2016-12-01

Life-Cycle Benefit-Cost Analysis of Safety Related Improvements on Roadways

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A thesis submitted to the faculty of
Brigham Young University
in partial fulfillment of the requirements for the degree of

Master of Science

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ABSTRACT

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The Highway Safety Manual (HSM) lists four different methods for determining the change in crash frequency in order of reliability. Currently, the Utah Department of Transportation (UDOT) uses the fourth reliable method. The goal of this research was to develop a tool that the most reliable method mentioned in the HSM could be used to perform life-cycle benefit-cost analyses. A spreadsheet program was built that performs the HSM's Part C Predictive Method for 11 different roadway segment types mentioned in HSM using Excel macros and Visual Basic for Applications (VBA) programming. Intersections were not included in this spreadsheet program as they were not included in the Utah Crash Prediction Model (UCPM) or the Utah Crash Severity Model (UCSM) at the time of this research. The methodology for analysis was set up to become part of the use of the models in selecting countermeasures. The concept and spreadsheet layout are discussed using the rural two-lane two-way (TLTW) highway spreadsheet as an example. Three examples are presented in this thesis, which are a case of rural TLTW highway, a case of five-lane urban arterial with a two-way left-turn lane (TWLTL), and a case of a freeway segment, each with two selected countermeasures to compare their benefit-cost ratios (BCRs). One important aspect associated with life-cycle benefit-cost analysis of safety related improvements is the cost of countermeasures. The spreadsheets developed in this research can predict the benefits associated with a countermeasure following the methods found in the HSM; however, it does not include a module to estimate costs associated with a countermeasure to be selected because costs of countermeasures are dependent on the way such improvements are included in construction contracts. The engineer should seek guidance from the cost estimate expert within the agency or outside consultants when determining the project costs.

ACKNOWLEDGEMENTS

TABLE OF CONTENTS

LIST OF TABLES

LIST OF FIGURES

1 INTRODUCTION

Safety on roadways is one aspect under consideration when roadways are being rebuilt, rehabilitated, or maintained. One important aspect when considering safety are life-cycle benefit-cost analyses. Life-cycle benefit-cost analysis is one necessary step to be performed with different safety countermeasures to determine which safety countermeasure provides the best benefit for the lowest cost. This research explores how these analyses can be performed using spreadsheets. This chapter presents the background information related to this research, explains the purpose and need for this research, and the organization of the report.

1.1 Background

Safety on roadways is important everywhere. The Utah Department of Transportation (UDOT) has made it one of its top priorities, which can be seen in their campaign: "Zero Fatalities: A Goal We Can All Live With™." This campaign is "all about eliminating fatalities on [Utah] roadways" (Zero Fatalities 2016). One way that UDOT accomplishes this goal of "Zero Fatalities" is by performing safety related improvements on roadway segments that have experienced a greater number of crashes than expected. When determining which safety related improvement will be most effective, various analyses must be performed. One of these analyses is a life-cycle benefit-cost analysis.

The Highway Safety Manual (HSM) presents the preferred methods for performing life-cycle cost benefit analyses of safety related improvements (AASHTO 2010a). Part of the life-cycle benefit-cost analysis of safety related improvements is to determine the change in the number of expected crashes for each proposed improvement. The HSM contains a process for determining the change in average crash frequency known as the Part C Predictive Method. The Part C Predictive Method is an 18-step method for predicting average crash frequencies. The Part C Predictive Method includes numerous predictive models that use safety performance functions (SPFs), crash modification factors (CMFs), and other factors to predict the number of crashes that a roadway segment or intersection will experience based on its physical characteristics. SPFs are regression models that estimate the average crash frequency for a specific roadway type as a function of the annual average daily traffic (AADT), segment length, and regression constants. These constants are determined based on the crash severity being considered and the roadway type. A CMF is an index of how much a crash rate is expected to change following a physical change in the roadway or intersection. A CMF is simply a ratio between the number of crashes per unit of time expected after a modification or an improvement measure is implemented and the number of crashes per unit of time estimated if the change does not take place (AASHTO 2010a).

The HSM outlines four different methods for determining the change in crashes in order of reliability. The most reliable method is the Part C Predictive Method, while the least reliable method uses observed crash data and applies a CMF without considering SPFs. Currently UDOT uses the latter method to determine the change in average crash frequency when performing benefit-cost analyses of safety related improvements. This research is intended to create a

method in which UDOT can use the Part C Predictive Method as part of the life-cycle benefit-cost analyses of safety related improvements.

1.2   Purpose and Need

The purpose of this research is to develop an Excel-based spreadsheet program that performs life-cycle benefit-cost analysis for safety related improvements using the method ranked most reliable in the HSM. This Excel-based spreadsheet program uses the Part C Predictive Method to determine the reduction in crash frequency, and uses the life-cycle, present value analysis method presented in Volume 1 of the HSM (AASHTO 2010a). The Part C Predictive Method does not have information for every type of roadway. The scope of this research includes 11 roadway types included in the HSM (AASHTO 2010a):

1. Rural two-lane two-way (TLTW) highways

2. Undivided rural multilane highways

3. Divided rural multilane highways

4. Two-lane undivided suburban/urban arterials

5. Three-lane suburban/urban arterials including a two-way left-turn lane (TWLTL)

6. Four-lane undivided suburban/urban arterials

7. Four-lane divided suburban/urban arterials

8. Five-lane suburban/urban arterials including a TWLTL

9. Rural and urban freeway segments

10. Freeway speed change lanes

11. Freeway ramps

The need for this research arose as UDOT does not currently use the most reliable method for performing life-cycle benefit-cost analyses of safety related improvements. The

purpose of life-cycle benefit-cost analyses is to help the safety engineer to determine which improvement will create the largest safety benefit compared to its cost. These analyses are essential because they are used to determine which improvements should be chosen and how tax payer money is used to benefit the public. Hence, it is important to perform the most accurate analysis possible recommended by the HSM to make sure that money is used effectively and to achieve the highest possible reduction of crashes.

As part of a previous and current research effort by Brigham Young University (BYU), the Utah Crash Prediction Model (UCPM) and Utah Crash Severity Model (UCSM) were developed (Schultz et al. 2015). These models are only used for roadway segments and cannot be used for intersections and interchanges at the time of this research. Since this research effort was in conjunction with the research effort for these models, intersections and interchanges were not included as part of the spreadsheets for this life-cycle benefit-cost analysis of safety related improvements.

1.3   Organization

This thesis consists of seven chapters. Chapter 1 presented an overview of the report along with a stated purpose and need for this research. Chapter 2 contains the literature review, which is a summary of topics related to the research. Chapter 3 explains the methodology used in this research project. Chapter 4 discusses the concept used in this research including the software development. Chapter 5 includes three sample applications: a rural highway, a suburban/urban arterial, and a freeway. Chapter 6 contains a discussion about the findings of the research. Chapter 7 contains conclusions and recommendations for use of the Excel-based spreadsheet program as well as possible further research projects. Following the body of the report, there are appendices that include sources and information that were used to complete this research.

2 LITERATURE REVIEW

A literature review was performed on traffic safety and the life-cycle benefit-cost analysis of safety related improvements. This chapter presents a background into traffic safety, the UCPM, SPF, CMF, the HSM method for performing life-cycle benefit-cost analysis of safety related improvements, and the current UDOT method for performing life-cycle benefit-cost analysis of safety related improvements. For more detail on the safety and crash analysis techniques, the reader should refer to previous research related to this topic conducted by BYU researchers (Saito et al. 2010, Schultz et al. 2011, Schultz et al. 2012, Schultz et al. 2013, Schultz et al. 2014, Schultz et al. 2015).

2.1 Traffic Safety Defined

The HSM defines safety as "the crash frequency or crash severity, or both, and collision type for a specific time period, a given location, and a given set of geometric and operational conditions" (AASHTO 2010a). There are two categories for safety: subjective and objective. Subjective safety concerns the perception of how safe a person feels on the transportation system. Objective safety is the use of a quantitative measure that is independent of the observer. Regardless of which type of safety metric is used, the general consensus is that the number of crashes on a roadway can help determine the level of safety on the roadway. The HSM defines a crash "as a set of events that result in injury or property damage due to the collision of at least

one motorized vehicle and may involve collision with another motorized vehicle, bicyclist, pedestrian, or object (AASHTO 2010a). Crash frequency is defined as the number of crashes occurring at a particular site, facility, or network in a one-year period" (AASHTO 2010a). There are many factors that affect the number of crashes that occur on a roadway such as "speed, roadway design, roadside design, median treatments, auxiliary lanes, horizontal and vertical alignment, lane and shoulder widths, shoulder types, and other cross-sectional elements" (AASHTO 2011). Based on these definitions and the idea that safety is based on crashes and crash frequency, the higher the crash frequency, the less safe a roadway segment is perceived to be. Safety has continued to become a focus for transportation officials and continues to be a critical aspect in the transportation decision making process (Tobias 2016). This thesis will help illustrate how safety can be integrated into the transportation decision making process.

Another major part of safety is crash severity. The HSM uses the KABCO scale, which separates different crashes into various categories based on how severe the crashes are. The different categories are outlined as follows (AASHTO 2010a).

- K – Fatal injury

- A – Incapacitating injury

- B – Non-incapacitating injury

- C – Possible injury

- O – No injury/Property Damage Only (PDO)

Crash severity can be helpful in determining which roadway segments truly are the least safe, as there may be segments with a high number of crashes, but all of them a type C or O while other segments may have a low number of crashes, but most of them are type K, A, and B

crashes. While UDOT definitely does not want crashes of any kind, their focus is on fatal injury crashes, which means that they would probably prefer to focus on segments that had a high number of fatal injury crashes, even if the overall number of crashes was lower when compared to other segments.

Safety has been a focus at UDOT for quite a while. To help with reducing the number of fatal injury crashes and crashes in general in Utah, two models have been created in previous research projects: UCPM and UCSM. The UCPM is used to predict the total crash frequency including all types of crashes that will take place on a given roadway segment, while the UCSM is used to determine which roadway segments have the highest number of severe injury crashes (Schultz et al. 2015). Since this research is focused on the life-cycle benefit-cost exploration, the UCPM will be more useful than the UCSM. The UCPM will be explained in further detail in the following section.

2.2 UCPM

In previous research efforts by BYU, the UCPM was developed to help UDOT identify sections that could have a higher number crashes than expected (Schultz et al. 2015). In this model, a variety of parameters such as vehicle-miles traveled (VMT), number of lanes, speed limit, and others are used to create a crash distribution for different road segments. "The mean of the distribution is used as the expected number of crashes that might occur on a specific segment based on the characteristics of that segment" (Saito et al. 2011). In this model, a pre-selection process is performed using the Bayesian horseshoe selection method, which takes all possible parameters in the dataset and produces a list of the significant ones that should be used. The selected parameter set can be used to predict the number of crashes for a given severity group.

To start the procedure, a statistical model must be chosen to provide the base dataset in the analysis and identification of the problem segments or "hot spots." The analysis that was completed in the previous research project used a statistical model that included all of the crashes from the years 2008 to 2012 (Schultz et al. 2015). The data for the model used included the total crash counts for each segment and the count of crashes for each attribute selected by the Bayesian horseshoe selection method. The UCPM required 100,000 iterations to obtain posterior predictive distributions on the number of crashes expected to occur on each segment. This model included total crash counts for both all severity levels and the severity level A and K.

The UCPM compared the actual number of crashes to the posterior predictive distribution of crash occurrences to determine the percentile for each segment as a number between 0 and 1. This percentile was used to rank each of the segments. The higher the percentile the higher the ranking for the segment. Along with other outputs of the model, the data entered into the model were used to determine the probability that the expected number of crashes actually occurred. This probability was also used in the ranking process.

As this model can be used to determine the number of crashes that are expected to occur on a given roadway segment, it can help determine the number of crashes that will be reduced on each roadway segment when the values of the selected variables are changed. As this model can also be used to determine number of each severity type crash, this can be useful in determining how many of each severity type will be reduced on a given roadway segment. The UCPM combined with SPFs and CMFs can help to obtain a reliable estimate of the number of crashes that can be reduced on a roadway segment. After the number of crashes reduced is determined, the benefit can be determined by comparing different possible treatments to improve safety. The

following sections further explore SPFs and CMFs and how they can work in determining the change in crash frequency on a roadway segment.

2.3 SPFs

SPFs are regression models that estimate average crash frequency for a specific site type as a function of AADT and segment length. There are base conditions such as lane width, lighting characteristics, turn lanes, and others that can be specified for each SPF (AASHTO 2010a). Equation 2-1 provides an example of a SPF for rural TLTW highways from the HSM (AASHTO 2010a).

$$N_{spf} = AADT \times L \times 365 \times 10^{-6} \times e^{-0.312} \tag{2-1}$$

where, N_{spf} =   number of predicted annual crashes,

     $AADT$ =   average annual daily traffic (vehicles per day), and

     L =   segment length (mi).

This SPF converts AADT into VMT per year by multiplying AADT by the segment length (L). By multiplying VMT by 10^{-6}, the model converts predicted number of crashes into million VMT per year, which makes the number of predicted annual crashes much easier to work with. The constant e or exponential is used in calculating the appropriate regression factors.

The HSM contains SPFs for three facility types (rural TLTW roads, rural multilane highways, and urban and suburban arterials). There are also SPFs for specific site types of each facility (signalized intersections, un-signalized intersections, divided roadway segments, undivided roadway segments). In order to apply an SPF, there are three pieces of information that must be known for the study site. The basic information of the study site is used to

determine whether an SPF is available for that facility and site type. The detailed geometric design and traffic control features of the site are then required to determine whether the conditions of the study site vary from the SPF baseline conditions. The AADT and traffic growth rate must also be known to help forecast estimates of AADT for future periods (AASHTO 2010a).

The SPFs in the HSM are developed using observed crash data collected over a number of years, but with the data from limited number of states and calibration is needed to reflect local conditions. The parameters of the SPFs are determined by assuming that the crash frequencies follow a negative binomial distribution. The negative binomial distribution is better suited for the crash data as opposed to the often-used Poisson distribution because the Poisson distribution is generally used when the mean and the variance of the data are equal. In the case of crash data, the variance usually exceeds the mean, which is defined as "over-dispersed." The amount of over-dispersion is represented by a statistic, known as the over-dispersion parameter, which is one of the statistics provided by statistical software programs. The larger the dispersion parameter, the more the crash data vary as compared to a Poisson distribution with the same mean and variance (AASHTO 2010a).

SPFs tend to be simplistic and have certain limitations as they estimate crash frequency for all crashes and do not separate the estimated crash frequency into components by crash severity levels and collision types (such as run-off-the-road or rear-end crashes). SPFs use a variety of different parameters such as speed limit, lane width, shoulder width, etc. and any number of parameters can be used in the model. The goal is to choose the correct parameters for the roadway segment under consideration. The SPF should be calibrated using local conditions to make the model applicable to the given segment. The SPFs in the HSM are based off of general

conditions such as 12-foot lane widths, six-foot paved shoulders, etc. If the segments that are

being examined differ from these conditions, then the model should be adjusted to the local

conditions by changing the parameters in the SPF or by using CMFs. Another limitation of SPFs

is that they contain predictive factors as opposed to causal factors such as human factors since

human factors are difficult to model and reflect in mathematical models. Since there are these

limitations to SPFs, the SPFs need to be adjusted, which is done by using CMFs (AASHTO

2010b). CMFs are discussed in section 2.4.

2.4   CMFs

The HSM defines CMFs as "the relative change in crash frequency due to a change in one

specific condition, estimating the effect of a particular geometric design or traffic control or the

effectiveness of a particular treatment or condition" (AASHTO 2010a). CMFs were originally

referred to as Accident Modification Factors (AMFs), but were changed in the final version of

the HSM to be CMFs (Fitzpatrick et al. 2008). CMFs can be used to determine the effectiveness

of a particular treatment or condition. CMFs are usually presented for the implementation of a

particular treatment, which is also known as a countermeasure, intervention, action, or alternative

design (Gross et al. 2010). Most CMFs have to do with roadway characteristics such as the

shoulder width, lane width, presence of rumble strips, etc. (AASHTO 2010a).

CMFs are the ratio of the crash frequency of a site under two different conditions.

Generally, the ratio is the number of crashes after a particular roadway change divided by the

number of crashes before the change took place. If a CMF is equal to 1.00, this means that there

was no change in the number of crashes on a roadway segment. If the CMF is greater than 1.00,

the number of crashes has increased, and if the CMF is less than 1.00 the number of crashes has

decreased. The CMF can also be used to calculate the percent in crash reduction. The equation

for the percent in crash reduction is shown in Equation 2-2.

$$\text{Percent Reduction in Crash} = 100 \times (1.00 - CMF) \qquad\qquad (2\text{-}2)$$

Essentially, CMFs are the percent of crashes that occurred after the change, while the

percent reduction in crashes is the percent of crashes that were removed or increased after the

change. For example, if the CMF is 0.6, then the percent reduction in crashes is 40% (100x(1-

0.6)). This means that after the change only 60% of the crashes occurred and there was a 40%

reduction. If the CMF is 1.3, then the percent reduction in crashes is -30% or a 30% increase in

crashes.

The HSM presents CMF values in three different formats. The CMFs are presented either

in text, in a formula referred to as a Crash Modification Function, or in a tabular form. Text is

usually used when there is a limited range of options for a particular treatment; a formula is used

where treatment options are continuous variables; tabular form is used where the values vary by

facility type. When CMFs are determined using an equation or graph, or when the CMF is

presented as a discrete value, the CMF is typically rounded to two decimal places (AASHTO

2010a). The following subsections will give more pertinent information regarding CMFs.

2.4.1 Combining Multiple CMFs

Many times when roadway improvements or treatments take place, there are multiple

treatments that are performed simultaneously. This creates a compound effect on crash reduction.

The general practice is to multiply all of the CMFs together to produce a new CMF. For

example, if a given roadway segment was to have two treatments, one with a CMF of 1.2 and the

other with a CMF of 0.5. The overall CMF for the combination of treatments is 0.6 (1.2 x 0.5).

There are cases where the treatments are not always compatible. Engineering judgment must be used when combining CMFs where multiple treatments change the overall nature of the site, and that different CMFs are not compatible. An example may be the installation of a roundabout at an urban two-way stop-controlled or signalized intersection. The usual procedure would be to try to estimate the current crash frequency and then apply a CMF for a conventional intersection to roundabout conversion. By installing the roundabout, the nature of the site is changed significantly and CMFs applicable to existing urban two-way stop-controlled or signalized intersections may no longer be relevant (AASHTO 2010a).

2.4.2   CMF Clearinghouse

The CMF Clearinghouse houses a web-based database of CMFs along with supporting documentation to help transportation engineers identify the most appropriate countermeasures for their safety needs. The CMF Clearinghouse also contains a great deal of resources to help in using the CMFs and SPFs. It also provides information on how to calibrate and use CMFs and SPFs (CMF Clearinghouse 2015).

There is a section in the CMF Clearinghouse that also includes all of the information about CMFs such as a frequently asked questions section, a glossary to define useful terms regarding CMFs, the relationship of CMFs to the HSM, and the option to submit a CMF research need. There is also a User Guide on the CMF Clearinghouse that can be used to help users know how to use the CMF Clearinghouse website effectively. The user guide provides an introduction to CMFs in general as well as the CMF Clearinghouse. The CMF Clearinghouse also has a majority of the CMFs that can be used for different projects, and the user guide has instructions on how appropriate CMFs can be selected for specific projects.

There is also a section in the CMF Clearinghouse where a user can submit a CMF based on their personal research. The CMF Clearinghouse also has a section where it has a variety of resources that can be helpful for users. Some of these resources include resources for how to develop and use CMFs and how to develop and use SPFs. Trainings are also available on the CMF Clearinghouse to help train users when using CMFs and the HSM. The following items are also included in the CMF Clearinghouse: a section that explains how CMFs are used in conjunction with the HSM, numerous resources for countermeasure selection and for behavioral countermeasures, international resources with links to road safety for different countries around the world, numerous publications regarding CMFs and different updates on how CMFs have changed over time, and contact information for users to contact the pertinent person from the Federal Highway Administration (FHWA) Office of Safety Programs.

Another useful feature of the CMF Clearinghouse is the information on life-cycle benefit-cost analysis. The CMF Clearinghouse contains various spreadsheets that represent compilations of information useful in analysis. One valuable resource is a spreadsheet that is the compilation of information from all 50 states on the different lengths of service life that each state uses in determining how long each feature such as pavement, striping, or signing will last. An example of this spreadsheet can be seen in Table 2-1 (CMF Clearinghouse 2015). Table 2-1 shows a portion of the spreadsheet for four states: Alaska (AK) in 2014, Arizona (AZ) in 2010, California (CA) in 2013, and Connecticut (CT) in 2014. The complete version of this spreadsheet can be found on the CMF Clearinghouse and contains information for all 50 states.

Table 2-1: Example of Service Life for Different Countermeasures from Various States (CMF Clearinghouse 2015)

Countermeasure Name	AK 2014 Alaska Highway Safety Improvement Program Handbook	AZ 2010 The Arizona Highway Safety Improvement Program Handbook	CA 2013 Local Road Safety - A Manual for California's Local Road Owners	CT 2014
Convert from two way traffic to one way traffic			20	
Convert to one way frontage roads				
Convert two lane facility to four lane divided				
Improve drainage				
Increase turning radius				
Install acceleration/deceleration lane(s)			20	
Install centerline rumble stripes				
Install centerline rumble strips	10			
Install centerline rumble strips/stripes			10	
Install climbing lane			20	
Install edgeline rumble strips				
Install edgeline rumble strips/stripes			10	
Install glare shields				
Install lane(s)	20			
Install left turn acceleration lane				
Install one way couple				
Install passing lane(s)				
Install right turn acceleration lane				
Install rumble strips				10
Install rumble strips on approaches to intersections				
Install through lane(s)				
Install truck escape ramp			20	
Install turnabout				

Another valuable resource in the CMF Clearinghouse is the crash cost summary table, which includes all of the values for each state of how much they value the cost of each crash. For example, a fatal injury crash has a much higher cost than a non-injury crash. A portion of the crash cost summary table can be seen in Table 2-2. These resources can be helpful in determining the life-cycle benefit-cost analysis of a roadway improvement or change.

Table 2-2: Crash Cost Summary Table (CMF Clearinghouse 2015)

State	Cost of Fatal Crash (K)	Cost of Incapacitating Injury Crash (A)	Cost of Non-Incapacitating Injury Crash (B)	Cost of Possible Injury Crash (C)	Cost of Property Damage Only Crash (O)
AK	1393000				13900
AZ	5800000	400000	80000	42000	4000
CA	4008900	216000	79000	44900	7400
CO	1420000				9100
DE					
IA	800000	120000	8000	2000	Actual value
ID	6391502	318302	89155	59097	6842
IL	1432800	70300	22700	12800	9000
IN					
KS	4634000	3913000	78300	41350	3200
KY	1410000	69000	22300	12600	2400

2.5   HSM Method

The HSM can be considered the basis for anything related to safety on roadways. This also applies to life-cycle benefit-cost analysis of safety related improvements and the method explained in the HSM can be considered the preferred method to complete this type of analysis. The specific details associated with the HSM Method can be found in the following subsections.

2.5.1   HSM for Determining Change in Crash Frequency

The benefits of safety for a project are determined using the crash information for a site. One of the most important parts of completing a life-cycle benefit-cost analysis of safety related improvements is to estimate the change in the number of crashes for a proposed project. The HSM outlines four different methods for estimating the change in expected average crash frequency of a proposed project or project design alternative (AASHTO 2010a). The Part C Predictive Method has a part in each of the four methods. The Part C Predictive Method refers to the method outlined in Volume 2 of the HSM (AASHTO 2010b). This method provides procedures to estimate the expected average crash frequency when geometric design and traffic

control features are specified (AASHTO 2010b). When the Part C Predictive Method is not available to be used, the Part D of the HSM method can be used instead. Part D presents a number of CMFs to represent how a certain modification will affect the crash frequency of a given roadway segment (AASHTO 2010b).

The four methods listed in the Part C are presented below in order of reliability:

- *Method 1* – Apply the Part C Predictive Method to estimate the expected average crash frequency of both the existing and proposed conditions

- *Method 2* – Apply the Part C Predictive Method to estimate the expected average crash frequency of the existing condition, and apply an appropriate project CMF from Part D to estimate the safety performance of the proposed condition.

- *Method 3* - If the Part C Predictive Method is not available, but an SPF applicable to the existing roadway condition is available (i.e., an SPF developed for a facility type that is not included in Part C), use that SPF to estimate the expected average crash frequency of the existing condition, and apply an appropriate project CMF from Part D to estimate the expected average crash frequency of the proposed condition. A locally derived project CMF can also be used in Method 3.

- *Method 4* – Use observed crash frequency to estimate the expected average crash frequency of the existing condition, and apply an appropriate project CMF from Part D to the estimated expected average crash frequency of the existing condition to obtain the estimated expected average crash frequency for the proposed condition. This method is applied to facility types not addressed by the Part C Predictive Method.

When a CMF from Part D of the HSM is used in one of the four methods, the associated standard error of the CMF can be applied to develop a confidence interval around the expected average crash frequency estimate. This range can help the analyst to see what type of variation could be expected when implementing a countermeasure. When there is no applicable Part C Predictive Method, SPF, and CMF, the HSM procedures cannot provide an estimate of the expected project effectiveness. In order to evaluate countermeasures, engineering judgment may be used to develop an estimated applicable CMF. The results of the analysis would be considered uncertain, and a sensitivity analysis based on a range of CMF estimates could be used to support decision-making (AASHTO 2010a).

2.5.2   HSM Method for Converting Change in Crash Frequency to Monetary Benefit

After the change in crashes has been estimated for a project, the benefits from preventing the crashes needs to be converted into a monetary value. The first step in converting the benefits to a monetary value is to calculate the annual monetary value. To calculate the annual monetary value for the benefits of reducing crashes, multiple data are needed. The accepted monetary value of crashes by severity is needed to determine how the reduction in each crash severity level has created a benefit for the project. There are numerous differing opinions on how these values of the different crash types should be calculated. The FHWA has completed a significant amount of research that establishes a basis for quantifying, in monetary terms, the human capital crash costs to society of fatalities and injuries from highway crashes. These estimates include the monetary losses associated with medical care, emergency services, property damage, lost productivity, etc. to society as a whole. The FHWA values for each crash severity level can be seen in Table 2-3 (AASHTO 2010a).

Table 2-3: Benefit Value Per Crash Provided by the FHWA for Each Crash Type (AASHTO 2010a)

Severity	Severity	Severity No.	Value
PDO	O	1	$7,400.00
Possible Injury	C	2	$44,900.00
Evident Injury	B	3	$79,000.00
Disabling Injury	A	4	$216,000.00
Fatal	K	5	$4,008,900.00

State and local jurisdictions often have accepted societal crash costs by crash severity and collision type. For example, UDOT has their own monetary values that they use in determining the value of each crash severity level (Wall 2016). There are five crash severity levels considered that are presented on a KABCO scale. As would be expected, fatal crashes have a higher value than PDO crashes. UDOT equalizes the scale for the fatal and disabling injuries so that the fatal crashes and the disabling injury crashes have the same monetary value. The values used by UDOT for each crash severity levels can be seen in Table 2-4 (Wall 2016). This is done to lessen the benefit provided by reducing fatal crashes and increase the benefit provided by reducing disabling injury crashes. While of course, fatal crashes are the crashes that should most definitely be prevented, in many cases, disabling injuries may cost more than fatal crashes in a long run because of lingering medical costs and the persons involved in these incapacitating injuries being prevented from ever working again. Other than these monetary values of crashes by severity, the change in crash estimates for different categories are also needed.

Table 2-4: Benefit Value Per Crash Provided by UDOT for Each Crash Type (Wall 2016)

Severity	Severity	Severity No.	Value
PDO	O	1	$3,200.00
Possible Injury	C	2	$62,500.00
Evident Injury	B	3	$122,400.00
Disabling Injury	A	4	$1,961,100.00
Fatal	K	5	$1,961,100.00

After the change in crash benefit is converted into an annual value, the annual value must be converted into the present value. There are two different methods for converting the annual monetary benefits to present value. One method is where the annual benefits are uniform over the service life of the project, while the other method is where the annual benefits vary over the life of the project.

The first method is used when the annual benefits are uniform over the service life of the project. In the first method, annual monetary benefits is multiplied by a conversion factor for a series of uniform annual amounts to present value to produce the present value of the project benefits for a specific site. The conversion factor is calculated using an equation that includes a minimum attractive rate of return or discount rate and the particular year in the service life of the countermeasure is being analyzed. This can be seen in Equation 2-3 (AASHTO 2010a).

$$P_{A,i,y} = \frac{(1.0+i)^y - 1.0}{i[(1.0+i)^y]} \qquad (2\text{-}3)$$

where, $P_{A,i,y}$ = Conversion factor for a series of uniform annual amounts to present value

i = Minimum attractive rate of return or discount rate

y = Year in the service life of the countermeasure(s)

The second method for converting the annual values to present values is used when the annual benefits vary over the service life of the project. Some countermeasures produce larger changes in expected crash frequency in the first years after the implementation than in subsequent years. In order to account for this occurrence over the service life of the countermeasure, non-uniform annual monetary values can be calculated as done in the first method. The first step in this method is to convert each annual monetary value to its individual present value. Each future annual value is treated as a single future value; therefore, a different present worth factor is applied to each year. The annual monetary benefits are multiplied by a different factor that converts a single future value to its present value. The equation for the factor can be seen in Equation 2-4 (AASHTO 2010a).

$$P_{F,i,y} = (1.0 + i)^{(-y)} \tag{2-4}$$

where, $P_{F,i,y}$ = Factor that converts a single future value to its present value

i = Minimum attractive rate of return or discount rate

y = Year in the service life of the countermeasure(s)

After these values are all calculated, the next step is to sum the individual present values to arrive at a single present value that represents the overall benefits of the project.

2.5.3 HSM Method for Determining Project Costs

After the benefits of the project are calculated the costs of the projects need to be estimated. Determining the costs associated with implementing a countermeasure follows the same procedure as performing cost estimates for other construction projects. Similar to other

roadway construction projects, expected project costs are unique to each site and to each proposed countermeasures. The cost of implementing a countermeasure or set of countermeasures could include a variety of factors, such as right-of-way acquisition, construction material costs, grading and earthwork, utility relocation, environmental impacts, maintenance, and planning and engineering design work conducted prior to construction (AASHTO 2003). Project costs are expressed as present values for use in economic evaluation. Project construction or implementation costs are typically already present values, but any annual or future costs for maintenance and operation need to be converted to present values using the same relationships presented in section 2.5.2 for project benefits (AASHTO 2010a).

2.5.4 Economic Evaluation Method for Individual Sites

After the benefits and costs are both calculated, the economic evaluation can be performed for the project sites. There are two steps in performing the economic evaluation: determine if a project is economically justified (the benefits are greater than the costs), and determine which project or alternative is most cost-effective. This section will explain different ways the most cost-effective improvement alternative can be determined.

The first step is to determine if a project is economically justified is by using the Net Present Value (NPV) method, which is also referred to the Net Present Worth (NPW) method (AASHTO 2010a). This method is used to express the difference between the present cost and present benefit of an individual improvement project in a single amount. The NPV or NPW method can be used for two basic functions. This method can be used to determine which countermeasure or set of countermeasures provides the most cost-efficient means to reduce crashes. The countermeasures or sets of countermeasures are ordered from the highest to lowest NPV. The method can also be used to evaluate if an individual project is economically justified.

Its first step is to estimate the number of crashes reduced due to the safety improvement project. The crash reduction is then converted to an annual monetary benefit. This annual monetary benefit is then converted to a present value. The present value of the costs associated with implementing the project is then calculated. These benefits and costs are then entered into Equation 2-5 to determine the NPV.

$$NPV = PV_{benefits} - PV_{costs} \tag{2-5}$$

where,   NPV = Net present value of the project

$PV_{benefits}$ = Present value of the project benefits

PV_{costs} = Present value of project costs

A project with a NPV greater than zero indicates a project with benefits that are sufficient enough to justify implementation of the countermeasure. A value less than zero indicates a project that does not produce enough benefits to justify implementation of the countermeasure.

There are strengths and weaknesses associated with the NPV analysis method. The strengths are that it evaluates the economic justification of a project, the NPV are ordered from highest to lowest, and it ranks the projects with the same rankings as produced by the incremental benefit-to-cost ratio method. One weakness of this method is that the magnitude cannot be easily interpreted as a benefit-cost ratio (BCR). This is because only the total monetary net benefit is calculated as opposed to comparing the benefits to costs. This method can help determine if a countermeasure is economically justified, but it does not necessarily determine which countermeasure would be the best.

After the NPV is calculated, a BCR can be calculated. A BCR is the ratio of the present-value benefits of a project to the implementation costs of the project. If the ratio is greater than 1.0, the project can be considered economically justified. After BCRs are calculated, countermeasures are then ranked from highest to lowest BCR. To calculate the BCR, the present value of the estimated change in average crash frequency and the present value of the costs associated with the safety improvement project need to be calculated. The BCR is calculated using Equation 2-6 (AASHTO 2010a).

$$BCR = \frac{PV_{benefits}}{PV_{costs}} \tag{2-6}$$

where, $\quad\quad\quad\quad$ BCR = Benefit-cost ratio

$\quad\quad\quad\quad$ $PV_{benefits}$ = Present value of the project benefits

$\quad\quad\quad\quad$ PV_{costs} = Present value of project costs

As stated previously, this method can only be used to determine the most valuable countermeasures for a specific site and can be used to evaluate economic justification of individual projects.

Another procedure to produce a cost-effectiveness analysis is to not convert the predicted change in average crash frequency into monetary values, but to compare them directly to project costs. The cost-effectiveness of a countermeasure implementation project is expressed as the annual cost per crash reduced. Both the project cost and the estimated average crash frequency reduced must apply to the same time period, either on an annual basis or over the entire life of the project. This method requires an estimate of the change in crashes and cost estimate

associated with implementing the countermeasure. It is used to gain a quantifiable understanding of the value of implementing an individual countermeasure or multiple countermeasures at an individual site when an agency does not support the monetary crash cost values used to convert a project's change in estimated average crash frequency reduction to a monetary value.

The first step in this cost-effectiveness analysis method is to estimate the change in expected average crash frequency due to the safety improvement project. The next step is to calculate the costs associated with implementing the project. The last step is to calculate the cost effectiveness of the safety improvement project at the site by dividing the present value of the costs by the estimated change in average crash frequency over the life of the countermeasure. This is shown in Equation 2-7.

$$Cost\ Effectiveness\ Index = \frac{PV_{costs}}{N_{predicted} - N_{observed}}$$ (2-7)

where, PV_{costs} = Present value of project costs

$N_{predicted}$ = Predicted crash frequency for year "y"

$N_{observed}$ = Observed crash frequency for year "y"

The strengths associated with this method are that it results in a simple and quick calculation that provides a general sense of an individual project's value. It produces a numeric value that can be compared to other safety improvement projects evaluated with the same method, and there is no need to convert the change in expected average crash frequency by severity to a monetary value. The weakness is that it does not differentiate between the value of reducing a fatal crash, injury crash, and a PDO crash.

2.5.5 Non-Monetary Considerations

While most cases will involve benefits being converted into monetary values and then comparing these values to the monetary costs, there are also cases where non-monetary considerations need to be taken into account. For example, many factors not directly related to changes in crash frequency enter into decisions about countermeasure implementation projects and many cannot be quantified in monetary terms. Examples of non-monetary considerations include: public demand, public perception and acceptance of safety improvement projects, meeting established and community-endorsed policies to improve mobility or accessibility along a corridor, road user needs, and others. For projects intended primarily to reduce crash frequency or severity, a benefit-cost analysis in monetary terms may serve as the primary decision-making tool, with secondary consideration of qualitative factors. The decision-making process on larger scale projects that do not focus only on change in crash frequency may be primarily qualitative or may be quantitative by applying weighting factors to specific decision criteria such as safety, traffic operations, air quality, noise, and others. While it is always easiest to determine the best alternative based on the monetary benefits, there are always other factors that should be taken into consideration (AASHTO 2010a).

2.6 UDOT Method

The current methods for performing a benefit-cost analysis at UDOT were explained to the BYU research team in an interview with Dallas Wall, an engineering consultant to UDOT. As explained in section 2.5.2, UDOT has a set of values that are used in calculating the monetary benefit for performing a specific type of crash. UDOT currently uses a model in which the CMF is multiplied by the number of crashes and then the reduction in crashes is determined. This reduction in the number of crashes is then used to calculate the monetary benefits based on the

crash costs explained previously. The benefits are then compared to the costs of implementing

the possible countermeasure, which becomes the basis for benefit-cost analysis.

The current UDOT model was found to follow the methods outlined in the HSM method

summarized in section 2.5. The model has entries for crash data to be used as the existing

average crash frequency. The crash data are generally observed crash data at the site from prior

years. The place where the existing crash data can be entered can be seen in Figure 2-1 (Wall

2016).

Figure 2-1: UDOT Safety Programs Benefit/Cost Worksheet Crash Data Entry (Wall 2016)

There are also entries for the various CMFs that are applicable to the various

countermeasures. The current UDOT model allows for the use of various countermeasures. The

model allows the user to enter the number of crashes that will be affected by each

countermeasure. These crashes are then multiplied by their respective CMFs to determine the reduction in crashes. This part of the spreadsheet can be seen in Figure 2-2.

Figure 2-2: UDOT Safety Programs Benefit/Cost Worksheet CMF and Crash Reduction (Wall 2016)

The reductions in crash frequency calculated using the UDOT model are then converted into annual monetary values by multiplying the reduced number of each crash type by the corresponding monetary benefit for each crash and then multiplying these monetary benefits by a conversion factor. The conversion factor used in this model is the conversion factor for a series of uniform annual amounts, which are brought to present value ($P_{A,i,y}$). This was shown previously in Equation 2-3. These annual monetary values are then converted into NPV using a default discount rate 3.0% and the expected service life of the project countermeasure. All of the benefits for each crash type are summed up and compared to the project costs. The benefits and

28

costs are then used to calculate a BCR using the same method as outlined in the HSM and explained in Section 2.5. The costs and discount rate as well as the resulting BCR section of the worksheet are shown in Figure 2-3.

Year (Project Construction)	2015	Crash Severity	Est. Red. of Crashes (Total)	Est. Annual Red. of Crashes	Average Cost per Crash (FHWA)*	Estimated Annual Cost Saving (Benefit)		B/C=	
Project Cost (exclude Right of Way)	$10,000,000.00	5			$ 1,961,100			Using present worth values:	
Right of Way Cost	$10,000.00	4			$ 1,961,100			Benefit = $	-
		3			$ 122,400			Cost = $	10,010,000
CAPITAL RECOVERY		2			$ 62,500				
Discount Rate	3.0%	1			$ 3,200				
Project Service Life (yrs)	25	Total	0.00	0.00		$ -			

Change only yellow-shaded boxes. Crash Modification Factors and Service Life values are from Utah Crash Modification Factors spreadsheet. Contact W. Scott Jones if you have questions.

UDOT Traffic and Safety

Severe Crashes Reduced (Ann.)

0.00

*Note: To keep results from updated yearly, break the link between this sheet and the KABCO sheet attached. OR change B6 on the AIS sheet to the current year.

Figure 2-3: UDOT Safety Programs Benefit/Cost Worksheet BCR (Wall 2016)

The method used for estimating the change in crash frequency for a project in this model most closely resembles the fourth method outline in section 2.5.1. This method also does not contain a method for determining the cost-effectiveness index.

2.7   Chapter Summary

As explained in the sections in this chapter, the most reliable method for estimating the change in average crash frequency is by using the Part C Predictive Method for determining the

existing crash data and the proposed crash data. The current model used by UDOT makes use of observed crash frequency for the existing crash data and uses CMFs to determine the proposed crash data. The UDOT method also does not give the option for using a conversion factor that converts non-uniform annual benefits to present value. It does not offer an option to create a cost-effectiveness index at the time when the method was evaluated.

The method to be created by the BYU research team will use method 1 in the HSM to determine the reduction in crashes for the proposed project by using the Part C Predictive Method for both the existing and proposed crash frequency. The BYU method will also make use of the UCPM and the Before and After model that have been developed and are currently being further improved by the BYU research team. It will use the UCPM to identify a list of "hot spot" segments that are in most need of safety improvements as well as possible countermeasures to improve the safety of those segments. This method will provide the UDOT engineers with another tool for determining the BCR for a project.

3   METHODOLOGY

This chapter presents the methodology used to complete the tasks to meet the objectives of the study. To perform a life-cycle benefit-cost analysis of a safety related improvement, three things need to be determined: the benefits associated with the improvement, the service life of the improvement, and the costs associated with the improvement including initial costs, right-of-way costs, rehabilitation costs, and maintenance costs. The service life is almost always a given value that is determined by the state agency for the improvement. The costs are also usually a case by case situation that is determined by the state agency. The research effort focused on the benefits and how they are calculated. This chapter will explain the method that the HSM prescribes as the most reliable method for determining benefits associated with a safety related improvement.

As explained in Chapter 2, each crash severity type has its own cost. The benefit is determined by multiplying the cost of each crash severity type by the crash reduction associated with that severity type and then summing all of those benefits together. This is a standard practice for most state agencies. The difference comes in how the reduction in crashes is calculated. As explained in chapter 2, the HSM prescribes that the Part C Predictive Method be used to determine the change in average crash frequency. The first section of this chapter explains the Part C Predictive Method and how it works, followed by a section that explains the steps associated with a life-cycle benefit-cost analysis of any kind.

3.1 Part C Predictive Method

The Part C Predictive Method presented in the HSM provides a quantitative measure of expected crash frequency under both existing conditions and conditions which have not yet occurred. It is applied to a given time period, traffic volume, and constant geometric design characteristics of the roadway, and consists of an 18-step procedure to estimate the "expected average crash frequency" of a roadway network, facility, or site. The 18-step procedure is as follows (AASHTO 2010b):

1. Define roadway limits and facility type

2. Define the period of study

3. Determine AADT and availability of crash data for every year in the period of interest

4. Determine geometric conditions

5. Divide the roadway into individual roadway segments and intersections

6. Assign observed crashes to individual sites (if applicable)

7. Select a roadway segment or intersection

8. Select first or next year of the evaluation period

9. Select and apply SPF

10. Apply CMFs

11. Apply a calibration factor

12. Is there another year?

    a. If yes, return to Step 8

    b. If no, go to Step 13

13. Apply site-specific Empirical Bayes (EB) method (if applicable)

14. Is there another site?

    a. If yes, return to Step 7

    b. If no, go to Step 15

15. Apply project-level EB method (if applicable)

16. Sum all sites and years

17. Is there an alternative design, treatment, or forecast AADT to be evaluated?

    a. If yes, return to Step 3

    b. If no, go to Step 18

18. Compare and evaluate results

There are two primary equations associated with the Part C Predictive Method. Equation 3-1 summarizes the calculation associated with determining the number of predicted crashes. The SPF is determined based on AADT, segment length, and regression constants associated with the roadway type. The CMFs are determined based on the specific roadway characteristics such as number of lanes, lane width, shoulder width, and other factors. The calibration factor is determined based on the specific location of the roadway segment.

$$N_{Predicted} = N_{spf} * \left(CMF_{1x} * CMF_{2x} * \dots * CMF_{yz} \right) * C_x \qquad \text{(3-1)}$$

where, $N_{predicted}$ = Predicted average crash frequency for a specific site type x;

        $N_{spf\,x}$ = Predicted average crash frequency determined for base conditions of the SPF developed for site type x:

        CMF_{yx} = Crash modification factors specific to SPF for site type x;

        C_x = Calibration factor to adjust SPF for local conditions for site type x.

Equation 3-2 uses the EB method to combine the results from Equation 3-1 with the observed crash frequency. An over-dispersion parameter, k, is used to balance the observed crash frequency with the predicted crash frequency from Equation 3-1.

$$N_{expeteced} = [1/(1+k* N_{predicted})]*N_{predicted} + \{1.00 - [1/(1+k* N_{predicted})]\}*N_{observed} \qquad (3-2)$$

where, $N_{expeteced}$ = Estimate of expected crash frequency for the study period

$N_{predicted}$ = Predicted model estimate of predicted average crash frequency for the study period

$N_{observed}$ = Observed crash frequency at the site over the study period

k = Over-dispersion parameter from the associated SPF

This process is performed for the existing conditions and for the proposed conditions. The result from this process is the expected number of crashes per year. The change in crash frequency is determined by subtracting the expected number of crashes for each year with the improvement from the expected number of crashes for each year if the improvement had not been determined. After the total change in average crash frequency is obtained, it is then multiplied by a distribution to determine the predicted number of crashes of each crash type that is reduced. A default distribution or a calibrated distribution based on the site location can be used. The number of reduced crashes for each crash severity type is then multiplied by the crash cost. As explained in previous sections, these crash costs may be the costs determined by the FHWA or may be costs determined by the state agency. All of these are summed up to determine the amount of safety benefit for each year. Since each year has its own benefit, the value of that benefit changes each year, which requires the benefits and costs to be all brought back to the

present year. The fundamentals of life-cycle benefit-cost analyses are presented in the next section.

3.2 Life-Cycle Benefit-Cost Analysis Fundamentals

One important aspect of life-cycle benefit-cost analysis is to determine the benefits and costs associated with an improvement for each year of the service life. For example, if an improvement has a service life of 20 years, the entire period of 20 years must be analyzed. The benefit produced each year was described in section 2.5. The benefit that was calculated based on the procedure is the future value of that benefit in that particular year. Each year's benefit needs to be discounted to the present year. This benefit needs to be multiplied by a factor that will convert this future value to present value. This factor is calculated using Equation 2-4 in chapter 2. After all of these benefits are brought back to the present value, they are all summed up to determine the total safety benefit associated with the improvement. After the total benefit is determined, the total cost of the improvement needs to be determined (Saito 1988).

Each countermeasure has its own costs that generally includes an initial cost, as well as possible periodic rehabilitation or reconstruction costs and annual maintenance costs. Since the initial cost occurs in the present year, it does not need to be brought to present value. Since the rehabilitation or reconstruction costs and annual maintenance costs occur in future years, these need to be brought back to the present year. Similar to the benefits, the costs are multiplied by the factor determined from Equation 2-4 to bring them back to present value. After all of the crash costs are brought back to present value, they are summed to determine the total cost of the improvement over the entire service life.

Once both the total present value benefit and total present value costs have been determined, a benefit-cost analysis can be performed. Section 2.5 presented three different ways

to perform this analysis. All of these methods are acceptable according to the HSM. UDOT

currently uses a BCR as their primary method. Since using a BCR is the current UDOT method

and since it is accepted by the HSM, it is the method used in this research. A BCR is determined

by dividing the total present value benefit by the total present value cost, as outlined previously

in Equation 2-6. A BCR is determined for each improvement that is being considered for a site

under evaluation, and usually an improvement with the highest BCR is selected.

3.3   Chapter Summary

The Part C Predictive Method is the primary method that was adopted to determine the

change in annual crash frequency for this research, which is an 18-step procedure that is used to

predict the expected crash frequency for a roadway segment. All benefit values and cost values

are discounted to the present year so that a BCR can be calculated. The equations presented in

chapter 2 are the equations that were used to discount the benefits and costs to the present value.

The next chapter explains how the methodology presented in chapter 3 was developed

into an Excel spreadsheet. Excel macros and Visual Basic for Applications (VBA) were used to

incorporate the methodology explained in this chapter into an Excel spreadsheet so that it would

be simple and easy to understand for UDOT safety engineers.

4   CONCEPT AND SPREADSHEET DEVELOPMENT

This chapter, describes the layout of the spreadsheet program, explains how the spreadsheet program was developed, and explains how the HSM method for performing a life-cycle benefit-cost analysis of safety related improvements was incorporated into an Excel-based spreadsheet program. The rural TLTW highway spreadsheet is used as an example to describe how the spreadsheet performs the analysis.

4.1   Layout of Spreadsheet Program

As explained in earlier chapters, spreadsheet programs were developed for 11 roadway types. Three of these roadway types were rural highways, five of these roadways types were suburban and urban arterials, and the other three roadway types are freeway types. Though each of these roadway types are different, the spreadsheet was developed to have the same look and layout for each of these roadway types. This section explains the basic layout of the spreadsheet program using the rural TLTW highway as an example. Each roadway type has its own workbook, and each workbook has six worksheets. Two of the worksheets are worksheets that the user enters necessary information. The other four worksheets are output reports that can be printed separately as needed. The following subsections explain each of the six worksheets.

4.1.1 Basic Information Worksheet

The first worksheet that the analyst sees is the Basic Information worksheet. An example of this worksheet from the rural TLTW highway workbook is shown in Figure 4-1.

Analyst	John Smith	Date	5/18/2016	Company	BYU
Route	US-89	Direction	Positive	Jurisdiction	Region 4
MP Begin	267.346	MP End	276.21		
Crash Study Begin	1/1/2010	Crash Study End	2/29/2016		

Crash Severity Data	
5 (K)	0
4 (A)	2
3 (B)	12
2 (C)	15
1 (O)	77

Growth Rate on AADT (Default is 0.5%)	1.0%

Figure 4-1: Basic Information Worksheet Example

As is shown in Figure 4-1, there are boxes that are green, blue, or yellow. The green and blue boxes are labels, while the yellow boxes are the places where the user can enter needed information. This worksheet was meant to be a place for users to enter basic information such as the name of the analyst, the date, company, route name, direction, jurisdiction, the beginning of the segment, end of the segment, the crash data, and growth rate to be used on the AADTs of future years. In this rural TLTW highway worksheet, all crashes, whether they be multiple vehicle or single vehicle are entered as total crashes for each crash severity level. The HSM Part C Predictive Method does not have different SPFs for different crash types for rural TLTW highways. There are some roadway types that do have different SPFs for different crash severity levels, and so the crash data section is different depending on the roadway type that is being

considered. Some of the information from the basic information worksheet is used for analysis in the Analysis worksheet, which is explained in the next section.

4.1.2 Analysis Worksheet

This section explains the other worksheet in the workbook that users enter information to perform the analysis. The Analysis worksheet is the worksheet where users enter the roadway characteristics of the segment that is being analyzed. Existing conditions are first entered, and then the future or proposed conditions. An example of this part of the Analysis worksheet is shown in Figure 4-2.

Similar to the Basic Information worksheet, the yellow boxes are where the analyst enters information. The white boxes denote places where the value is calculated based on other entries. As can be seen in Figure 4-2, there are numerous inputs that the analyst needs to enter. The next chapter explains how the analyst can use outputs from the UCPM to obtain the roadway characteristics data needed for the inputs in Figure 4-2. As can be seen in Figure 4-2, the last input data is the calibration factor. As explained in Chapter 3, the calibration factor is used to adjust the results of SPFs in the HSM. The CMFs that are used for the analysis can be seen in Figure 4-3. As explained in Chapter 3, the Part C Predictive Method uses SPFs, calibration factors, and CMFs to calculate the predicted number of crashes. Figure 4-3 displays the CMFs that are used for the rural TLTW highway analysis. Similar to the other parts of this workbook, the white boxes denote where the spreadsheet calculates the value. The yellow boxes denote where the analyst needs to enter information. All of the CMFs that have the white boxes are CMFs that are calculated based on the information entered by the analyst in the roadway characteristics section of the worksheet.

Roadway Segment Characteristics				
Existing Conditions			Future Conditions	
AADT	3000	AADT	3661
Lane Width (ft.)	12	Lane Width (ft.)	12
Shoulder Width (ft.)	5	Shoulder Width (ft.)	5
Shoulder Type	Paved ▾	Shoulder Type	Paved ▾
Length of roadway segment (miles)	8.864	Length of roadway segment (miles)	8.864
Length of Horizontal Curve (miles)	0.0898	Length of Horizontal Curve (miles)	0.0898
Radius of Curvature (feet)	5333	Radius of Curvature (feet)	5333
Spiral Transition Curve (1 if yes, 0 if no, 0.5 if present at only one end)	0	Spiral Transition Curve (1 if yes, 0 if no, 0.5 if present at only one end)	0
Supereelvation (ft/ft)	0	Supereelvation (ft/ft)	0
Grade (%)	-4.41	Grade (%)	-4.41
Driveway Density (driveways/mile)	0	Driveway Density (driveways/mile)	0
Presence of Rumble Strips (1 if yes, 0 if no)	1	Presence of Rumble Strips (1 if yes, 0 if no)	1
Presence of Passing Lanes (2 for Passing Lanes in both directions, 1 for Passing Lanes in one direction, 0 for no passing lanes)	0	Presence of Passing Lanes (2 for Passing Lanes in both directions, 1 for Passing Lanes in one direction, 0 for no passing lanes)	1
Roadside Hazard Rating (1-7) Use Appendix from Chapter 13 of HSM, base conditions is 3	3	Roadside Hazard Rating (1-7) Use Appendix from Chapter 13 of HSM, base conditions is 3	3
Proportion of Total Nighttime Fatal or Injury Crashes (use 0.382 for default)	0.382	Proportion of Total Nighttime Fatal or Injury Crashes (use 0.382 for default)	0.382
Proportion of Total Nighttime PDO crashes (use 0.618 for default)	0.618	Proportion of Total Nighttime PDO crashes (use 0.618 for default)	0.618
Proportion of total crashes for unlighted roadway segments that occur at night (use 0.370 for default)	0.37	Proportion of total crashes for unlighted roadway segments that occur at night (use 0.370 for default)	0.37
Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0	Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0
Calibration Factor (site specific, Use 1.00 for Default)	1	Calibration Factor (site specific, Use 1.00 for Default)	1

Figure 4-2: Inputs of Example Analysis Worksheet

Figure 4-4 displays the average observed crash frequency and Figure 4-5 displays the crash severity distribution used for the analysis. The observed crash frequency displayed in the column with the white background in Figure 4-4 is calculated from the Basic Information worksheet. Figure 4-4 shows a drop-down menu, which allows the user to choose the analysis method. The crash distribution displayed in Figure 4-5 is calculated based on this drop-down menu shown in Figure 4-4. The information that is used for the calculation of the predicted crashes can be seen in Figure 4-6.

Crash Modification Factors			
Existing Conditions		Future Conditions	
CMF_{RA}	1.00	CMF_{RA}	1.00
CMF_{WRA}	1.15	CMF_{WRA}	1.15
CMF_{TRA}	1.00	CMF_{TRA}	1.00
CMF_{1r}	1.00	CMF_{1r}	1.00
CMF_{2r}	1.09	CMF_{2r}	1.09
CMF_{3r}	1.11	CMF_{3r}	1.11
CMF_{4r}	1.00	CMF_{4r}	1.00
CMF_{5r}	1.00	CMF_{5r}	1.00
CMF_{6r}	1.00	CMF_{6r}	1.00
CMF_{7r}	0.94	CMF_{7r}	0.94
CMF_{8r}	1.00	CMF_{8r}	0.75
CMF_{9r}	1.00	CMF_{9r}	1.00
CMF_{10r}	1.00	CMF_{10r}	1.00
CMF_{11r}	0.92	CMF_{11r}	0.92
CMF_{12r}	1.00	CMF_{12r}	1.00
Project Specific			
CMF_1	1.00	CMF_4	1.00
CMF_2	1.00	CMF_5	1.00
CMF_3	1.00	CMF_6	1.00

Figure 4-3: CMF Portion of Example Analysis Worksheet

Observed Crash Severity Frequency		
Fatal	5 (K)	0.0
Injury	4 (A)	0.3
	3 (B)	1.9
	2 (C)	2.4
PDO	1 (O)	12.5
	Total	17.2
Default Distribution		

Figure 4-4: Observed Crash Frequency of Example Analysis Worksheet

Crash Severity Distribution	
Fatal	1.3%
Incapacitating Injury	5.4%
Nonincapacitating Injury	10.9%
Possible Injury	14.5%
Property Damage Only	67.9%
Total	100.0%

Figure 4-5: Crash Distribution of Example Analysis Worksheet

Observed Crashes		Predicted Crashes	
k	0.027	k	0.027
w	0.8060	w	0.8471
N_{spfrs}	8.7	N_{spfrs}	8.7
$N_{predicted\ rs}$	9.04	$N_{predicted\ rs}$	6.78
Part C Predictive Method ▼			
Total Number of Crashes	9.0	Total Number ofCrashes	6.8

Figure 4-6: SPF Information of Example Analysis Worksheet

N_{spfrs}, or the number of crashes predicted by the SPF, refers to the value produced from the SPF. $N_{predicted\ rs}$ refers to the number of predicted crashes calculated by multiplying the SPF by the calibration factors and CMFs. The drop-down menu in Figure 4-6 allows the user to choose either the Part C Predictive Method or the EB method. The total number of crashes is determined based on which option the analyst chooses in the drop down menu. The benefits based on the crash costs can be seen in Figure 4-7.

	UDOT Recommended ▼		
Crash Severity		**Estimated Reduction in Crashes**	**Crash Severity Value (Use Options Above)**	**Estimated Safety Benefit**
5 (K)	Fatal	0.5	$ 1,982,000.00	$ 781,612.18
4 (A)	Incapacitating Injury	2.2	$ 1,982,000.00	$ 3,246,696.75
3 (B)	Nonincapacitating Injury	4.5	$ 123,700.00	$ 409,016.20
2 (C)	Possible Injury	6.0	$ 63,200.00	$ 277,990.14
1 (O)	Property Damage Only	28.0	$ 3,200.00	$ 65,911.94
Total		41.2		$ 4,781,227.21

Figure 4-7: Crash Benefits and Costs of Example Analysis Worksheet

The portion of the worksheet shown in Figure 4-7 is where the analyst can see the

number of crashes that have been reduced for each crash severity level. The crash type value can

also be seen in this section. This worksheet has three different options for determining the crash

costs associated with the crash severity level. The three choices can be chosen from the drop-

down menu shown in Figure 4-7 including: FHWA Recommended costs and UDOT

Recommended costs. An explanation of these different crash costs for different severity levels

can be found in Section 2.5 of this thesis. The estimated safety benefit is determined by

multiplying the number of reduced crashes by the crash severity level. The information regarding

the improvement costs can be found in Figure 4-8. The information used in Figure 4-8 is then

used in the BCR calculator, which can be seen in Figure 4-9. As explained in Chapter 3, the BCR

is the criterion used for the analysis in this spreadsheet program. The BCR is calculated by

dividing the present worth benefits by the present worth costs. As can be seen in Figure 4-9, the

benefits and costs need to be in present worth. This part of the analysis is shown in Figure 4-10,

which displays the buttons for two choices. The "Calculate Benefit/Cost Ratio" button performs

all of the life-cycle cost-benefit analysis for the safety related improvement. Pressing this button

allows the user to calculate all CMFs, generates all of the present value benefit and cost

calculations, and grows the AADT each year based on the growth rate the analyst entered in the

Basic Information worksheet.

Initial Project Cost	$	1,000,000.00
Rehabilitation Cycle Cost	$	500,000.00
Number of Years For Each Rehabilitation		5
Annual Maintenance	$	20,000.00
Discount Rate		3%
Service Life (years)		20
Number of Maintenance Periods		4
Total Maintenance Costs Present Value	$	1,421,831.82
Total Cost	$	2,421,831.82

Figure 4-8: Improvement Costs of Example Analysis Worksheet

B/C=	1.97
Using present worth values:	
Benefit =	**$ 4,781,227**
Cost =	**$ 2,421,832**

Figure 4-9: BCR of Example Analysis Worksheet

Calculate Benefit/Cost Ratio

Print BCR Report
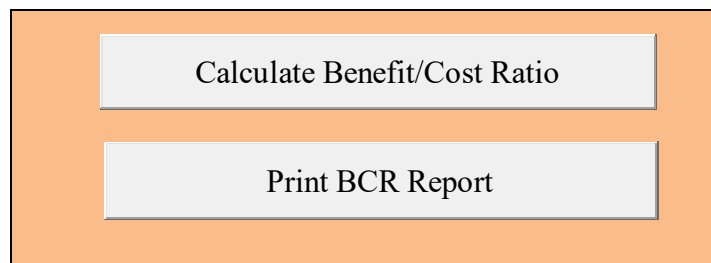
Figure 4-10: VBA Buttons Used to Perform Analysis and Print Reports

44

Rural Two-Lane Two-Way Highway

Roadway Segment Characteristics

Existing Conditions		Future Conditions	
AADT	3000	AADT	3661
Lane Width (ft.)	12	Lane Width (ft.)	12
Shoulder Width (ft.)	5	Shoulder Width (ft.)	5
Shoulder Type	Paved ▾	Shoulder Type	Paved ▾
Length of roadway segment (miles)	8.864	Length of roadway segment (miles)	8.864
Length of Horizontal Curve (miles)	0.0898	Length of Horizontal Curve (miles)	0.0898
Radius of Curvature (feet)	5333	Radius of Curvature (feet)	5333
Spiral Transition Curve (1 if yes, 0 if no, 0.5 if present at only one end)	0	Spiral Transition Curve (1 if yes, 0 if no, 0.5 if present at only one end)	0
Supereelvation (ft/ft)	0	Supereelvation (ft/ft)	0
Grade (%)	-4.41	Grade (%)	-4.41
Driveway Density (driveways/mile)	0	Driveway Density (driveways/mile)	0
Presence of Rumble Strips (1 if yes, 0 if no)	1	Presence of Rumble Strips (1 if yes, 0 if no)	1
Presence of Passing Lanes (2 for Passing Lanes in both directions, 1 for Passing Lanes in one direction, 0 for no passing lanes)	0	Presence of Passing Lanes (2 for Passing Lanes in both directions, 1 for Passing Lanes in one direction, 0 for no passing lanes)	1
Roadside Hazard Rating (1-7) Use Appendix from Chapter 13 of HSM, base conditions is 3	3	Roadside Hazard Rating (1-7) Use Appendix from Chapter 13 of HSM, base conditions is 3	3
Proportion of Total Nighttime Fatal or Injury Crashes (use 0.382 for default)	0.382	Proportion of Total Nighttime Fatal or Injury Crashes (use 0.382 for default)	0.382
Proportion of Total Nighttime PDO crashes (use 0.618 for default)	0.618	Proportion of Total Nighttime PDO crashes (use 0.618 for default)	0.618
Proportion of total crashes for unlighted roadway segments that occur at night (use 0.370 for default)	0.37	Proportion of total crashes for unlighted roadway segments that occur at night (use 0.370 for default)	0.37
Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0	Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0
Calibration Factor (site specific, Use 1.00 for Default)	1	Calibration Factor (site specific, Use 1.00 for Default)	1

Crash Modification Factors

Existing Conditions		Future Conditions	
CMF_{RA}	1.00	CMF_{RA}	1.00
CMF_{WRA}	1.15	CMF_{WRA}	1.15
CMF_{TRA}	1.00	CMF_{TRA}	1.00
CMF_{1r}	1.00	CMF_{1r}	1.00
CMF_{2r}	1.09	CMF_{2r}	1.09
CMF_{3r}	1.11	CMF_{3r}	1.11
CMF_{4r}	1.00	CMF_{4r}	1.00
CMF_{5r}	1.00	CMF_{5r}	1.00
CMF_{6r}	1.00	CMF_{6r}	1.00
CMF_{7r}	0.94	CMF_{7r}	0.94
CMF_{8r}	1.00	CMF_{8r}	0.75
CMF_{9r}	1.00	CMF_{9r}	1.00
CMF_{10r}	1.00	CMF_{10r}	1.00
CMF_{11r}	0.92	CMF_{11r}	0.92
CMF_{12r}	1.00	CMF_{12r}	1.00

Project Specific

CMF_1	1.00	CMF_4	1.00
CMF_2	1.00	CMF_5	1.00
CMF_3	1.00	CMF_6	1.00

Observed Crash Severity Frequency

Fatal	5 (K)	0.0
Injury	4 (A)	0.3
	3 (B)	1.9
	2 (C)	2.4
PDO	1 (O)	12.5
	Total	17.2

Default Distribution ▾

Crash Severity Distribution

Fatal	1.3%
Incapacitating Injury	5.4%
Nonincapacitating Injury	10.9%
Possible Injury	14.5%
Property Damage Only	67.9%
Total	100.0%

Observed Crashes		Predicted Crashes	
k	0.027	k	0.027
w	0.8060	w	0.8471
N_{spfrs}	8.7	N_{spfrs}	8.7
$N_{predicted\ rs}$	9.04	$N_{predicted\ rs}$	6.78

Part C Predictive Method ▾

Total Number of Crashes	9.0	Total Number of Crashes	6.8

UDOT Recommended ▾

Crash Severity		Estimated Reduction in Crashes	Crash Severity Value (Use Options Above)	Estimated Safety Benefit
5 (K)	Fatal	0.5	$ 1,982,000.00	$ 781,612.18
4 (A)	Incapacitating Injury	2.2	$ 1,982,000.00	$ 3,246,696.75
3 (B)	Nonincapacitating Injury	4.5	$ 123,700.00	$ 409,016.20
2 (C)	Possible Injury	6.0	$ 63,200.00	$ 277,990.14
1 (O)	Property Damage Only	28.0	$ 3,200.00	$ 65,911.94
	Total	41.2		$ 4,781,227.21

Initial Project Cost	$ 1,000,000.00
Rehabilitation Cycle Cost	$ 500,000.00
Number of Years For Each Rehabilitation	5
Annual Maintenance	$ 20,000.00
Discount Rate	3%
Service Life (years)	20
Number of Maintenance Periods	4
Total Maintenance Costs Present Value	$ 1,421,831.82
Total Costs	$ 2,421,831.82

Calculate Benefit/Cost Ratio

Print BCR Report

B/C=	1.97
Using present worth values:	
Benefit =	$ 4,781,227
Cost =	$ 2,421,832

Figure 4-11: Example Analysis Worksheet

4.1.3 Output Worksheets

This section presents the layouts of the four output report worksheets, which are the following:

- Basic Output

- CMF and SPF Reports

- Benefit Table

- Cost Table

Figure 4-12 displays the basic output worksheet. This worksheet takes the roadway segment characteristics, the crash benefits, the costs, and the BCR. It is meant to be the basic output that the user would want. Figure 4-13 shows the CMFs and SPF values, observed crash frequency, and the crash distribution used for the analysis. Figure 4-14 displays the present values of all of the benefits for each year of the service life. A service life of 20 years was used as an example in this analysis. Figure 4-15 displays the present values of the maintenance and rehabilitation costs for each year. Since a service life of 20 years was used, each year of the service life needed to be brought back to the present year. The results of the calculations for each year of the service life for the benefits can be seen in Figure 4-14, and the results of the calculations for each year of the service life for the maintenance and rehabilitation costs can be seen in Figure 4-15.

Roadway Segment Characteristics			
Existing Conditions		**Future Conditions**	
AADT	3000	AADT (Assuming 0.5% Growth Rate)	3661
Lane Width (ft)	12	Lane Width (ft)	12
Shoulder Width (ft)	5	Shoulder Width (ft)	5
Shoulder Type	Paved	Shoulder Type	Paved
Length of roadway segment (miles)	8.864	Length of roadway segment (miles)	8.864
Length of Horizontal Curve (miles)	0.0898	Length of Horizontal Curve (miles)	0.0898
Radius of Curvature (feet)	5333	Radius of Curvature (feet)	5333
Spiral Transition Curve (1 if yes, 0 if no, 0.5 if present at only one end)	0	Spiral Transition Curve (1 if yes, 0 if no, 0.5 if present at only one end)	0
Supereelevation (ft/ft)	0	Supereelevation (ft/ft)	0
Grade (%)	-4.41	Grade (%)	-4.41
Driveway Density (driveways/mile)	0	Driveway Density (driveways/mile)	0
Presence of Rumble Strips (1 if yes, 0 if no)	1	Presence of Rumble Strips (1 if yes, 0 if no)	1
Presence of Passing Lanes (2 for Passing Lanes in both directions, 1 for Passing Lanes in one direction, 0 for no passing lanes)	0	Presence of Passing Lanes (2 for Passing Lanes in both directions, 1 for Passing Lanes in one direction, 0 for no passing lanes)	1
Roadside Hazard Rating (1-7) Use Appendix from Chapter 13 of HSM, base conditions is 3	3	Roadside Hazard Rating (1-7) Use Appendix from Chapter 13 of HSM, base conditions is 3	3
Proportion of Total Nighttime Fatal or Injury Crashes (use 0.382 for default)	0.382	Proportion of Total Nighttime Fatal or Injury Crashes (use 0.382 for default)	0.382
Proportion of Total Nighttime PDO crashes (use 0.618 for default)	0.618	Proportion of Total Nighttime PDO crashes (use 0.618 for default)	0.618
Proportion of total crashes for unlighted roadway segments that occur at night (use 0.370 for default)	0.37	Proportion of total crashes for unlighted roadway segments that occur at night (use 0.370 for default)	0.37
Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0	Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0
Calibration Factor (site specific, Use 1.00 for Default)	1	Calibration Factor (site specific, Use 1.00 for Default)	1

	Crash Severity	Estimated Reduction in Crashes	Crash Severity Value (Use Options Above)	Estimated Safety Benefit
5 (K)	Fatal	0.5	$ 1,982,000.00	$ 781,612.18
4 (A)	Incapacitating Injury	2.2	$ 1,982,000.00	$ 3,246,696.75
3 (B)	Nonincapacitating Injury	4.5	$ 123,700.00	$ 409,016.20
2 (C)	Possible Injury	6.0	$ 63,200.00	$ 277,990.14
1 (O)	Property Damage Only	28.0	$ 3,200.00	$ 65,911.94
	Total	41.2		$ 4,781,227.21

Initial Project Cost	$ 1,000,000.00	**B/C=**	**1.97**
Maintenance Cost Per Period	$ 500,000.00	Using present worth values:	
Number of Years For Each Maintenance	5	**Benefit =**	**$ 4,781,227**
Annual Maintenance	$ 20,000.00	**Cost =**	**$ 2,421,832**
Discount Rate	3%		
Service Life (years)	20		
Number of Maintenance Periods	4		
Total Maintenance Costs Present Value	$ 1,421,831.82		
Total Costs	$ 2,421,831.82		

Figure 4-12: Basic Output

Figure 4-13: CMF and SPF Reports

Crash Modification Factors				Observed Crash Frequency		
Existing Conditions		Future Conditions		Fatal	5 (K)	0.00
CMF_{RA}	1.00	CMF_{RA}	1.00	Injury	4 (A)	0.32
CMF_{WRA}	1.15	CMF_{WRA}	1.15		3 (B)	1.95
CMF_{TRA}	1.00	CMF_{TRA}	1.00		2 (C)	2.43
CMF_{1r}	1.00	CMF_{1r}	1.00	PDO	1 (O)	12.49
CMF_{2r}	1.09	CMF_{2r}	1.09		Total	17.20
CMF_{3r}	1.11	CMF_{3r}	1.11	Default Distribution		
CMF_{4r}	1.00	CMF_{4r}	1.00	Crash Distribution		
CMF_{5r}	1.00	CMF_{5r}	1.00	Fatal		1%
CMF_{6r}	1.00	CMF_{6r}	1.00	Incapacitating Injury		5%
CMF_{7r}	0.94	CMF_{7r}	0.94	Nonincapacitating Injury		11%
CMF_{8r}	1.00	CMF_{8r}	0.75	Possible Injury		15%
CMF_{9r}	1.00	CMF_{9r}	1.00	Property Damage Only		68%
CMF_{10r}	1.00	CMF_{10r}	1.00	Total		100%
CMF_{11r}	0.92	CMF_{11r}	0.92	Existing Crashes		Future Crashes
CMF_{12r}	1.00	CMF_{12r}	1.00	k	0.027	k	0.027
Project Specific				w	0.806	w	0.847
CMF_1	1	CMF_4	1	N_{spfrs}	8.669	N_{spfrs}	8.669
CMF_2	1	CMF_5	1	$N_{predicted\ rs}$	9.037	$N_{predicted\ rs}$	6.778
CMF_3	1	CMF_6	1	Predictive Method		
				Total Crashes	9.0	Total Crashes	6.8

Figure 4-13: CMF and SPF Reports

Year	AADT	Crashes Reduced	Fatal Benefit	Incapacitating injury Benefit	Nonincapacitating Injury Benefit	Possible Injury Benefits	PDO Benefit	Total Benefits
1	3030	1.870218988	$ 46,784.53	$ 194,335.73	$ 24,482.26	$ 16,639.50	$ 3,945.25	$ 286,187.26
2	3060.3	1.888921178	$ 45,876.09	$ 190,562.22	$ 24,006.87	$ 16,316.40	$ 3,868.65	$ 280,630.23
3	3090.903	1.90781039	$ 44,985.29	$ 186,861.98	$ 23,540.72	$ 15,999.58	$ 3,793.53	$ 275,181.10
4	3121.81203	1.926888494	$ 44,111.79	$ 183,233.59	$ 23,083.62	$ 15,688.91	$ 3,719.87	$ 269,837.78
5	3153.03015	1.946157379	$ 43,255.25	$ 179,675.66	$ 22,635.39	$ 15,384.27	$ 3,647.64	$ 264,598.21
6	3184.560452	1.965618953	$ 42,415.34	$ 176,186.81	$ 22,195.87	$ 15,085.55	$ 3,576.81	$ 259,460.38
7	3216.406056	1.985275142	$ 41,591.74	$ 172,765.71	$ 21,764.88	$ 14,792.62	$ 3,507.36	$ 254,422.31
8	3248.570117	2.005127894	$ 40,784.14	$ 169,411.03	$ 21,342.26	$ 14,505.39	$ 3,439.25	$ 249,482.07
9	3281.055818	2.025179173	$ 39,992.21	$ 166,121.50	$ 20,927.85	$ 14,223.73	$ 3,372.47	$ 244,637.76
10	3313.866376	2.045430964	$ 39,215.66	$ 162,895.84	$ 20,521.48	$ 13,947.54	$ 3,306.99	$ 239,887.51
11	3347.00504	2.065885274	$ 38,454.20	$ 159,732.81	$ 20,123.01	$ 13,676.72	$ 3,242.77	$ 235,229.51
12	3380.47509	2.086544127	$ 37,707.51	$ 156,631.20	$ 19,732.27	$ 13,411.15	$ 3,179.81	$ 230,661.94
13	3414.279841	2.107409568	$ 36,975.33	$ 153,589.82	$ 19,349.12	$ 13,150.74	$ 3,118.06	$ 226,183.07
14	3448.42264	2.128483664	$ 36,257.36	$ 150,607.50	$ 18,973.41	$ 12,895.38	$ 3,057.52	$ 221,791.16
15	3482.906866	2.1497685	$ 35,553.33	$ 147,683.08	$ 18,604.99	$ 12,644.99	$ 2,998.15	$ 217,484.54
16	3517.735935	2.171266185	$ 34,862.98	$ 144,815.45	$ 18,243.73	$ 12,399.45	$ 2,939.93	$ 213,261.54
17	3552.913294	2.192978847	$ 34,186.03	$ 142,003.49	$ 17,889.48	$ 12,158.69	$ 2,882.85	$ 209,120.54
18	3588.442427	2.214908636	$ 33,522.22	$ 139,246.15	$ 17,542.12	$ 11,922.60	$ 2,826.87	$ 205,059.95
19	3624.326851	2.237057722	$ 32,871.30	$ 136,542.34	$ 17,201.49	$ 11,691.09	$ 2,771.98	$ 201,078.20
20	3660.57012	2.259428299	$ 32,233.03	$ 133,891.03	$ 16,867.48	$ 11,464.08	$ 2,718.15	$ 197,173.77
Total		41.18035938	$ 781,635.33	$ 3,246,792.92	$ 409,028.32	$ 277,998.38	$ 65,913.89	$ 4,781,368.83

Figure 4-14: Benefit Table

Year	Period	Present Value Rehabilitation/ Reconstruction Cost	Annual Maintenance Cost
1			$ 19,417.48
2			$ 18,851.92
3			$ 18,302.83
4			$ 17,769.74
5	1	$ 431,304.39	$ 17,252.18
6			$ 16,749.69
7			$ 16,261.83
8			$ 15,788.18
9			$ 15,328.33
10	2	$ 372,046.96	$ 14,881.88
11			$ 14,448.43
12			$ 14,027.60
13			$ 13,619.03
14			$ 13,222.36
15	3	$ 320,930.97	$ 12,837.24
16			$ 12,463.34
17			$ 12,100.33
18			$ 11,747.89
19			$ 11,405.72
20			$ 11,073.52
Total		$ 1,124,282.32	$ 297,549.50

Figure 4-15: Cost Table

4.2   Spreadsheet Development in Excel

This section explains how the Part C Predictive Method was developed into an Excel-based spreadsheet program. As explained in Chapter 3, the HSM's Part C Predictive Method has 18 steps (AASHTO 2010b). The HSM lists four different methods for determining the change in crash frequency in order of reliability. Currently, UDOT uses the fourth reliable method (Method 4). The goal of this research was to develop a tool that the most reliable method mentioned in the HSM could be used to perform life-cycle benefit-cost analyses (Method 1). A spreadsheet program was built that performs the Part C Predictive Method for 11 different roadway segment types. Intersections were not included in this spreadsheet program as they are not included in the UCPM or the UCSM at the time of this research. The methodology for analysis was set up to become part of the use of the models in selecting countermeasures. The concept and spreadsheet layout are discussed in section 4.1 using the rural TLTW highway spreadsheet as an example. One important aspect associated with life-cycle benefit-cost analysis of safety related improvements is the cost of countermeasures. This spreadsheet program, however, does not include a module to estimate costs associated with a countermeasure to be selected because such costs vary significantly depending on the way countermeasures have been implemented. At the time of this study, no systematic way to estimate such costs are available. The engineer should seek guidance from the cost estimate expert within the agency when determining the project costs.

The first eight steps of the Part C Predictive Method (see section 3.1) are comprised of gathering all of the needed data including the roadway characteristics, crash data, AADT, and defining the crash study period. The crash study period and crash data are entered in the Basic Information worksheet. The AADT and roadway segment characteristics are entered in the

Analysis worksheet. Steps 9 through 12 have to do with applying appropriate SPFs, CMFs, and calibration factors. The CMFs are calculated in the spreadsheet using the roadway segment characteristics. Each CMF is calculated using VBA when the "Calculate Benefit/Cost Ratio" button is selected. The SPFs are calculated using the AADT data and the segment length. The calibration factor is meant to calibrate the expected crash frequency to local conditions. The calibration factor is one of the inputs that the analyst enters as part of the roadway characteristics. Step 13 is about applying the EB method. This is accomplished by letting the user either choose to use the EB method or the Part C Predictive Method by using the drop-down menu as shown in Figure 4-6. Step 16 is executed by summing all of the years that are part of the service life. The other steps in the Part C Predictive Method have to do with repeating the process and with comparing the results. These steps are up to the analyst and require engineering judgement to make the decision.

Once the change in crash frequency due to a countermeasure selected is calculated, the benefits and costs need to be calculated. The benefits are obtained by multiplying the crash type values by the number of reduced crashes. The number of reduced crashes is obtained from the average change in crash frequency. The user can choose the crash by type by using the drop-down menu shown previously in Figure 4-7. The costs are determined using the information entered as shown previously in Figure 4-8. The "Calculate Benefit/Cost Ratio" button is used to determine the present benefit values and the present cost values. The BCR is also calculated in the spreadsheet when the "Calculate Benefit/Cost Ratio" button is executed.

4.3   Spreadsheet Analysis Procedure

This section explains how the spreadsheet program performs the analysis. The rural TLTW highway spreadsheet is used as an example. Example conditions are used for the analysis.

The analysis starts with the Basic Information worksheet, followed by the Analysis worksheet and the use of the Output Report worksheets. The Basic Information worksheet for this sample analysis is shown in Figure 4-16.

Analyst	John Smith	Date	5/18/2016	Company	BYU
Route	US-1	Direction	Positive	Jurisdiction	Region 4
MP Begin	200	MP End	205		
Crash Study Begin	1/1/2010	Crash Study End	1/1/2016		

Crash Severity Data				
5 (K)	3		Growth Rate on AADT (Default is 0.5%)	0.5%
4 (A)	3			
3 (B)	12			
2 (C)	15			
1 (O)	77			

Figure 4-16: Basic Information Worksheet for Example Analysis

As can be seen in Figure 4-16, the beginning mile point of this sample segment is 200, and the ending mile point is 205, meaning that the segment length will be 5 miles. The crash study period goes from January 1, 2010 to January 1, 2016 meaning that this includes six total years of crashes. The crash severity distribution is an estimate, but the Analysis worksheet will divide these crashes by six to come up with an annual average observed crash frequency. The growth rate on AADT was set to be 0.5 percent. This means that for each year of the study, the AADT will grow by 0.5%. The traffic growth rate for a study site can be obtained from UDOT's historical AADT data. The roadway characteristics that were used for this sample analysis are found in Figure 4-17. The CMFs that are produced from these characteristics is shown in Figure 4-18. These CMFs are determined based on the physical conditions using the methods described

in the HSM. All CMF computation routines are included in the spreadsheet. Appendix A

contains all CMFs used for the rural TLTW highway module of the spreadsheet. As shown in

Figure 4-17, the shoulder width was changed from 2 feet to 8 feet, the presence of rumble strips

was added, two passing lanes were added, and the presence of automated speed enforcement was

added, as illustrated in the yellow columns on the left and on the right.

Roadway Segment Characteristics			
Existing Conditions		Future Conditions	
AADT	30000	AADT	33147
Lane Width (ft.)	12	Lane Width (ft.)	12
Shoulder Width (ft.)	2	Shoulder Width (ft.)	8
Shoulder Type	Paved	Shoulder Type	Paved
Length of roadway segment (miles)	5.000	Length of roadway segment (miles)	5.000
Length of Horizontal Curve (miles)	1.0000	Length of Horizontal Curve (miles)	1.0000
Radius of Curvature (feet)	6000	Radius of Curvature (feet)	6000
Spiral Transition Curve (1 if yes, 0 if no, 0.5 if present at only one end)	0	Spiral Transition Curve (1 if yes, 0 if no, 0.5 if present at only one end)	0
Supereelvation (ft/ft)	0	Supereelvation (ft/ft)	0
Grade (%)	0	Grade (%)	0.00
Driveway Density (driveways/mile)	0	Driveway Density (driveways/mile)	0
Presence of Rumble Strips (1 if yes, 0 if no)	0	Presence of Rumble Strips (1 if yes, 0 if no)	1
Presence of Passing Lanes (2 for Passing Lanes in both directions, 1 for Passing Lanes in one direction, 0 for no passing lanes)	0	Presence of Passing Lanes (2 for Passing Lanes in both directions, 1 for Passing Lanes in one direction, 0 for no passing lanes)	2
Roadside Hazard Rating (1-7) Use Appendix from Chapter 13 of HSM, base conditions is 3	3	Roadside Hazard Rating (1-7) Use Appendix from Chapter 13 of HSM, base conditions is 3	3
Proportion of Total Nighttime Fatal or Injury Crashes (use 0.382 for default)	0.382	Proportion of Total Nighttime Fatal or Injury Crashes (use 0.382 for default)	0.382
Proportion of Total Nighttime PDO crashes (use 0.618 for default)	0.618	Proportion of Total Nighttime PDO crashes (use 0.618 for default)	0.618
Proportion of total crashes for unlighted roadway segments that occur at night (use 0.370 for default)	0.37	Proportion of total crashes for unlighted roadway segments that occur at night (use 0.370 for default)	0.37
Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0	Presence of Automated Speed Enforcement (1 if yes, 0 if no)	1
Calibration Factor (site specific, Use 1.00 for Default)	1	Calibration Factor (site specific, Use 1.00 for Default)	1

Figure 4-17: Roadway Characteristics for Example Analysis

Crash Modification Factors			
Existing Conditions		Future Conditions	
CMF_{RA}	1.00	CMF_{RA}	1.00
CMF_{WRA}	1.30	CMF_{WRA}	0.87
CMF_{TRA}	1.00	CMF_{TRA}	1.00
CMF_{1r}	1.00	CMF_{1r}	1.00
CMF_{2r}	1.17	CMF_{2r}	0.93
CMF_{3r}	1.01	CMF_{3r}	1.01
CMF_{4r}	1.00	CMF_{4r}	1.00
CMF_{5r}	1.00	CMF_{5r}	1.00
CMF_{6r}	1.00	CMF_{6r}	1.00
CMF_{7r}	1.00	CMF_{7r}	0.94
CMF_{8r}	1.00	CMF_{8r}	0.65
CMF_{9r}	1.00	CMF_{9r}	1.00
CMF_{10r}	1.00	CMF_{10r}	1.00
CMF_{11r}	0.92	CMF_{11r}	0.92
CMF_{12r}	1.00	CMF_{12r}	0.93
Project Specific			
CMF_1	1.00	CMF_4	1.00
CMF_2	1.00	CMF_5	1.00
CMF_3	1.00	CMF_6	1.00

Figure 4-18: CMFs for Example Analysis

As shown in Figure 4-18, five CMFs changed from the existing conditions to future conditions: CMF_{WRA}, CMF_{2r}, CMF_{7r}, CMF_{8r}, and CMF_{12r}. The calculation procedures for each of these five CMFs can be found in Appendix A. Refer to Volume 2 of the HSM for the CMF equations (AASHTO 2010b). The calculated observed crash frequency for different severity levels are found in Figure 4-19.

Observed Crash Frequency		
Fatal	5 (K)	0.5
Injury	4 (A)	0.5
	3 (B)	2.0
	2 (C)	2.5
PDO	1 (O)	12.8
	Total	18.3
Default Distribution ▼		

Figure 4-19: Observed Crash Frequency for Example Analysis

Figure 4-19 shows the observed crash frequency, which is calculated based on the crash study period and the crash data entered in the Basic Information worksheet. The calculation procedure for each of these crash severity levels can be found in Appendix A for verification. Figure 4-19 also shows the drop-down menu in which the analyst uses the default crash severity distribution. The default crash severity distribution for the rural TLTW highway can be found in Volume 2 of the HSM, which is shown in Figure 4-20 (AASHTO 2010b).

Crash Severity Distribution	
Fatal	1.3%
Incapacitating Injury	5.4%
Nonincapacitating Injury	10.9%
Possible Injury	14.5%
Property Damage Only	67.9%
Total	100.0%

Figure 4-20: Crash Severity Distribution for Example Analysis

The results of the SPF calculations are shown in Figure 4-21. The Part C Predictive Method states that the k value for rural TLTW highways is equal to 0.236 divided by the length (AASHTO 2010b). The calculations for k, w, and N_{spfrs} can be seen in Appendix A. The $N_{predictedrs}$ is determined by multiplying the results of the N_{spfrs} by the CMFs and the calibration factor. As shown in Figure 4-17, the calibration factor was 1.00, and the CMFs were summarized previously in Figure 4-18. The total number of crashes is dependent upon whether or not the EB method is selected or if the Part C Predictive Method option is selected. If the Part C Predictive Method option is selected, then the Total Crashes is equal to the $N_{predicted\ rs}$. If the EB method is selected, then the $N_{predicted\ rs}$ value is weighted with the observed crash frequency summarized previously in Figure 4-19, which takes into account the k value and w value (Hauer et al. 2002).

Observed Crashes		Predicted Crashes	
k	0.047	k	0.047
w	0.3051	w	0.4947
N_{spfrs}	44.3	N_{spfrs}	44.3
$N_{predicted\ rs}$	48.25	$N_{predicted\ rs}$	21.64
Part C Predictive Method ▼			
Total Number of Crashes	48.2	Total Number ofCrashes	21.6

Figure 4-21: SPF Results for Example Analysis

The results of the benefit part of the analysis are shown in Figure 4-22. The benefits are calculated for each year. Since the service life was set at 20 years, 20 years of benefits were calculated for this analysis. These values were then used to generate the benefit values found in Figure 4-23. In this calculation, the crash costs recommended by UDOT recommended were

used. The values shown in the "Estimated Safety Benefit" of Figure 4-23 are the present worth values of the safety benefits. The calculation procedure to obtain the present worth of the safety benefits can be found in Appendix A. The inputs for the cost analysis are presented in Figure 4-24.

Year	AADT	Crashes Reduced	Fatal Benefit	Incapacitating injury Benefit	Nonincapacitating Injury Benefit	Possible Injury Benefits	PDO Benefit	Total Benefits
1	30150	24.19812219	$ 605,328.95	$ 2,514,443.32	$ 316,767.52	$ 215,292.81	$ 51,046.29	$ 3,702,878.88
2	30300.75	24.3191128	$ 590,636.50	$ 2,453,413.14	$ 309,078.98	$ 210,067.25	$ 49,807.30	$ 3,613,003.18
3	30452.25375	24.44070836	$ 576,300.66	$ 2,393,864.28	$ 301,577.07	$ 204,968.53	$ 48,598.39	$ 3,525,308.93
4	30604.51502	24.5629119	$ 562,312.78	$ 2,335,760.78	$ 294,257.23	$ 199,993.57	$ 47,418.82	$ 3,439,743.18
5	30757.53759	24.68572646	$ 548,664.41	$ 2,279,067.56	$ 287,115.07	$ 195,139.36	$ 46,267.87	$ 3,356,254.27
6	30911.32528	24.8091551	$ 535,347.31	$ 2,223,750.38	$ 280,146.26	$ 190,402.96	$ 45,144.87	$ 3,274,791.79
7	31065.88191	24.93320087	$ 522,353.45	$ 2,169,775.86	$ 273,346.59	$ 185,781.53	$ 44,049.12	$ 3,195,306.55
8	31221.21132	25.05786688	$ 509,674.97	$ 2,117,111.40	$ 266,711.96	$ 181,272.27	$ 42,979.96	$ 3,117,750.56
9	31377.31737	25.18315621	$ 497,304.21	$ 2,065,725.20	$ 260,238.37	$ 176,872.46	$ 41,936.76	$ 3,042,077.01
10	31534.20396	25.30907199	$ 485,233.72	$ 2,015,586.24	$ 253,921.91	$ 172,579.44	$ 40,918.88	$ 2,968,240.19
11	31691.87498	25.43561735	$ 473,456.21	$ 1,966,664.24	$ 247,758.75	$ 168,390.62	$ 39,925.70	$ 2,896,195.52
12	31850.33436	25.56279544	$ 461,964.55	$ 1,918,929.67	$ 241,745.19	$ 164,303.47	$ 38,956.63	$ 2,825,899.51
13	32009.58603	25.69060942	$ 450,751.82	$ 1,872,353.71	$ 235,877.59	$ 160,315.52	$ 38,011.08	$ 2,757,309.72
14	32169.63396	25.81906246	$ 439,811.24	$ 1,826,908.23	$ 230,152.41	$ 156,424.37	$ 37,088.48	$ 2,690,384.73
15	32330.48213	25.94815777	$ 429,136.21	$ 1,782,565.80	$ 224,566.18	$ 152,627.66	$ 36,188.28	$ 2,625,084.13
16	32492.13454	26.07789856	$ 418,720.28	$ 1,739,299.64	$ 219,115.55	$ 148,923.10	$ 35,309.92	$ 2,561,368.49
17	32654.59521	26.20828806	$ 408,557.17	$ 1,697,083.63	$ 213,797.21	$ 145,308.46	$ 34,452.88	$ 2,499,199.35
18	32817.86819	26.3393295	$ 398,640.73	$ 1,655,892.28	$ 208,607.96	$ 141,781.56	$ 33,616.65	$ 2,438,539.18
19	32981.95753	26.47102614	$ 388,964.99	$ 1,615,700.72	$ 203,544.66	$ 138,340.26	$ 32,800.71	$ 2,379,351.33
20	33146.86732	26.60338127	$ 379,524.09	$ 1,576,484.68	$ 198,604.25	$ 134,982.49	$ 32,004.58	$ 2,321,600.09
Total		507.6551987	$ 9,682,684.25	$ 40,220,380.74	$ 5,066,930.71	$ 3,443,767.70	$ 816,523.18	$ 59,230,286.59

Figure 4-22: Benefit Table Results for Example Analysis

	UDOT Recommended		
Crash Severity	Estimated Reduction in Crashes	Crash Severity Value (Use Options Above)	Estimated Safety Benefit
5 (K) Fatal	6.6	$ 1,982,000.00	$ 9,682,684.25
4 (A) Incapacitating Injury	27.4	$ 1,982,000.00	$ 40,220,380.74
3 (B) Nonincapacitating Injury	55.3	$ 123,700.00	$ 5,066,930.71
2 (C) Possible Injury	73.6	$ 63,200.00	$ 3,443,767.70
1 (O) Property Damage Only	344.7	$ 3,200.00	$ 816,523.18
Total	507.7		$ 59,230,286.58

Figure 4-23: Benefit Results for Example Analysis

57

Initial Project Cost	$ 10,000,000.00
Rehabilitation Cycle Cost	$ 500,000.00
Number of Years For Each Rehabilitation	5
Annual Maintenance	$ 20,000.00
Discount Rate	3%
Service Life (years)	20
Number of Maintenance Periods	4
Total Maintenance Costs Present Value	$ 1,421,831.82
Total Cost	$ 11,421,831.82

Figure 4-24: Inputs for Cost Analysis

As shown in Figure 4-24, the initial cost was assumed to be $10,000,000.00, the rehabilitation cost was estimated to be $500,000.00 repeated every five years, and the annual maintenance cost is estimated at $20,000.00. After all these costs are brought back to present worth, the total cost was calculated. A summary of how the costs were brought to present value is shown in Figure 4-25. The BCR for this example analysis is performed and the resulting BCR is shown in Figure 4-26.

As shown in Figure 4-26, the BCR is greater than 1.0 for this analysis, meaning that the present value costs are less than the present value benefits and the installation of this countermeasure is justified. All of the pertinent calculation procedures for this example analysis are found in Appendix A.

Year	Period	Present Value Rehabilitation/ Reconstruction Cost	Annual Maintenance Cost
1			$ 19,417.48
2			$ 18,851.92
3			$ 18,302.83
4			$ 17,769.74
5	1	$ 431,304.39	$ 17,252.18
6			$ 16,749.69
7			$ 16,261.83
8			$ 15,788.18
9			$ 15,328.33
10	2	$ 372,046.96	$ 14,881.88
11			$ 14,448.43
12			$ 14,027.60
13			$ 13,619.03
14			$ 13,222.36
15	3	$ 320,930.97	$ 12,837.24
16			$ 12,463.34
17			$ 12,100.33
18			$ 11,747.89
19			$ 11,405.72
20			$ 11,073.52
Total		$ 1,124,282.32	$ 297,549.50

Figure 4-25: Cost Table Results for Example Analysis

B/C=	5.19
Using present worth values:	
Benefit =	$ 59,230,287
Cost =	$ 11,421,832

Figure 4-26: BCR for Example Analysis

4.4 Chapter Summary

This chapter explained how the spreadsheet program was laid out and gave an example of its application using a rural TLTW highway segment project. It also explained how the spreadsheet was developed. The next chapter presents three different examples, using the results of the UCPM and how the data are entered.

5   APPLICATION THROUGH EXAMPLE

This chapter describes how the Excel-based spreadsheet program can be used to perform a life-cycle benefit-cost analysis of safety related improvements using the segments chosen by the UCPM. The UCPM ranks all of the segments in Utah in terms of the deviation from the probability distribution of expected number of crashes to observed number of crashes. The output from the UCPM is a report that explains some of the main roadway characteristics of the segment, as well as possible countermeasures that can be used to improve the safety on these roadway segments. Analyses of three different roadway segments that were found among the top 20 hot spots, or least safe segments, identified by the UCPM, including a rural TLTW highway example, a five-lane arterial including TWLTL example, and a freeway segment example.

5.1   Rural TLTW Example

This section explains how the Excel-based spreadsheet program developed for this research is used to perform an analysis for one of the segments that was determined to be a top 20 hot spot by the UCPM (Schultz et. al 2015). Each of these 20 hot spots has a two-page report that is created for it. The two-page report for this hot spot can be found in Figure B-1 in Appendix B.

As shown in Figure B-1, this rural segment is on US-89, in Sanpete County, in UDOT Region 4, and runs from mile point (MP) 267.346 to MP 276.210, and has a total segment length

of 8.864 miles. The second page of the two-page report shows that this segment has a 5-ft. shoulder made of asphalt, a maximum grade of -4.41%, a curve with a 5333-ft. radius, and a 474-ft. curve length. The second page also shows that this roadway segment has rumble strips.

The crash data used for this analysis was taken from the UDOT SafeMap website (UDOT SafeMap 2016). The Basic Info worksheet used to perform the life-cycle benefit-cost analysis is shown in Figure 5-1.

Analyst	John Smith	Date	5/18/2016	Company	BYU
Route	US-1	Direction	Positive	Jurisdiction	Region 4
MP Begin	267.346	MP End	276.21		
Crash Study Begin	1/1/2010	Crash Study End	4/30/2016		

Crash Severity Data				
5 (K)	0		Growth Rate on AADT	0.5%
4 (A)	2		(Default is 0.5%)	
3 (B)	12			
2 (C)	16			
1 (O)	81			

Figure 5-1: Basic Info Rural TLTW Example

As shown on the second page of the two-page report seen in Figure B-1, there are various countermeasures listed that can be used to improve the safety on this roadway segment. This example performs a life-cycle benefit-cost analysis for two of the safety related improvements listed in Figure B-1:

- Widen the shoulder from 5 ft. to 8 ft.

- Add passing lanes in both directions

Each of the countermeasures will be discussed in the following subsections.

5.1.1   Widening the Shoulder

The first analysis to be performed is to widen the shoulder from 5 ft. to 8 ft. All of the roadway attributes were entered into the spreadsheet program, and the future condition includes an 8-ft. shoulder. In both cases, the shoulder is paved since the existing shoulder is made of asphalt. All of the necessary data for the existing conditions and future conditions are shown in Figure 5-2.

Roadway Segment Characteristics			
Existing Conditions		Future Conditions	
AADT	2675	AADT	2956
Lane Width (ft.)	12	Lane Width (ft.)	12
Shoulder Width (ft.)	5	Shoulder Width (ft.)	8
Shoulder Type	Paved	Shoulder Type	Paved
Length of roadway segment (miles)	8.864	Length of roadway segment (miles)	8.864
Length of Horizontal Curve (miles)	0.0898	Length of Horizontal Curve (miles)	0.0898
Radius of Curvature (feet)	5333	Radius of Curvature (feet)	5333
Spiral Transition Curve (1 if yes, 0 if no, 0.5 if present at only one end)	0	Spiral Transition Curve (1 if yes, 0 if no, 0.5 if present at only one end)	0
Supereelvation (ft/ft)	0	Supereelvation (ft/ft)	0
Grade (%)	-4.41	Grade (%)	-4.41
Driveway Density (driveways/mile)	0	Driveway Density (driveways/mile)	0
Presence of Rumble Strips (1 if yes, 0 if no)	1	Presence of Rumble Strips (1 if yes, 0 if no)	1
Presence of Passing Lanes (2 for Passing Lanes in both directions, 1 for Passing Lanes in one direction, 0 for no passing lanes)	0	Presence of Passing Lanes (2 for Passing Lanes in both directions, 1 for Passing Lanes in one direction, 0 for no passing lanes)	0
Roadside Hazard Rating (1-7) Use Appendix from Chapter 13 of HSM, base conditions is 3	3	Roadside Hazard Rating (1-7) Use Appendix from Chapter 13 of HSM, base conditions is 3	3
Proportion of Total Nighttime Fatal or Injury Crashes (use 0.382 for default)	0.382	Proportion of Total Nighttime Fatal or Injury Crashes (use 0.382 for default)	0.382
Proportion of Total Nighttime PDO crashes (use 0.618 for default)	0.618	Proportion of Total Nighttime PDO crashes (use 0.618 for default)	0.618
Proportion of total crashes for unlighted roadway segments that occur at night (use 0.370 for default)	0.37	Proportion of total crashes for unlighted roadway segments that occur at night (use 0.370 for default)	0.37
Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0	Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0
Calibration Factor (site specific, Use 1.00 for Default)	1	Calibration Factor (site specific, Use 1.00 for Default)	1

Figure 5-2: Roadway Segment Characteristics for Rural TLTW Example

As shown in Figure 5-2, the AADT for the "Future Conditions" is higher than the AADT for the "Existing Conditions." This is because the AADT is expected to grow each year, and so the growth rate used in Figure 5-1 is used to determine how much the AADT will grow each year. All of the roadway characteristics in Figure 5-2 correspond to different CMFs. The CMFs that were calculated according to these attributes are shown in Figure 5-3. As shown in Figure 5-3, the project specific CMFs are all equal to one. This is because the shoulder widening improvement is represented in the CMFs that are specific to rural TLTW highways. As shown in Figure 5-3, CMF_{WRA} and CMF_{2r} are both different when comparing the existing conditions to the future conditions. Both of these CMFs are lower for the future conditions, (1.15 vs. 0.87 for CMF_{WRA} and 1.09 vs. 0.93 for CMF_{2r}), which result in the reduced crashes that will be seen for each year of the service life. These CMFs are lower for future conditions because it is expected that an 8-ft. shoulder will cause fewer crashes than a 5-ft. shoulder. The observed crash frequency for this rural TLTW highway is shown in Figure 5-4.

The observed crash frequency shown in Figure 5-4 represents the average number of crashes per year for each severity. This is calculated based on the crash data entered, which were shown previously in Figure 5-1. The crash distribution for this analysis is shown in Figure 5-5. This crash distribution is based on the default distribution for rural TLTW highways given in the HSM (AASHTO 2010b).

Crash Modification Factors			
Existing Conditions		Future Conditions	
CMF_{RA}	1.00	CMF_{RA}	1.00
CMF_{WRA}	1.15	CMF_{WRA}	0.87
CMF_{TRA}	1.00	CMF_{TRA}	1.00
CMF_{1r}	1.00	CMF_{1r}	1.00
CMF_{2r}	1.09	CMF_{2r}	0.93
CMF_{3r}	1.11	CMF_{3r}	1.11
CMF_{4r}	1.00	CMF_{4r}	1.00
CMF_{5r}	1.00	CMF_{5r}	1.00
CMF_{6r}	1.00	CMF_{6r}	1.00
CMF_{7r}	0.94	CMF_{7r}	0.94
CMF_{8r}	1.00	CMF_{8r}	1.00
CMF_{9r}	1.00	CMF_{9r}	1.00
CMF_{10r}	1.00	CMF_{10r}	1.00
CMF_{11r}	0.92	CMF_{11r}	0.92
CMF_{12r}	1.00	CMF_{12r}	1.00
Project Specific			
CMF_1	1.00	CMF_4	1.00
CMF_2	1.00	CMF_5	1.00
CMF_3	1.00	CMF_6	1.00

Figure 5-3: CMFs for Rural TLTW Example

Observed Crash Severity Frequency		
Fatal	5 (K)	0.0
Injury	4 (A)	0.3
	3 (B)	1.9
	2 (C)	2.5
PDO	1 (O)	12.8
	Total	17.5
Default Distribution ▼		

Figure 5-4: Observed Crash Frequency for Rural TLTW Example

Crash Severity Distribution	
Fatal	1.3%
Incapacitating Injury	5.4%
Nonincapacitating Injury	10.9%
Possible Injury	14.5%
Property Damage Only	67.9%
Total	100.0%

Figure 5-5: Crash Distribution for Rural TLTW Example

The results of the SPFs are shown in Figure 5-6. As explained in section 2.3, SPFs are calculated using AADT and segment length. The k value is the overdispersion parameter, which is based on segment length for rural TLTW highways. $N_{predicted\ rs}$ is the result of multiplying the N_{spfrs} value by all of the CMFs from Figure 5-3 and the calibration factor from Figure 5-2. The Total Crashes value that is presented in Figure 5-6 is based on the Part C Predictive Method, which combines the results of the $N_{predicted\ rs}$ value with the observed crash frequency.

Observed Crashes		Predicted Crashes	
k	0.027	k	0.027
w	0.8373	w	0.8580
N_{spfrs}	7.0	N_{spfrs}	7.0
$N_{predicted\ rs}$	7.30	$N_{predicted\ rs}$	6.22
Part C Predictive Method ▾			
Total Number of Crashes	7.3	Total Number ofCrashes	6.2

Figure 5-6: SPF Results for Rural TLTW Example

The total benefits that were calculated for this example are shown in Figure 5-7. As can be seen in Figure 5-7, the Crash Type Values that were used for this analysis are the UDOT Recommended values outlined previously in Figure 2-4. These benefit values were determined by converting all of the future values of benefits into present values using the discount rate 3 percent that is found in the Costs section in Figure 5-8.

	Crash Severity	Estimated Reduction in Crashes	Crash Severity Value (Use Options Above)	Estimated Safety Benefit
	UDOT Recommended			
5 (K)	Fatal	0.3	$ 1,982,000.00	$ 393,007.67
4 (A)	Incapacitating Injury	1.1	$ 1,982,000.00	$ 1,632,493.39
3 (B)	Nonincapacitating Injury	2.2	$ 123,700.00	$ 205,660.18
2 (C)	Possible Injury	3.0	$ 63,200.00	$ 139,778.09
1 (O)	Property Damage Only	14.0	$ 3,200.00	$ 33,141.62
	Total	20.6		$ 2,404,080.95

Figure 5-7: Total Benefits for Rural TLTW Example

The total costs associated with this improvement is found in Figure 5-8. As shown in Figure 5-8, the initial project cost is estimated to be $2,250,000, and the annual maintenance cost is estimated to be $2,000. These are example amounts, and the difficult part of predicting costs is explained in section 5.4. The initial project cost is already in present value, while the annual maintenance value is brought back to present value for each year. For this analysis, cyclic rehabilitation cost is ignored.

Initial Project Cost	$	2,250,000.00
Rehabilitation Cycle Cost	$	-
Number of Years For Each Rehabilitation		1
Annual Maintenance	$	2,000.00
Discount Rate		3%
Service Life (years)		20
Number of Maintenance Periods		20
Total Maintenance Costs Present Value	$	29,754.95
Total Cost	$	2,279,754.95

Figure 5-8: Costs for Rural TLTW Example

The results of this life-cycle cost-benefit analysis is shown in Figure 5-9. The BCR is determined by dividing the total benefits by the total costs, and it is 1.05 in this example, meaning that the total benefit is slightly greater than the total cost. UDOT requires that the BCR be greater than 1.0, therefore this countermeasure may be recommended. However, if there is a countermeasure with a larger BCR that countermeasure is preferred. The values that are calculated for the benefits in this example are reliable because they are based on the procedures explained in the HSM: however, as mentioned previously, the costs for this analysis are estimates. The entire spreadsheet for the analysis is shown in Figure 5-10. All of the previous sections shown in this section, from Figure 5-2 through Figure 5-9, are located in this figure.

B/C=	1.05
Using present worth values:	
Benefit =	$ 2,404,081
Cost =	$ 2,279,755

Figure 5-9: Cost-Benefit Results for Rural TLTW Example

Rural Two-Lane Two-Way Highway

Roadway Segment Characteristics

Existing Conditions / Future Conditions

Existing Conditions		Future Conditions	
AADT	2675	AADT	2956
Lane Width (ft.)	12	Lane Width (ft.)	12
Shoulder Width (ft.)	5	Shoulder Width (ft.)	8
Shoulder Type	Paved	Shoulder Type	Paved
Length of roadway segment (miles)	8.864	Length of roadway segment (miles)	8.864
Length of Horizontal Curve (miles)	0.0898	Length of Horizontal Curve (miles)	0.0898
Radius of Curvature (feet)	5333	Radius of Curvature (feet)	5333
Spiral Transition Curve (1 if yes, 0 if no, 0.5 if present at only one end)	0	Spiral Transition Curve (1 if yes, 0 if no, 0.5 if present at only one end)	0
Supereelevation (ft/ft)	0	Supereelevation (ft/ft)	0
Grade (%)	-4.41	Grade (%)	-4.41
Driveway Density (driveways/mile)	0	Driveway Density (driveways/mile)	0
Presence of Rumble Strips (1 if yes, 0 if no)	1	Presence of Rumble Strips (1 if yes, 0 if no)	1
Presence of Passing Lanes (2 for Passing Lanes in both directions, 1 for Passing Lanes in one direction, 0 for no passing lanes)	0	Presence of Passing Lanes (2 for Passing Lanes in both directions, 1 for Passing Lanes in one direction, 0 for no passing lanes)	0
Roadside Hazard Rating (1-7) Use Appendix from Chapter 13 of HSM, base conditions is 3	3	Roadside Hazard Rating (1-7) Use Appendix from Chapter 13 of HSM, base conditions is 3	3
Proportion of Total Nighttime Fatal or Injury Crashes (use 0.382 for default)	0.382	Proportion of Total Nighttime Fatal or Injury Crashes (use 0.382 for default)	0.382
Proportion of Total Nighttime PDO crashes (use 0.618 for default)	0.618	Proportion of Total Nighttime PDO crashes (use 0.618 for default)	0.618
Proportion of total crashes for unlighted roadway segments that occur at night (use 0.370 for default)	0.37	Proportion of total crashes for unlighted roadway segments that occur at night (use 0.370 for default)	0.37
Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0	Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0
Calibration Factor (site specific, Use 1.00 for Default)	1	Calibration Factor (site specific, Use 1.00 for Default)	1

Crash Modification Factors

Existing Conditions		Future Conditions	
CMF_{RA}	1.00	CMF_{RA}	1.00
CMF_{WRA}	1.15	CMF_{WRA}	0.87
CMF_{TRA}	1.00	CMF_{TRA}	1.00
CMF_{1r}	1.00	CMF_{1r}	1.00
CMF_{2r}	1.09	CMF_{2r}	0.93
CMF_{3r}	1.11	CMF_{3r}	1.11
CMF_{4r}	1.00	CMF_{4r}	1.00
CMF_{5r}	1.00	CMF_{5r}	1.00
CMF_{6r}	1.00	CMF_{6r}	1.00
CMF_{7r}	0.94	CMF_{7r}	0.94
CMF_{8r}	1.00	CMF_{8r}	1.00
CMF_{9r}	1.00	CMF_{9r}	1.00
CMF_{10r}	1.00	CMF_{10r}	1.00
CMF_{11r}	0.92	CMF_{11r}	0.92
CMF_{12r}	1.00	CMF_{12r}	1.00

Project Specific

CMF_1	1.00	CMF_4	1.00
CMF_2	1.00	CMF_5	1.00
CMF_3	1.00	CMF_6	1.00

Observed Crash Severity Frequency

Fatal	5 (K)	0.0
Injury	4 (A)	0.3
	3 (B)	1.9
	2 (C)	2.5
PDO	1 (O)	12.8
	Total	17.5

Default Distribution

Crash Severity Distribution

Fatal	1.3%
Incapacitating Injury	5.4%
Nonincapacitating Injury	10.9%
Possible Injury	14.5%
Property Damage Only	67.9%
Total	100.0%

Observed Crashes		Predicted Crashes	
k	0.027	k	0.027
w	0.8373	w	0.8580
N_{spfrs}	7.0	N_{spfrs}	7.0
$N_{predicted\ rs}$	7.30	$N_{predicted\ rs}$	6.22
		Part C Predictive Method	
Total Number of Crashes	7.3	Total Number of Crashes	6.2

UDOT Recommended

Crash Severity		Estimated Reduction in Crashes	Crash Severity Value (Use Options Above)	Estimated Safety Benefit
5 (K)	Fatal	0.3	$ 1,982,000.00	$ 393,007.67
4 (A)	Incapacitating Injury	1.1	$ 1,982,000.00	$ 1,632,493.39
3 (B)	Nonincapacitating Injury	2.2	$ 123,700.00	$ 205,660.18
2 (C)	Possible Injury	3.0	$ 63,200.00	$ 139,778.09
1 (O)	Property Damage Only	14.0	$ 3,200.00	$ 33,141.62
	Total	20.6		$ 2,404,080.95

Calculate Benefit/Cost Ratio	
Print BCR Report	

Initial Project Cost	$ 2,250,000.00
Rehabilitation Cycle Cost	$ -
Number of Years For Each Rehabilitation	5
Annual Maintenance	$ 2,000.00
Discount Rate	3%
Service Life (years)	20
Number of Maintenance Periods	4
Total Maintenance Costs Present Value	$ 29,754.95
Total Costs	$ 2,279,754.95

B/C=	1.05
Using present worth values:	
Benefit =	$ 2,404,081
Cost =	$ 2,279,755

Figure 5-10: Complete Spreadsheet for Rural TLTW Example

5.1.2 Adding a Passing Lane

The second countermeasure for the rural TLTW example is to add a passing lane in each direction. Figure 5-1 is still valid for this analysis since none of the crash data or any of the other factors have been changed. The roadway segment characteristics for the existing and future conditions are shown in Figure 5-11.

Roadway Segment Characteristics			
Existing Conditions		Future Conditions	
AADT	2675	AADT	2956
Lane Width (ft.)	12	Lane Width (ft.)	12
Shoulder Width (ft.)	5	Shoulder Width (ft.)	5
Shoulder Type	Paved	Shoulder Type	Paved
Length of roadway segment (miles)	8.864	Length of roadway segment (miles)	8.864
Length of Horizontal Curve (miles)	0.0898	Length of Horizontal Curve (miles)	0.0898
Radius of Curvature (feet)	5333	Radius of Curvature (feet)	5333
Spiral Transition Curve (1 if yes, 0 if no, 0.5 if present at only one end)	0	Spiral Transition Curve (1 if yes, 0 if no, 0.5 if present at only one end)	0
Supereelvation (ft/ft)	0	Supereelvation (ft/ft)	0
Grade (%)	-4.41	Grade (%)	-4.41
Driveway Density (driveways/mile)	0	Driveway Density (driveways/mile)	0
Presence of Rumble Strips (1 if yes, 0 if no)	1	Presence of Rumble Strips (1 if yes, 0 if no)	1
Presence of Passing Lanes (2 for Passing Lanes in both directions, 1 for Passing Lanes in one direction, 0 for no passing lanes)	0	Presence of Passing Lanes (2 for Passing Lanes in both directions, 1 for Passing Lanes in one direction, 0 for no passing lanes)	2
Roadside Hazard Rating (1-7) Use Appendix from Chapter 13 of HSM, base conditions is 3	3	Roadside Hazard Rating (1-7) Use Appendix from Chapter 13 of HSM, base conditions is 3	3
Proportion of Total Nighttime Fatal or Injury Crashes (use 0.382 for default)	0.382	Proportion of Total Nighttime Fatal or Injury Crashes (use 0.382 for default)	0.382
Proportion of Total Nighttime PDO crashes (use 0.618 for default)	0.618	Proportion of Total Nighttime PDO crashes (use 0.618 for default)	0.618
Proportion of total crashes for unlighted roadway segments that occur at night (use 0.370 for default)	0.37	Proportion of total crashes for unlighted roadway segments that occur at night (use 0.370 for default)	0.37
Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0	Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0
Calibration Factor (site specific, Use 1.00 for Default)	1	Calibration Factor (site specific, Use 1.00 for Default)	1

Figure 5-11: Roadway Segment Characteristics for Second Rural TLTW Example

70

As shown in Figure 5-11, the value for the passing lanes has changed from a 0 to a 2. This means that there will be passing lane in both directions. The CMFs for this analysis and how they are different from the first analysis are shown in Figure 5-12.

Crash Modification Factors			
Existing Conditions		Future Conditions	
CMF_{RA}	1.00	CMF_{RA}	1.00
CMF_{WRA}	1.15	CMF_{WRA}	1.15
CMF_{TRA}	1.00	CMF_{TRA}	1.00
CMF_{1r}	1.00	CMF_{1r}	1.00
CMF_{2r}	1.09	CMF_{2r}	1.09
CMF_{3r}	1.11	CMF_{3r}	1.11
CMF_{4r}	1.00	CMF_{4r}	1.00
CMF_{5r}	1.00	CMF_{5r}	1.00
CMF_{6r}	1.00	CMF_{6r}	1.00
CMF_{7r}	0.94	CMF_{7r}	0.94
CMF_{8r}	1.00	CMF_{8r}	0.65
CMF_{9r}	1.00	CMF_{9r}	1.00
CMF_{10r}	1.00	CMF_{10r}	1.00
CMF_{11r}	0.92	CMF_{11r}	0.92
CMF_{12r}	1.00	CMF_{12r}	1.00
Project Specific			
CMF_1	1	CMF_4	1
CMF_2	1	CMF_5	1
CMF_3	1	CMF_6	1

Figure 5-12: CMF for Second Rural TLTW Example

As shown in Figure 5-12, the value for CMF_{8r} is 1.00 for the existing conditions, but is only 0.65 for the future condition. CMF_{8r} is the CMF that correlates to adding or removing

71

passing lanes. When there are no passing lanes, the CMF is 1.00, and when there are two passing

lanes, the CMF is 0.65. This is the CMF that is associated with adding passing lanes. As shown

in Figure 5-12, CMF_{8r} is the only CMF that has a different value for existing and future

conditions. The results of the SPFs are shown in Figure 5-13.

Observed Crashes		Predicted Crashes	
k	0.027	k	0.027
w	0.8373	w	0.8879
N_{spfrs}	7.0	N_{spfrs}	7.0
$N_{predicted\ rs}$	7.30	$N_{predicted\ rs}$	4.74
Part C Predictive Method ▾			
Total Number of Crashes	7.3	Total Number ofCrashes	4.7

Figure 5-13: SPF Results for Second Rural TLTW Example

As shown in Figure 5-13, the values for k and N_{spfrs} are the same for both existing crashes

and future crashes, while the values for w, $N_{predicted\ rs}$, and Total Crashes are all different for

existing and future crashes. The values for w are dependent upon the number of predicted

crashes compared to the number of observed crashes. The number of observed crashes for this

analysis is the same for both existing and future crashes, but the number of predicted crashes

changes because the Future Crashes value is determined by multiplying the predicted crashes by

all of the pertinent CMFs. Figure 5-14 shows the benefits for this analysis. As shown in Figure 5-

14, the crash costs that are used for this analysis are the UDOT recommended values outlined

previously in Figure 2-4. Figure 5-14 also shows the total estimated safety benefit for this

analysis, $5,686,133.10. This is more than two times greater than the total estimated safety

benefit for the shoulder widening analysis. The costs that are associated with this analysis are found in Figure 5-15.

Crash Severity		Estimated Reduction in Crashes	Crash Severity Value (Use Options Above)	Estimated Safety Benefit
	UDOT Recommended			
5 (K)	Fatal	0.6	$ 1,982,000.00	$ 929,541.87
4 (A)	Incapacitating Injury	2.6	$ 1,982,000.00	$ 3,861,173.93
3 (B)	Nonincapacitating Injury	5.3	$ 123,700.00	$ 486,427.54
2 (C)	Possible Injury	7.1	$ 63,200.00	$ 330,603.19
1 (O)	Property Damage Only	33.1	$ 3,200.00	$ 78,386.58
	Total	48.7		$ 5,686,133.10

Figure 5-14: Total Benefits Results for Second Rural TLTW Example

Initial Project Cost	$ 8,000,000.00
Rehabilitation Cycle Cost	$ -
Number of Years For Each Rehabilitation	1
Annual Maintenance	$ -
Discount Rate	3%
Service Life (years)	20
Number of Maintenance Periods	20
Total Maintenance Costs Present Value	$ -
Total Cost	$ 8,000,000.00

Figure 5-15: Total Cost Results for Second Rural TLTW Example

As shown in Figure 5-15, the initial project cost for this analysis is estimated to be $8,000,000.00. It is also assumed that there would be no rehabilitation costs or annual

maintenance costs. Similar to the previous analysis, a service life of 20 years is considered with a 3 percent discount rate. Figure 5-16 shows the BCR for this countermeasure of adding passing lanes analysis.

B/C=	0.71
Using present worth values:	
Benefit =	$ 5,686,133
Cost =	$ 8,000,000

Figure 5-16: BCR Results for Second Rural TLTW Example

Even though the benefits are much larger for this analysis, the BCR for this analysis is less than the BCR for the previous analysis because the second countermeasure, adding a passing lane, requires much higher cost than that of the first countermeasure. As explained previously, this sample analysis is only reliable for benefit computations. As such, the costs need to be accurately determined as much as possible by the engineer performing the analysis. As can be seen in Figure 5-16, the BCR is 0.71. This means that the benefits are less than the costs since the BCR is less than 1.0. Since this BCR is less than 1.0, this countermeasure is not advised, and the countermeasure to widen the shoulder is preferred because its BCR is greater than 1.0. It is interesting to note that the benefits for the passing lanes are greater than the benefits for the shoulder widening countermeasures. The entire spreadsheet that is used for this analysis is shown in Figure 5-17.

Rural Two-Lane Two-Way Highway

Roadway Segment Characteristics

Existing Conditions		Future Conditions	
AADT	2675	AADT	2956
Lane Width (ft.)	12	Lane Width (ft.)	12
Shoulder Width (ft.)	5	Shoulder Width (ft.)	5
Shoulder Type	Paved	Shoulder Type	Paved
Length of roadway segment (miles)	8.864	Length of roadway segment (miles)	8.864
Length of Horizontal Curve (miles)	0.0898	Length of Horizontal Curve (miles)	0.0898
Radius of Curvature (feet)	5333	Radius of Curvature (feet)	5333
Spiral Transition Curve (1 if yes, 0 if no, 0.5 if present at only one end)	0	Spiral Transition Curve (1 if yes, 0 if no, 0.5 if present at only one end)	0
Supereelevation (ft/ft)	0	Supereelevation (ft/ft)	0
Grade (%)	-4.41	Grade (%)	-4.41
Driveway Density (driveways/mile)	0	Driveway Density (driveways/mile)	0
Presence of Rumble Strips (1 if yes, 0 if no)	1	Presence of Rumble Strips (1 if yes, 0 if no)	1
Presence of Passing Lanes (2 for Passing Lanes in both directions, 1 for Passing Lanes in one direction, 0 for no passing lanes)	0	Presence of Passing Lanes (2 for Passing Lanes in both directions, 1 for Passing Lanes in one direction, 0 for no passing lanes)	2
Roadside Hazard Rating (1-7) Use Appendix from Chapter 13 of HSM, base conditions is 3	3	Roadside Hazard Rating (1-7) Use Appendix from Chapter 13 of HSM, base conditions is 3	3
Proportion of Total Nighttime Fatal or Injury Crashes (use 0.382 for default)	0.382	Proportion of Total Nighttime Fatal or Injury Crashes (use 0.382 for default)	0.382
Proportion of Total Nighttime PDO crashes (use 0.618 for default)	0.618	Proportion of Total Nighttime PDO crashes (use 0.618 for default)	0.618
Proportion of total crashes for unlighted roadway segments that occur at night (use 0.370 for default)	0.37	Proportion of total crashes for unlighted roadway segments that occur at night (use 0.370 for default)	0.37
Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0	Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0
Calibration Factor (site specific, Use 1.00 for Default)	1	Calibration Factor (site specific, Use 1.00 for Default)	1

Crash Modification Factors

Existing Conditions		Future Conditions	
CMF_{RA}	1.00	CMF_{RA}	1.00
CMF_{WRA}	1.15	CMF_{WRA}	1.15
CMF_{TRA}	1.00	CMF_{TRA}	1.00
CMF_{1r}	1.00	CMF_{1r}	1.00
CMF_{2r}	1.09	CMF_{2r}	1.09
CMF_{3r}	1.11	CMF_{3r}	1.11
CMF_{4r}	1.00	CMF_{4r}	1.00
CMF_{5r}	1.00	CMF_{5r}	1.00
CMF_{6r}	1.00	CMF_{6r}	1.00
CMF_{7r}	0.94	CMF_{7r}	0.94
CMF_{8r}	1.00	CMF_{8r}	0.65
CMF_{9r}	1.00	CMF_{9r}	1.00
CMF_{10r}	1.00	CMF_{10r}	1.00
CMF_{11r}	0.92	CMF_{11r}	0.92
CMF_{12r}	1.00	CMF_{12r}	1.00

Project Specific

CMF_1	1.00	CMF_4	1.00
CMF_2	1.00	CMF_5	1.00
CMF_3	1.00	CMF_6	1.00

Observed Crash Severity Frequency

Fatal	5 (K)	0.0
	4 (A)	0.3
Injury	3 (B)	1.9
	2 (C)	2.5
PDO	1 (O)	12.8
	Total	17.5

Default Distribution

Crash Severity Distribution

Fatal	1.3%
Incapacitating Injury	5.4%
Nonincapacitating Injury	10.9%
Possible Injury	14.5%
Property Damage Only	67.9%
Total	100.0%

Observed Crashes / Predicted Crashes

Observed Crashes		Predicted Crashes	
k	0.027	k	0.027
w	0.8373	w	0.8879
N_{spfrs}	7.0	N_{spfrs}	7.0
$N_{predicted\,rs}$	7.30	$N_{predicted\,rs}$	4.74
		Part C Predictive Method	
Total Number of Crashes	7.3	Total Number of Crashes	4.7

Calculate Benefit/Cost Ratio

Print BCR Report

Crash Severity	Estimated Reduction in Crashes	Crash Severity Value (Use Options Above)	Estimated Safety Benefit
	UDOT Recommended		
5 (K) Fatal	0.6	$ 1,982,000.00	$ 929,541.87
4 (A) Incapacitating Injury	2.6	$ 1,982,000.00	$ 3,861,173.93
3 (B) Nonincapacitating Injury	5.3	$ 123,700.00	$ 486,427.54
2 (C) Possible Injury	7.1	$ 63,200.00	$ 330,603.19
1 (O) Property Damage Only	33.1	$ 3,200.00	$ 78,386.58
Total	48.7		$ 5,686,133.10

Initial Project Cost	$ 8,000,000.00
Rehabilitation Cycle Cost	$ -
Number of Years For Each Rehabilitation	5
Annual Maintenance	$ -
Discount Rate	3%
Service Life (years)	20
Number of Maintenance Periods	4
Total Maintenance Costs Present Value	$ -
Total Costs	$ 8,000,000.00

B/C=	0.71
Using present worth values:	
Benefit =	$ 5,686,133
Cost =	$ 8,000,000

Figure 5-17: Complete Spreadsheet for Second Rural TLTW Example

5.2 Five-Lane Arterial Including TWLTL Example

Similar to the previous section, which explored two different countermeasures using the rural TLTW spreadsheet, this section explores analyses of two different countermeasures for an

urban/suburban five-lane arterial including TWLTL spreadsheet. The segment examined for this example is US-89 in Box Elder county. The Hot Spot Two-Page Report for this segment can be found in Figure B-2. This segment is in UDOT Region 1 and ranked 9th by the UCPM (Schultz et al. 2015). As can be seen in Figure B-2, there are a number of countermeasures suggested to improve safety for the segment. The two countermeasures that were chosen for the analyses in this example are the following:

- Remove on-street parking

- Install lighting.

Each of the countermeasures will be discussed in the following subsections.

5.2.1 Removing On-Street Parking

The first analysis example is to remove the on-street parking. The Basic Info worksheet of the spreadsheet for this example is shown in Figure 5-18.

Analyst	John Smith	Date	4/18/2016	Company	BYU
Route	US-89	Direction	Positive	Jurisdiction	Region 1
MP Begin	431.317	MP End	433.164		
Crash Study Begin	1/1/2010	Crash Study End	4/30/2016		
Crash Severity	Multiple Vehicle	Single Vehicle	Growth Rate on AADT	0.5%	
5 (K)	1	0			
4 (A)	5	3			
3 (B)	13	1			
2 (C)	13	4			
1 (O)	33	46			

Figure 5-18: Basic Info for Urban/Suburban 5T Arterial Example

As shown in Figure 5-18, the route, mile points beginning and end, and all of the crash

data, as well as the growth rate on AADT are all entered. Similar to the previous analysis for the

rural TLTW highway case, the crash data were obtained from the UDOT SafeMap. Similar to the

previous analysis, a growth rate of 0.5 percent is used on AADT. The roadway segment

characteristics for the existing conditions and future conditions are shown in Figure 5-19.

Roadway Segment Characteristics			
Existing Conditions		Future Conditions	
AADT	15495	AADT	17120
Total Curb Length with On Street Parking For both sides of the street (miles)	2.165	Total Curb Length with On Street Parking For both sides of the street (miles)	0
Median Width (feet) (0 for undivided)	0	Median Width (feet)	0
On-Street Parking Type	Parallel Commercial	On-Street Parking Type	Parallel Commercial
Length of roadway segment (miles)	1.847	Length of roadway segment (miles)	1.847
Offset to Fixed Objects (feet)	10	Offset to Fixed Objects (feet)	10
Fixed Object Density (Fixed Objects/mile)	30	Fixed Object Density (Fixed Objects/mile)	30
Proportion of Total Nighttime Unlighted Fatal or Injury Crashes (use 0.432 for default)	0.432	Proportion of Total Nighttime Unlighted Fatal or Injury Crashes (use 0.424 for default)	0.432
Proportion of Total Nighttime unlighted PDO crashes (use 0.468 for default)	0.468	Proportion of Total Nighttime unlighted PDO crashes (use 0.576 for default)	0.468
Proportion of total crashes for unlighted roadway segments that occur at night (use 0.274 for default)	0.274	Proportion of total crashes for unlighted roadway segments that occur at night (use 0.316 for default)	0.274
Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0	Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0
Calibration Factor (site specific, Use 1.00 for Default)	1	Calibration Factor (site specific, Use 1.00 for Default)	1

Figure 5-19: Roadway Segment Characteristics for 5T First Example

As shown in Figure 5-19, the AADT used for this analysis is taken from the two-page

report information found in Figure B-2 in Appendix B. As shown in Figure 5-19, the on-street

parking is 2.165 miles for the existing conditions, and is 0 miles for the future conditions. The

distance of 2.165 miles is determined by the user by measuring the amount of on-street parking

on both sides of the street. It is also determined by the user that the parking is parallel

commercial parking. The other values are also all obtained and entered by the user. The CMFs for this example analysis can be seen in Figure 5-20.

Crash Modification Factors			
Existing Conditions		Future Conditions	
CMF_{1r}	1.42	CMF_{1r}	1.00
CMF_{2r}	1.00	CMF_{2r}	1.00
CMF_{3r}	1.01	CMF_{3r}	1.01
CMF_{4r}	0.92	CMF_{4r}	0.92
CMF_{5r}	1.00	CMF_{5r}	1.00
Project Specific			
CMF_1	1.00	CMF_3	1.00
CMF_2	1.00	CMF_4	1.00

Figure 5-20: CMFs for 5T First Example

Figure 5-20 contains all of the CMFs are the same for both the existing and future conditions except for CMF_{1r}. The value for the existing CMF_{1r} is 1.42, while it is 1.00 for the future conditions. The observed crash frequency and crash distribution for this example analysis are found in Figure 5-21.

Observed Crash Frequency				Crash Severity Distribution	
	Crash Severity	Multiple-Vehicle	Single-Vehicle	Multiple-Vehicle	Single-Vehicle
Fatal	5 (K)	0.2	0.0	2%	0%
Injury	4 (A)	0.8	0.5	8%	6%
	3 (B)	2.1	0.2	21%	0%
	2 (C)	2.1	0.6	19%	6%
PDO	1 (O)	5.2	7.3	51%	88%
	Total	10.3	8.5	100%	100%
All Crashes Included (KABCO)					▾

Figure 5-21: Observed Crash Frequency and Crash Distribution for 5T First Example

As shown in Figure 5-21, the observed crash frequency is obtained by dividing the number of crashes found in Figure 5-18 by the number of years in the crash study period. As shown in Figure 5-21, the crash distribution included all five crash types. The results of the SPFs are shown in Figure 5-22.

Existing Crashes		Predicted Crashes	
Multiple-Vehicle Crashes			
a	-9.700	a	-9.700
b	1.17	b	1.17
k	0.810	k	0.810
w	0.0847	w	0.1159
N_{spfru}	10.2	N_{spfru}	10.2
$N_{predicted\ us}$	13.3	$N_{predicted\ us}$	9.4
Total Crashes	13.3	Total Crashes	9.4
Single-Vehicle Crashes			
a	-4.820	a	-4.820
b	0.54	b	0.54
k	0.520	k	0.520
w	0.3374	w	0.4188
N_{spfru}	2.9	N_{spfru}	2.9
$N_{predicted\ us}$	3.8	$N_{predicted\ us}$	2.7
Part C Predictive Method			
Total Number of Crashes	3.8	Total Number of Crashes	2.7

Figure 5-22: SPF Results for First 5T Example Analysis

As shown in Figure 5-22, the Part C Predictive Method is used for this example. Figure 5-23 shows the total benefits for this first countermeasure analysis.

	Crash Severity	Estimated Reduction in Crashes	Crash Severity Value (Use Options Above)	Estimated Safety Benefit
	UDOT Recommended			
5 (K)	Fatal	0.0	$ 1,982,000.00	$ 0.87
4 (A)	Incapacitating Injury	1.3	$ 1,982,000.00	$ 1,870,059.03
3 (B)	Non-incapacitating Injury	0.0	$ 123,700.00	$ 11.31
2 (C)	Possible Injury	1.3	$ 63,200.00	$ 59,640.84
1 (O)	Property Damage Only	19.1	$ 3,200.00	$ 45,316.75
	Total	21.6		$ 1,975,028.80

Figure 5-23: Total Benefits for First 5T Example

As shown in Figure 5-23, the total benefits for this analysis are $1,975,028.80. The benefits for the fatal crashes are very small. This is primarily due to the fact that the crash distribution did not include any fatal crashes since the observed crash frequency did not have any of these crashes. This is an example of where a default distribution should be used wherever possible. However, there is not a default distribution in the HSM for this roadway type. The distribution used for this example was determined using the historic crash data. Figure 5-24 shows the total cost for this countermeasure.

Initial Project Cost	$ 500,000.00
Rehabilitation Cost	$ -
Number of Years For Each Rehabilitation	1
Annual Maintenance	$ 10,000.00
Discount Rate	3%
Service Life (years)	20
Number of Maintenance Periods	20
Total Maintenance Costs Present Value	$ 148,774.75
Total Cost	$ 648,774.75

Figure 5-24: Total Costs for First 5T Example

As shown in Figure 5-24, it was estimated that this project would have an initial project cost of $500,000.00, and that the annual maintenance cost would be $10,000.00. It is expected that there would not be any rehabilitation costs during the 20 years of service life. Similar to the previous example, these costs are difficult to determine, and section 5.4 discusses this issue. As explained earlier, these spreadsheets can predict the benefits based on the crash frequencies predicted, but the costs must be carefully predicted. The users performing the analysis need to determine the costs. Figure 5-25 shows the BCR for this analysis.

B/C=	3.04
Using present worth values:	
Benefit =	$ 1,975,029
Cost =	$ 648,775

Figure 5-25: BCR for First 5T Example

As shown in Figure 5-25, the BCR is determined to be 3.04. It is determined by dividing the total benefits by the total costs. Since the BCR is greater than 1.0, this countermeasure can be considered economically viable and since the BCR is so large, this countermeasure is recommended. All of these values are brought back to the present value. The entire spreadsheet used for this example analysis for a five-lane suburban/urban arterial including a TWLTL where the on-street parking is removed is found in Figure 5-26.

Five-Lane Arterial Including a TWLTL

Roadway Segment Characteristics

Existing Conditions		Future Conditions	
AADT	15495	AADT	17120
Total Curb Length with On Street Parking For both sides of the street (miles)	2.165	Total Curb Length with On Street Parking For both sides of the street (miles)	0
Median Width (feet) (0 for undivided)	0	Median Width (feet)	0
On-Street Parking Type	Parallel Commercial ▼	On-Street Parking Type	Parallel Commercial ▼
Length of roadway segment (miles)	1.847	Length of roadway segment (miles)	1.847
Offset to Fixed Objects (feet)	10	Offset to Fixed Objects (feet)	10
Fixed Object Density (Fixed Objects/mile)	30	Fixed Object Density (Fixed Objects/mile)	30
Proportion of Total Nighttime Unlighted Fatal or Injury Crashes (use 0.432 for default)	0.432	Proportion of Total Nighttime Unlighted Fatal or Injury Crashes (use 0.424 for default)	0.432
Proportion of Total Nighttime unlighted PDO crashes (use 0.468 for default)	0.468	Proportion of Total Nighttime unlighted PDO crashes (use 0.576 for default)	0.468
Proportion of total crashes for unlighted roadway segments that occur at night (use 0.274 for default)	0.274	Proportion of total crashes for unlighted roadway segments that occur at night (use 0.316 for default)	0.274
Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0	Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0
Calibration Factor (site specific, Use 1.00 for Default)	1	Calibration Factor (site specific, Use 1.00 for Default)	1

Crash Modification Factors

Existing Conditions		Future Conditions	
CMF_{1r}	1.42	CMF_{1r}	1.00
CMF_{2r}	1.00	CMF_{2r}	1.00
CMF_{3r}	1.01	CMF_{3r}	1.01
CMF_{4r}	0.92	CMF_{4r}	0.92
CMF_{5r}	1.00	CMF_{5r}	1.00

Project Specific

CMF_1	1.00	CMF_3	1.00
CMF_2	1.00	CMF_4	1.00

Observed Crash Frequency / Crash Severity Distribution

Crash Severity		Multiple-Vehicle	Single-Vehicle	Multiple-Vehicle	Single-Vehicle
Fatal	5 (K)	0.2	0.0	2%	0%
	4 (A)	0.8	0.5	8%	6%
Injury	3 (B)	2.1	0.2	21%	0%
	2 (C)	2.1	0.6	19%	6%
PDO	1 (O)	5.2	7.3	51%	88%
	Total	10.3	8.5	100%	100%

All Crashes Included (KABCO) ▼

Existing Crashes / Predicted Crashes

Multiple-Vehicle Crashes

	Existing Crashes		Predicted Crashes
a	-9.700	a	-9.700
b	1.17	b	1.17
k	0.810	k	0.810
w	0.0847	w	0.1159
N_{spfru}	10.2	N_{spfru}	10.2
$N_{predicted\ us}$	13.3	$N_{predicted\ us}$	9.4
Total Crashes	13.3	Total Crashes	9.4

Single-Vehicle Crashes

a	-4.820	a	-4.820
b	0.54	b	0.54
k	0.520	k	0.520
w	0.3374	w	0.4188
N_{spfru}	2.9	N_{spfru}	2.9
$N_{predicted\ us}$	3.8	$N_{predicted\ us}$	2.7
Part C Predictive Method ▼			
Total Number of Crashes	3.8	Total Number of Crashes	2.7

UDOT Recommended ▼

Crash Severity		Estimated Reduction in Crashes	Crash Severity Value (Use Options Above)	Estimated Safety Benefit
5 (K)	Fatal	0.0	$ 1,982,000.00	$ 0.87
4 (A)	Incapacitating Injury	1.3	$ 1,982,000.00	$ 1,870,059.03
3 (B)	Non-incapacitating Injury	0.0	$ 123,700.00	$ 11.31
2 (C)	Possible Injury	1.3	$ 63,200.00	$ 59,640.84
1 (O)	Property Damage Only	19.1	$ 3,200.00	$ 45,316.75
	Total	21.6		$ 1,975,028.80

Initial Project Cost	$ 500,000.00
Rehabilitation Cost	$ -
Number of Years For Each Rehabilitation	1
Annual Maintenance	$ 10,000.00
Discount Rate	3%
Service Life (years)	20
Number of Maintenance Periods	20
Total Maintenance Costs Present Value	$ 148,774.75
Total Cost	$ 648,774.75

[Calculate Benefit/Cost Ratio]   [Print BCR Report]

B/C=	3.04

Using present worth values:

Benefit =	$ 1,975,029
Cost =	$ 648,775

Figure 5-26: Entire 5T Spreadsheet for First 5T Example

5.2.2 Installation of Roadway Lighting

The second example is installation of roadway lighting. The basic info section for this analysis are found in Figure 5-18 since the information is the same, only the countermeasure being instituted will change. The roadway segment characteristics for this second example analysis are found in Figure 5-27.

Roadway Segment Characteristics			
Existing Conditions		**Future Conditions**	
AADT	15495	AADT	17120
Total Curb Length with On Street Parking For both sides of the street (miles)	2.165	Total Curb Length with On Street Parking For both sides of the street (miles)	2.165
Median Width (feet) (0 for undivided)	0	Median Width (feet)	0
On-Street Parking Type	Parallel Commercial ▾	On-Street Parking Type	Parallel Commercial ▾
Length of roadway segment (miles)	1.847	Length of roadway segment (miles)	1.847
Offset to Fixed Objects (feet)	10	Offset to Fixed Objects (feet)	10
Fixed Object Density (Fixed Objects/mile)	30	Fixed Object Density (Fixed Objects/mile)	30
Proportion of Total Nighttime Unlighted Fatal or Injury Crashes (use 0.432 for default)	0.432	Proportion of Total Nighttime Unlighted Fatal or Injury Crashes (use 0.424 for default)	0.432
Proportion of Total Nighttime unlighted PDO crashes (use 0.468 for default)	0.468	Proportion of Total Nighttime unlighted PDO crashes (use 0.576 for default)	0.468
Proportion of total crashes for unlighted roadway segments that occur at night (use 0.274 for default)	0.274	Proportion of total crashes for unlighted roadway segments that occur at night (use 0.316 for default)	0.274
Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0	Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0
Calibration Factor (site specific, Use 1.00 for Default)	1	Calibration Factor (site specific, Use 1.00 for Default)	1

Figure 5-27: Roadway Segment Characteristics for Second 5T Example

As shown in Figure 5-27, all of the existing and future conditions are the same. These conditions are the same because the CMF for installing roadway lighting is not included in the Part C Predictive Method for this roadway type is not included in the HSM. Figure 5-28 shows the CMF developed by UDOT and used for this analysis. As shown in Figure 5-28, all of the first five CMFs that are determined by the Part C Predictive Method are the same for both existing and future conditions. Only CMF_1 from the Project Specific section has changed. As shown in

Figure 5-28, the value for this CMF has been changed to 0.72, which is the CMF that was determined by UDOT regarding installing roadway lighting.

Crash Modification Factors			
Existing Conditions		Future Conditions	
CMF_{1r}	1.42	CMF_{1r}	1.42
CMF_{2r}	1.00	CMF_{2r}	1.00
CMF_{3r}	1.01	CMF_{3r}	1.01
CMF_{4r}	0.92	CMF_{4r}	0.92
CMF_{5r}	1.00	CMF_{5r}	1.00
Project Specific			
CMF_1	0.72	CMF_3	1.00
CMF_2	1.00	CMF_4	1.00

Figure 5-28: CMFs for Second 5T Example Analysis

The observed crash frequency and crash distribution are the same for this example analysis as they were for the previous example analysis. Figure 5-21 shows these values and Figure 5-29 shows the results of the SPFs. As shown in Figure 5-29, the Part C Predictive Method is used. The total benefits for this analysis are shown in Figure 5-30. As shown in Figure 5-30, the total benefits for this analysis are $1,883,843.08. Similar to the previous example analysis, the benefit values for fatal crashes were very small. This is because there is no default distribution, and so the observed crash frequency is used to determine the distribution. Figure 5-31 shows the total cost for this analysis.

Existing Crashes		Predicted Crashes	
Multiple-Vehicle Crashes			
a	-9.700	a	-9.700
b	1.17	b	1.17
k	0.810	k	0.810
w	0.0847	w	0.1139
N_{spfru}	10.2	N_{spfru}	10.2
$N_{predicted\ us}$	13.3	$N_{predicted\ us}$	9.6
Total Crashes	13.3	Total Crashes	9.6
Single-Vehicle Crashes			
a	-4.820	a	-4.820
b	0.54	b	0.54
k	0.520	k	0.520
w	0.3374	w	0.4142
N_{spfru}	2.9	N_{spfru}	2.9
$N_{predicted\ us}$	3.8	$N_{predicted\ us}$	2.7
Part C Predictive Method ▾			
Total Number of Crashes	3.8	Total Number of Crashes	2.7

Figure 5-29: SPF Results for Second 5T Example

		UDOT Recommended ▾	
Crash Severity		Estimated Reduction in Crashes	Crash Severity Value (Use Options Above)	Estimated Safety Benefit
5 (K)	Fatal	0.0	$ 1,982,000.00	$ 0.83
4 (A)	Incapacitating Injury	1.2	$ 1,982,000.00	$ 1,783,719.69
3 (B)	Non-incapacitating Injury	0.0	$ 123,700.00	$ 10.79
2 (C)	Possible Injury	1.2	$ 63,200.00	$ 56,887.26
1 (O)	Property Damage Only	18.2	$ 3,200.00	$ 43,224.51
Total		20.6		$ 1,883,843.08

Figure 5-30: Total Benefits for Second 5T Example

Initial Project Cost	$	250,000.00
Rehabilitation Cost	$	-
Number of Years For Each Rehabilitation		1
Annual Maintenance	$	10,000.00
Discount Rate		3%
Service Life (years)		20
Number of Maintenance Periods		20
Total Maintenance Costs Present Value	$	148,774.75
Total Cost	$	398,774.75

Figure 5-31: Total Costs for Second 5T Example

As shown in Figure 5-31, the total initial project cost is estimated to be $250,000.00. This

value is determined because it is assumed that the lighting would not be a very expensive

countermeasure. As explained previously, the costs associated with these countermeasures are at

the discretion of the user, and this spreadsheet program does not contain a cost estimation,

module or routine. Figure 5-32 shows the BCR computed for this analysis.

B/C=	4.72
Using present worth values:	
Benefit =	$ 1,883,843
Cost =	$ 398,775

Figure 5-32: BCR for Second 5T Example

As shown in Figure 5-32, the BCR for this second analysis is 4.72. This means that

though the benefits for this countermeasure are lower than for removing the on-street parking,

the BCR is still higher because the installation of roadway lighting costs much less than the

removal of on-street parking. The entire spreadsheet that is used for this analysis is found in Figure 5-33.

Five-Lane Arterial Including a TWLTL

Roadway Segment Characteristics				Crash Modification Factors			
Existing Conditions		**Future Conditions**		**Existing Conditions**		**Future Conditions**	
AADT	15495	AADT	17120	CMF$_{1r}$	1.42	CMF$_{1r}$	1.42
Total Curb Length with On Street Parking For both sides of the street (miles)	2.165	Total Curb Length with On Street Parking For both sides of the street (miles)	2.165	CMF$_{2r}$	1.00	CMF$_{2r}$	1.00
Median Width (feet) (0 for undivided)	0	Median Width (feet)	0	CMF$_{3r}$	1.01	CMF$_{3r}$	1.01
On-Street Parking Type	Parallel Commercial	On-Street Parking Type	Parallel Commercial	CMF$_{4r}$	0.92	CMF$_{4r}$	0.92
Length of roadway segment (miles)	1.847	Length of roadway segment (miles)	1.847	CMF$_{5r}$	1.00	CMF$_{5r}$	1.00
Offset to Fixed Objects (feet)	10	Offset to Fixed Objects (feet)	10	**Project Specific**			
Fixed Object Density (Fixed Objects/mile)	30	Fixed Object Density (Fixed Objects/mile)	30	CMF$_1$	0.72	CMF$_3$	1.00
Proportion of Total Nighttime Unlighted Fatal or Injury Crashes (use 0.432 for default)	0.432	Proportion of Total Nighttime Unlighted Fatal or Injury Crashes (use 0.424 for default)	0.432	CMF$_2$	1.00	CMF$_4$	1.00
Proportion of Total Nighttime unlighted PDO crashes (use 0.468 for default)	0.468	Proportion of Total Nighttime unlighted PDO crashes (use 0.576 for default)	0.468				
Proportion of total crashes for unlighted roadway segments that occur at night (use 0.274 for default)	0.274	Proportion of total crashes for unlighted roadway segments that occur at night (use 0.316 for default)	0.274	**Existing Crashes**		**Predicted Crashes**	
Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0	Presence of Automated Speed Enforcement (1 if yes, 0 if no)	0	**Multiple-Vehicle Crashes**			
Calibration Factor (site specific, Use 1.00 for Default)	1	Calibration Factor (site specific, Use 1.00 for Default)	1	a	-9.700	a	-9.700

				b	1.17	b	1.17
Observed Crash Frequency				k	0.810	k	0.810
				w	0.0847	w	0.1139
Crash Severity	**Multiple-Vehicle**	**Single-Vehicle**		N$_{spfru}$	10.2	N$_{spfru}$	10.2

	Crash Severity	Multiple-Vehicle	Single-Vehicle	Multiple-Vehicle	Single-Vehicle
Fatal	5 (K)	0.2	0.0	2%	0%
	4 (A)	0.8	0.5	8%	6%
Injury	3 (B)	2.1	0.2	21%	0%
	2 (C)	2.1	0.6	19%	6%
PDO	1 (O)	5.2	7.3	51%	88%
	Total	10.3	8.5	100%	100%

	Crash Severity Distribution			
Multiple-Vehicle		**Single-Vehicle**	N$_{predicted us}$	13.3	N$_{predicted us}$	9.6
Total Crashes	13.3	Total Crashes	9.6

Single-Vehicle Crashes			
a	-4.820	a	-4.820
b	0.54	b	0.54
k	0.520	k	0.520
w	0.3374	w	0.4142
N$_{spfru}$	2.9	N$_{spfru}$	2.9
N$_{predicted us}$	3.8	N$_{predicted us}$	2.7

All Crashes Included (KABCO)

Part C Predictive Method

Total Number of Crashes	3.8	Total Number of Crashes	2.7

UDOT Recommended

Crash Severity	Estimated Reduction in Crashes	Crash Severity Value (Use Options Above)	Estimated Safety Benefit
5 (K) Fatal	0.0	$ 1,982,000.00	$ 0.83
4 (A) Incapacitating Injury	1.2	$ 1,982,000.00	$ 1,783,719.69
3 (B) Non-incapacitating Injury	0.0	$ 123,700.00	$ 10.79
2 (C) Possible Injury	1.2	$ 63,200.00	$ 56,887.26
1 (O) Property Damage Only	18.2	$ 3,200.00	$ 43,224.51
Total	20.6		$ 1,883,843.08

Initial Project Cost	$ 250,000.00
Rehabilitation Cost	$ -
Number of Years For Each Rehabilitation	1
Annual Maintenance	$ 10,000.00
Discount Rate	3%
Service Life (years)	20
Number of Maintenance Periods	20
Total Maintenance Costs Present Value	$ 148,774.75
Total Cost	$ 398,774.75

Calculate Benefit/Cost Ratio

Print BCR Report

B/C=	**4.72**
Using present worth values:	
Benefit =	**$ 1,883,843**
Cost =	**$ 398,775**

Figure 5-33: Entire Spreadsheet for Second 5T Example

5.3 Freeway Segment Example

This section presents two different countermeasure analyses using a freeway segment. The freeway segment used for this example is I-15 in Salt Lake County in Region 2. The Hot Spot Two Page Report from the UCPM can be seen in Figure B-3 in Appendix B. This segment ranked 4th in the ranking produced by the UCPM (Schultz et al. 2015). The procedures used for the calculations in this freeway spreadsheet are from the Supplement of the HSM (AASHTO 2014). The Basic Info for this freeway segment and for both analyses are found in Figure 5-34.

Analyst	John Smith	Date	4/18/2016	Company	BYU
Route	I-15	Direction	Positive	Jurisdiction	Region 2
MP Begin	292.596	MP End	293.634		
Crash Study Begin	1/1/2010	Crash Study End	4/30/2016		
Crash Severity	Multiple Vehicle	Single Vehicle	Growth Rate on AADT	0.5%	
5 (K)	0	0	(Default is 0.5%)		
4 (A)	0	1			
3 (B)	5	4			
2 (C)	21	4			
1 (O)	102	41			

Figure 5-34: Basic Info for Freeway Segment Example

As shown in Figure 5-34, the information for the mile points and route can be found in Figure B-3. The crash data for this analysis was taken from the UDOT SafeMap (UDOT 2016). As shown in Figure B.3, there are multiple countermeasures that are noted to increase the safety on this roadway segment. The two countermeasures analyzed as examples in this section are the following:

- Install inside and outside shoulder rumble strips

- Implement automated speed enforcement.

5.3.1 Installation of Inside and Outside Shoulder Rumble Strips

The roadway segment characteristics for the first countermeasure involving installing center line and shoulder rumble strips can be seen in Figure 5-35. As can be seen in Figure 5-35, the value for the segment with shoulder rumble strips and center line rumble strips is 0 miles for the existing conditions, while it is 2.076 miles long for the future conditions. There are rumble strips in both directions, so the total length of the inside and outside rumble strip segments becomes 2.076 miles, though the segment analyzed is 1.038 miles.

The CMFs that are used for this analysis are found in Figure 5-36. As shown in Figure 5-36, all of the CMFs are the same for both the existing and future conditions except for CMF_{6fs} for the single vehicle CMFs, which is 1.00 for existing and has been switched to 0.62 for the future conditions. This means that only the single vehicle crashes will see a change. The observed crash frequency and crash distribution for this analysis are shown in Figure 5-37.

As shown in Figure 5-37, the observed crash frequency is determined by the crash data entered in the Basic Info worksheet. Figure 5-37 also shows that all crashes except PDO crashes are considered because the HSM Part C Predictive Method for freeways does not include SPFs for total crashes. The crash distribution was determined using the observed crash frequency data. Figure 5-38 shows the results of the SPFs.

As shown in Figure 5-38, the Part C Predictive Method is used for this example analysis. Figure 5-38 also shows that the multiple vehicle crashes did not change from the existing to future conditions since the CMF associated with rumble strips only affects single vehicle crashes. Figure 5-39 shows the total benefits computed for this analysis. As was done in the previous examples, the UDOT recommended severity values were used for this example analysis.

Roadway Segment Characteristics			
Existing Conditions		Future Conditions	
AADT	157,325	AADT (assuming 0.5% growth rate)	173828
Lane Width (ft)	12	Lane Width (ft)	12
Inside Shoulder Width (ft)	11	Inside Shoulder Width (ft)	11
Rural or Urban	Urban	Rural or Urban	Urban
Horizontal Curves	No	Horizontal Curves	No
Lane Change	No	Lane Change	No
Freeway Segment Length (miles)	1.0380	Freeway Segment Length (miles)	1.0380
Number of Lanes	10	Number of Lanes	10
Total Exit Ramps Length (miles)	0.616	Total Exit Ramps Length (miles)	0.616
Total Entrance Ramps Length (miles)	0.417	Total Entrance Ramps Length (miles)	0.417
Median Width (ft)	0	Median Width (ft)	0
Median Length (miles)	0	Median Length (miles)	0
Distance from Edge of Inside Shoulder to Barrier Face (ft)	12	Distance from Edge of Inside Shoulder to Barrier Face (ft)	12
Paved Outside Shoulder Width (ft)	12	Paved Outside Shoulder Width (ft)	12
Segment Length with Rumble Strips on Inside Shoulder (miles)	0.000	Segment Length with Rumble Strips on Inside Shoulder (miles)	2.076
Segment Length with Rumble Strips on Outside Shoulder (miles)	0.000	Segment Length with Rumble Strips on Outside Shoulder (miles)	2.076
Segment Length with Barrier Present (miles)	1.038	Segment Length with Barrier Present (miles)	1.038
Clear Zone Width (ft)	30	Clear Zone Width (ft)	30
Distance from Edge of Outside Shoulder to Barrier Face (ft)	0	Distance from Edge of Outside Shoulder to Barrier Face (ft)	0
Number of Hours per day that flow rates exceed 1,000 vphpln	13	Number of Hours per day that flow rates exceed 1,000 vphpln	13
Calibration Factor (site specific, Use 1.00 for Default)	1	Calibration Factor (site specific, Use 1.00 for Default)	1

Figure 5-35: Roadway Segment Characteristics for First Freeway Segment Example

Crash Modification Factors					
Existing Conditions			**Future Conditions**		
Crash Type	Multiple Vehicle	Single Vehicle	Crash Type	Multiple Vehicle	Single Vehicle
CMF_{1fs}	1.00	1.00	CMF_{1fs}	1.00	1.00
CMF_{2fs}	1.00	1.00	CMF_{2fs}	1.00	1.00
CMF_{3fs}	0.92	0.92	CMF_{3fs}	0.92	0.92
CMF_{4fs}	0.80	1.08	CMF_{4fs}	0.80	1.08
CMF_{5fs}	1.00	1.00	CMF_{5fs}	1.00	1.00
CMF_{6fs}	1.21	0.96	CMF_{6fs}	1.21	0.96
CMF_{7fs}	1.00	1.00	CMF_{7fs}	1.00	1.00
CMF_{8fs}	1.00	0.88	CMF_{8fs}	1.00	0.88
CMF_{9fs}	1.00	1.00	CMF_{9fs}	1.00	0.62
CMF_{10fs}	1.00	1.09	CMF_{10fs}	1.00	1.09
CMF_{11fs}	1.00	1.00	CMF_{11fs}	1.00	1.00
CMF_{12fs}	1.00	1.00	CMF_{12fs}	1.00	1.00
CMF_{13fs}	1.00	1.00	CMF_{13fs}	1.00	1.00
Project Specific					
CMF_1	1.00	CMF_2	1.00	CMF_3	1.00

Figure 5-36: CMFs for First Freeway Segment Example

Observed Crash Frequency				Crash Severity Distribution	
	Crash Severity	Multiple-Vehicle	Single-Vehicle	Multiple-Vehicle	Single-Vehicle
Fatal	5 (K)	0.0	0.0	0%	0%
Injury	4 (A)	0.0	0.2	0%	11%
	3 (B)	0.8	0.6	19%	44%
	2 (C)	3.3	0.6	81%	44%
PDO	1 (O)	16.1	6.5	0%	0%
	Total	20.2	7.9	100%	100%
All Crashes Except PDO (KABC)					

Figure 5-37: Observed Crash Frequency and Crash Distribution for Freeway Examples

	Existing Crashes			Predicted Crashes		
Crash Type	Multiple Vehicle	Single Vehicle	Crash Type	Multiple Vehicle	Single Vehicle
L*	0.522	0.522	L*	0.522	0.522
a	-5.842	-1.915	a	-5.842	-1.915
b	1.492	0.646	b	1.492	0.646
c	0.001	0.001	c	0.001	0.001
k	0.109	0.064	k	0.109	0.064
w	0.1929	0.3796	w	0.1929	0.4950
N_{spfru}	3.3	2.2	N_{spfru}	3.3	2.2
$N_{predicted\ us}$	38.4	25.7	$N_{predicted\ us}$	38.4	16.0
Part C Predictive Method ▼					
Total Number of Crashes	38.4	25.7	Total Number of Crashes	38.4	16.0

Figure 5-38: SPF Results for First Freeway Segment Example

		UDOT Recommended ▼		
	Crash Severity	Estimated Reduction in Crashes	Crash Severity Value (Use Options Above)	Estimated Safety Benefit
5 (K)	Fatal	0.0	$ 1,982,000.00	$ -
4 (A)	Incapacitating Injury	19.8	$ 1,982,000.00	$ 28,634,815.17
3 (B)	Non-incapacitating Injury	79.2	$ 123,700.00	$ 7,148,590.59
2 (C)	Possible Injury	79.2	$ 63,200.00	$ 3,652,311.44
1 (O)	Property Damage Only	0.0	$ 3,200.00	$ -
	Total	178.2		$ 39,435,717.20

Figure 5-39: Total Benefits for First Freeway Segment Example

As shown in Figure 5-39, the total benefits for this analysis are $39,435,717.20. Figure 5-39 also shows that there is no benefit for fatal crashes or PDO crashes. This is because PDO crashes are not included in this analysis as explained previously, and because there are no fatal crashes observed on this freeway segment. Since the crash distribution was determined using the

observed crash frequency, the fatal crashes are assumed to be zero. Figure 5-40 shows the total

costs for this analysis.

As shown in Figure 5-40, the initial cost is estimated to be $10,000,000.00. Similar to

other instances, this value is merely an educated guess, and is not meant to be used for an actual

analysis. The annual maintenance cost is estimated to be $50,000.00. The total costs after being

brought to present value are $10,743,873.74. The BCR for this analysis is shown in Figure 5-41.

As shown in Figure 5-41, the total benefit is divided by the total cost. The resulting BCR

is 3.67. This means that there will be 3.67 times more benefit than cost associated with this

countermeasure. Since the BCR is greater than 1.0, this treatment can be considered acceptable.

If this BCR is greater than the BCR for all of the other countermeasures, this countermeasure

would be the preferred countermeasure. As mentioned previously, the costs for this analysis are

estimates and for illustration purposes only. It may be that the costs are considerably larger or

smaller than what was used in this example analysis. The entire spreadsheet that is used for this

example analysis is shown in Figure 5-42.

Initial Project Cost	$ 10,000,000.00
Maintenance Cost Per Period	
Number of Years For Each Maintenance	5
Annual Maintenance	$ 50,000.00
Discount Rate	3%
Service Life (years)	20
Number of Maintenance Periods	4
Total Maintenance Costs Present Value	$ 743,873.74
Total Cost	$ 10,743,873.74

Figure 5-40: Total Costs for First Freeway Segment Example

B/C=	3.67
Using present worth values:	
Benefit =	$ 39,435,717
Cost =	$ 10,743,874

Figure 5-41: BCR for First Freeway Segment Example

Freeway Segment

Roadway Segment Characteristics

Existing Conditions		Future Conditions	
AADT	157,325	AADT (assuming 0.5% growth rate)	173828
Lane Width (ft)	12	Lane Width (ft)	12
Inside Shoulder Width (ft)	11	Inside Shoulder Width (ft)	11
Rural or Urban	Urban	Rural or Urban	Urban
Horizontal Curves	No	Horizontal Curves	No
Lane Change	No	Lane Change	No
Freeway Segment Length (miles)	1.0380	Freeway Segment Length (miles)	1.0380
Number of Lanes	10	Number of Lanes	10
Total Exit Ramps Length (miles)	0.616	Total Exit Ramps Length (miles)	0.616
Total Entrance Ramps Length (miles)	0.417	Total Entrance Ramps Length (miles)	0.417
Median Width (ft)	0	Median Width (ft)	0
Median Length (miles)	0	Median Length (miles)	0
Distance from Edge of Inside Shoulder to Barrier Face (ft)	12	Distance from Edge of Inside Shoulder to Barrier Face (ft)	12
Paved Outside Shoulder Width (ft)	12	Paved Outside Shoulder Width (ft)	12
Segment Length with Rumble Strips on Inside Shoulder (miles)	0.000	Segment Length with Rumble Strips on Inside Shoulder (miles)	2.076
Segment Length with Rumble Strips on Outside Shoulder (miles)	0.000	Segment Length with Rumble Strips on Outside Shoulder (miles)	2.076
Segment Length with Barrier Present (miles)	1.038	Segment Length with Barrier Present (miles)	1.038
Clear Zone Width (ft)	30	Clear Zone Width (ft)	30
Distance from Edge of Outside Shoulder to Barrier Face (ft)	0	Distance from Edge of Outside Shoulder to Barrier Face (ft)	0
Number of Hours per day that flow rates exceed 1,000 vphpln	13	Number of Hours per day that flow rates exceed 1,000 vphpln	13
Calibration Factor (site specific, Use 1.00 for Default)	1	Calibration Factor (site specific, Use 1.00 for Default)	1

Crash Modification Factors

Existing Conditions			Future Conditions		
Crash Type	Multiple Vehicle	Single Vehicle	Crash Type	Multiple Vehicle	Single Vehicle
CMF_{1fs}	1.00	1.00	CMF_{1fs}	1.00	1.00
CMF_{2fs}	1.00	1.00	CMF_{2fs}	1.00	1.00
CMF_{3fs}	0.92	0.92	CMF_{3fs}	0.92	0.92
CMF_{4fs}	0.80	1.08	CMF_{4fs}	0.80	1.08
CMF_{5fs}	1.00	1.00	CMF_{5fs}	1.00	1.00
CMF_{6fs}	1.21	0.96	CMF_{6fs}	1.21	0.96
CMF_{7fs}	1.00	1.00	CMF_{7fs}	1.00	1.00
CMF_{8fs}	1.00	0.88	CMF_{8fs}	1.00	0.88
CMF_{9fs}	1.00	1.00	CMF_{9fs}	1.00	0.62
CMF_{10fs}	1.00	1.09	CMF_{10fs}	1.00	1.09
CMF_{11fs}	1.00	1.00	CMF_{11fs}	1.00	1.00
CMF_{12fs}	1.00	1.00	CMF_{12fs}	1.00	1.00
CMF_{13fs}	1.00	1.00	CMF_{13fs}	1.00	1.00

Project Specific				
CMF_1	1.00	CMF_2	1.00	CMF_3	1.00

Observed Crash Frequency / Crash Severity Distribution

	Crash Severity	Multiple-Vehicle	Single-Vehicle	Multiple-Vehicle	Single-Vehicle
Fatal	5 (K)	0.0	0.0	0%	0%
Injury	4 (A)	0.0	0.2	0%	11%
	3 (B)	0.8	0.6	19%	44%
	2 (C)	3.3	0.6	81%	44%
PDO	1 (O)	16.1	6.5	0%	0%
	Total	20.2	7.9	100%	100%

All Crashes Except PDO (KABC)

Existing Crashes			Predicted Crashes		
Crash Type	Multiple Vehicle	Single Vehicle	Crash Type	Multiple Vehicle	Single Vehicle
L*	0.522	0.522	L*	0.522	0.522
a	-5.842	-1.915	a	-5.842	-1.915
b	1.492	0.646	b	1.492	0.646
c	0.001	0.001	c	0.001	0.001
k	0.109	0.064	k	0.109	0.064
w	0.1929	0.3796	w	0.1929	0.4950
N_{spfru}	3.3	2.2	N_{spfru}	3.3	2.2
$N_{predicted\ us}$	38.4	25.7	$N_{predicted\ us}$	38.4	16.0

Part C Predictive Method

Total Number of Crashes	38.4	25.7	Total Number of Crashes	38.4	16.0

UDOT Recommended

Crash Severity	Estimated Reduction in Crashes	Crash Severity Value (Use Options Above)	Estimated Safety Benefit
5 (K) Fatal	0.0	$ 1,982,000.00	$ -
4 (A) Incapacitating Injury	19.8	$ 1,982,000.00	$ 28,634,815.17
3 (B) Non-incapacitating Injury	79.2	$ 123,700.00	$ 7,148,590.59
2 (C) Possible Injury	79.2	$ 63,200.00	$ 3,652,311.44
1 (O) Property Damage Only	0.0	$ 3,200.00	$ -
Total	178.2		$ 39,435,717.20

Initial Project Cost	$ 10,000,000.00
Maintenance Cost Per Period	$ -
Number of Years For Each Maintenance	5
Annual Maintenance	$ 50,000.00
Discount Rate	3%
Service Life (years)	20
Number of Maintenance Periods	4
Total Maintenance Costs Present Value	$ 743,873.74
Total Cost	$ 10,743,873.74

Calculate Benefit/Cost Ratio

Print BCR Report

B/C=	3.67
Using present worth values:	
Benefit =	$ 39,435,717
Cost =	$ 10,743,874

Figure 5-42: Entire Spreadsheet for First Freeway Segment Example

94

5.3.2 Implementation of Automated Speed Enforcement

The second example analysis for this freeway spreadsheet is to introduce automated speed enforcement. It is understood that automated speed enforcement is not practiced in Utah; however, it is included in this report simply for instructional and educational purposes. The Basic Info worksheet for this analysis is the same as it is for the first analysis. Figure 5-43 shows the Roadway Segment Characteristics section of the worksheet.

Roadway Segment Characteristics			
Existing Conditions		Future Conditions	
AADT	157,325	AADT (assuming 0.5% growth rate)	173828
Lane Width (ft)	12	Lane Width (ft)	12
Inside Shoulder Width (ft)	11	Inside Shoulder Width (ft)	11
Rural or Urban	Urban ▾	Rural or Urban	Urban ▾
Horizontal Curves	No	Horizontal Curves	No
Lane Change	No	Lane Change	No
Freeway Segment Length (miles)	1.0380	Freeway Segment Length (miles)	1.0380
Number of Lanes	10 ▾	Number of Lanes	10 ▾
Total Exit Ramps Length (miles)	0.616	Total Exit Ramps Length (miles)	0.616
Total Entrance Ramps Length (miles)	0.417	Total Entrance Ramps Length (miles)	0.417
Median Width (ft)	0	Median Width (ft)	0
Median Length (miles)	0	Median Length (miles)	0
Distance from Edge of Inside Shoulder to Barrier Face (ft)	12	Distance from Edge of Inside Shoulder to Barrier Face (ft)	12
Paved Outside Shoulder Width (ft)	12	Paved Outside Shoulder Width (ft)	12
Segment Length with Rumble Strips on Inside Shoulder (miles)	0	Segment Length with Rumble Strips on Inside Shoulder (miles)	0
Segment Length with Rumble Strips on Outside Shoulder (miles)	0	Segment Length with Rumble Strips on Outside Shoulder (miles)	0
Segment Length with Barrier Present (miles)	1.038	Segment Length with Barrier Present (miles)	1.038
Clear Zone Width (ft)	30	Clear Zone Width (ft)	30
Distance from Edge of Outside Shoulder to Barrier Face (ft)	0	Distance from Edge of Outside Shoulder to Barrier Face (ft)	0
Number of Hours per day that flow rates exceed 1,000 vphpln	13	Number of Hours per day that flow rates exceed 1,000 vphpln	13
Calibration Factor (site specific, Use 1.00 for Default)	1	Calibration Factor (site specific, Use 1.00 for Default)	1

Figure 5-43: Roadway Segment Characteristics for Second Freeway Example

95

As shown in Figure 5-43, the characteristics for this countermeasure are the same for both the existing and future conditions because this analysis is to determine the effectiveness of putting in automated speed enforcement. This countermeasure is not included in the freeway segment Part C Predictive Method in the HSM. Figure 5-44 shows the CMFs that are used for this analysis.

Crash Modification Factors					
Existing Conditions			Future Conditions		
Crash Type	Multiple Vehicle	Single Vehicle	Crash Type	Multiple Vehicle	Single Vehicle
CMF_{1fs}	1.00	1.00	CMF_{1fs}	1.00	1.00
CMF_{2fs}	1.00	1.00	CMF_{2fs}	1.00	1.00
CMF_{3fs}	0.92	0.92	CMF_{3fs}	0.92	0.92
CMF_{4fs}	0.80	1.08	CMF_{4fs}	0.80	1.08
CMF_{5fs}	1.00	1.00	CMF_{5fs}	1.00	1.00
CMF_{6fs}	1.21	0.96	CMF_{6fs}	1.21	0.96
CMF_{7fs}	1.00	1.00	CMF_{7fs}	1.00	1.00
CMF_{8fs}	1.00	0.88	CMF_{8fs}	1.00	0.88
CMF_{9fs}	1.00	1.00	CMF_{9fs}	1.00	1.00
CMF_{10fs}	1.00	1.09	CMF_{10fs}	1.00	1.09
CMF_{11fs}	1.00	1.00	CMF_{11fs}	1.00	1.00
CMF_{12fs}	1.00	1.00	CMF_{12fs}	1.00	1.00
CMF_{13fs}	1.00	1.00	CMF_{13fs}	1.00	1.00
Project Specific					
CMF_1	0.95	CMF_2	1.00	CMF_3	1.00

Figure 5-44: CMFs for Second Freeway Example

As shown in Figure 5-44, the only CMF that has changed is one of the project specific CMFs. This has changed from 1.00 to 0.95 as can be seen by comparing Figure 5-44 to Figure 5-

36. 0.95 is the value of the CMF that is associated with automated speed enforcement obtained from the HSM (AASHTO 2010c). The observed crash frequency and crash distribution are the same as they are for the first countermeasure. Figure 5-45 shows the results of the SPF calculations for this analysis.

Existing Crashes			Predicted Crashes		
Crash Type	Multiple Vehicle	Single Vehicle	Crash Type	Multiple Vehicle	Single Vehicle
L*	0.522	0.522	L*	0.522	0.522
a	-5.842	-1.915	a	-5.842	-1.915
b	1.492	0.646	b	1.492	0.646
c	0.001	0.001	c	0.001	0.001
k	0.109	0.064	k	0.109	0.064
w	0.1929	0.3796	w	0.2011	0.3918
N_{spfru}	3.3	2.2	N_{spfru}	3.3	2.2
$N_{predicted\ us}$	38.4	25.7	$N_{predicted\ us}$	36.5	24.4
Part C Predictive Method ⌄					
Total Number of Crashes	38.4	25.7	Total Number of Crashes	36.5	24.4

Figure 5-45: SPF Results for Second Freeway Segment Example

As shown in Figure 5-45, the Part C Predictive Method is used for this analysis. As can also be seen in Figure 5-45, both the multiple vehicle crashes and single vehicle crashes are reduced when comparing the number of existing crashes and the number of future crashes. Figure 5-46 shows the total benefits associated with this countermeasure.

		UDOT Recommended		
Crash Severity		Estimated Reduction in Crashes	Crash Severity Value (Use Options Above)	Estimated Safety Benefit
5 (K)	Fatal	0.0	$ 1,982,000.00	$ -
4 (A)	Incapacitating Injury	2.6	$ 1,982,000.00	$ 3,808,849.29
3 (B)	Non-incapacitating Injury	17.4	$ 123,700.00	$ 950,871.90
2 (C)	Possible Injury	39.5	$ 63,200.00	$ 485,830.91
1 (O)	Property Damage Only	0.0	$ 3,200.00	$ -
Total		59.5		$ 5,245,552.10

Figure 5-46: Total Benefits for Second Freeway Segment Example

As shown in Figure 5-46, the total benefits for this countermeasure are determined to be $5,245,391.63. Figure 5-46 also shows that there are no benefits for the fatal crashes and PDO crashes because the Part C Predictive Method does not predict for all crashes, and there are no observed fatalities on this freeway segment during the crash study period. This results in the Figure 5-47 shows the total costs associated with this countermeasure.

Initial Project Cost	$ 500,000.00
Maintenance Cost Per Period	$ -
Number of Years For Each Maintenance	5
Annual Maintenance	$ 5,000.00
Discount Rate	3%
Service Life (years)	20
Number of Maintenance Periods	4
Total Maintenance Costs Present Value	$ 74,387.37
Total Cost	$ 574,387.37

Figure 5-47: Total Costs for Second Freeway Segment Example

As shown in Figure 5-47, the total costs associated with this countermeasure were estimated to be $574,387.37. The initial cost is estimated to be $500,000.00 and the annual maintenance cost is assumed to be $5,000.00 as the speed cameras and other equipment will need to be cleaned and repaired. Figure 5-48 shows the resulting BCR for this countermeasure.

B/C=	9.13
Using present worth values:	
Benefit =	$ 5,245,552
Cost =	$ 574,387

Figure 5-48: BCR for Second Freeway Segment Example

As shown in Figure 5-48, the BCR for this analysis is 9.13. This means that this countermeasure will provide 9.13 times more benefit than the costs of the countermeasure. Note that the BCR is an estimate because the cost entered is an estimated value to explain the analysis procedure. Figure 5-49 shows the entire spreadsheet used for this analysis.

If all entries are accurate and reliable, this would mean that the automated speed enforcement would be able to provide the highest BCR (see Figure 5-41) though the benefits would be much higher with the installation of rumble strips. The reason for this higher BCR is because the costs associated with the rumble strips are so much higher than the costs associated with automated speed enforcement.

Freeway Segment

Roadway Segment Characteristics

Existing Conditions		Future Conditions	
AADT	157,325	AADT (assuming 0.5% growth rate)	173828
Lane Width (ft)	12	Lane Width (ft)	12
Inside Shoulder Width (ft)	11	Inside Shoulder Width (ft)	11
Rural or Urban	Urban	Rural or Urban	Urban
Horizontal Curves	No	Horizontal Curves	No
Lane Change	No	Lane Change	No
Freeway Segment Length (miles)	1.0380	Freeway Segment Length (miles)	1.0380
Number of Lanes	10	Number of Lanes	10
Total Exit Ramps Length (miles)	0.616	Total Exit Ramps Length (miles)	0.616
Total Entrance Ramps Length (miles)	0.417	Total Entrance Ramps Length (miles)	0.417
Median Width (ft)	0	Median Width (ft)	0
Median Length (miles)	0	Median Length (miles)	0
Distance from Edge of Inside Shoulder to Barrier Face (ft)	12	Distance from Edge of Inside Shoulder to Barrier Face (ft)	12
Paved Outside Shoulder Width (ft)	12	Paved Outside Shoulder Width (ft)	12
Segment Length with Rumble Strips on Inside Shoulder (miles)	0.000	Segment Length with Rumble Strips on Inside Shoulder (miles)	0.000
Segment Length with Rumble Strips on Outside Shoulder (miles)	0.000	Segment Length with Rumble Strips on Outside Shoulder (miles)	0.000
Segment Length with Barrier Present (miles)	1.038	Segment Length with Barrier Present (miles)	1.038
Clear Zone Width (ft)	30	Clear Zone Width (ft)	30
Distance from Edge of Outside Shoulder to Barrier Face (ft)	0	Distance from Edge of Outside Shoulder to Barrier Face (ft)	0
Number of Hours per day that flow rates exceed 1,000 vphpln	13	Number of Hours per day that flow rates exceed 1,000 vphpln	13
Calibration Factor (site specific, Use 1.00 for Default)	1	Calibration Factor (site specific, Use 1.00 for Default)	1

Crash Modification Factors

Existing Conditions			Future Conditions		
Crash Type	Multiple Vehicle	Single Vehicle	Crash Type	Multiple Vehicle	Single Vehicle
CMF_{1fs}	1.00	1.00	CMF_{1fs}	1.00	1.00
CMF_{2fs}	1.00	1.00	CMF_{2fs}	1.00	1.00
CMF_{3fs}	0.92	0.92	CMF_{3fs}	0.92	0.92
CMF_{4fs}	0.80	1.08	CMF_{4fs}	0.80	1.08
CMF_{5fs}	1.00	1.00	CMF_{5fs}	1.00	1.00
CMF_{6fs}	1.21	0.96	CMF_{6fs}	1.21	0.96
CMF_{7fs}	1.00	1.00	CMF_{7fs}	1.00	1.00
CMF_{8fs}	1.00	0.88	CMF_{8fs}	1.00	0.88
CMF_{9fs}	1.00	1.00	CMF_{9fs}	1.00	1.00
CMF_{10fs}	1.00	1.09	CMF_{10fs}	1.00	1.09
CMF_{11fs}	1.00	1.00	CMF_{11fs}	1.00	1.00
CMF_{12fs}	1.00	1.00	CMF_{12fs}	1.00	1.00
CMF_{13fs}	1.00	1.00	CMF_{13fs}	1.00	1.00

Project Specific

CMF_1	0.95	CMF_2	1.00	CMF_3	1.00

Observed Crash Frequency / Crash Severity Distribution

	Crash Severity	Multiple-Vehicle	Single-Vehicle	Multiple-Vehicle	Single-Vehicle
Fatal	5 (K)	0.0	0.0	0%	0%
	4 (A)	0.0	0.2	0%	11%
Injury	3 (B)	0.8	0.6	19%	44%
	2 (C)	3.3	0.6	81%	44%
PDO	1 (O)	16.1	6.5	0%	0%
	Total	20.2	7.9	100%	100%

All Crashes Except PDO (KABC)

Existing Crashes / Predicted Crashes

Crash Type	Multiple Vehicle	Single Vehicle	Crash Type	Multiple Vehicle	Single Vehicle
L*	0.522	0.522	L*	0.522	0.522
a	-5.842	-1.915	a	-5.842	-1.915
b	1.492	0.646	b	1.492	0.646
c	0.001	0.001	c	0.001	0.001
k	0.109	0.064	k	0.109	0.064
w	0.1929	0.3796	w	0.2011	0.3918
N_{spfru}	3.3	2.2	N_{spfru}	3.3	2.2
$N_{predicted\ us}$	38.4	25.7	$N_{predicted\ us}$	36.5	24.4

Part C Predictive Method

Total Number of Crashes	38.4	25.7	Total Number of Crashes	36.5	24.4

UDOT Recommended

Crash Severity	Estimated Reduction in Crashes	Crash Severity Value (Use Options Above)	Estimated Safety Benefit
5 (K) Fatal	0.0	$ 1,982,000.00	$ -
4 (A) Incapacitating Injury	2.6	$ 1,982,000.00	$ 3,808,849.29
3 (B) Non-incapacitating Injury	17.4	$ 123,700.00	$ 950,871.90
2 (C) Possible Injury	39.5	$ 63,200.00	$ 485,830.91
1 (O) Property Damage Only	0.0	$ 3,200.00	$ -
Total	59.5		$ 5,245,552.10

Initial Project Cost	$ 500,000.00
Maintenance Cost Per Period	$ -
Number of Years For Each Maintenance	5
Annual Maintenance	$ 5,000.00
Discount Rate	3%
Service Life (years)	20
Number of Maintenance Periods	4
Total Maintenance Costs Present Value	$ 74,387.37
Total Cost	$ 574,387.37

Calculate Benefit/Cost Ratio

Print BCR Report

B/C=	9.13

Using present worth values:

Benefit =	$ 5,245,552
Cost =	$ 574,387

Figure 5-49: Entire Spreadsheet for Second Freeway Segment Example

5.4   Project Costs

As mentioned multiple times in the previous sections, project costs are one of the most important entries for performing a life-cycle benefit-cost analysis. If the cost is not correct, the result of the analysis will not accurately portray the effectiveness of a safety countermeasure. The costs that were used in this chapter were estimates and were simply meant to illustrate how this spreadsheet can be used to perform an analysis. It is the duty of the user to accurately determine the costs associated with a particular project. Those costs will most likely differ among the segments depending on the location, countermeasure, contract type, and possibly even time of the year. The users should contact their local state or municipal agency to determine general expected costs for certain countermeasures under consideration.

5.5   Chapter Summary

This chapter applied the life-cycle benefit-cost analysis spreadsheet program to three different roadway types. For each roadway type, two different countermeasures were analyzed. The three roadway segments were chosen based on the results of the UCPM from 2008 to 2012. The three roadway segments were identified to be among the 20 most unsafe roadway segments in Utah according to the 2008 to 2012 UCPM analysis results (Schultz et al. 2015). Issues on using appropriate project costs were also discussed in this chapter. The spreadsheet program does not contain a cost prediction feature because costs for countermeasures are affected by various conditions such as location of the work, how contracts are made for countermeasures, and contractors may not wish to reveal detailed cost breakdowns for countermeasures. Hence, the user must consult cost estimate experts when they perform benefit-cost analyses.

6 CONCLUSIONS AND RECOMMENDATIONS

The goal of this research was to automate the life-cycle benefit-cost analysis of safety related improvements. The HSM lists four different methods for determining the change in crash frequency in order of reliability. Currently, UDOT uses the fourth most reliable method. The goal of this research was to develop a way that the most reliable method mentioned in the HSM could be used to perform the life-cycle benefit-cost analysis. A spreadsheet program approach was undertaken to carry out the Part C Predictive Method of the HSM to perform a life-cycle benefit-cost analysis of safety related improvements for 11 different roadway types including:

- Rural TLTW Highway (Chapter 10 of HSM Volume 2)

- Divided Multilane Highway (Chapter 11 of HSM Volume 2)

- Undivided Multilane Highway (Chapter 11 of HSM Volume 2)

- Two-Lane Undivided Arterials (Chapter 12 of HSM Volume 2)

- Three-Lane Arterials Including a TWLTL (Chapter 12 of HSM Volume 2)

- Four-Lane Divided Arterials (Chapter 12 of HSM Volume 2)

- Four-Lane Undivided Arterials (Chapter 12 of HSM Volume 2)

- Five –Lane Arterials Including a TWLTL (Chapter 12 of HSM Volume 2)

- Freeway Segments (Chapter 18 of HSM Supplement)

- Freeway Speed Change Lanes (Chapter 18 of HSM Supplement)

- Freeway Ramps (Chapter 19 of HSM Supplement)

Other roadway types that may exist in the field are not included in this spreadsheet program because these are the only roadway types that are included in the HSM Part C Predictive Method. Intersections are not included in this spreadsheet program as they are not yet included in the UCPM or the UCSM at the time of this research.

6.1   Conclusions

A literature review was performed and summarized in Chapter 2, indicated that a tool was needed to realize life-cycle benefit-cost analysis on safety countermeasures. Chapter 3 explained the methodology associated with this research effort including the Part C Predictive Method, life-cycle benefit-cost analysis fundamentals, and the application of the methodology into this spreadsheet-based analysis program. Chapter 4 explained the concept and spreadsheet layout using the rural TLTW highway spreadsheet as an example. Chapter 5 explored application through example by examining three different spreadsheets: rural TLTW highway, five-lane arterial including a TWLTL, and a freeway segment. For each spreadsheet, two countermeasures were considered to determine which countermeasure had the higher BCR.

One important aspect associated with life-cycle benefit-cost analysis of safety related improvements is the cost estimation. The spreadsheets developed in this study can reliably predict the benefits associated with a countermeasure following the method found in the HSM; however, it does not include a module to estimate costs associated with a countermeasure. These spreadsheets can only use the information entered by the user to perform the analysis. The user should seek guidance from the cost estimate expert within the agency when determining the

project costs. As explained previously, it is suggested that only the Part C Predictive Method be used for benefits, but the option of using the EB method is also available in the spreadsheet program. Furthermore, the crash severity distribution is also important in determining the total benefits.

6.2   Issues Related to Life-Cycle Benefit-Cost Analysis

This section discusses issues related to performing a life-cycle benefit-cost analysis of safety related countermeasures, which are the problems with using the EB method from the HSM, the difficulties with defining crash severity distributions, and the limitations of the model developed in this study.

6.2.1   Difficulty with Using the EB Method in the Life-Cycle Benefit-Cost Analysis

The Part C Predictive Method of the HSM explains that the EB method should be used wherever appropriate. The EB method combines the results of the SPFs with observed crash frequency. This means that the EB method should be used when there are observed crash data from multiple years. All of the examples present in chapter 5 had crash data from multiple years. There is some difficulty in using the EB method when the user is trying to forecast the number of expected crashes for the next 20 years because the user would be using past crash data from only a few years and must have observed crashes. While the EB method is not necessarily perfect, it does include observed crashes, which helps to calibrate the results of the SPFs to make the results more indicative of the actual site being considered. The problem is that there are no real observed crashes for future years to perform the EB method. Also the HSM is not entirely clear on how to use the EB method when trying to forecast expected crashes for the future (AASHTO

2010b). It is of the opinion of the author of this thesis that only the Part C Predictive Method be used in a life-cycle benefit-cost analysis.

6.2.2   Difficulty with Crash Severity Distributions

As explained in chapter 5, crash severity distributions can have a significant impact on the overall result of the life-cycle benefit-cost analysis as the results of the SPFs are multiplied by the distribution to determine how many of each crash type will be reduced. These results are then multiplied by specific crash costs. Therefore, even slight changes in crash type distributions can have a significant impact on the overall result of the benefits. The only roadway type that has a default distribution of crash types in the HSM is the rural TLTW highway (AASHTO 2010b). None of the other roadway types have a default distribution. UDOT has their own default distribution, but it is for any roadway type, which may not be the most accurate way to determine the crash distribution for a specific roadway type. The spreadsheet program developed in this study has the option to choose either the UDOT distribution, which is the same for all roadway types, or to use the observed crash frequency to come up with the crash distribution for the segment under study. Using the observed crash frequency presents difficulty since it is basing the number of each crash type on only a few years of data. As seen in some of the examples, if there are only PDO crashes or no fatalities, the crash distribution will not accurately display the benefits as there would more than likely, though hopefully not, be a probability of one fatality on that roadway segment in the future.

Another essential aspect when determining crash distributions is to calibrate each segment. A calibration factor is included in each spreadsheet, and each calibration factor is meant to make sure that the results are specific to the site in question.

It is recommended that further research be performed to determine a default crash severity distribution for each roadway type. Currently, as explained previously, there is only a default distribution for the rural TLTW highway in the HSM. If a distribution of crash types can be developed for each roadway type, the life-cycle benefit-cost analysis outcome can be significantly improved.

6.2.3   Limitations of Spreadsheet Program

This section explains some of the limitations of the spreadsheet-based life-cycle benefit-cost analysis developed in this study:

- One of the major limitations of this spreadsheet program is the fact that only some roadway types are explored. For example, urban and suburban arterials that have more than 5 lanes could not be analyzed using this spreadsheet program. The reason for this is that there is no Part C Predictive Method or SPFs for these roadway types in the HSM. All of the roadway types that are contained in the HSM Part C Predictive Method are contained in this spreadsheet-based program.

- Another limitation of this spreadsheet program is that intersections are not included in it. Intersections are not included because they are excluded from the UCPM and UCSM. Since these models do not output any results for intersections, this spreadsheet does not include intersections and it should be used to analyze only roadway segments. Further research should be performed to build a spreadsheet program that includes intersections in the analysis.

- Another limitation of this spreadsheet program is the costs of implementing the countermeasures. As explained previously, this spreadsheet was programmed to analyze and predict the benefits of a proposed countermeasure using the method contained in the

HSM, but it does not contain a module that will predict the costs associated with a countermeasure. It is up to the discretion of the user to determine the costs. This spreadsheet can only use the results of the costs that the user enters to determine the BCR.

- Another limitation regarding costs is the fact that the rehabilitation costs and annual maintenance costs are expected to be the same throughout the analysis period. This means that rehabilitation five years after the installation of the countermeasure will cost the same as the rehabilitation 10 years after the installation of the countermeasure, which may not always be the case.

6.3   Recommendations

The following are topics for further research recommended based on the findings of this research in the order of their significant effect on the outcome of life-cycle benefit-cost analysis:

- As explained in Section 6.2.2, crash severity distributions are one of the main parts that affect the outcome of the benefit-cost analysis. Currently, the HSM has a default distribution only for the rural TLTW highway. At present, UDOT has a default distribution which can be used for any roadway type. These may not be the most reliable crash severity distributions since it averages a number of different roadway types. Further research should be performed to determine default distributions for each roadway type. This would help improve the reliability in determining the amount of benefit in each analysis.

- Costs are also a major concern as explained in Section 5.4. Further research should be performed to determine what the best way would be to include rehabilitation costs

and annual maintenance costs in the life-cycle benefit-cost analysis and how these

should be brought back to present value.

- As explained in Section 6.2.1, the EB method may not be an appropriate way to

  perform a life-cycle benefit-cost analysis because it requires observed crash

  frequency for future years, which do not exist. Further research should be performed

  to determine how the EB method could be used in a life-cycle benefit-cost analysis.

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LIST OF ACRONYMS

AADT	Annual Average Daily Traffic
AASHTO	American Association of State Highway and Transportation Officials
AMF	Accident Modification Factors
BCR	Benefit-Cost Ratio
BYU	Brigham Young University
CMF	Crash Modification Factor
EB	Empirical Bayes
FHWA	Federal Highway Administration
HSM	Highway Safety Manual
MP	Mile Point
NPV	Net Present Value
NPW	Net Present Worth
SPF	Safety Performance Function
TLTW	Two-Lane Two-Way
TWLTL	Two-Way Left Turn Lane
UCPM	Utah Crash Prediction Model
UCSM	Utah Crash Severity Model
UDOT	Utah Department of Transportation
VBA	Visual Basic for Applications
VMT	Vehicle-Miles Traveled

APPENDIX A.   HSM CHAPTER 10 CMFS

Appendix A presents the sections from the HSM pertaining to the CMFs for rural TLTW highways. This Appendix A should be used as a reference following the discussions given for the examples presented in Chapter 4 and 5.

Table 10-7. Summary of Crash Modification Factors (CMFs) in Chapter 10 and the Corresponding Safety Performance Functions (SPFs)

Facility Type	CMF	CMF Description	CMF Equations and Tables
Rural Two-Lane Two-Way Roadway Segments	CMF_{1r}	Lane Width	Table 10-8, Figure 10-7, Equation 10-11
	CMF_{2r}	Shoulder Width and Type	Table 10-9, Figure 10-8, Table 10-10, Equation 10-12
	CMF_{3r}	Horizontal Curves: Length, Radius, and Presence or Absence of Spiral Transitions	Table 10-7
	CMF_{4r}	Horizontal Curves: Superelevation	Equation 10-14, 10-15, 10-16,
	CMF_{5r}	Grades	Table 10-11
	CMF_{6r}	Driveway Density	Table 10-11
	CMF_{7r}	Centerline Rumble Strips	See text
	CMF_{8r}	Passing Lanes	See text
	CMF_{9r}	Two-Way Left-Turn Lanes	Equation 10-18, 10-19
	CMF_{10r}	Roadside Design	Equation 10-20
	CMF_{11r}	Lighting	Equation 10-21, Table 10-12
	CMF_{12r}	Automated Speed Enforcement	See text
Three- and four-leg stop control intersections and four-leg signalized intersections	CMF_{1i}	Intersection Skew Angle	Equation 10-22, 10-23
	CMF_{2i}	Intersection Left-Turn Lanes	Table 10-13
	CMF_{3i}	Intersection Right-Turn Lanes	Table 10-14
	CMF_{4i}	Lighting	Equation 10-24, Table 10-15

10.7.1. Crash Modification Factors for Roadway Segments

The CMFs for geometric design and traffic control features of rural two-lane, two-way roadway segments are presented below. These CMFs are applied in Step 10 of the predictive method and used in Equation 10-2 to adjust the SPF for rural two-lane, two-way roadway segments presented in Equation 10-6, to account for differences between the base conditions and the local site conditions.
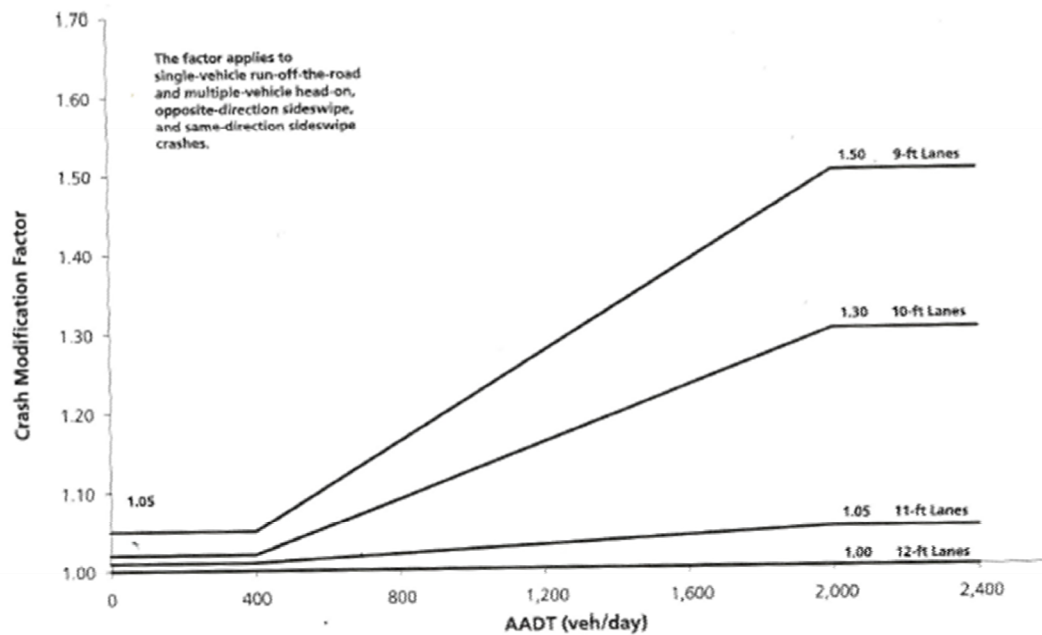
CMF_{1r}—Lane Width

The CMF for lane width on two-lane highway segments is presented in Table 10-8 and illustrated by the graph in Figure 10-7. This CMF was developed from the work of Zegeer et al. (16) and Griffin and Mak (4). The base value for the lane width CMF is 12 ft. In other words, the roadway segment SPF will predict safety performance of a roadway segment with 12-ft lanes. To predict the safety performance of the actual segment in question (e.g., one with lane widths different than 12 ft), CMFs are used to account for differences between base and actual conditions. Thus, 12-ft lanes are assigned a CMF of 1.00. CMF_{1r} is determined from Table 10-8 based on the applicable lane width and traffic volume range. The relationships shown in Table 10-8 are illustrated in Figure 10-7. Lanes with widths greater than 12 ft are assigned a CMF equal to that for 12-ft lanes.

For lane widths with 0.5-ft increments that are not depicted specifically in Table 10-8 or Figure 10-7, a CMF value can be interpolated using either of these exhibits since there is a linear transition between the various AADT effects.

113

Table 10-8. CMF for Lane Width on Roadway Segments (CMF_{ra})

Lane Width	AADT (vehicles per day)		
	< 400	400 to 2000	> 2000
9 ft or less	1.05	$1.05 + 2.81 \times 10^{-4}(AADT - 400)$	1.50
10 ft	1.02	$1.02 + 1.75 \times 10^{-4}(AADT - 400)$	1.30
11 ft	1.01	$1.01 + 2.5 \times 10^{-5}(AADT - 400)$	1.05
12 ft or more	1.00	1.00	1.00

Note: The collision types related to lane width to which this CMF applies include single-vehicle run-off-the-road and multiple-vehicle head-on, opposite-direction sideswipe, and same-direction sideswipe crashes.

Figure 10-7. Crash Modification Factor for Lane Width on Roadway Segments

If the lane widths for the two directions of travel on a roadway segment differ, the CMF are determined separately for the lane width in each direction of travel and the resulting CMFs are then be averaged.

The CMFs shown in Table 10-8 and Figure 10-7 apply only to the crash types that are most likely to be affected by lane width: single-vehicle run-off-the-road and multiple-vehicle head-on, opposite-direction sideswipe, and same-direction sideswipe crashes. These are the only crash types assumed to be affected by variation in lane width, and other crash types are assumed to remain unchanged due to the lane width variation. The CMFs expressed on this basis are, therefore, adjusted to total crashes within the predictive method. This is accomplished using Equation 10-11:

$$CMF_{lr} = (CMF_{ra} - 1.0) \times p_{ra} + 1.0 \qquad (10\text{-}11)$$

Where:

CMF_{1r} = crash modification factor for the effect of lane width on total crashes;

CMF_{ra} = crash modification factor for the effect of lane width on related crashes (i.e., single-vehicle run-off-the-road and multiple-vehicle head-on, opposite-direction sideswipe, and same-direction sideswipe crashes), such as the crash modification factor for lane width shown in Table 10-8; and

p_{ra} = proportion of total crashes constituted by related crashes.

The proportion of related crashes, p_{ra}, (i.e., single-vehicle run-off-the-road, and multiple-vehicle head-on, opposite-direction sideswipe, and same-direction sideswipes crashes) is estimated as 0.574 (i.e., 57.4 percent) based on the default distribution of crash types presented in Table 10-4. This default crash type distribution, and therefore the value of p_{ra}, may be updated from local data as part of the calibration process.

CMF_{2r}—Shoulder Width and Type

The CMF for shoulders has a CMF for shoulder width (CMF_{wra}) and a CMF for shoulder type (CMF_{tra}). The CMFs for both shoulder width and shoulder type are based on the results of Zegeer et al. (16, 17). The base value of shoulder width and type is a 6-foot paved shoulder, which is assigned a CMF value of 1.00.

CMF_{wra} for shoulder width on two-lane highway segments is determined from Table 10-9 based on the applicable shoulder width and traffic volume range. The relationships shown in Table 10-9 are illustrated in Figure 10-8.

Shoulders over 8-ft wide are assigned a CMF_{wra} equal to that for 8-ft shoulders. The CMFs shown in Table 10-9 and Figure 10-8 apply only to single-vehicle run-off the-road and multiple-vehicle head-on, opposite-direction sideswipe, and same-direction sideswipe crashes.

Table 10-9. CMF for Shoulder Width on Roadway Segments (CMF_{wra})

Shoulder Width	AADT (vehicles per day)		
	< 400	400 to 2000	> 2000
0 ft	1.10	$1.10 + 2.5 \times 10^{-4} (AADT - 400)$	1.50
2 ft	1.07	$1.07 + 1.43 \times 10^{-4} (AADT - 400)$	1.30
4 ft	1.02	$1.02 + 8.125 \times 10^{-5} (AADT - 400)$	1.15
6 ft	1.00	1.00	1.00
8 ft or more	0.98	$0.98 + 6.875 \times 10^{-5} (AADT - 400)$	0.87

Note: The collision types related to shoulder width to which this CMF applies include single-vehicle run-off the-road and multiple-vehicle head-on, opposite-direction sideswipe, and same-direction sideswipe crashes.
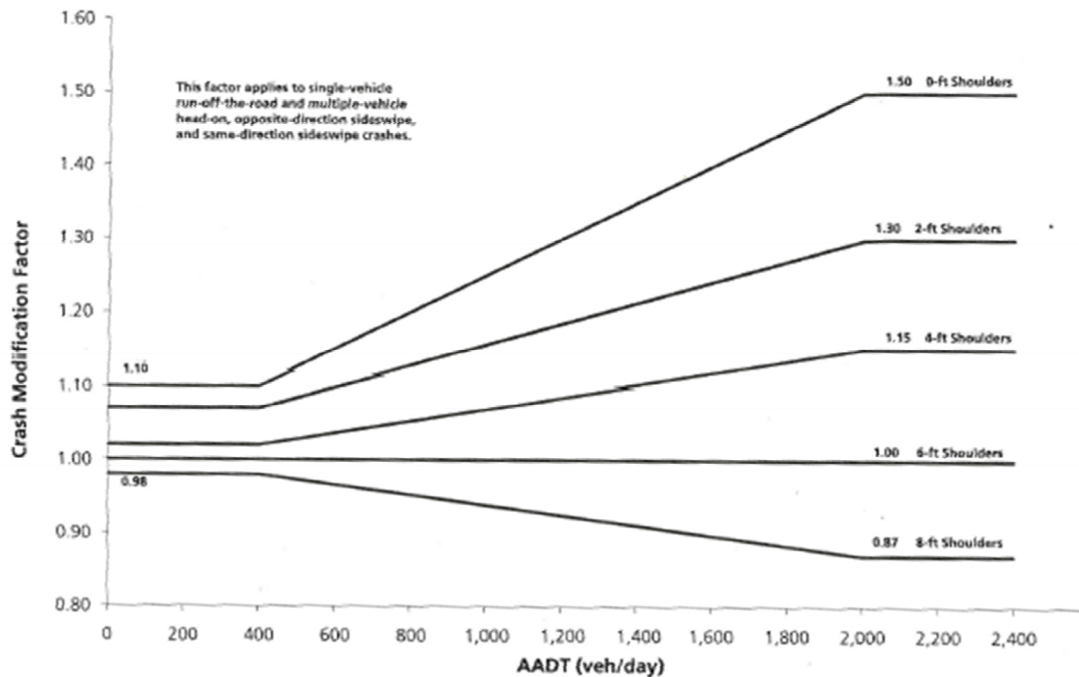
Figure 10-8. Crash Modification Factor for Shoulder Width on Roadway Segments

The base condition for shoulder type is paved. Table 10-10 presents values for CMF_{ra} which adjusts for the safety effects of gravel, turf, and composite shoulders as a function of shoulder width.

Table 10-10. Crash Modification Factors for Shoulder Types and Shoulder Widths on Roadway Segments (CMF_{ra})

Shoulder Type	Shoulder Width (ft)						
	0	1	2	3	4	6	8
Paved	1.00	1.00	1.00	1.00	1.00	1.00	1.00
Gravel	1.00	1.00	1.01	1.01	1.01	1.02	1.02
Composite	1.00	1.01	1.02	1.02	1.03	1.04	1.06
Turf	1.00	1.01	1.03	1.04	1.05	1.08	1.11

Note: The values for composite shoulders in this table represent a shoulder for which 50 percent of the shoulder width is paved and 50 percent of the shoulder width is turf.

If the shoulder types and/or widths for the two directions of a roadway segment differ, the CMF are determined separately for the shoulder type and width in each direction of travel and the resulting CMFs are then be averaged.

The CMFs for shoulder width and type shown in Table 9, Figure 8, and Table 10 apply only to the collision types that are most likely to be affected by shoulder width and type: single-vehicle run-off the-road and multiple-vehicle head-on, opposite-direction sideswipe, and same-direction sideswipe crashes. The CMFs expressed on this basis are, therefore, adjusted to total crashes using Equation 10-12.

$$CMF_{2r} = (CMF_{wra} \times CMF_{tra} - 1.0) \times p_{ra} + 1.0 \tag{10-12}$$

Where:

CMF_{2r} = crash modification factor for the effect of shoulder width and type on total crashes;

CMF_{wra} = crash modification factor for related crashes (i.e., single-vehicle run-off-the-road and multiple-vehicle head-on, opposite-direction sideswipe, and same-direction sideswipe crashes), based on shoulder width (from Table 10-9);

CMF_{tra} = crash modification factor for related crashes based on shoulder type (from Table 10-10); and

p_{ra} = proportion of total crashes constituted by related crashes.

The proportion of related crashes, p_{ra}, (i.e., single-vehicle run-off-the-road, and multiple-vehicle head-on, opposite-direction sideswipe, and same-direction sideswipes crashes) is estimated as 0.574 (i.e., 57.4 percent) based on the default distribution of crash types presented in Table 10-4. This default crash type distribution, and therefore the value of pra, may be updated from local data by a highway agency as part of the calibration process.

CMF_{3r}—Horizontal Curves: Length, Radius, and Presence or Absence of Spiral Transitions

The base condition for horizontal alignment is a tangent roadway segment. A CMF has been developed to represent the manner in which crash experience on curved alignments differs from that of tangents. This CMF applies to total roadway segment crashes.

The CMF for horizontal curves has been determined from the regression model developed by Zegeer et al. (18).

The CMF for horizontal curvature is in the form of an equation and yields a factor similar to the other CMFs in this chapter. The CMF for length, radius, and presence or absence of spiral transitions on horizontal curves is determined using Equation 10-13.

$$CMF_{3r} = \frac{(1.55 \times L_c) + \left(\dfrac{80.2}{R}\right) - (0.012 \times S)}{(1.55 \times L_c)} \tag{10-13}$$

Where:

CMF_{3r} = crash modification factor for the effect of horizontal alignment on total crashes;

L_c = length of horizontal curve (miles) which includes spiral transitions, if present;

R = radius of curvature (feet); and

S = 1 if spiral transition curve is present; 0 if spiral transition curve is not present; 0.5 if a spiral transition curve is present at one but not both ends of the horizontal curve.

Some roadway segments being analyzed may include only a portion of a horizontal curve. In this case, L_c represents the length of the entire horizontal curve, including portions of the horizontal curve that may lie outside the roadway segment of interest.

In applying Equation 10-13, if the radius of curvature (R) is less than 100-ft, R is set to equal to 100 ft. If the length of the horizontal curve (L_c) is less than 100 feet, L_c is set to equal 100 ft.

CMF values are computed separately for each horizontal curve in a horizontal curve set (a curve set consists of a series of consecutive curve elements). For each individual curve, the value of L_c used in Equation 10-13 is the total length of the compound curve set and the value of R is the radius of the individual curve.

If the value of CMF_{3r} is less than 1.00, the value of CMF_{3r} is set equal to 1.00.

117

CMF$_{4r}$—Horizontal Curves: Superelevation

The base condition for the CMF for the superelevation of a horizontal curve is the amount of superelevation identified in *A Policy on Geometric Design of Highways and Streets*—also called the AASHTO Green Book (1). The superelevation in the AASHTO Green Book is determined by taking into account the value of maximum superelevation rate, e$_{max}$, established by highway agency policies. Policies concerning maximum superelevation rates for horizontal curves vary between highway agencies based on climate and other considerations.

The CMF for superelevation is based on the superelevation variance of a horizontal curve (i.e., the difference between the actual superelevation and the superelevation identified by AASHTO policy). When the actual superelevation meets or exceeds that in the AASHTO policy, the value of the superelevation CMF is 1.00. There is no effect of superelevation variance on crash frequency until the superelevation variance exceeds 0.01. The general functional form of a CMF for superelevation variance is based on the work of Zegeer et al. (18, 19).

The following relationships present the CMF for superelevation variance:

$$CMF_{4r} = 1.00 \text{ for } SV < 0.01 \tag{10-14}$$

$$CMF_{4r} = 1.00 + 6 \times (SV - 0.01) \text{ for } 0.01 \leq SV < 0.02 \tag{10-15}$$

$$CMF_{4r} = 1.06 + 3 \times (SV - 0.02) \text{ for } SV \geq 0.02 \tag{10-16}$$

Where:

CMF_{4r} = crash modification factor for the effect of superelevation variance on total crashes; and

SV = superelevation variance (ft/ft), which represents the superelevation rate contained in the AASHTO Green Book minus the actual superelevation of the curve.

CMF_{4r} applies to total roadway segment crashes for roadway segments located on horizontal curves.

CMF$_{5r}$—Grades

The base condition for grade is a generally level roadway. Table 10-11 presents the CMF for grades based on an analysis of rural two-lane, two-way highway grades in Utah conducted by Miaou (8). The CMFs in Table 10-11 are applied to each individual grade segment on the roadway being evaluated without respect to the sign of the grade. The sign of the grade is irrelevant because each grade on a rural two-lane, two-way highway is an upgrade for one direction of travel and a downgrade for the other. The grade factors are applied to the entire grade from one point of vertical intersection (PVI) to the next (i.e., there is no special account taken of vertical curves). The CMFs in Table 10-11 apply to total roadway segment crashes.

Table 10-11. Crash Modification Factors (CMF$_{5r}$) for Grade of Roadway Segments

Approximate Grade (%)		
Level Grade (≤ 3%)	Moderate Terrain (3%< grade ≤ 6%)	Steep Terrain (> 6%)
1.00	1.10	1.16

CMF$_{6r}$—Driveway Density

The base condition for driveway density is five driveways per mile. As with the other CMFs, the model for the base condition was established for roadways with this driveway density. The CMF for driveway density is determined using Equation 10-17, derived from the work of Muskaug (9).

$$CMF_{6r} = \frac{0.322 + DD \times [0.05 - 0.005 \times \ln(AADT)]}{0.322 + 5 \times [0.05 - 0.005 \times \ln(AADT)]} \tag{10-17}$$

Where:

CMF_{6r} = crash modification factor for the effect of driveway density on total crashes;

$AADT$ = average annual daily traffic volume of the roadway being evaluated (vehicles per day); and

DD = driveway density considering driveways on both sides of the highway (driveways/mile).

If driveway density is less than 5 driveways per mile, CMF_{6r} is 1.00. Equation 10-17 can be applied to total roadway crashes of all severity levels.

Driveways serving all types of land use are considered in determining the driveway density. All driveways that are used by traffic on at least a daily basis for entering or leaving the highway are considered. Driveways that receive only occasional use (less than daily), such as field entrances are not considered.

CMF_{7r}—Centerline Rumble Strips

Centerline rumble strips are installed on undivided highways along the centerline of the roadway which divides opposing directions of traffic flow. Centerline rumble strips are incorporated in the roadway surface to alert drivers who unintentionally cross, or begin to cross, the roadway centerline. The base condition for centerline rumble strips is the absence of rumble strips.

The value of CMF_{7r} for the effect of centerline rumble strips for total crashes on rural two-lane, two-way highways is derived as 0.94 from the CMF value presented in Chapter 13 and crash type percentages found in Chapter 10. Details of this derivation are not provided.

The CMF for centerline rumble strips applies only to two-lane undivided highways with no separation other than a centerline marking between the lanes in opposite directions of travel. Otherwise the value of this CMF is 1.00.

CMF_{8r}—Passing Lanes

The base condition for passing lanes is the absence of a lane (i.e., the normal two-lane cross section). The CMF for a conventional passing or climbing lane added in one direction of travel on a rural two-lane, two-way highway is 0.75 for total crashes in both directions of travel over the length of the passing lane from the upstream end of the lane addition taper to the downstream end of the lane drop taper. This value assumes that the passing lane is operationally warranted and that the length of the passing lane is appropriate for the operational conditions on the roadway. There may also be some safety benefit on the roadway downstream of a passing lane, but this effect has not been quantified.

The CMF for short four-lane sections (i.e., side-by-side passing lanes provided in opposite directions on the same section of roadway) is 0.65 for total crashes over the length of the short four-lane section. This CMF applies to any portion of roadway where the cross section has four lanes and where both added lanes have been provided over a limited distance to increase passing opportunities. This CMF does not apply to extended four-lane highway sections.

The CMF for passing lanes is based primarily on the work of Harwood and St.John (6), with consideration also given to the results of Rinde (11) and Nettelblad (10). The CMF for short four-lane sections is based on the work of Harwood and St. John (6).

CMF_{9r}—Two-Way Left-Turn Lanes

The installation of a center two-way left-turn lane (TWLTL) on a rural two-lane, two-way highway to create a three-lane cross-section can reduce crashes related to turning maneuvers at driveways. The base condition for two-way left-turn lanes is the absence of a TWLTL. The CMF for installation of a TWLTL is:

$$(10-18)$$

$$CMF_{9r} = 1.0 - (0.7 \times p_{dwy} \times p_{LTD})$$

Where:

CMF_{9r} = crash modification factor for the effect of two-way left-turn lanes on total crashes;

p_{dwy} = driveway-related crashes as a proportion of total crashes; and

p_{LTD} = left-turn crashes susceptible to correction by a TWLTL as a proportion of driveway-related crashes.

The value of p_{dwy} can be estimated using Equation 10-19 (6).

$$p_{dwy} = \frac{(0.0047 \times DD) + \left(0.0024 \times DD^{(2)}\right)}{1.199 + (0.0047 \times DD) + \left(0.0024 \times DD^{(2)}\right)}$$

$$(10-19)$$

Where:

P_{dwy} = driveway-related crashes as a proportion of total crashes; and

DD = driveway density considering driveways on both sides of the highway (driveways/mile).

The value of p_{LTD} is estimated as 0.5 (6).

Equation 10-18 provides the best estimate of the CMF for TWLTL installation that can be made without data on the left-turn volumes within the TWLTL. Realistically, such volumes are seldom available for use in such analyses though Section A.1. of Appendix A to Part C describes how to appropriately calibrate this value. This CMF applies to total roadway segment crashes.

The CMF for TWLTL installation is not applied unless the driveway density is greater than or equal to five driveways per mile. If the driveway density is less than five driveways per mile, the CMF for TWLTL installation is 1.00.

CMF$_{10r}$—Roadside Design

For purposes of the HSM predictive method, the level of roadside design is represented by the roadside hazard rating (1–7 scale) developed by Zegeer et al. (16). The CMF for roadside design was developed in research by Harwood et al. (5). The base value of roadside hazard rating for roadway segments is 3. The CMF is:

$$CMF_{10r} = \frac{e^{(-0.6869 + 0.0668 \times RHR)}}{e^{(-0.4865)}}$$

$$(10-20)$$

Where:

CMF_{10r} = crash modification factor for the effect of roadside design; and

RHR = roadside hazard rating.

This CMF applies to total roadway segment crashes. Photographic examples and quantitative definitions for each roadside hazard rating (1–7) as a function of roadside design features such as sideslope and clear zone width are presented in Chapter 13, Appendix 13A.

CMF$_{11r}$—Lighting

The base condition for lighting is the absence of roadway segment lighting. The CMF for lighted roadway segments is determined, based on the work of Elvik and Vaa (2), as:

$$CMF_{11r} = 1.0 - [(1.0 - 0.72 \times p_{inr} - 0.83 \times p_{pnr}) \times p_{nr}] \qquad (10\text{-}21)$$

Where:

CMF_{11r} = crash modification factor for the effect of lighting on total crashes;

p_{inr} = proportion of total nighttime crashes for unlighted roadway segments that involve a fatality or injury;

p_{pnr} = proportion of total nighttime crashes for unlighted roadway segments that involve property damage only; and

p_{nr} = proportion of total crashes for unlighted roadway segments that occur at night.

This CMF applies to total roadway segment crashes. Table 10-12 presents default values for the nighttime crash proportions p_{inr}, p_{pnr}, and p_{nr}. HSM users are encouraged to replace the estimates in Table 10-12 with locally derived values. If lighting installation increases the density of roadside fixed objects, the value of CMF_{10r} is adjusted accordingly.

Table 10-12. Nighttime Crash Proportions for Unlighted Roadway Segments

Roadway Type	Proportion of Total Nighttime Crashes by Severity Level		Proportion of Crashes that Occur at Night
	Fatal and Injury p_{inr}	PDO p_{pnr}	p_{nr}
2U	0.382	0.618	0.370

Note: Based on HSIS data for Washington (2002–2006)

CMF_{12r}—Automated Speed Enforcement

Automated speed enforcement systems use video or photographic identification in conjunction with radar or lasers to detect speeding drivers. These systems automatically record vehicle identification information without the need for police officers at the scene. The base condition for automated speed enforcement is that it is absent.

The value of CMF_{12r} for the effect of automated speed enforcement for total crashes on rural two-lane, two-way highways is derived as 0.93 from the CMF value presented in Chapter 17 and crash type percentages found in Chapter 10. Details of this derivation are not provided.

APPENDIX B.   APPLICATION THROUGH EXAMPLE SUPPLEMENTS

Safety Analysis on Hot Spot Segments

Introduction

The purpose of this report is to summarize and present preliminary results from a safety-specific micro analysis on an identified hot spot segment. This report includes identification of the roadway segment and sub-segments, micro analysis data, and segment definition including roadway characteristics. A discussion of the problem at the location including possible countermeasures is also included.

Segment Identification

Table 1: Segment Metadata

Road Name:	US-89	**UC Model Used:**	UCPM
Road Direction:	Positive	**Ranking from Model:**	6
Beginning Mile Point:	267.346	**UDOT Region:**	4
Ending Mile Point:	276.21	**County:**	SANPETE
Dates of Data Source:	2008-2012	**Date of Analysis:**	December 15 2015

Table 2: Segment Characteristics

Function Class:	Other Principal Arterial	**AADT:**	2,675
Number of Thru Lanes:	2	**Speed Limit (MPH):**	65

Table 3: Segment Length

Beginning Mile Point	Ending Mile Point	Length
267.346	276.21	8.864

Micro Analysis

Crash Data

Table 4: Crash Count and Severity

Mile Points	# of Crashes	Severity 5	Severity 4	Severity 3
267.346 - 276.21	17	0	2	15

Table 5: Top 8 Crash Factors

	IMPROPER RESTRAINT	OVERTURN ROLLOVER	SINGLE VEHICLE	ROADWAY DEPARTURE	TEENAGE DRIVER INVOLVED	DISTRACTED DRIVING	NIGHT DARK CONDITION	COLLISION WITH FIXED OBJECT
Segment Total	10/17	10/17	9/17	8/17	7/17	6/17	6/17	5/17

Current Conditions and Historical Perspective

This 8.86 mile segment of US-89 is a two-lane two-way highway, between Ephraim and Mt Pleasant, Utah. This rural highway serves as the main arterial for those who live in the area. The surrounding land is rural, with farmlands and some residential and commercial development.

Due to winter conditions, a personal site visit was not personally conducted for this segment along US-89. However, Internet tools, such as Roadview Explorer and Google Earth, were used to understand the characteristics of the roadway. Previous driving experience along this segment will also be drawn on. From the Internet images, it appears that rumble strips were installed after 2010. Although there isn't a wide paved shoulder, the slopes appear to be mild for most of the roadway. The road appears to be very flat, with minor curvature. It is likely that wild animals would try to cross the road.

Figure B-1: Hot Sport Two-Page Report for Rural TLTW Example

Segment Definition

The 8.86 mile segment of US-89 near Ephraim is a two-lane, two-way highway. There is a 5 foot asphalt shoulder on fairly level terrain. The horizontal curvature is mild. There are rumble strips. The median only exists near interchanges to other highways. Additional roadway data is given in Table 6.

Table 6: Roadway Characteristics

Mile Points	Median	IPM	SPM	Shoulder	Grade	Curve	Lanes	Wall/ Barrier	Rumble
267.346-276.21	Undivided, 6 ft	1/0.1	74/8.2	Asphalt, 5 ft	-4.41 (max)	Class A, L = 474, R = 5333	2 Thru, Right Turn Lane, Accel Lane, Decel Lane	No (Wall), No (Barrier)	Yes

Problem Definition

From the data given from the crashes, there have been a number of injury related crashes but no fatalities between 2008 and 2012. The most common crash factors include roadway departure, distracted driving, and night conditions.

Countermeasures and Recommendations

This section includes a list of suggested countermeasures for implementation at the site.

Reallocate total two lane roadway width (lane and shoulder) to include a narrow "buffer median"
Use alternating passing lanes or four lane sections at key locations
Improve visibility of the intersection by providing lighting
Provide enhanced pavement markings
Apply shoulder treatments like eliminating shoulder drop off or widening shoulders
Design safer slopes and ditches to prevent rollovers
Improve design of roadside hardware
Install shoulder and/or centerline rumble strips
Improve access to safe stopping and resting areas
Improve rest area security and services
Conduct education and awareness campaigns targeting the general driving public
Strengthen graduated driver licensing requirements for young drivers

Figure B-1: Continued

Safety Analysis on Hot Spot Segments

Introduction

The purpose of this report is to summarize and present preliminary results from a safety-specific micro analysis on an identified hot spot segment. This report includes identification of the roadway segment and sub-segments, micro analysis data, and segment definition including roadway characteristics. A discussion of the problem at the location including possible countermeasures is also included.

Segment Identification

Table 1: Segment Metadata

Road Name:	US-89	**UC Model Used:**	UCPM
Road Direction:	Positive	**Ranking from Model:**	9
Beginning Mile Point:	431.317	**UDOT Region:**	1
Ending Mile Point:	433.164	**County:**	BOX ELDER
Dates of Data Source:	2008-2012	**Date of Analysis:**	December 16 2015

Table 2: Segment Characteristics

Function Class:	Other Principal Arterial	**AADT:**	15,495
Number of Thru Lanes:	4	**Speed Limit (MPH):**	50

Table 3: Segment Length

Beginning Mile Point	Ending Mile Point	Length
431.317	433.164	1.847

Micro Analysis

Crash Data

Table 4: Crash Count and Severity

Mile Points	# of Crashes	Severity 5	Severity 4	Severity 3
431.317 - 433.164	16	0	7	9

Table 5: Top 8 Crash Factors

	ROADWAY DEPARTURE	DISTRACTED DRIVING	DROWSY DRIVING	TEENAGE DRIVER INVOLVED	OLDER DRIVER INVOLVED	NIGHT DARK CONDITION	COLLISION WITH FIXED OBJECT	MOTORCYCLE INVOLVED
Segment Total	5/16	4/16	4/16	3/16	3/16	3/16	3/16	2/16

Current Conditions and Historical Perspective

This 1.85 mile segment of US-89 is located in Perry, Utah, just south of Brigham City. This four lane highway has a center two-way, left turn lane. Although there are not very many signalized intersections along the segment, there are many driveways and access points for residential and commercial areas. The population of Perry is approximately 4500.

Due to winter conditions, a personal site visit was not conducted on December 16 2015. However, Internet tools, such as Roadview Explorer and Google Earth, were used to assess roadway conditions. There is an asphalt shoulder along side of the roadway. There is some lighting along the roadway. The roadway is fairly straight. There may be a few cases where trees or vegetation block the view of the drivers approaching US-89 from the minor streets.

Figure B-2: Hot Spot Two-Page Report for Suburban/Urban Arterial Example

Segment Definition

This 1.8 mile segment is a four lane highway, with a center two-way left turn lane. There are not many signalized intersections but there are many driveways to residential homes and commercial businesses. The roadway is fairly straight, with minimum change in vertical grade. Additional roadway characteristics are given in Table 6.

Table 6: Roadway Characteristics

Mile Points	Median	IPM	SPM	Shoulder	Grade	Curve	Lanes	Wall/ Barrier	Rumble
431.317-433.164	None	1/0.4	6/2.6	Asphalt, 6 ft	-1.37 (max)	Class A, L = 986, R = 4257	4 Thru, Left Turn Lane, Right Turn Lane, Decel Lane, TWLTL	No (Wall), No (Barrier)	No

Problem Definition

According to the crash data, there were no fatal crashes on this roadway between 2008 and 2012. The most common crash factors (although not applicable to all crash types) include roadway departure, distracted driving, drowsy driving, teenage driver, older driver, and night conditions. It appears that some crashes involved multiple vehicles, while other crashes involved fixed objects.

Countermeasures and Recommendations

This section includes a list of suggested countermeasures for implementation at the site.

Remove/relocate objects in hazardous locations
Delineate trees or utility poles with retroreflective tape
Use breakaway devices
Place utilities underground
Strengthen graduated driver licensing requirements for young drivers
Incorporate information on distracted/fatigued driving into education programs and materials for young drivers
Mowing and Vegetation Control Guidelines
Remove Trees in Hazardous Locations
Clear sight triangles on stop or yield controlled approaches to intersections
Eliminate parking that restricts sight distance
Retime adjacent signal to create gaps at stop controlled intersections
Improve visibility of the driveway by providing lighting
Provide a stop bar (or provide a wider stop bar) on minor road approaches
Provide pavement markings with supplementary messages such as STOP AHEAD
Provide targeted public information and education on safety problems at specific intersections
Provide turn path marking

Figure B-2: Continued

Safety Analysis on Hot Spot Segments

Introduction

The purpose of this report is to summarize and present preliminary results from a safety-specific micro analysis on an identified hot spot segment. This report includes identification of the roadway segment and sub-segments, micro analysis data, and segment definition including roadway characteristics. A discussion of the problem at the location including possible countermeasures is also included.

Segment Identification

Table 1: Segment Metadata

Road Name:	I-15	**UC Model Used:**	UCPM
Road Direction:	Positive	**Ranking from Model:**	4
Beginning Mile Point:	292.596	**UDOT Region:**	2
Ending Mile Point:	293.634	**County:**	SALT LAKE
Dates of Data Source:	2008-2012	**Date of Analysis:**	#######

Table 2: Segment Characteristics

Function Class:	Interstate	**AADT:**	157,325
Number of Thru Lanes:	10	**Speed Limit (MPH):**	65

Table 3: Segment Length

Beginning Mile Point	Ending Mile Point	Length
292.596	293.634	1.038

Micro Analysis

Crash Data

Table 4: Crash Count and Severity

Mile Points	# of Crashes	Severity 5	Severity 4	Severity 3
292.596 - 293.634	25	1	2	22

Table 5: Top 8 Crash Factors

	INTERSTATE HIGHWAY	SPEED RELATED	COLLISION WITH FIXED OBJECT	TEENAGE DRIVER INVOLVED	ROADWAY DEPARTURE	COMMERCIAL MOTOR VEH INVOLVED	OLDER DRIVER INVOLVED	NIGHT DARK CONDITION
Segment Total	25/25	12/25	8/25	6/25	4/25	4/25	4/25	4/25

Current Conditions and Historical Perspective

This segment of I-15 is located in the Salt Lake Valley. It runs along the boundary of Sandy (to the east) and South Jordan (to the west). The beginning and ending milepoints of this segment correspond to two freeway exits. The surrounding area has several commercial properties that are accessible from the two freeway exits including Walmart, the South Town Center, and Costco. This means that the area probably generates a higher-than-average trip amount. According to Roadview Explorer, in 2008 the segment also had 5 lanes, with one being the HOV lane. However, the right shoulder was only a few feet wide. There also was no freeway entrance from 11400 S as there is now. By 2011, the shoulder had been widened and the 11400 S entrance had been added. The 2011 conditions match those of the 2014 conditions as shown on Roadview Explorer. There is a barrier separating north- and south-bound traffic.

Figure B-3: Hot Spot Two Page Report for Freeway Segment Example

A site visit was carried out on Wednesday, November 25, 2015 to hot spot segment 4 of the UCPM at about 4:00 PM. It had rained earlier in the day at the location and the sky was overcast. Traffic was going at speed limit speeds in the segment. The roadway characteristics were similar to those shown on Roadview Explorer in 2014. There are 5-lanes one way, with one being the HOV lane. There is a 12-foot right shoulder. As seen in Roadview Explorer, the 11400 S entrance comes in soon after the beginning of the segment and turns into an exit-only lane for the 10600 S exit. There's a sign as the lane enters that says "Lane Ends 300 Feet". Because of the light traffic, there was not much movement in and out of this lane. Only one car was observed merging into the lane to exit at 10600 S. There is little of any horizontal curvature in the roadway

Segment Definition

Based on the site visit and Roadview Explorer, a main crash factor is determined to be the freeway entrance from 11400 S that becomes the exit-only lane for the 10600 S exit. There will also be large amounts of cars attempting to merge into the exit-only lane to exit at 10600 S. The short distance between entrance to exit gives drivers little opportunity to merge in and out during heavy traffic times. Traffic would tend to slow down significantly in order for cars to maneuver safely. However, the slower speeds will cause other crashes. The roadway characteristics are shown in Table 6.

Table 6: Roadway Characteristics

Mile Points	Median	IPM	SPM	Shoulder	Grade	Curve	Lanes	Wall/ Barrier	Rumble
292.596-293.634	None	0/0	19/18.3	Concrete, 11 ft	0 (max)	None	10 Thru, HOV Lane	No (Wall), Constant Slope Concrete (Center & (Outside Barrier)	No

Problem Definition

According to the crash data, the top few crash factors besides interstate were speed related, collision with a fixed object, and teenage drivers. Most of the crashes were either front to rear bumper or sideswipe in the same direction. There was only one fatal crash and most were a 3 severity. With so many vehicles entering the freeway, there will normally be several cars merging over into the thru lanes at once. Also, cars will be slowing down to merge into the exit-only lane, therefore causing front to rear collisions. Younger drivers would have difficulty in an area like this if they are not familiar with it already.

Countermeasures and Recommendations

This section includes a list of suggested countermeasures for implementation at the site.

Install shoulder and/or centerline rumble strips
Conduct education and awareness campaigns targeting the general driving public
Visibly enforce existing statutes to deter distracted and drowsy driving
Strengthen graduated driver licensing requirements for young drivers
Encourage employers to offer fatigue management programs to employees working nighttime/rotating shifts
Set speed limits which account for roadway design, traffic, and environment
Increase public awareness of the risk of driving at unsafe speeds
Use targeted conventional speed enforcement programs at locations known to have speeding related crashes
Implement automated speed enforcement
Implement active speed warning signs
Use in-pavement measures to communicate the need to reduce speeds
(High speeds only) Implement variable message signs
Effect safe speed transitions through design elements and on approaches to lower speed areas
Provide adequate sight distance for expected speeds

Figure B-3: Continued

APPENDIX C.   SOFTWARE AVAILABILITY

The software developed for this thesis was created by Jordan Frustaci and Mitsuru Saito as part of a funded research project at Brigham Young University (BYU). The software has been provided to UDOT and others for free use for any purpose. The software is hereby released to the public under the MIT open source license. The MIT license has been chosen for this purpose since it allows for wide use and modification of the software without restriction. This license protects the developers, the copyright holder, and future users from any claims to exclusive use. It also protects the developer and copyright holder from claims for damages that may arise from use of the software. Note that, as a funded research project through BYU, BYU is the copyright holder.

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