote

$$
\begin{aligned}
D(t) & =\{x \in M: F(x) \leq t\} \\
B(t)=B\left(x_{0}, t\right) & =\left\{x \in M: d\left(x_{0}, x\right) \leq t\right\} .
\end{aligned}
$$

### 2.4 Case 1: steady soliton with Ric $>0$

First of all, we need the following key fact, valid for 4-dimensional gradient steady Ricci solitons in general, due to Munteanu and Wang [45].

Lemma 2.4.1. (Munteanu-Wang [45]) Let $\left(M^{4}, g_{i j}, f\right)$ be a complete noncompact gradient steady soliton satisfying (1.1). Then there exists some universal constant $c>0$ such that

$$
|R m| \leq c\left(\frac{|\nabla R i c|}{|\nabla f|}+\frac{|R i c|^{2}}{|\nabla f|^{2}}+\mid \text { Ric } \mid\right)
$$

Proof. This follows from the same arguments as in the proof of Proposition 1.1 of [45], but without replacing $|\nabla f|^{2}$ by $f$ in their argument.

Proposition 2.4.1. Let $\left(M^{4}, g_{i j}, f\right)$ be a complete noncompact gradient steady soliton with positive Ricci curvature such that $R$ attains a maximum. Then, there exists some constant $C>0$, depending on the constant $c_{1}$ in (2.7), such that outside a compact set,

$$
|R m| \leq C\left(|\nabla R i c|+|R i c|^{2}+|R i c|\right)
$$

Proof. This easily follows from Lemma 2.4.1 and the following fact shown by CaoChen [16]:

$$
\begin{equation*}
|\nabla f|^{2} \geq c_{1}>0 \tag{2.5}
\end{equation*}
$$

Remark 2.4.1. Note that, combining (2.5) with (2.2) and (2.3), we have

$$
\begin{equation*}
0<c_{1} \leq|\nabla F|^{2}=|\nabla f|^{2} \leq 1 \tag{2.6}
\end{equation*}
$$

Now we are ready to prove our first main result.
Theorem 2.4.1. Let $\left(M^{4}, g_{i j}, f\right)$ be a complete noncompact gradient steady soliton with positive Ricci curvature Ric $>0$ such that $R$ attains its maximum at some point $x_{0} \in M^{4}$. Then, there exists some constant $C>0$, depending on $c_{1}$ in (2.5), such that

$$
\sup _{x \in M}|R m| \leq C
$$

Proof. First of all, from (2.4), we have $R \leq 1$. Hence, since Ric $>0$, it follows that

$$
\begin{equation*}
0<|R i c| \leq R \leq 1 \tag{2.7}
\end{equation*}
$$

Thus, by Proposition 2.4.1 and (2.7), we see that

$$
\begin{equation*}
|\nabla R i c|^{2} \geq \frac{1}{2 C^{2}}|R m|^{2}-\left(|R i c|^{2}+|R i c|\right)^{2} \geq \frac{1}{2 C^{2}}|R m|^{2}-4 \tag{2.8}
\end{equation*}
$$

Using the first two inequalities in Lemma 1.2.3, we obtain

$$
\begin{equation*}
\Delta_{f}\left(|R m|+\lambda|R i c|^{2}\right) \geq-C|R m|^{2}+2 \lambda\left(|\nabla R i c|^{2}-2|R m||R i c|^{2}\right) \tag{2.9}
\end{equation*}
$$

By (2.8), (2.9), and picking constant $\lambda>0$ sufficiently large (depending on the constant $C$ in Proposition 2.4.1, hence on $c_{1}$ ), it follows that

$$
\begin{equation*}
\Delta_{f}\left(|R m|+\lambda|R i c|^{2}\right) \geq 2|R m|^{2}-4 \lambda|R m|-C^{\prime} \geq\left(|R m|+\lambda|R i c|^{2}\right)^{2}-C \tag{2.10}
\end{equation*}
$$

Next, let $\varphi(t)$ be a smooth function on $\mathbb{R}^{+}$so that $0 \leq \varphi(t) \leq 1, \varphi(t)=1$ for $0 \leq t \leq R_{0}, \varphi(t)=0$ for $t \geq 2 R_{0}$, and

$$
\begin{equation*}
t^{2}\left(\left|\varphi^{\prime}(t)\right|^{2}+\left|\varphi^{\prime \prime}(t)\right|\right) \leq c \tag{2.11}
\end{equation*}
$$

for some universal constant $c$ and $R_{0}>0$ arbitrary large. We now take $\varphi=\varphi(F(x))$ as a cut-off function with support in $D\left(2 R_{0}\right)$. Note that

$$
\begin{equation*}
|\nabla \varphi|=\left|\varphi^{\prime}\right||\nabla F| \leq \frac{c}{R_{0}} \quad \text { and } \quad\left|\Delta_{f} \varphi\right| \leq\left|\varphi^{\prime} \Delta_{f} F\right|+\left|\varphi^{\prime \prime}\right||\nabla F|^{2} \leq \frac{c}{R_{0}} \tag{2.12}
\end{equation*}
$$

on $D\left(2 R_{0}\right) \backslash D\left(R_{0}\right)$ for some universal constant $c$.
Setting $u=|R m|+\lambda|R i c|^{2}$ and $G=\varphi^{2} u$, then direct computations, (2.10) and (2.12) yield

$$
\begin{aligned}
\varphi^{2} \Delta_{f} G & =\varphi^{4} \Delta_{f} u+\varphi^{2} u \Delta_{f}\left(\varphi^{2}\right)+2 \varphi^{2} \nabla u \cdot \nabla \varphi^{2} \\
& \geq \varphi^{4}\left(u^{2}-C\right)+\varphi^{2} u\left(2 \varphi \Delta_{f} \varphi+2|\nabla \varphi|^{2}\right)+2 \nabla G \cdot \nabla \varphi^{2}-8|\nabla \varphi|^{2} G \\
& \geq G^{2}+2 \nabla G \cdot \nabla \varphi^{2}-C G-C
\end{aligned}
$$

Now it follows from the maximum principle that $G \leq C$ on $D\left(2 R_{0}\right)$ by some constant $C>0$ depending on $c_{1}$ but independent of $R_{0}$. Hence $u=|R m|+\lambda|R i c|^{2} \leq C$ on $D\left(R_{0}\right)$. Since $R_{0}>0$ is arbitrary large, we see that

$$
\sup _{x \in M}|R m| \leq \sup _{x \in M}\left(|R m|+\lambda|R i c|^{2}\right) \leq C
$$

This completes the proof of Theorem 2.4.1.
Proposition 2.4.2. Let $\left(M^{4}, g_{i j}, f\right)$ be a complete noncompact gradient steady soliton with positive Ricci curvature Ric $>0$ and $R$ attains its maximum at $x_{0} \in M^{4}$. Then the function $u=\frac{|R m|+\lambda \mid \text { Ric }\left.\right|^{2}}{R}$, with $\lambda>0$ sufficiently large, satisfies the differential inequality

$$
\Delta_{f} u \geq u^{2} R-C R-2 \nabla u \cdot \nabla(\log R)
$$

for some constant $C>0$ outside a compact set.
Proof. First of all, by an argument similar to that of (2.8)-(2.10) in the proof of Theorem 2.4.1, by choosing $\lambda$ sufficiently large we have

$$
\begin{aligned}
\Delta_{f}\left(|R m|+\lambda|R i c|^{2}\right) & \geq\left(|R m|+\lambda|R i c|^{2}\right)^{2}-4 \lambda^{2}|R i c|^{4}-\lambda\left(|R i c|^{4}+|R i c|^{2}\right) \\
& \geq\left(|R m|+\lambda|R i c|^{2}\right)^{2}-C|R i c|^{2}
\end{aligned}
$$

for some constant $C>0$. Here we have also used the fact (2.8).

Thus, by a direct computation,

$$
\begin{aligned}
\Delta_{f} u= & R^{-1} \Delta_{f}\left(|R m|+\lambda|R i c|^{2}\right)+(u R) \Delta_{f}\left(R^{-1}\right)+2 \nabla(u R) \cdot \nabla\left(R^{-1}\right) \\
\geq & \frac{\left(|R m|+\lambda|R i c|^{2}\right)^{2}-C|R i c|^{2}}{R}+(u R)\left[2 \frac{|R i c|^{2}}{R^{2}}+2 \frac{|\nabla R|^{2}}{R^{3}}\right] \\
& -\frac{2}{R^{2}}\left(u|\nabla R|^{2}+R \nabla u \cdot \nabla R\right) \\
\geq & R u^{2}-C R-2 \nabla u \cdot \nabla \log R .
\end{aligned}
$$

Theorem 2.4.2. Let $\left(M^{4}, g_{i j}, f\right)$ be a complete noncompact gradient steady Ricci soliton with Ric $>0$ such that $R$ attains its maximum. Suppose $R$ has at most linear decay, i.e. for some $c>0, R(x) \geq c / r(x)$, outside a compact set. Then

$$
\sup _{x \in M} \frac{|R m|}{R} \leq C
$$

Proof. Fix $\lambda$ sufficient large so that Proposition 2.4.2 holds and set $u=\frac{|R m|+\lambda|R i c|^{2}}{R}$. Next, let $\varphi(t)$ be a Lipschitz function on $\mathbb{R}^{+}$so that $\varphi(t)=\frac{d-t}{d}$ for $0 \leq t \leq d$, $\varphi(t)=0$ for $t \geq d$. Let $\varphi=\varphi(F)$ and $G=\varphi^{2} u$. Then on $D(d) \backslash D(1) \varphi$ satisfies,

$$
\begin{aligned}
& |\nabla \varphi|=\left|\varphi^{\prime} \nabla F\right| \leq \frac{1}{d} \\
& \Delta_{f} \varphi=\varphi^{\prime} \Delta_{f} F=-\frac{1}{d}
\end{aligned}
$$

Then outside $D(1)$, we have,

$$
\begin{aligned}
\varphi^{2} \triangle_{f}(G)= & \varphi^{4}\left(\triangle_{f} u\right)+\varphi^{2} u\left(\triangle_{f} \varphi^{2}\right)+2 \varphi^{2} \nabla \varphi^{2} \cdot \nabla u \\
\geq & \varphi^{4}\left(R u^{2}-c R-2 \nabla u \cdot \nabla \log R\right) \\
& +2\left(\varphi \triangle_{f} \varphi+|\nabla \varphi|^{2}\right) G+2 \varphi^{2} \nabla \varphi^{2} \cdot \nabla u \\
\geq & R G^{2}-c R+4 \varphi(\nabla \varphi \cdot \nabla \log R) G \\
& -\frac{8}{d} G+\left(2 \nabla \varphi^{2}-2 \varphi^{2} \nabla \log R\right) \cdot \nabla G
\end{aligned}
$$

Now by Lemma 1.2.3 and Ric $>0$, we have $|\nabla \log R|=2\left|\frac{R i c(\nabla f)}{R}\right| \leq 2$. Also, when $R$ has at most linear decay outside some $D\left(t_{0}\right)$ and for $d>t_{0}$, we have $R \geq \frac{a}{d}$ in $D(d) \backslash D\left(t_{0}\right)$ for some constant $a>0$ independent $d$. Therefore there exists $c$ independent of $d$ such that on $D(d) \backslash D(1)$, following inequalities holds,

$$
\begin{aligned}
\varphi^{2} \triangle_{f}(G) & \geq R G^{2}-c R-\frac{c}{d} G+\left(2 \nabla \varphi^{2}-2 \varphi^{2} \nabla \log R\right) \cdot \nabla G \\
& \geq \frac{1}{2} R G^{2}-c R+\left(2 \nabla \varphi^{2}-2 \varphi^{2} \nabla \log R\right) \cdot \nabla G
\end{aligned}
$$

Recall $u>0$, therefore the maximum of $G_{d}$ must attains in the interior of $D(d)$. Then it follows from maximum principle argument that $u \leq C$ on $M^{4}$, hence $|R m| \leq$ $C R$ on $M^{4}$.

### 2.5 Case 2: steady soliton with $\lim _{x \rightarrow \infty} R(x)=0$

In this section, we prove our second main result, Theorem 2.2.2. Throughout the section we assume $\left(M^{4}, g_{i j}, f\right)$ is a complete noncompact, non Ricci-flat, 4-dimensional gradient steady Ricci soliton such that

$$
\begin{equation*}
\lim _{x \rightarrow \infty} R(x)=0 \tag{2.13}
\end{equation*}
$$

Note that, by Remark $1.2 .2,\left(M^{4}, g_{i j}, f\right)$ necessarily satisfies $R>0$.
First of all, we need the following useful Laplacian comparison type result for gradient Ricci solitons.

Lemma 2.5.1. Let $\left(M^{n}, g_{i j}, f\right)$ be any gradient steady Ricci soliton and let $r(x)=$ $d\left(x_{0}, x\right)$ denote the distance function on $M^{n}$ from a fixed base point $x_{0}$. Suppose that

$$
R i c \leq(n-1) K
$$

on the geodesic ball $B\left(x_{0}, r_{0}\right)$ for some constants $r_{0}>0$ and $K>0$. Then, for any
$x \in M^{n} \backslash B\left(x_{0}, r_{0}\right)$, we have

$$
\Delta_{f} r(x) \leq(n-1)\left(\frac{2}{3} K r_{0}+r_{0}^{-1}\right)
$$

Remark 2.5.1. Lemma 2.5.1 is a special case of a more general result valid for solutions to the Ricci flow due to Perelman [51], see, e.g., Lemma 3.4.1 in [18]. Also see [33] and [62] for a different version.

Theorem 2.5.1. Let $\left(M^{4}, g_{i j}, f\right)$ be a complete noncompact gradient steady Ricci soliton which is not Ricci-flat,. If $\lim _{x \rightarrow \infty} R(x)=0$, then, for each $0<a<1$, there exists a constant $C>0$ such that

$$
\sup _{x \in M}|R i c|^{2} \leq C R^{a} \quad \text { and } \quad \sup _{x \in M}|R m| \leq C
$$

Proof. The proof is similar to that of Munteanu-Wang [45] except we need to use the distance function to cut-off rather than the potential function since the potential function may not be proper.

Since $\lim _{x \rightarrow \infty} R(x)=0$, it follows from (2.4) that

$$
|\nabla f| \geq c_{1}>0
$$

for some $0<c_{1}<1$ outside a compact set. By Lemma 1.2.1 and Lemma 2.4.1, we have

$$
\begin{aligned}
\Delta_{f}|R i c|^{2} & \geq 2|\nabla R i c|^{2}-C \mid \text { Rm }|\mid \text { Ric }|^{2} \\
& \geq 2|\nabla R i c|^{2}-C\left(|\nabla R i c|+\mid \text { Ric }\left.\right|^{2}+\mid \text { Ric } \mid\right) \mid \text { Ric }\left.\right|^{2}
\end{aligned}
$$

Also, since $R>0$ on $M^{4}$, by using the first identity in Lemma 2.3 we have

$$
\Delta_{f}\left(\frac{1}{R^{a}}\right)=2 a \frac{|R i c|^{2}}{R^{a+1}}+a(a+1) \frac{|\nabla R|^{2}}{R^{a+2}}
$$

Hence,

$$
\begin{aligned}
\Delta_{f}\left(\frac{|R i c|^{2}}{R^{a}}\right)= & \frac{\Delta_{f}|R i c|^{2}}{R^{a}}+|R i c|^{2} \Delta_{f}\left(\frac{1}{R^{a}}\right)+2 \nabla|R i c|^{2} \cdot \nabla\left(\frac{1}{R^{a}}\right) \\
\geq & \frac{2|\nabla R i c|^{2}}{R^{a}}-C \frac{\left(|\nabla R i c|+|R i c|^{2}+|R i c|\right)|R i c|^{2}}{R^{a}} \\
& +|R i c|^{2}\left[2 a \frac{|R i c|^{2}}{R^{a+1}}+a(a+1) \frac{|\nabla R|^{2}}{R^{a+2}}\right]-4 a \frac{|R i c||\nabla| R i c| ||\nabla R|}{R^{a+1}}
\end{aligned}
$$

Apply Cauchy's inequality to the last term

$$
\begin{aligned}
-4 a \frac{|R i c||\nabla| R i c| ||\nabla R|}{R^{a+1}} & \geq-4 a \frac{|R i c||\nabla R i c||\nabla R|}{R^{a+1}} \\
& \geq-a(a+1) \frac{|R i c|^{2}|\nabla R|^{2}}{R^{a+2}}-\frac{4 a}{a+1} \frac{|\nabla R i c|^{2}}{R^{a}}
\end{aligned}
$$

Thus, we have

$$
\begin{aligned}
\Delta_{f}\left(|R i c|^{2} R^{-a}\right) \geq & \frac{2(1-a)}{1+a} \frac{|\nabla R i c|^{2}}{R^{a}}-C \frac{|\nabla R i c||R i c|^{2}}{R^{a}} \\
& -C \frac{\mid \text { Ric }\left.\right|^{4}+\mid \text { Ric }\left.\right|^{3}}{R^{a}}+2 a \frac{|R i c|^{4}}{R^{a+1}} \\
\geq & \left(2 a-\frac{C R}{1-a}\right) \frac{|R i c|^{4}}{R^{a+1}}-C \frac{|R i c|^{3}}{R^{a}}
\end{aligned}
$$

Therefore, for $u=\frac{|R i c|^{2}}{R^{a}}$, we have derived the differential inequality

$$
\begin{equation*}
\Delta_{f} u \geq\left(2 a-\frac{C R}{1-a}\right) u^{2} R^{a-1}-C u^{3 / 2} R^{a / 2} \tag{2.14}
\end{equation*}
$$

Since $R \rightarrow 0$, for any $0<a<1$, we can choose a fixed $d_{0}>0$ depending on $a$ and sufficiently large so that

$$
\begin{equation*}
\left(2 a-\frac{C R}{1-a}\right) \geq a \tag{2.15}
\end{equation*}
$$

outside the geodesic ball $B\left(x_{0}, d_{0}\right)$.
Next, for any $D_{0}>2 d_{0}$, we choose a function $\varphi(t)$ as follows: $0 \leq \varphi(t) \leq 1$ is a
smooth function on $\mathbb{R}$ such that

$$
\varphi(t)= \begin{cases}1, & 2 d_{0} \leq t \leq D_{0} \\ 0, & t \leq d_{0} \text { or } t \geq 2 D_{0}\end{cases}
$$

Also,

$$
\begin{equation*}
t^{2}\left|\varphi^{\prime \prime}(t)\right| \leq c \quad \text { and } \quad 0 \geq \varphi^{\prime}(t) \geq-\frac{c}{D_{0}}, \text { if } 2 d_{0} \leq t \leq 2 D_{0} \tag{2.16}
\end{equation*}
$$

Now we use $\varphi=\varphi(r(x))$ as a cut-off function whose support is in $B\left(x_{0}, 2 D_{0}\right) \backslash$ $B\left(x_{0}, d_{0}\right)$. Note that by lemma 2.5.1, we get

$$
\begin{equation*}
|\nabla \varphi|^{2}=\left|\varphi^{\prime}\right|^{2} \leq \frac{c}{D_{0}^{2}} \quad \text { and } \quad \Delta_{f} \varphi=\varphi^{\prime} \Delta_{f} r(x)+\varphi^{\prime \prime} \geq-\frac{C}{D_{0}} \tag{2.17}
\end{equation*}
$$

on $B\left(x_{0}, 2 D_{0}\right) \backslash B\left(x_{0}, 2 d_{0}\right)$ respectively.
Setting $G=\varphi^{2} u$, then by our choice of $\varphi$ and (2.17), we see that

$$
\begin{aligned}
\varphi^{2} \Delta_{f} G & =\varphi^{4} \Delta_{f} u+\varphi^{2} u \Delta_{f} \varphi^{2}+2 \varphi^{2}\left(\nabla u \cdot \nabla \varphi^{2}\right) \\
& \geq \varphi^{4}\left(a u^{2} R^{a-1}-C u^{3 / 2} R^{a / 2}\right)+2 \varphi^{2} u\left(\Delta_{f} \varphi^{2}\right)-8|\nabla \varphi|^{2} G+2 \nabla G \cdot \nabla \varphi^{2} \\
& \geq a G^{2} R^{a-1}-C G^{3 / 2} R^{a / 2}-C G+2 \nabla G \cdot \nabla \varphi^{2}
\end{aligned}
$$

Assume $G$ achieves its maximum at some point $p \in B\left(x_{0}, 2 D_{0}\right)$. If $p \in B\left(x_{0}, 2 D_{0}\right) \backslash$ $B\left(x_{0}, 2 d_{0}\right)$, then it follows from the maximum principle that

$$
0 \geq a G^{2}(p) R^{a-1}(p)-C G^{3 / 2}(p) R^{a / 2}(p)-C G(p)
$$

On the other hand, noticing that the fact $0<a<1$ and $R$ uniformly bounded from above, implies.

$$
G(p) \leq C
$$

for some constant $C$ depending on $a$ but independent of $D_{0}$.

Thus,

$$
\max _{B\left(x_{0}, D_{0}\right)} u \leq \max _{B\left(x_{0}, 2 D_{0}\right)} G \leq \max \left\{C, \max _{B\left(2 d_{0}\right)} u\right\} \leq C^{\prime}
$$

for some $C^{\prime}>0$ indepedent of $D_{0}$. Therefore $|R i c|^{2} \leq C R^{a}$ on $M^{4}$.
It remains to show $|R m| \leq C$ on $M^{4}$. However, once we know $\sup _{x \in M} R i c \leq C$, $|R m| \leq C$ follows essentially from the same argument as in the proof of Theorem 2.4.1. We leave the details to the reader.

Lemma 2.5.2. Let $\left(M^{4}, g_{i j}, f\right)$, which is not Ricci-flat, be a complete noncompact gradient steady Ricci soliton with $\lim _{x \rightarrow \infty} R(x)=0$. Then for each $0<a<1$ and $\mu>0$, there exist constants $\lambda>0$ and $D>0$ so that function

$$
v=\frac{|R m|^{2}+\lambda|R i c|^{2}}{R^{a}}
$$

satisfies the differential inequality

$$
\Delta_{f} v \geq \mu v-D
$$

Proof. By Lemma 1.2.2 and Theorem 2.5.1,

$$
\begin{aligned}
\Delta_{f} v= & \frac{\Delta_{f}\left(|R m|^{2}+\lambda|R i c|^{2}\right)}{R^{a}}+v R^{a} \Delta_{f}\left(\frac{1}{R^{a}}\right)+2 \nabla\left(v R^{a}\right) \cdot \nabla\left(R^{-a}\right) \\
\geq & \frac{2|\nabla R m|^{2}+2 \lambda|\nabla R i c|^{2}}{R^{a}}-c \frac{|R m|^{2}+\lambda|R i c|^{2}}{R^{a}} \\
& +\left(|R m|^{2}+\lambda|R i c|^{2}\right)\left[-a \frac{\triangle_{f} R}{R^{a+1}}+a(a+1) \frac{|\nabla R|^{2}}{R^{a+2}}\right] \\
& -4 a \frac{|R m||\nabla R m||\nabla R|}{R^{a+1}}-4 a \lambda \frac{|R i c||\nabla R i c||\nabla R|}{R^{a+1}}
\end{aligned}
$$

By applying Cauchy's inequality to terms with $|\nabla R|$,

$$
\begin{aligned}
\Delta_{f} v \geq & \frac{2|\nabla R m|^{2}+2 \lambda|\nabla R i c|^{2}}{R^{a}}-c \frac{|R m|^{2}+\lambda|R i c|^{2}}{R^{a}} \\
& -\frac{4 a}{a+1} \frac{|\nabla R m|^{2}}{R^{a}}-\frac{4 a \lambda}{a+1} \frac{|\nabla R i c|^{2}}{R^{a}} \\
\geq & \frac{2 \lambda(1-a)}{1+a} \frac{|\nabla R i c|^{2}}{R^{a}}-c \frac{|R m|^{2}+\lambda|R i c|^{2}}{R^{a}} .
\end{aligned}
$$

Now by Proposition 2.4.1, for some constant $\epsilon>0$, we have

$$
\begin{aligned}
2 \epsilon|R m|^{2} & \leq\left(|\nabla R i c|+|R i c|^{2}+|R c|\right)^{2} \\
& \leq 2|\nabla R i c|^{2}+2\left(|R i c|^{2}+|R i c|\right)^{2}
\end{aligned}
$$

Thus,

$$
\begin{aligned}
\Delta_{f} v & \geq\left[\frac{2 \epsilon \lambda(1-a)}{1+a}-c\right] \frac{|R m|^{2}}{R^{a}}-\left[2 \lambda \frac{1-a}{1+a}(|R i c|+1)^{2}+c \lambda\right] \frac{|R i c|^{2}}{R^{a}} \\
& \geq[\epsilon \lambda(1-a)-c]\left(v-\lambda \frac{|R i c|^{2}}{R^{a}}\right)-\lambda\left[2(1-a)(|R i c|+1)^{2}+c\right] \frac{|R i c|^{2}}{R^{a}}
\end{aligned}
$$

Therefore, by Theorem 2.5.1, for each $0<a<1$ and $\mu>0$ one can choose $\lambda \geq$ $C /(1-a)$, with $C>0$ depending on $\mu$ and sufficiently large, so that

$$
\Delta_{f} v \geq \mu v-D
$$

for some constant $D>0$ depending on $\lambda$.
Theorem 2.5.2. Let $\left(M^{4}, g_{i j}, f\right)$, which is not Ricci-flat, be a complete noncompact gradient steady Ricci soliton with $\lim _{r \rightarrow \infty} R=0$. Suppose $R$ has at most polynomial decay, i.e., $R(x) \geq C / r^{k}(x)$ outside $B\left(r_{0}\right)$ for some fixed $r_{0}>1$, some constant $c>0$ and positive integer $k$. Then, for each $0<a<1$, there exists a constant $C$ such that

$$
|R m| \leq C R^{a / 2}
$$

Proof. Let $p=\frac{k}{2}$. Consider the following function on $\mathbb{R}^{+}$:

$$
\varphi(t)=\left\{\begin{array}{cr}
\left(\frac{d-t}{d}\right)^{p} & 0 \leq t \leq d \\
0 & t \geq d
\end{array}\right.
$$

Next, let $\varphi=\varphi\left(r\left(x_{0}\right)\right)$ on $M^{4}$. Then on $B(d) \backslash\left(C u t\left(x_{0}\right) \cup B\left(r_{0}\right)\right)$ we have,

$$
\begin{aligned}
|\nabla \varphi| & =\frac{p}{d}\left(\frac{d-r}{d}\right)^{p-1}|\nabla r|=\frac{p}{d-r} \varphi \\
\triangle_{f} \varphi & =-\frac{p}{d}\left(\frac{d-r}{d}\right)^{p-1} \triangle_{f} r+\frac{p(p-1)}{d^{2}}\left(\frac{d-r}{d}\right)^{p-2}|\nabla r|^{2} \\
& =\left[-\frac{p}{d-r} \triangle_{f} r+\frac{p(p-1)}{(d-r)^{2}}\right] \varphi
\end{aligned}
$$

Consider $w=v-\frac{D}{\mu}$ with $v=\frac{|R m|^{2}+\lambda|R i c|^{2}}{R^{a}}, \mu$ and $D$ as in Lemma 2.5.2. Then, $w$ satisfies

$$
\triangle_{f} w \geq \mu w
$$

Let $G=\varphi^{2} w$, then on $B(d) \backslash B\left(r_{0}\right)$, we have

$$
\begin{align*}
\triangle_{f} G & =\left(\Delta_{f} \varphi^{2}\right) w+\varphi^{2} \Delta_{f} w+2\left(\nabla \varphi^{2}\right) \cdot \nabla w \\
& \geq\left(2 \varphi \Delta_{f} \varphi+2|\nabla \varphi|^{2}\right) w+\mu \varphi^{2} w+4 \varphi \nabla \varphi \cdot \nabla \frac{G}{\varphi^{2}} \\
& \geq\left(\mu+\frac{2 \triangle_{f} \varphi}{\varphi}-6 \frac{|\nabla \varphi|^{2}}{\varphi^{2}}\right) G+\frac{4}{\varphi}\langle\nabla G, \nabla \varphi\rangle . \tag{2.18}
\end{align*}
$$

Recall that $G=0$ outside $B(d)$. Now consider a maximum point $q$ of $G$.
Case 1. $G(q) \leq 0$. Then, $\max _{B(d)} w \leq 0$.

Case 2. $G(q)>0$ and $q \in B\left(r_{0}\right)$. Then, on $\Omega=B\left(\left(1-\frac{1}{2^{1 / p}}\right) d\right)$, we have

$$
\begin{aligned}
\max _{\Omega} w & \leq \max _{\Omega} \frac{1}{\varphi^{2}} \cdot G(q) \\
& \leq 4 G(q) \\
& \leq 4 \max _{B\left(r_{0}\right)} w
\end{aligned}
$$

Case 3. $G(q)>0$ and $q \notin B\left(r_{0}\right), q \notin C u t\left(x_{0}\right)$. Then we could apply by (2.18) and Lemma 2.5.1, at $q$,

$$
\begin{aligned}
0 & \geq \mu+2 \frac{\triangle_{f} \varphi}{\varphi}-6 \frac{|\nabla \varphi|^{2}}{\varphi^{2}} \\
& \geq \mu-2 p K_{0} \frac{1}{d-r}-\left(4 p^{2}+2 p\right) \frac{1}{(d-r)^{2}}
\end{aligned}
$$

for some constant $K_{0}>0$ depending on $r_{0}$ and $\max _{B\left(r_{0}\right)} \mid$ Ric|. Hence $\frac{1}{d-r(q)}>C$ for some constant $C$ depending on $\mu, p=k / 2$ and $K_{0}$. Thus, we have

$$
\begin{equation*}
d-r(q) \leq c \tag{2.19}
\end{equation*}
$$

for some constant $c>0$ independent of $d$.
Therefore,

$$
\begin{aligned}
\max _{\Omega} w & \leq \max _{\Omega} \frac{1}{\varphi^{2}} \cdot G(q) \\
& \leq 4 G(q) \\
& \leq 4 \frac{(d-r(q))^{2 p}}{d^{2 p}} \frac{\left(|R m|^{2}+\lambda \mid \text { Ric }\left.\right|^{2}\right)}{R^{a}}(q) \\
& \leq C \frac{r^{a k}(q)}{d^{2 p}} \\
& \leq C d^{(a-1) k} \leq C
\end{aligned}
$$

for some constant $C>0$ independent of $d$.
Case 4. $G(q)>0, q \notin B\left(r_{0}\right), q \in C u t\left(x_{0}\right)$. Then we could not apply (2.18) directly since $d\left(x_{0},-\right)$ is not smooth at $p$. Now consider the support function $G_{\epsilon}$
constructed by the following procedure. Firstly, pick any minimal geodesic $\gamma$ from $x_{0}$ to $p$, then choose a point $x_{1} \in \gamma$ very close to $x_{0}$. Notice that $x_{1} \notin \operatorname{Cut}(p)$. Let $\epsilon=d\left(x_{0}, x_{1}\right)$, consider $r_{\epsilon}(x)=d\left(x_{1}, x\right)$. Then we have,

- $r_{\epsilon}(q)+\epsilon=r(q)$
- $r_{\epsilon}(x)+\epsilon \geq r(q)$
- $r_{\epsilon}(x)$ is smooth near $q$

Now consider $G_{\epsilon}(x)=\varphi\left(r_{\epsilon}(x)+\epsilon\right)^{2} w$ where $\varphi$ was defined in the beginning of the section. Then $G_{\epsilon}(x) \leq G(x) \leq G(q)=G_{\epsilon}(q)$. Then we could apply maximum principle at $q$ since $G_{\epsilon}$ is smooth at $q$.

$$
\begin{aligned}
0 & \geq \mu+2 \frac{\triangle_{f} \varphi_{\epsilon}}{\varphi_{\epsilon}}-6 \frac{\left|\nabla \varphi_{\epsilon}\right|^{2}}{\varphi_{\epsilon}^{2}} \\
& \geq \mu-2 p K_{0}\left(x_{1}\right) \frac{1}{d-r_{\epsilon}-\epsilon}-\left(4 p^{2}+2 p\right) \frac{1}{\left(d-r_{\epsilon}-\epsilon\right)^{2}}
\end{aligned}
$$

Hence $\frac{1}{d-r_{\epsilon}(q)-\epsilon}>C$ for some constant $C$ depending on $\mu, p=k / 2$ and $K_{0}\left(x_{1}\right)$. In order to get rid of the dependence of $x_{1}$, we let $\epsilon \rightarrow 0$, then we have

$$
\begin{equation*}
d-r(q) \leq c \tag{2.20}
\end{equation*}
$$

for some constant $c>0$ independent of $d$.
Now follow the exact same argument of Case 3, we get an uniform estimate of $\max _{\Omega} w$ on $\Omega=B\left(\left(1-\frac{1}{2^{1 / p}}\right) d\right)$ which is independent of $d$.

Therefore $\sup _{M} w \leq C$, and hence $|R m|^{2} \leq C R^{a}$ on $M^{4}$ for each $0<a<1$.

## Chapter 3

## Curvature and volume growth of steady Kähler Ricci solitons

### 3.1 Background

We call a Riemannian metric $g_{i j}$ Kähler if there exists a $(1,1)$ tensor $J$ such that

- $J^{2}=-I d_{T M}$
- $g(J X, J Y)=g(X, Y)$ for any $X, Y \in T M$
- $\nabla J=0$

If a steady Ricci soliton is Kähler, we call it a steady Kähler Ricci soliton. For properties of Kähler manifold readers may consult [2], [32]. We are going to list some notations we will use in this chapter.

Firstly consider the complexified tangent bundle $T M^{\mathbb{C}}=T M \otimes \mathbb{C}$. Then extend $J$ by complex linearity. Denote

- $T^{1,0} M=\{X-i J X \mid X \in T M\}$,
- $T^{0,1} M=\{X+i J X \mid X \in T M\}$.

Now extend $g$ using complex linearily to $T M^{\mathbb{C}}=T M \otimes \mathbb{C}$. Then $g_{\mathbb{C}}$ satisfies

- $g_{\mathbb{C}}(\bar{X}, \bar{Y})=\overline{g_{\mathbb{C}}(X, Y)}$
- $g_{\mathbb{C}}(X, \bar{X})>0$ for $X \in T M^{\mathbb{C}}-0$
- $g_{\mathbb{C}}(X, Y)=0$ for $X, Y \in T^{1,0} M$
$g_{\mathbb{C}}$ becomes a Hermitian metric on $T^{1,0} M$, for simplicity we use $g_{i \bar{j}}$ for this Hermitian metric in this chapter. Since $\nabla J=0$, Ric also shares the similar symmetry. We denote $R i c_{i \bar{j}}$ for the non vanishing part of the complexified tensor.

In this part we are going to analyze the asymptotic behaviour of steady Kähler Ricci solitons with positive Ricci curvature. We are going to focus on two parts; the first one is volume growth and the second one is curvature decay.

For the volume growth, when the manifold has nonnegative Ricci curvature the classical Bishop comparison theorem implies the volume growth is at most Euclidean. And under the same condition, the volume growth is at least linear by a result of Yau and Calabi [64]. If furthermore the manifold has positive holomorphic bisectional curvature, Bing-Long Chen and Xi-Ping Zhu showed [23] that the volume growth is at least half Euclidean growth and curvature has to decay in the average sense. Applying their method, we showed that if the manifold is a steady Kähler Ricci soliton metric, then similar results hold when the metric has positive Ricci curvature.

### 3.2 Volume growth

Theorem 3.2.1. For any Kähler Ricci soliton $\left(M^{2 n}, g_{\bar{j}}, f\right)$ with positive Ricci curvature and scalar curvature attaining its maximum, volume growth is at least half Euclidean, i.e.,

$$
\operatorname{Vol}\left(B_{r}\right) \geq c r^{n}
$$

here $r$ is the geodesic distance to some point $x_{0}$.
Proof. Fix $r>1$, and consider positive function $\varphi_{r}=e^{-\frac{F}{r}}$ where $F=-f$. Here we
consider the Ricci form $\Omega=\operatorname{Ric}(J X, Y)$ and Kähler form $\omega=g(J X, Y)$.

$$
\begin{aligned}
& \int_{\left\{\varphi_{r}>\delta\right\}}\left(\varphi_{r}-\delta\right)^{n}(\sqrt{-1})^{n}(\partial \bar{\partial} F)^{n} \\
= & -\int_{\left\{\varphi_{r}>\delta\right\}} n\left(\varphi_{r}-\delta\right)^{n-1}\left(\partial \varphi_{r} \wedge \bar{\partial} F\right) \wedge(\sqrt{-1})^{n}(\partial \bar{\partial} F)^{n-1} \\
= & \int_{\left\{\varphi_{r}>\delta\right\}} n\left(\varphi_{r}-\delta\right)^{n-1}\left(\frac{\varphi_{r}}{r} \partial F \wedge \bar{\partial} F\right) \cdot(\sqrt{-1})^{n}(\partial \bar{\partial} F)^{n-1} \\
\leq & \int_{\left\{\varphi_{r}>\delta\right\}} n\left(\varphi_{r}-\delta\right)^{n-1} \frac{\varphi_{r}}{r}|\nabla F|_{g}^{2} \wedge(\sqrt{-1})^{n-1}(\partial \bar{\partial} F)^{n-1} \wedge \omega \\
\leq & \int_{\left\{\varphi_{r}>\delta\right\}} C_{1}\left(n, R_{0}\right) \frac{\left(\varphi_{r}-\delta\right)^{n-1} \varphi_{r}}{r}(\sqrt{-1})^{n-1}(\partial \bar{\partial} F)^{n-1} \wedge \omega \\
\leq & \int_{\left\{\varphi_{r}>\delta\right\}} C_{2}\left(n, R_{0}\right) \frac{\left(\varphi_{r}-\delta\right)^{n-2} \varphi_{r}^{2}}{r^{2}}(\sqrt{-1})^{n-2}(\partial \bar{\partial} F)^{n-2} \wedge \omega^{2} \\
\cdots & \int_{\left\{\varphi_{r}>\delta\right\}} C_{n}\left(n, R_{0}\right) \frac{\varphi_{r}^{n}}{r^{n}} \omega^{n} \\
\leq & \int_{0}
\end{aligned}
$$

Here $R_{0}$ is the maximum value of scalar curvature, recall we have $|\nabla F|^{2} \leq R_{0}$.
Let $\delta \rightarrow 0$ we get

$$
\int_{M} \varphi_{r}^{n} \Omega^{n} \leq \frac{C\left(n, R_{0}\right)}{r^{n}} \int_{M} \varphi_{r}^{n} \omega^{n}
$$

Left hand side has a strictly lower bound since Ricci form is a positive $(1,1)$ form. Therefore we have,

$$
c \leq \frac{C\left(n, R_{0}\right)}{r^{n}} \int_{M} \varphi_{r}^{n} \omega^{n}
$$

Recall from (2.4) the potential function estimate $c_{1} d(x)-c_{2} \leq F \leq \sqrt{R_{0}} d(x)+$ $\left|F\left(x_{0}\right)\right|$ which gives the following estimate,

$$
\varphi_{r} \leq e^{-\frac{c_{1} d(x)-c_{2}}{r}} \leq C e^{-c_{1} \frac{d}{r}}
$$

outside $B\left(x_{0}, 1\right)$. Therefore we have,

$$
\begin{aligned}
\int_{M} \varphi_{r}^{n} \omega^{n} & \leq C^{\prime} \int_{M} e^{-c_{1} n \frac{d}{r}} \omega^{n} \\
& \leq C^{\prime} \sum_{i=0}^{\infty} \int_{B_{2^{i+1_{r}}-B_{2^{i_{r}}}}} e^{-c_{1} n \frac{d}{r}} \omega^{n}+C^{\prime} \int_{B_{r}} e^{-c_{1} n \frac{d}{r}} \omega^{n} \\
& \leq C^{\prime} \sum_{i=0}^{\infty} \int_{B_{2^{i+11_{r}}}} e^{-c_{1} n \frac{2^{i} r}{r}} \omega^{n}+C^{\prime} \int_{B_{r}} e^{-c_{1} n \frac{r}{r}} \omega^{n} \\
& =C^{\prime} \sum_{i=0}^{\infty} e^{-2^{i} c_{1} n} \int_{B_{2^{i+1} r}} \omega^{n}+C^{\prime} e^{-c_{1} n} \operatorname{Vol}\left(B_{r}\right) \\
& \leq \sum_{i=0}^{\infty} e^{-2^{i} c_{1} n} \operatorname{Vol}\left(B_{2^{i+1} r}\right)+C^{\prime} e^{-c_{1} n} \operatorname{Vol}\left(B_{r}\right) \\
& \leq \sum_{i=0}^{\infty} e^{-2^{i} c_{1} n} 2^{(i+1) 2 n} \operatorname{Vol}\left(B_{r}\right)+C^{\prime} e^{-c_{1} n} \operatorname{Vol}\left(B_{r}\right) \\
& \leq C^{\prime \prime}(c 1, c 2, n) \cdot \operatorname{Vol}\left(B_{r}\right)
\end{aligned}
$$

Here $c_{1}, c_{2}$ come from the estimate for $\varphi_{r}$ from the previous page.
Therefore

$$
c \leq \frac{C\left(n, R_{0}\right)}{r^{n}} \int_{M} \varphi_{r}^{n} \omega^{n} \leq C\left(n, R_{0}, c_{1}, c_{2}\right) \frac{V o l B_{r}}{r^{n}}
$$

### 3.3 Curvature estimates

Theorem 3.3.1. For a steady Kähler Ricci soliton ( $M^{2 n}, g_{i \bar{j}}, f_{i \bar{j}}$ ) with positive Ricci curvature such that the scalar curvature attains its maximum, for any $x_{0}$ there exists $C$ such that

$$
\frac{1}{\operatorname{Vol}(B(r))} \int_{B(r)} R(x) \leq \frac{C}{1+r},
$$

here $B(r)$ is a geodesic ball of radius $r$ to any point.
Proof. We are going to use the following theorem by Hörmander. The version we are going to use is in Chapter VIII, Theorem 6.5. [32] With the natural function $F$ our manifold is Stein. Furthermore we have the following inequality,

$$
\sqrt{-1} \partial \bar{\partial}(F)+c_{1}\left(K_{M}\right)+\text { Ric }=\text { Ric }>0
$$

Now fix a base point $x_{0}$ and some cut off function $\theta$ near $x_{0}$. Let $\epsilon$ be some small number such that $\sqrt{-1} \partial \bar{\partial}\left(F+2 \epsilon \theta \log \left|z-x_{0}\right|\right)$ is still positive. Then for $m$ large enough such that $[m \epsilon]-n>0$ we find a nontrivial $L^{2}$ section $S$ of $K_{M}^{m}$ with prescribed value at $x_{0}$, say $S\left(x_{0}\right)$. Furthermore

$$
\begin{gathered}
\int_{M}|S|_{h}^{2} e^{-m F} d V_{g}<\infty \\
\sqrt{-1} \partial \bar{\partial} \log |S|_{h}^{2}=[S=0]+m \text { Ric } \geq m \text { Ric }
\end{gathered}
$$

Since the Ricci curvature is nonnegative, the mean value inequality for subharmonic functions gives,

$$
\begin{aligned}
|S|^{2}(x) & \leq \frac{c(n)}{\operatorname{Vol}\left(B\left(x, 3 d\left(x_{0}, x\right)\right)\right)} \int_{B\left(x, 3 d\left(x_{0}, x\right)\right)}|S|^{2}(x) \\
& =\frac{c(n)}{\operatorname{Vol}\left(B\left(x, 3 d\left(x_{0}, x\right)\right)\right)} \int_{B\left(x, 3 d\left(x_{0}, x\right)\right)}|S|^{2}(x) e^{-m F} e^{m F} \\
& \leq C^{\prime} e^{m \sqrt{R_{0}} d\left(x, x_{0}\right)}
\end{aligned}
$$

Now consider $\widetilde{M}=M \times \mathbb{C}^{2}$, with the product metric. This space has nonnegative Ricci curvature, therefore parabolicity translates to volume growth.([42] Theorem 5.2). The volume growth of $\widetilde{M}$ is at least $n+4$, therefore there exists a positive Green function $\widetilde{G}(x, y)$ on $\widetilde{M}$. Now consider $\widetilde{G}(x)=\widetilde{G}\left(x_{0}^{\prime}, x\right)$ where $x_{0}^{\prime}=\left(x_{0}, 0\right)$ where $x_{0}$ is the point that we can prescribe $S$. Recall that we have,

$$
\triangle \log \left(|S|^{2}\right) \geq m R
$$

and $\log \left(|S|^{2}\right)$ has singularity along $S=0$. Therefore we consider $\log \left(|S|^{2}+\delta\right)$.

$$
\triangle \log \left(|S|^{2}+\delta\right) \geq m R \frac{|S|^{2}}{|S|^{2}+\delta}
$$

Now pull back functions $|S|^{2}, R$ on $M$ through map $\widetilde{M} \rightarrow M$, we get functions $\widetilde{|S|^{2}}, \widetilde{R}$ such that,

$$
\begin{aligned}
\triangle \log \left(\widetilde{|S|^{2}}+\right. & \delta) \geq m \widetilde{R} \frac{\widetilde{|S|^{2}}}{\mid \widetilde{\left.S\right|^{2}}+\delta} \\
\int_{\beta>\widetilde{G}>\alpha} m \widetilde{R} \frac{\widetilde{|S|^{2}}}{\widetilde{|S|^{2}}+\delta}(\widetilde{G}-\alpha)^{1+\epsilon} \leq & \int_{\beta>\widetilde{G}>\alpha} \Delta \log \left(\widetilde{\left.S\right|^{2}}+\delta\right)(\widetilde{G}-\alpha)^{1+\epsilon} \\
= & \int_{\beta>\widetilde{G}>\alpha} \log \left(\widetilde{|S|^{2}}+\delta\right) \triangle(\widetilde{G}-\alpha)^{1+\epsilon} \\
& +\int_{\widetilde{G}=\beta} \frac{\partial \log \left(\widetilde{|S|^{2}}+\delta\right)}{\partial n}(\widetilde{G}-\alpha)^{1+\epsilon} \\
& -(1+\epsilon) \int_{\widetilde{G}=\beta} \log \left(\widetilde{\left.S\right|^{2}}+\delta\right)(\widetilde{G}-\alpha)^{\epsilon} \frac{\partial \widetilde{G}}{\partial n} \\
\int_{\beta>\widetilde{G}>\alpha} \log \left(\widetilde{|S|^{2}}+\delta\right) \triangle(\widetilde{G}-\alpha)^{1+\epsilon} \leq & \sup _{\widetilde{G}>\alpha} \log \left(\widetilde{\left(|S|^{2}\right.}+\delta\right) \int_{\beta>\widetilde{G}>\alpha} \triangle(\widetilde{G}-\alpha)^{1+\epsilon} \\
= & \underset{\widetilde{G}>\alpha}{\sup } \log \left(\widetilde{\left(|S|^{2}\right.}+\delta\right) \int_{\widetilde{G}=\beta}(1+\epsilon)(\widetilde{G}-\alpha)^{\epsilon} \frac{\partial \widetilde{G}}{\partial n}
\end{aligned}
$$

Letting $\epsilon \rightarrow 0$, we get

$$
\begin{aligned}
\int_{\beta>\widetilde{G}>\alpha} m \widetilde{R} \frac{\widetilde{|S|^{2}}}{\mid \widetilde{\left.S\right|^{2}}+\delta}(\widetilde{G}-\alpha) \leq & \sup _{\widetilde{G}>\alpha} \log \left(\widetilde{\left(|S|^{2}\right.}+\delta\right) \int_{\widetilde{G}=\beta} \frac{\partial \widetilde{G}}{\partial n} \\
& +\int_{\widetilde{G}=\beta} \frac{\partial \log \left(\widetilde{|S|^{2}}+\delta\right)}{\partial n}(\widetilde{G}-\alpha) \\
& -\int_{\widetilde{G}=\beta} \log \left(\widetilde{|S|^{2}}+\delta\right) \frac{\partial \widetilde{G}}{\partial n}
\end{aligned}
$$

We'll prove later such that $\widetilde{G} \sim \frac{c}{d^{2 n+2}},\left|\frac{\partial \widetilde{G}}{\partial n}\right| \sim \frac{c^{\prime}}{d^{2 n+3}}$. By using these facts, we obtain,

$$
\begin{gathered}
\int_{\widetilde{G}=\beta} \frac{\partial \widetilde{G}}{\partial n} \sim \frac{c d^{2 n+3}}{d^{2 n+3}} \sim c \\
\int_{\widetilde{G}=\beta}|\widetilde{G}-\alpha| \rightarrow \frac{c d^{2 n+3}}{d^{2 n+2}}=c d \rightarrow 0 \\
\mid \widetilde{\left.S\left(x_{0}\right)\right|^{2}}=1
\end{gathered}
$$

Letting $\beta \rightarrow+\infty$, then letting $\delta \rightarrow 0$ (furthermore use $\widetilde{S}=0$ has codimension 1)

$$
\int_{\widetilde{G}>\alpha} m \widetilde{R}(\widetilde{G}-\alpha) \leq c(n) \sup _{\widetilde{G}>\alpha} \log \left(\widetilde{|S|^{2}}\right)
$$

On $\widetilde{G}>2 \alpha$, we have $(\widetilde{G}-\alpha) \geq \frac{1}{2} \widetilde{G}$ therefore

$$
\int_{\widetilde{G}>2 \alpha} m \widetilde{R} \widetilde{G} \leq c(n) \sup _{\widetilde{G}>\alpha} \log \left(\widetilde{|S|^{2}}\right)
$$

Goal: Change $G\left(x_{0},-\right)$ level set coordinates back to regular geodesic ball.
Tool: Green function estimate

$$
\frac{c(n)^{-1} \tilde{d}^{2}\left(x, x_{0}\right)}{\operatorname{Vol}\left(\tilde{B}\left(x_{0}, \tilde{d}\left(x, x_{0}\right)\right)\right.} \leq \tilde{G}\left(x, x_{0}\right) \leq \frac{c(n) \tilde{d}^{2}\left(x, x_{0}\right)}{\operatorname{Vol}\left(\tilde{B}\left(x_{0}, \tilde{d}\left(x, x_{0}\right)\right)\right.}
$$

From [42] Thm5.2, we have the following estimate for a space with nonnegative Ricci curvature:

$$
c(n)^{-1} \int_{d^{2}}^{\infty} \frac{d t}{\operatorname{Vol}(\sqrt{t})} \leq G\left(x, x_{0}\right) \leq c(n) \int_{d^{2}}^{\infty} \frac{d t}{\operatorname{Vol}(\sqrt{t})}
$$

## Lower bound:

$$
\int_{d^{2}}^{\infty} \frac{d t}{\operatorname{Vol}(\sqrt{t})} \geq \int_{d^{2}}^{\infty} \frac{c(n) d^{2 n+2} d t}{\operatorname{Vol}\left(\sqrt{d^{2}}\right) \cdot t^{n+1}}=\frac{c(n) d^{2 n+2} d t}{\operatorname{Vol}(d)} \int_{d^{2}}^{\infty} t^{-n-1}=c^{\prime} \frac{d^{2}}{V(d)}
$$

Here we use Bishop-Gromov: $\frac{\operatorname{Vol}\left(\sqrt{d^{2}}\right)}{\operatorname{Vol}(\sqrt{t})} \geq\left(\frac{\sqrt{d^{2}}}{\sqrt{t}}\right)^{2 n+2}$ when $t>d^{2}$.
Upper bound: This is way back to observation (23) in Shi's construction. Because we have a flat factor which has accurate volume growth information, $\frac{V o l\left(\sqrt{d^{2}}\right)}{\operatorname{Vol}(\sqrt{ } t)} \leq$ $C(n)\left(\frac{\sqrt{d^{2}}}{\sqrt{t}}\right)^{4}$.

Since the volume is locally are Euclidean, the above estimates imply $\widetilde{G} \sim \frac{c}{d^{2 n+2}}$ when $d \rightarrow 0$. By the Cheng-Yau gradient estimate $\left|\frac{\partial \widetilde{G}}{\partial n}\right| \sim \frac{c^{\prime}}{d^{2 n+3}}$.

Let $r(\alpha)$ be the largest number such that $\widetilde{B}\left(x_{0}, r(\alpha)\right) \subset\{\tilde{G}>\alpha\}$. Because of the Green function estimate,

$$
\tilde{B}\left(x_{0}, r(\alpha)\right) \subset\{\tilde{G}>\alpha\} \subset \tilde{B}\left(x_{0}, c(n) r(\alpha)\right)
$$

Recall we have,

$$
\int_{\widetilde{G}>\alpha} m \widetilde{R} \widetilde{G} \leq c(n) \sup _{\widetilde{G}>\frac{1}{2} \alpha} \log \left(\widetilde{|S|^{2}}\right),
$$

together with the lower bound $G \geq \frac{r(\alpha)^{2}}{\operatorname{Vol(r(\alpha ))}}$ inside $B(r(\alpha))$,

$$
\begin{aligned}
\int_{\widetilde{G}>\alpha} m \widetilde{R} \widetilde{G} & \geq \int_{\widetilde{B}(r(\alpha))} m \widetilde{R} \widetilde{G} \\
& \geq m \cdot C \frac{r(\alpha)^{2}}{\operatorname{Vol}(r(\alpha))} \int_{\widetilde{B}(r(\alpha))} \widetilde{R} .
\end{aligned}
$$

By Green function estimate, and the estimate for $\log \left(\widetilde{|S|^{2}}\right)$,

$$
\sup _{\widetilde{G}>\frac{1}{2} \alpha} \log \left(\widetilde{|S|^{2}}\right) \leq \sup _{B(c(n) r(\alpha))} \log \left(\widetilde{|S|^{2}}\right) \leq c(n)\left(\widetilde{r}+c^{\prime}\right)
$$

Therefore on $\widetilde{M}$ we have,

$$
\frac{1}{\operatorname{Vol}(\widetilde{r})} \int_{\widetilde{B}(r(\alpha))} \widetilde{R} \leq c \frac{\widetilde{r}+c}{\widetilde{r}^{2}} \leq c \frac{1}{\widetilde{r}+1} .
$$

The above estimates also hold for $M$ since

$$
B_{M}\left(\frac{1}{2} r\right) \times B_{\mathbb{C}^{2}}\left(\frac{1}{2} r\right) \subset B(\widetilde{r}) \subset B_{M}(r) \times B_{\mathbb{C}^{2}}(r)
$$

## Chapter 4

## Uniqueness under constraints of the asymptotic geometry.

### 4.1 Background

Recall a steady Ricci soliton $(M, g)$ is a Riemannian metric which satisfies the equation 2 Ric $=\mathcal{L}_{X}(g)$. For a steady Ricci soliton $(M, g)$ if in addition the metric is Kähler and $X$ is the gradient of some real valued function, then we call it steady gradient Kähler Ricci soliton.
H.D. Cao constructed a family of steady gradient Kähler Ricci solitons on $\mathbb{C}^{n}$ with positive holomorphic bisectional curvature in [11]. This is the first noncompact (nontrivial) example of a steady Kähler Ricci soliton. There are also many important examples of Kähler Ricci solitons constructed by Koiso in [49], M. Feldman, T. Ilmanen, and D. Knopf in [43] and Akito Futaki and Mu-Tao Wang in [1].

In [11], Cao asked a question on symmetry of steady Kähler Ricci solitons with positive holomorphic bisectional curvature on $\mathbb{C}^{n}$. O. Schnürer, and A. Chau's result in [24] gave a partial answer to this question.

Recently S. Brendle showed $O(n)$-symmetry of certain steady solitons in [57] [58]. His work solved an open problem proposed by Perelman in [51]. Otis Chodosh extended the argument to expanding solitons in [26]. Otis Chodosh and Frederick

Tsz-Ho Fong showed $U(n)$-symmetry of certain gradient expanding Kähler Ricci Solitons in [27].

In this chapter we will give a partial answer to the question proposed by Cao in [11]. The argument is similar to [27] which comes from [57] [58] [26].

We are going to compute norms, gradients and distance with respect to the model metric constructed by Cao in [11] in this Chapter.

### 4.2 Main Theorem

Main Theorem For $n \geq 2$. Let $\left(\mathbb{C}^{n}, g_{m}, X_{m}\right)$ be a steady gradient Kähler Ricci solitons constructed by Cao in [11]. Let $\left(\mathbb{C}^{n}, \widetilde{g}, \widetilde{X}\right)$ be some steady gradient Kähler Ricci soliton with following properties.

1. $r^{2+\frac{j}{2}}\left|\nabla^{j}\left(\widetilde{g}-g_{m}\right)\right|=o(1) \quad$ for $j=0,1$
2. $\widetilde{g}$ has positive holomorphic bisectional curvature,
here $r$ is the geodesic distance to the origin with respect to $g_{m}$.
Then there exists a point $p \in \mathbb{C}^{n}$ and a map $\Phi_{p}: z \rightarrow z+p$ such that $g=\Phi_{p}^{*}(\widetilde{g})$ satisfies standard $U(n)-$ symmetry.

### 4.3 Preliminary

In this section we are going to present expression and basic properties of the metric construct by H.-D. Cao in [11]. Let $\left(z_{1}, z_{2}, \ldots, z_{n}\right)$ be standard holomorphic coordinate on $\mathbb{C}^{n}$. Let $t=\log \left(|z|^{2}\right)$. Then the $\mathrm{U}(\mathrm{n})$-symmetric steady Kähler Ricci soliton in [11] is given by

$$
\begin{gather*}
\left(g_{m}\right)_{i \bar{j}}=e^{-t} \phi(t) \delta_{i \bar{j}}+e^{-2 t} \overline{z_{i}} z_{j}\left(\phi^{\prime}(t)-\phi(t)\right)  \tag{4.1}\\
\left(g_{m}\right)^{i \bar{j}}=e^{t} \frac{\delta^{i \bar{j}}}{\phi(t)}+z_{i} \overline{z_{j}}\left(\frac{1}{\phi^{\prime}(t)}-\frac{1}{\phi(t)}\right) \tag{4.2}
\end{gather*}
$$

where $\phi(t)$ satisfies $\phi^{n-1} \phi^{\prime} e^{\phi}=e^{n t}$ after normalization. From computations in [11] we have following properties.

$$
\begin{aligned}
\phi(t) & \rightarrow n t \\
\phi^{\prime}(t) & \rightarrow n \\
\phi^{\prime \prime}(t) & \rightarrow 0 \\
\phi^{\prime \prime \prime}(t) & \rightarrow 0 \\
r(t) & =O(t)
\end{aligned}
$$

Here $r$ is the distance to origin with respect to $g_{m}$. We'll always use $r, t$ for above purpose.

### 4.4 Calculations

In the calculation part, we are going to analyze, under the asymptotic constraint, how much could various quantities differ from the original model. From now on $g$ is some steady gradient Kahler Ricci soliton metric satisfies assumptions $1,2 . g_{m}$ is the model metric constructed in [11].

### 4.4.1 Killing vectors of the model metric

We are going to show $\left|U_{a}\right|=O\left(r^{\frac{1}{2}}\right),\left|\nabla U_{a}\right|=O(1),|X|=O\left(r^{\frac{1}{2}}\right),|\nabla X|=O(1)$ by straightforward computations. Here $U_{a}$ are killing vectors coming from the unitary symmetry of $g_{m}, X$ is the soliton vector of the model metric. $r$ is the distance to origin with respect to $g_{m}$. Notice that $J X$ is Killing, therefore we only need to do explicit computation for Killing vector fields.

We pick following explicit $\mathbb{R}$-basis of Killing vectors of $g_{m}$.

1. $U_{k}^{1,0}=i z_{k} \frac{\partial}{\partial z_{k}}$,
2. $U_{u, v}^{1,0}=z_{u} \frac{\partial}{\partial z_{v}}-z_{v} \frac{\partial}{\partial z_{u}}$ where $u \neq v$,
3. $\widetilde{U}_{u, v}^{1,0}=i\left(z_{u} \frac{\partial}{\partial z_{v}}+z_{v} \frac{\partial}{\partial z_{u}}\right)$ where $u \neq v$.

Our goal is to show $\left|U_{a}\right|=O\left(r^{\frac{1}{2}}\right),\left|\nabla U_{a}\right|=O(1)$. We can restrict the computation to the direction $\left(z_{1}, 0, \ldots, 0\right) \in \mathbb{C}^{n}$ by symmetry.

- $\left|U_{a}\right|=O\left(r^{\frac{1}{2}}\right)$

By expression 4.1, at $\left(z_{1}, 0, \ldots, 0\right)$, metric looks like

$$
\begin{equation*}
g_{i \bar{j}}=e^{-t} \operatorname{diag}\left\{\phi^{\prime}(t), \phi(t), \ldots, \phi(t)\right\} \tag{4.3}
\end{equation*}
$$

From the expression of Killing vectors above and the relationship between the Kähler metric and its associated Riemannian metric. It's sufficient to calculate the length of $z_{1} \frac{\partial}{\partial z_{1}}, z_{1} \frac{\partial}{\partial z_{k}}$ using the Kähler metric .
(a) $\left|z_{1} \frac{\partial}{\partial z_{1}}\right|^{2}=e^{-t}\left|z_{1}\right|^{2} \phi^{\prime}(t)=\frac{1}{\left|z_{1}\right|^{2}}\left|z_{1}\right|^{2} \phi^{\prime}(t)=\phi^{\prime}(t) \rightarrow n \sim O(1)$
(b) $\left|z_{1} \frac{\partial}{\partial z_{k}}\right|^{2}=e^{-t}\left|z_{1}\right|^{2} \phi(t)=\frac{1}{\left|z_{1}\right|^{2}}\left|z_{1}\right|^{2} \phi(t)=\phi(t) \rightarrow n t \sim O(r)$

Here we have used the asymptotic behaviour of $\phi(t)$ in Section 4.3.

- $\left|\nabla U_{a}\right|=O(1)$

Since all $U_{a}$ are real holomorphic, when we calculate $\left|\nabla U_{a}\right|$, we can restrict all discussion to $T_{\mathbb{C}}^{1,0}$. From 4.1, Christoffel symbol $\Gamma_{j k}^{i}$ is

$$
\begin{equation*}
\frac{g^{\bar{l} i}}{e^{2 t}}\left\{\overline{z_{j}}\left[\left(-\phi(t)+\phi^{\prime}(t)\right) \delta_{k \bar{l}}+e^{-t}\left(2 \phi(t)-3 \phi^{\prime}(t)+\phi^{\prime \prime}(t)\right) \overline{z_{k}} z_{l}\right]+\left(\phi^{\prime}(t)-\phi(t)\right) \overline{z_{k}} \delta_{j \bar{l}}\right\} \tag{4.4}
\end{equation*}
$$

At $(z, 0, \ldots, 0)$ we have the following 4 cases
(A) $j \neq 1$

$$
\Gamma_{j k}^{i}=g^{\bar{j}} \overline{\overline{z_{k}}} e^{-2 t}\left(\phi^{\prime}(t)-\phi(t)\right)
$$

(B) $j=1, k \neq 1 \quad \Gamma_{1 k}^{i}=g^{\bar{k} i} \overline{z_{1}} e^{-2 t}\left(\phi^{\prime}(t)-\phi(t)\right)$
(C) $j=1, k=1, i \neq 1 \quad \Gamma_{11}^{i}=0$
(D) $j=1, k=1, i=1 \quad \Gamma_{11}^{1}=g^{\overline{1} 1} \overline{z_{1}} e^{-2 t}\left(\phi^{\prime \prime}(t)-\phi^{\prime}(t)\right)$

From the expression of a basis of Killing vectors we pick at the beginning of 4.4.1, we only need to estimate the length of $\nabla\left(z^{u} \frac{\partial}{\partial z^{v}}\right)$ along $(z, 0, \ldots 0)$.

Case I $\quad u=v=k$ where $k \neq 1$
I.1) $\nabla_{\frac{\partial}{\partial z}}\left(z^{k} \frac{\partial}{\partial z^{k}}\right)=0$ for $l \neq k$
I.2) $\nabla_{\frac{\partial}{\partial z^{k}}}\left(z^{k} \frac{\partial}{\partial z^{k}}\right)=\frac{\partial}{\partial z^{k}}$

Therefore $\left|\nabla\left(z^{k} \frac{\partial}{\partial z^{k}}\right)\right|_{g_{m}}=\frac{1}{\left|\frac{\partial}{\partial z^{k}}\right|}\left|\frac{\partial}{\partial z^{k}}\right|=1$

Case II $\quad u=v=1$
II.1) Taking the derivative along $\frac{\partial}{\partial z^{l}}$ where $l \neq 1$
$\nabla_{\frac{\partial}{\partial z^{l}}}\left(z^{1} \frac{\partial}{\partial z^{1}}\right)=z^{1} \Gamma_{l 1}^{m} \frac{\partial}{\partial z^{m}}=\frac{1}{\phi(t)}\left(\phi^{\prime}(t)-\phi(t)\right) \frac{\partial}{\partial z^{l}}$
$\frac{1}{\phi(t)}\left(\phi^{\prime}(t)-\phi(t)\right)$ is bounded by the properties of $\phi(t)$ listed in Section 4.3.
II.2) Taking the derivative along $\frac{\partial}{\partial z^{1}}$
$\nabla_{\frac{\partial}{\partial z^{1}}}\left(z^{1} \frac{\partial}{\partial z^{1}}\right)=\frac{\partial}{\partial z^{1}}+z^{1} \Gamma_{l 1}^{m} \frac{\partial}{\partial z^{m}}=\left[1+\frac{1}{\phi^{\prime}(t)}\left(\phi^{\prime \prime}(t)-\phi^{\prime}(t)\right)\right] \frac{\partial}{\partial z^{1}}$
$\frac{1}{\phi(t)}\left(\phi^{\prime}(t)-\phi(t)\right)$ is bounded by Section 4.3.
Therefore $\left|\nabla\left(z^{1} \frac{\partial}{\partial z^{1}}\right)\right|_{g_{m}}=O(1)$

Case III $\quad u \neq v$ and $u \neq 1$

$$
\nabla_{\frac{\partial}{\partial z^{l}}}\left(z^{u} \frac{\partial}{\partial z^{v}}\right)=\delta_{l u} \frac{\partial}{\partial z^{v}}
$$

Therefore $\left|\nabla\left(z^{u} \frac{\partial}{\partial z^{v}}\right)\right|_{g_{m}} \leq \frac{1}{\left|\frac{\partial}{\partial z^{u}}\right|} C\left|\frac{\partial}{\partial z^{u}}\right| \leq C\left(\frac{\partial}{\partial z_{u}}\right.$ direction is longer by 4.3 and properties of $\phi(t)$ in Section 4.3 )

Case IV $\quad u \neq v$ and $u=1$
VI.1)Taking the derivative along $\frac{\partial}{\partial z^{l}}$ where $l \neq 1$

$$
\nabla_{\frac{\partial}{\partial z^{l}}}\left(z^{1} \frac{\partial}{\partial z^{v}}\right)=\delta_{1 v} \frac{1}{\phi(t)}\left(\phi^{\prime}(t)-\phi(t)\right) \frac{\partial}{\partial z^{l}}
$$

VI.2)Taking the derivative along $\frac{\partial}{\partial z^{1}}$

$$
\nabla_{\frac{\partial}{\partial z^{1}}}\left(z^{1} \frac{\partial}{\partial z^{v}}\right)=\frac{\partial}{\partial z^{v}}+z^{1} \Gamma_{l v}^{s} \frac{\partial}{\partial z^{s}}=\frac{\phi^{\prime}(t)}{\phi(t)}\left(\frac{\partial}{\partial z^{v}}\right)
$$

From the expression of the metric in 4.3 and the properties of $\phi(t)$ in Section 4.3 we see that $\left|\nabla\left(z^{1} \frac{\partial}{\partial z^{v}}\right)\right|_{g_{m}}$ is also $O(1)$

### 4.4.2 Shifting preserves the assumption 1

We are going to show for $\widetilde{g}$ satisfies Assumption 1,2 , and any point $p \in \mathbb{C}^{n}, \Phi_{p}^{*}(\widetilde{g})$ also satisfies Assumption 1, 2.

We just need to check for Assumption 1 still holds for $\Phi_{p}^{*}(g)$. This is equivalent to say that $r^{2+\frac{j}{2}}\left|\nabla^{j}\left(\Phi_{p}^{*}(\widetilde{g})-g_{m}\right)\right|_{g_{m}}=o(1)$ for $j=0,1$.

Directly pull back Assumption 1 by $\Phi_{p}^{*}$, we get.

$$
r^{2+\frac{j}{2}}\left|\nabla^{j}\left(\widetilde{g}-g_{m}\right)\right|_{g_{m}}=o(1) \Longrightarrow r^{2+\frac{j}{2}}\left|\Phi_{p}^{*}(\nabla)^{j}\left(\Phi_{p}^{*}(\widetilde{g})-\Phi_{p}^{*}\left(g_{m}\right)\right)\right|_{\Phi_{p}^{*}\left(g_{m}\right)}=o(1)
$$

After this, it's sufficient to check following facts..

1. $\left|\Phi_{p}^{*}\left(g_{m}\right)-g_{m}\right|_{g_{m}}=O\left(\frac{\log \left(|z|^{2}\right)}{|z|}\right)$
2. $\left|\nabla\left(\Phi_{p}^{*}\left(g_{m}\right)-g_{m}\right)\right|_{g_{m}}=O\left(\frac{\left(\log \left(|z|^{2}\right)\right)^{2}}{|z|}\right)$
3. $r^{2+\frac{j}{2}}\left|\left(\Phi_{p}^{*} \nabla\right)^{j}(k)\right|_{\Phi_{p}^{*} g_{m}}=o(1)$ for $j=0,1$ implies $r^{2+\frac{j}{2}}\left|\nabla^{j}(k)\right|_{g_{m}}=o(1)$ for $j=0,1$

STEP $1 \quad\left|\Phi_{p}^{*}\left(g_{m}\right)-g_{m}\right|_{g_{m}}=O\left(\frac{\log \left(|z|^{2}\right)}{|z|}\right)$
Plug 4.1 into $\left(\Phi_{p}^{*}\left(g_{m}\right)-g_{m}\right)_{i \bar{j}}$, we get

$$
\begin{align*}
& \left(\Phi_{p}^{*}\left(g_{m}\right)-g_{m}\right)_{i \bar{j}}=\left[\frac{\phi\left(\log \left(|z+p|^{2}\right)\right)}{|z+p|^{2}}-\frac{\phi\left(\log \left(|z|^{2}\right)\right)}{|z|^{2}}\right] \\
& +\left(\overline{z_{i}}+\overline{p_{i}}\right)\left(z_{j}+p_{j}\right)\left[\frac{\phi^{\prime}\left(\log \left(|z+p|^{2}\right)\right)-\phi\left(\log \left(|z+p|^{2}\right)\right)}{|z+p|^{4}}-\frac{\phi^{\prime}\left(\log \left(|z|^{2}\right)\right)-\phi\left(\log \left(|z|^{2}\right)\right)}{|z|^{4}}\right] \\
& +\frac{\phi^{\prime}\left(\log \left(|z|^{2}\right)\right)-\phi\left(\log \left(|z|^{2}\right)\right)}{|z|^{4}}\left[\left(\overline{z_{i}}+\overline{p_{i}}\right)\left(z_{j}+p_{j}\right)-\overline{z_{i}} z_{j}\right] \tag{4.5}
\end{align*}
$$

For the norm of the first two terms, apply mean value theorem to real valued function $f(x)=\frac{\phi\left(\log \left(x^{2}\right)\right)}{x^{2}}$, we get $\left|f\left(|z+p|^{2}\right)-f\left(|z|^{2}\right)\right| \leq|p|\left|f^{\prime}(|z|+\xi)\right|, \xi \in(-|p|,|p|)$ $\left|f^{\prime}(|z|+\xi)\right|=2\left|\frac{\phi^{\prime}\left(\log \left((|z|+\xi)^{2}\right)-\phi\left(\log \left((|z|+\xi)^{2}\right)\right)\right.}{(|z|+\xi)^{3}}\right| \leq C \frac{\log \left(|z|^{2}\right)}{|z|^{3}}$. The last step uses the asymptotic of $\phi$ in Section 4.3. Therefore the norms of the first two terms is bounded by $C \frac{\log \left(|z|^{2}\right)}{|z|^{3}}$. This bound works for other 2 coupled terms by similar arguments.

Together with the coarse estimate $\left|g^{u \bar{v}}\right| \leq \widetilde{C} e^{t}=\widetilde{C}|z|^{2}$ from expression 4.2, we have $\left|\Phi_{p}^{*}\left(g_{m}\right)-g_{m}\right|_{g_{m}}=O\left(\frac{\log \left(|z|^{2}\right)}{|z|}\right)$

STEP $2\left|\nabla\left(\Phi_{p}^{*}\left(g_{m}\right)-g_{m}\right)\right|_{g_{m}}=O\left(\frac{\left(\log \left(|z|^{2}\right)\right)^{2}}{|z|}\right)$
Let $\delta g=\Phi_{p}^{*}\left(g_{m}\right)-g_{m}$. Then for any $i, j,(\delta g)_{i \bar{j}}=O\left(\frac{\log \left(|z|^{2}\right)}{|z|^{3}}\right)$ by STEP 1 .
$\left(\nabla_{m} \delta g\right)_{i \bar{j}}=\frac{\partial}{\partial z_{m}}\left(\delta g_{i \bar{j}}\right)-(\delta g)\left(\nabla_{m} \frac{\partial}{\partial z_{i}}, \frac{\partial}{\partial \bar{z}_{j}}\right)$

1. $\frac{\partial}{\partial z_{m}}\left(\delta g_{i \bar{j}}\right)$

Expression of $\delta g_{m \bar{t}}$ has been separated into three lines in 4.5
When $\frac{\partial}{\partial z_{m}}$ hits the first line of 4.5

$$
\begin{aligned}
& \frac{\partial}{\partial z_{m}}\left[\frac{\phi\left(\log \left(|z+p|^{2}\right)\right)}{|z+p|^{2}}-\frac{\phi\left(\log \left(|z|^{2}\right)\right)}{|z|^{2}}\right] \\
& =\left(\overline{z_{m}+p_{m}}\right)\left[\frac{\left(\phi^{\prime}-\phi\right)\left(\log \left(|z+p|^{2}\right)\right)}{|z+p|^{4}}-\frac{\left(\phi^{\prime}-\phi\right)\left(\log \left(|z|^{2}\right)\right)}{|z|^{4}}\right] \\
& +\frac{\left(\phi^{\prime}-\phi\right)\left(\log \left(|z|^{2}\right)\right)}{|z|^{4}}\left[\overline{z_{m}+p_{m}}-\overline{z_{m}}\right]
\end{aligned}
$$

By applying the mean value theorem to $f(x)=\frac{\phi^{\prime}\left(\log \left(x^{2}\right)\right)-\phi\left(\log \left(x^{2}\right)\right)}{x^{4}}$ and asymptotic of $\phi(x)$, we get the order of the sum of these two terms is $O\left(\frac{\log \left(|z|^{2}\right)}{|z|^{4}}\right)$.

When $\frac{\partial}{\partial z_{m}}$ hits the second and third line of 4.5 , the order is also $O\left(\frac{\log \left(|z|^{2}\right)}{|z|^{4}}\right)$ by the asymptotic of $\phi(t)$ up to third order and a similar discussion.
2. $(\delta g)\left(\nabla_{m} \frac{\partial}{\partial z_{i}}, \frac{\partial}{\partial \bar{z}_{j}}\right)=O\left(\frac{\left(\log \left(|z|^{2}\right)\right)^{2}}{|z|^{4}}\right)$ This is done by using the result from STEP 1 and the coarse bound $\left|\Gamma_{p q}^{r}\right|=O\left(\frac{\log \left(|z|^{2}\right)}{|z|}\right)$ which is directly from its expression 4.4

Therefore $\left|\nabla\left(\Phi_{p}^{*}\left(g_{m}\right)-g_{m}\right)\right|_{g_{m}}=O\left(\frac{\left(\log \left(|z|^{2}\right)\right)^{2}}{|z|}\right)$
STEP $3 \quad r^{2+\frac{j}{2}}\left|\left(\Phi_{p}^{*} \nabla\right)^{j}(k)\right|_{\Phi_{p}^{*} g_{m}}=o(1) j=0,1$ implies $r^{2+\frac{j}{2}}\left|\nabla^{j}(k)\right|_{g_{m}}=o(1)$
For $j=0$, this comes from the equivalence of $\Phi_{p}^{*} g_{m}$ and $g_{m}$ by STEP 1.
For $j=1$, it's sufficient to show $\left.\left|\left(\Phi_{p}^{*} \nabla-\nabla\right) k\right|_{g_{m}}=O\left(\frac{\log \left(|z|^{2}\right)}{|z|}\right)\right)$
$\left(\left(\Phi_{p}^{*} \nabla_{i}-\nabla_{i}\right) k\right)_{j \bar{l}}=k_{s \bar{l}}\left(\widetilde{\Gamma_{i j}^{s}}-\Gamma_{i j}^{s}\right)=k_{s \bar{l}}\left(\widetilde{g}^{s \bar{v}} \partial_{i} \widetilde{g}_{j \bar{v}}-g^{s \bar{v}} \partial_{i} g_{j \bar{v}}\right)$
1.As a complex number, $\left|k_{s \bar{l}}\right|=O\left(\frac{1}{|z|^{2}}\right)$ by properties of $k$ and $g$.
2. $\left|\widetilde{g}^{s \bar{v}} \partial_{i} \widetilde{g}_{j \bar{v}}-g^{s \bar{v}} \partial_{i} g_{j \bar{v}}\right|=\left|\left(\widetilde{g}^{s \bar{v}}-g^{s \bar{v}}\right) \partial_{i} \widetilde{g}_{j \bar{v}}-g^{s \bar{v}} \partial_{i}\left(\widetilde{g}_{j \bar{v}}-g_{j \bar{v}}\right)\right|=O\left(\frac{\log \left(|z|^{2}\right)}{|z|^{2}}\right)$ $\left.\left|\left(\Phi_{p}^{*} \nabla-\nabla\right) k\right|_{g_{m}}=O\left(\frac{\log \left(|z|^{2}\right)}{|z|}\right)\right)$ holds by 1,2 together with $\left|g^{u \bar{v}}\right| \leq|z|^{2}$.

### 4.4.3 Rigidity of the soliton vector

In this subsection we are going to see the soliton vector $\widetilde{X}$ of $g$ must satisfies $\widetilde{X}^{1,0}=$ $\left(\lambda z^{i}+b^{i}\right) \frac{\partial}{\partial z_{i}}$ where $\operatorname{Re}(\lambda) \neq 0$. Therefore there exists an shifting map $\left(\Phi_{p}^{*}(\widetilde{X})\right)^{1,0}=$ $\lambda z^{i} \frac{\partial}{\partial z_{i}}$. In other words, the soliton vector field is rigid suppose we know information about the asymptotic geometry.

Write $\widetilde{X}^{1,0}$ as $u^{i}(z) \frac{\partial}{\partial z_{i}}$. Then $u^{i}(z)$ is a holomorphic function on $\mathbb{C}^{n}$.
By [12] $|\widetilde{X}|_{g}^{2}+R(g)$ is constant. $R(g)>0$ by Assumption 2 . Therefore we have $|\widetilde{X}|_{g}^{2}<\infty$. By Assumption 1, we see that $|\widetilde{X}|_{g_{m}}^{2}<\infty$

From properties of $\phi(t)$ and $\phi^{\prime}(t)$ in section 4.3 . We see that there exists a positive $C\left(t_{0}\right)$ s.t. $\phi(t), \phi^{\prime}(t)$ is greater than $C$ for all $t>t_{0}$. Recall the expression of $g_{m}$ at $(z, 0, \ldots 0)$ is $\operatorname{diag}\left\{\frac{\phi^{\prime}(t)}{e^{t}}, \frac{\phi(t)}{e^{t}} \ldots \frac{\phi(t)}{e^{t}}\right\}$. Therefore $|\widetilde{X}|_{g_{m}}^{2}$ is finite implies for $|z|>e^{t_{0}},+\infty>g_{i \bar{j}} u^{i}(z) \overline{u^{j}(z)} \geq \sum_{i} C \frac{\left|u^{i}(z)\right|^{2}}{|z|^{2}}$. Therefore $\left|u^{i}(z)\right|^{2}$ is at most linear growth. $u^{i}(z)=a_{j}^{i} z^{j}+b^{i}$. Let $\widetilde{X_{L}}=b^{i} \frac{\partial}{\partial z_{i}}$ Then $\left|\widetilde{X_{L}}\right|_{g_{m}} \rightarrow 0$ uniformly.

1. $a_{j}^{i}=\delta_{j}^{i} \widetilde{a^{j}}$. To see this we use $\left|\widetilde{X}-\widetilde{X_{L}}\right|_{g_{m}}$ is finite and make a calculation at $(0, \ldots, z, \ldots, 0)$ where the $j$-th place is not 0 . By 4.1 , the metric is $\frac{1}{|z|^{2}} \operatorname{diag}\left\{\phi, \ldots, \phi^{\prime}, \ldots, \phi\right\}$ at this point.

$$
\begin{aligned}
\infty>\left|X-X_{L}\right|_{g_{m}} & =\left\langle a_{p}^{q} z^{p} \frac{\partial}{\partial z_{q}}, \overline{a_{r}^{s} z^{r} \frac{\partial}{\partial z_{s}}}\right\rangle \\
& =a_{j}^{q} \overline{a_{j}^{s}}\left|z^{j}\right|^{2} g_{q \bar{s}} \\
& =\sum_{q \neq j} \phi(t)\left|a_{j}^{q}\right|^{2}+\left|a_{j}^{j}\right|^{2} \phi^{\prime}(t)
\end{aligned}
$$

From the properties of $\phi(t)$ in Section 4.3. We must have $a_{j}^{q}=0$ for $q \neq j$
2. $\widetilde{a^{1}}=\widetilde{a^{2}}=\ldots=\widetilde{a^{n}}$ We still use $\left|\widetilde{X}-\widetilde{X_{L}}\right|_{g_{m}}$ is finite and make a calculation at $(0, \ldots, z, \ldots, z, \ldots, 0)$. Here the nonzero places, the $i$ th and $j$ th ones, are equal. By 4.1, at this point, we have

$$
\begin{aligned}
\left(g_{m}\right)_{p \bar{p}} & =\left(g_{m}\right)_{q \bar{q}}=e^{-t} \phi(t)+e^{-2 t}|z|^{2}\left(\phi^{\prime}(t)-\phi(t)\right) \\
\left(g_{m}\right)_{p \bar{q}} & =\left(g_{m}\right)_{q \bar{p}}=e^{-2 t}|z|^{2}\left(\phi^{\prime}(t)-\phi(t)\right)
\end{aligned}
$$

Therefore $\infty>\left|\widetilde{X}-\widetilde{X_{L}}\right|_{g_{m}}=\frac{1}{4}\left(\left|\widetilde{a^{i}}\right|^{2}+\left|\widetilde{a^{j}}\right|^{2}\right) \phi^{\prime}(t)+\frac{1}{4}\left|\widetilde{a^{i}}-\widetilde{a^{j}}\right|^{2} \phi(t)$. From Section 4.3, we see that $\widetilde{a^{i}}=\widetilde{a^{j}}, \forall i, j$
3. $\operatorname{Re}(\lambda) \neq 0$ Suppose $\lambda$ is purely imaginary. Then there exists a closed circle as integral curve for vector field $\widetilde{X}$. This contradicts with $\widetilde{X}$ being the gradient of some real function.

### 4.4.4 Decay rate of Ricci of the model metric

We are going to show there exists a $C>0$ such that $\operatorname{Ric}_{m}-\frac{C}{t^{2}} g_{m} \geq 0$ by straightforward computations. Since both $\operatorname{Ric}_{m}$ and $g_{m}$ are $U(n)$-symmetric, we can restrict our discussion along $(z, 0, \ldots, 0)$. Along this direction, we have

$$
\begin{aligned}
& g_{i \bar{j}}=e^{-t} \operatorname{diag}\left\{\phi^{\prime}(t), \phi(t), \ldots, \phi(t)\right\} \\
& R_{i \bar{j}}=e^{-t} \operatorname{diag}\left\{v^{\prime \prime}(t), v^{\prime}(t), \ldots, v^{\prime}(t)\right\}
\end{aligned}
$$

where $v(t)=n t-(n-1) \log (\phi(t))-\log \left(\phi^{\prime}(t)\right)$. As we assume $g_{m}$ have the same normalization as in [11]. The equation of $\phi$ is $\phi^{n-1} \phi^{\prime} e^{\phi}=e^{n t}$.

Let's consider $\lambda_{1}(t)=\frac{v^{\prime \prime}(t)}{\phi^{\prime}(t)}, \lambda_{k}(t)=\frac{v^{\prime}(t)}{\phi(t)}$ where $k \geq 2$

1. $\lambda_{k}, k \geq 2$

$$
\lambda_{k}=\frac{n-(n-1) \frac{\phi^{\prime}(t)}{\phi(t)}-\frac{\phi^{\prime \prime}(t)}{\phi^{\prime}(t)}}{\phi(t)}>\frac{C_{k}}{t}
$$

2. $\lambda_{1}$

$$
\lambda_{1}=\frac{1}{\phi^{\prime}(t)}\left[(n-1) \frac{\left(\phi^{\prime}(t)\right)^{2}-\phi^{\prime \prime}(t) \phi(t)}{(\phi(t))^{2}}+\frac{\left(\phi^{\prime \prime}(t)\right)^{2}-\phi^{\prime \prime \prime}(t) \phi^{\prime}(t)}{\left(\phi^{\prime}(t)\right)^{2}}\right]
$$

We have the following identities from Cao's paper [11]

$$
\begin{aligned}
\phi^{\prime \prime}= & n \phi^{\prime}-\left(\phi^{\prime}\right)^{2}-(n-1) \frac{\left(\phi^{\prime}\right)^{2}}{\phi} \\
\phi^{\prime \prime \prime}= & n^{2} \phi^{\prime}-3 n\left(\phi^{\prime}\right)^{2}+2\left(\phi^{\prime}\right)^{3}-3 n(n-1) \frac{\left(\phi^{\prime}\right)^{2}}{\phi} \\
& +4(n-1) \frac{\left(\phi^{\prime}\right)^{3}}{\phi}+(n-1)(2 n-1) \frac{\left(\phi^{\prime}\right)^{2}}{\phi^{2}}
\end{aligned}
$$

Plugging them into expression of $\lambda_{1}$, we have

$$
\lambda_{1}=\frac{1}{\phi^{\prime}}\left[\phi^{\prime \prime}+\frac{(2 n-1)(n-1) \phi^{\prime}}{\phi^{2}}\left(\phi^{\prime}-1\right)\right]
$$

By the asymptotic of $\phi$ in Section 4.3, we see that $\frac{(2 n-1)(n-1) \phi^{\prime}}{\phi^{2}}\left(\phi^{\prime}-1\right) \sim$ $\frac{n(2 n-1)(n-1)^{2}}{t^{2}}$

Therefore we only need to show $\phi^{\prime \prime}>0$ if $n>1$.
Since $\phi^{\prime}>0$, we can write $t$ as a function of $\phi$. From the soliton equation, we have $\phi^{\prime}=\frac{e^{n t}}{\phi^{n-1} e^{\phi}}$ as a function of $\phi$. Plug it into the expression of $\phi^{\prime \prime}$, we have

$$
\phi^{\prime \prime}=\frac{e^{n t}}{\phi^{2 n-2} e^{2 \phi} \phi}\left(\phi^{n} e^{\phi} n-e^{n t} \phi-(n-1) e^{n t}\right) .
$$

Let $f_{k}(\phi)=\frac{d^{k}}{d \phi^{k}}\left(\phi^{n} e^{\phi} n-e^{n t} \phi-(n-1) e^{n t}\right)$. By expansion of $\phi$ at zero from [11], $\lim _{\phi \rightarrow 0} f_{0}(\phi)=0$. Now take the derivative on $f_{0}$ using $\frac{d}{d \phi} e^{n t}=n \phi^{n-1} e^{\phi}$

$$
f_{1}(\phi)=\frac{d}{d \phi} f_{0}=n \phi^{n-1} e^{\phi}-e^{n t} .
$$

Then we have $\lim _{\phi \rightarrow 0} f_{1}(\phi)=0$. Take the derivative again

$$
f_{2}(\phi)=\frac{d}{d \phi} f_{1}=n \phi^{n-2} e^{\phi}(n-1)>0 .
$$

Therefore we have $\phi^{\prime \prime}>0$. Hence $\exists C_{1}>0$ s.t. $\lambda_{1}>\frac{C}{t^{2}}$.

### 4.4.5 Main Argument

Proof We can assume that $g_{m}$ has the same normalization $(\alpha=1, \beta=1)$ as in [11], since scaling on metric and dilation on coordinates does not affect our assumption. Pick an $\mathbb{R}$-basis of Killing vectors of $g_{m},\left\{U_{a}\right\}_{a=1}^{n^{2}}$.

We have seen in 4.4.3 that there exist a $p \in \mathbb{C}^{n}$ s.t. $\widetilde{X_{p}}=0$. For this specific $p$, let $g=\Phi_{p}^{*}(\widetilde{g}), X=\Phi_{p}^{*}(\widetilde{X})$. We'll show $U_{a}$ is also Killing for $g$.

Now let $h=\mathcal{L}_{U_{a}} g, Z=\triangle_{\mathbb{R}} U_{a}+\operatorname{Ric}\left(U_{a}\right)=0$, then by Proposition 2.3.7 in[53]

$$
\begin{aligned}
\triangle_{L}(h) & =-2 \mathcal{L}_{U_{a}}(\text { Ric })+\mathcal{L}_{Z}(g) \\
& =-\mathcal{L}_{U_{a}}\left(\mathcal{L}_{X}(g)\right) \\
& =-\mathcal{L}_{X}\left(\mathcal{L}_{U_{a}}(g)\right) \\
& =-\mathcal{L}_{X}(h)
\end{aligned}
$$

Here we use a fact in 4.4.3 that $X$ is a radial vector. Therefore $\left[X, U_{a}\right]=0$. Furthermore $U_{a}$ is real holomorphic, hence $Z=\triangle_{\mathbb{R}} U_{a}+\operatorname{Ric}\left(U_{a}\right)=0$

In 4.4.1, we have seen that $|X|=O(1),|\nabla X|=O(1)$. Since assumption 1 is preserved by shifting by 4.4.2, we get $\left|\mathcal{L}_{X}\left(g-g_{m}\right)\right|=o\left(r^{-2}\right)$. By the argument in 4.4.3, $X^{1,0}=\lambda X_{m}^{1,0}$ where $\operatorname{Re}(\lambda) \neq 0$. Hence we have $\left|\operatorname{Ric}_{g}-\operatorname{Re}(\lambda) \operatorname{Ric}_{g_{m}}\right|=o\left(r^{-2}\right)$. In 4.4.4 we saw that $R i c_{g_{m}} \geq \frac{c}{r^{2}} g_{m}$ for $n \geq 2$. Together with positivity of $R i c_{g}$, we get Ric $_{g} \geq \frac{\widetilde{c}}{r^{2}} g_{m}$.

By 4.4.1, $\left|U_{a}\right|=O\left(r^{\frac{1}{2}}\right),\left|\nabla U_{a}\right|=O(1)$. These combined with assumption 1 give us $|h|=o\left(r^{-2}\right)$. Therefore for sufficient large $\theta, \theta\left(\right.$ Ric $\left._{g}\right)>h$. The following argument is quite similar to the analysis in Prop 4.4 in [27].

Consider $\theta_{0}=\inf \left\{\theta \mid \theta\left(\right.\right.$ Ric $\left.\left._{g}\right)>h\right\}$. And let $w=\theta_{0}$ Ric $_{g}-h$.
We'll see that $\theta_{0}>0$ leads to a contradiction. If $\theta_{0}>0$, by Ric $c_{g} \geq \frac{\widetilde{c}}{r^{2}} g_{m}$, $|h|=o\left(r^{-2}\right)$ and the positivity of $R i c_{g}, \exists p \in M, e_{1} \in T_{p} M$ s.t. $w\left(e_{1}, e_{1}\right)=0$. Parallel translating $e_{1}$ in a neighbourhood of $p$, then we have $(\Delta w)\left(e_{1}, e_{1}\right)>0$, $\left(D_{X} w\right)\left(e_{1}, e_{1}\right)=0$ at $p$.

Now the discussion goes to the complexified tangent bundle. Extend $w$ by $\mathbb{C}$-linearity. The discussion separates into two parts. The first part is to show
$\operatorname{Tr} w=0$ at $p$. The second part is to show $\operatorname{Tr} w$ satisfies $\triangle(\operatorname{Tr} w)+D_{X}(\operatorname{Tr} w) \leq 0$.
For the first part, let $\eta_{1}=\frac{1}{2}\left(e_{1}-i J e_{1}\right) \in T_{p, \mathbb{C}}^{1,0}$, then $w\left(\eta_{1}, \overline{\eta_{1}}\right)=0$. Together with $w \geq 0$, this implies we can extend $\eta_{1}$ into unitary basis $\eta_{1} \ldots \eta_{n} \in T_{q, \mathbb{C}}^{1,0}$ such that $w\left(\eta_{i}, \overline{\eta_{j}}\right)$ is diagonal. Also we can parallel extend $\eta_{i}$ like $\eta_{1}$.

Since $\triangle_{L} w+\mathcal{L}_{X} w=0$, plug in $\eta_{i}, \overline{\eta_{i}} \in T_{p, \mathbb{C}}^{1,0} M$ (Extend $J$-invariant ( 0,2 )-tensor $w$ by $\mathbb{C}$-linearity.)

$$
\begin{array}{r}
0=(\triangle w)\left(\eta_{i}, \overline{\eta_{i}}\right)+2 \Sigma_{k} \operatorname{Rm}\left(\eta_{i}, \overline{\eta_{k}}, \overline{\eta_{i}}, \eta_{k}\right) w\left(\eta_{k}, \overline{\eta_{k}}\right)-2 w\left(\operatorname{Ric}\left(\eta_{i}\right), \overline{\eta_{i}}\right) \\
+\left(D_{X} w\right)\left(\eta_{i}, \overline{\eta_{i}}\right)+w\left(D_{\eta_{i}} X, \overline{\eta_{i}}\right)+w\left(\eta_{i}, D_{\overline{\bar{\eta}_{i}}} X\right) \\
w\left(D_{\eta_{i}} X, \overline{\eta_{i}}\right)=\eta_{i}\left(\eta_{\bar{i}} f\right) w\left(\eta_{i}, \eta_{\bar{i}}\right)=\eta_{\bar{i}}\left(\eta_{i} f\right) w\left(\eta_{i}, \eta_{\bar{i}}\right)=w\left(\eta_{i}, D_{\overline{\eta_{i}}} X\right)
\end{array}
$$

From the soliton equation, we have $\operatorname{Ric}\left(\eta_{i}\right)=D_{\eta_{i}} X$, therefore

$$
\begin{equation*}
0=(\triangle w)\left(\eta_{i}, \overline{\eta_{i}}\right)+2 \Sigma_{k} R m\left(\eta_{i}, \overline{\eta_{k}}, \overline{\eta_{i}}, \eta_{k}\right) w\left(\eta_{k}, \overline{\eta_{k}}\right)+\left(D_{X} w\right)\left(\eta_{i}, \overline{\eta_{i}}\right) . \tag{4.6}
\end{equation*}
$$

Now take $i=1$, we see that $0 \geq 2 \Sigma_{k} R m\left(\eta_{1}, \overline{\eta_{k}}, \overline{\eta_{1}}, \eta_{k}\right) w\left(\eta_{k}, \overline{\eta_{k}}\right)$. That $g$ has positive holomorphic bisectional curvature implies $R m\left(\eta_{1}, \overline{\eta_{k}}, \overline{\eta_{1}}, \eta_{k}\right)>0$. Therefore $w\left(\eta_{k}, \overline{\eta_{k}}\right)=0$ for any $k$ at $p$. The nonnegative function $\operatorname{Tr} w=0$ at $p$.

Equation (4.6) only uses $\triangle_{L} w+\mathcal{L}_{X} w=0$, the soliton equation, $w\left(\eta_{i}, \overline{\eta_{j}}\right)$ is diagonal and the extension is parallel. Now sum (4.6) for all $i$ at $q$ give us $\triangle(\operatorname{Tr} w)+$ $D_{X}(\operatorname{Tr} w) \leq 0$.

By Hopf's strong maximum principle, $\operatorname{Tr} w=0$. Therefore $w$ is 0 . This violates the asymptotic of $R i c_{g}$ and $h$. Therefore $\theta_{0}=0, h \leq 0$. Now apply a similar argument to $-h$ implies $h=0$. Therefore $g$ is $U(n)$-symmetric. Therefore it must be in the family of steady solitons in [11].

## Bibliography

[1] Akito Futaki and Mu-Tao Wang, Constructing Kähler-Ricci solitons from SasakiEinstein manifolds, Asian J. Math. 15 (2011), no. 1, 33?2. MR 2786464 (2012e:53077)
[2] Ballmann, Werner. Lectures on Kähler manifolds. European mathematical society, 2006.
[3] Buzano, M., Dancer, A. S., Gallaugher, M. and Wang, M., A family of steady Ricci solitons and Ricci-flat metrics, preprint (2014), arXiv:1309.6140v2 [math.DG].
[4] Berman, Robert J., and Bo Berndtsson. "The volume of KählerVEinstein Fano varieties and convex bodies." Journal fur die reine und angewandte Mathematik (Crelles Journal) (2014).
[5] Brendle, Simon, and Richard Schoen. "Manifolds with $1 / 4$-pinched curvature are space forms." Journal of the American Mathematical Society 22.1 (2009): 287-307.
[6] Brendle, Simon. "Rotational symmetry of self-similar solutions to the Ricci flow." Inventiones mathematicae 194.3 (2013): 731-764.
[7] Brendle, Simon. Rotational symmetry of Ricci solitons in higher dimensions.J. Differential Geom. 97 (2014), no. 2, 191-214.
[8] Bryant, Robert L. "Ricci flow solitons in dimension three with SO (3)symmetries." preprint, Duke Univ (2005).
[9] Bryant, Robert L. "Gradient Kahler Ricci solitons." arXiv preprint math/0407453 (2004).
[10] Bryant, R., unpublished work (http://math.duke.edu/ bryant/3DRotSymRicciSolitons.pdf)
[11] Cao, H.-D., Existence of gradient Kahler-Ricci solitons, Elliptic and Parabolic Methods in Geometry (Minneapolis, MN, 1994), A. K. Peters (ed.), Wellesley, MA, 1996, 1-16.
[12] Cao, H.-D., Richard S. Hamilton. "Gradient Kähler-Ricci Solitons and Periodic Orbits." arXiv preprint math/9807009 (1998).
[13] Cao, Huai-Dong. "Geometry of complete gradient shrinking Ricci solitons." arXiv preprint arXiv:0903.3927 (2009).
[14] Cao, H.-D., Recent progress on Ricci solitons, Recent advances in geometric analysis, 1-38, Adv. Lect. Math. (ALM), 11 Int. Press, Somerville, MA, 2010. MR2648937
[15] Cao, Huai-Dong; Zhou, Detang. On complete gradient shrinking Ricci solitons. J. Differential Geom. 85 (2010), no. 2, 175-186.
[16] Cao, Huai-Dong, and Qiang Chen. "On locally conformally flat gradient steady Ricci solitons." Transactions of the American Mathematical Society 364.5 (2012): 2377-2391.
[17] Cao, Huai-Dong, and Xin Cui. "Curvature Estimates for Four-Dimensional Gradient Steady Ricci Solitons." arXiv preprint arXiv:1411.3631 (2014).
[18] Cao H.-D. and Zhu, X.-P., A complete proof of the Poincaré and geometrization conjectures - application of the Hamilton-Perelman theory of the Ricci flow, Asian J. Math. 10 (2006), no. 2, 165-492. MR2233789 (2008d:53090)
[19] Cao, H.-D., Catino, G., Chen, Q., Mantegazza, C., and Mazzieri, L., Bachflat gradient steady Ricci solitons, Calc. Var. Partial Differential Equations, 49 (2014), no. 1-2, 125-138.
[20] Catino, G. and Mantegazza, C., Evolution of the Weyl tensor under the Ricci flow, Ann. Inst. Fourier. 61 (2011), no. 4, 1407-1435.
[21] Chau, Albert, and Luen-fai Tam. "Gradient Kähler-Ricci solitons and a uniformization conjecture." arXiv preprint math/0310198 (2003).
[22] Chen, B.-L., Strong uniqueness of the Ricci flow, J. Differential Geom. 82 (2009), 363-382. MR2520796 (2010h:53095)
[23] Chen, Bing-Long, and Xi-Ping Zhu. "Volume Growth and Curvature Decay of Positively Curved Kä hler manifolds." arXiv preprint math/0211374 (2002).
[24] Schnurer, O., and A. Chau. Stability of Gradient Kähler-Ricci Solitons., Communications in analysis and geometry 13.4 (2005): 769-800.
[25] Chen, X.X. and Wang, Y., On four-dimensional anti-self-dual gradient Ricci solitons, to appear in J. Geom. Anal.
[26] Chodosh Otis, Expanding Ricci Solitons Asymptotic to Cones, arXiv preprint, arXiv:1303.2983, (2013).
[27] Chodosh Otisand Frederick Tsz-Ho Fong, Rotational Symmetry of Conical Kähler-Ricci Solitons, arXiv preprint, arXiv:1304.0277, (2013).
[28] Chow, B. et al., The Ricci flow: techniques and applications. Part I Geometric aspects.Mathematical Surveys and Monographs, 135. American Mathematical Society, Providence, RI, 2007. MR2302600 (2008f:53088)
[29] Chow, B., Lu, P. and Yang, B., Lower bounds for the scalar curvatures of noncompact gradient Ricci solitons, C. R. Math. Acad. Sci. Paris 349 (2011), no. 23-24, 1265-1267.
[30] Dancer, A. and Wang, M., Some new examples of non-Kähler Ricci solitons, Math. Res. Lett. 16 (2009), 349-363.
[31] Dancer, A. and Wang, M., On Ricci solitons of cohomogeneity one, Ann. Glob. Anal. Geom., 39 (2011) 259-292.
[32] Demailly, Jean-Pierre. Complex analytic and differential geometry. Université de Grenoble I, 1997.
[33] Fang, F., Li, X.-D. \& Zhang, Z., Two Generalizations of Cheeger-Gromoll Splitting theorem via Bakry-Emery Ricci Curvature, Ann. Inst. Fourier (Grenoble) 59 (2009), no. 2, 563-573.
[34] Fernndez-López, M. and Garca-Río, E., A sharp lower bound for the scalar curvature of certain steady gradient Ricci solitons, Proc. Amer. Math. Soc. 141 (2013), no. 6, 2145-2148.
[35] Fujita, Kento. "Optimal bounds for the volumes of Kähler-Einstein Fano manifolds." arXiv preprint arXiv:1508.04578 (2015).
[36] Hamilton, R. S., The Ricci flow on surfaces,Contemporary Mathematics 71 (1988), 237-261. MR0954419 (89i:53029)
[37] Hamilton, Richard S. Three-manifolds with positive Ricci curvature. J. Differential Geom. 17 (1982), no. 2, 255-306.
[38] Hamilton, R. S., The Ricci flow on surfaces, Contemporary Mathematics 71 (1988), 237-261. MR0954419 (89i:53029)
[39] Hamilton, Richard S. The formation of singularities in the Ricci flow, Surveys in Differential Geometry, 2,pp. 7-136, International Press, 1995.
[40] Hamilton, R. S., The formation of singularities in the Ricci flow, Surveys in Differential Geometry (Cambridge, MA, 1993), 2, 7-136, International Press, Cambridge, MA, 1995. MR1375255 (97e:53075)
[41] Ivey, T., New examples of complete Ricci solitons, Proc. AMS 122 (1994), 241245.
[42] Li, Peter, and Shing Tung Yau. "On the parabolic kernel of the Schrödinger operator." Acta Mathematica 156.1 (1986): 153-201.
[43] Mikhail Feldman, Tom Ilmanen, and Dan Knopf, Rotationally symmetric shrinking and expanding gradient Kahler-Ricci solitons, J. Differential Geom. 65 (2003), no. 2, 169?09. MR 2058261 (2005e:53102)
[44] Munteanu, Ovidiu, and Natasa Sesum. "On gradient Ricci solitons." Journal of Geometric Analysis 23.2 (2013): 539-561.
[45] Munteanu, Ovidiu, and Jiaping Wang. "Geometry of shrinking Ricci solitons." arXiv preprint arXiv:1410.3813 (2014).
[46] Munteanu, Ovidiu, and Jiaping Wang. "Analysis of weighted Laplacian and applications to Ricci solitons." Communications in Analysis and Geometry 20.1 (2012).
[47] Ni, Lei. "ANCIENT SOLUTIONS TO KAHLER-RICCI FLOW." Mathematical Research Letters 12 (2005): 633-654.
[48] Carrillo, Jose A., and Nei Ni. "Sharp logarithmic Sobolev inequalities on gradient solitons and applications." Communications in Analysis and Geometry 17.4 (2009).
[49] N. Koiso, On rotationally symmetric Hamilton equation for Kähler-Einstein metrics, Recent Topics in Differential and Analytic Geometry (T. Ochiai, editor), Advanced Studies in Pure Math., 18(1), 1990, Kinokuniya (Tokyo) and Academic Press (Boston), 327?37, MR 1145263 (93d:53057), Zbl 0739.53052.
[50] O. Debarre, Higher-dimensional algebraic geometry, Universitext, New York, NY, Springer,2001.
[51] Perelman G., The entropy formula for the Ricci flow and its geometric applications, available at http://arxiv.org/abs/math/0211159.
[52] G. Perelman, Ricci flow with surgery on three-manifolds, arxiv:0303109
[53] Peter Topping, Lectures on the Ricci Flow, London Mathematical Society Lecture Note Series, vol. 325, Cambridge University Press, Cambridge, 2006. MR 2265040(2007h:53105)
[54] Petersen, P. and Wylie, W., Rigidity of gradient Ricci solitons, Pacific J. Math, 241(2009), 329-345.
[55] Schnurer, O. C., and A. Chau. "Stability of Gradient Kahler-Ricci Solitons." Communications in analysis and geometry 13.4 (2005): 769-800.
[56] Tian, Gang, et al. "Perelmans entropy and Kähler-Ricci flow on a Fano manifold." Transactions of the American Mathematical Society 365.12 (2013): 66696695.
[57] Simon Brendle, Rotational symmetry of self-similar solutions to the Ricci flow, Inventiones mathematicae, (2012): 1-34.
[58] Simon Brendle, Rotational symmetry of Ricci solitons in higher dimensions, arXiv preprint, arXiv:1203.0270, (2012).
[59] Shi, Wan-Xiong. "Ricci flow and the uniformization on complete noncompact Kähler manifolds." Journal of Differential Geometry 45.1 (1997): 94-220.
[60] Wang, Xu-Jia, and Xiaohua Zhu. "Kähler Ricci solitons on toric manifolds with positive first Chern class." Advances in Mathematics 188.1 (2004): 87-103.APA
[61] Wei, G. and Wu, P., On volume growth of gradient steady Ricci solitons, Pacific J. Math. 265 (2013), no. 1, 233-241.
[62] Wei, Guofang, and William Wylie. "Comparison geometry for the Bakry-Emery Ricci tensor." Journal of differential geometry 83.2 (2009): 377-406.
[63] Wu, Peng. "On the potential function of gradient steady Ricci solitons." Journal of Geometric Analysis 23.1 (2013): 221-228.
[64] Some function-theoretic properties of complete Riemannian manifolds and their applications to geometry, Indiana Univ. Math. J. 25(1976), 659-670.

## Xin Cui

Department of Mathematics, Lehigh University
Christmas-Saucon Hall, 14 East Packer Avenue, Bethlehem, PA 18015
Phone: 610-888-8731

## Education

- B.S. in Mathematics, Zhejiang University, Hangzhou, China, 2010.
- Ph.D. in Mathematics, Lehigh University, PA, May 2016 (expected).


## Academic Honors

- First Prize, 9th East China Math Modeling Competition, 2007.
- Second Prize, Contemporary Undergraduate Mathematical Contest in Modeling, 2007.
- Certificate for Chu Kochen Honors Program, Zhejiang University, 2010.
- University Fellowship, Lehigh University, 2010-2011.
- Strohl Summer Research Fellowship, Lehigh University, 2013.
- Strohl Dissertation Fellowship, Lehigh University, 2015-2016.


## Research Interests

- Differential Geometry, Ricci Flow and Ricci solitons, Complex Geometry.


## Publication

- Huai-Dong, Cao and Xin Cui. "Curvature Estimates for Four-Dimensional Gradient Steady Ricci Solitons." arXiv preprint arXiv:1411.3631 (2014).
- Xin Cui. "A note on complete steady Kahler-Ricci solitons with positive Ricci curvature", in preparation.


## Talk

- Graduate Student Intercollegiate Mathematics Seminar Talk, Lehigh University, Fall 2013.


## Conference Attendance

- Conference on Geometric Analysis in honor of Peter Lis 60th Birthday, UC Irvine, 2012.
- Lehigh Geometry/Topology conference, Lehigh University, 2012.
- Yamabe Memorial Symposium, University of Minnesota: Twin Cities, 2012.
- Great Lakes Geometry Conference, Northeastern University, 2013.
- Complex Geometry, and Mathematical Physics: A Conference in Honor of Duong H. Phong, Columbia University,2013.
- Graduate Workshop on Kahler Geometry, Stony Brook University, 2013.
- Summer school in complex geometry, Rutgers University, 2013.
- RU-CUNY Symposium on Geometric Analysis, Rutgers University, 2013.
- Journal of Differential Geometry Conference, Harvard University, 2014.


## Teaching Experience

Teaching Assistant:

- Math 22, Calculus 2, Fall 2011.
- Math 22, Calculus 2, Fall 2012.
- Math 22, Calculus 2, Spring 2013.
- Math 23, Calculus 3, Fall 2013.
- Math 22, Calculus 2, Fall 2014.
- Math 23, Calculus 2, Spring 2015.

Grader:

- Math 205, Linear Algebra, Spring 2012.
- Math 401, Real Analysis (Graduate course), Fall 2013.

